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(NASA-CR-159484) USER'S GUIDE TO COMPUTER  
PROGRAMS JET 5A AND CIVM-JET 5B TO CALCULATE  
THE LARGE ELASTIC-PLASTIC  
DYNAMICALLY-INDUCED DEFORMATIONS OF  
MULTILAYER PARTIAL (Massachusetts Inst. of

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**USER'S GUIDE TO COMPUTER PROGRAMS JET 5A AND  
CIVM-JET 5B TO CALCULATE THE LARGE ELASTIC-PLASTIC  
DYNAMICALLY-INDUCED DEFORMATIONS OF MULTILAYER  
PARTIAL AND/OR COMPLETE STRUCTURAL RINGS**

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November 1978



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Prepared for  
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## FOREWORD

This report has been prepared by the Aeroelastic and Structures Research Laboratory (ASRL), Department of Aeronautics and Astronautics, Massachusetts Institute of Technology, Cambridge, Massachusetts under Grant No. NGR 22-009-339 from the Lewis Research Center, National Aeronautics and Space Administration, Cleveland, Ohio 44135. Dr. Arthur G. Holms, Mr. Solomon Weiss, and Mr. Robert D. Siewert of the Lewis Research Center served as technical monitors. The cooperation and helpful suggestions of Mr. Raymond W. Palmer and Mr. Richard B. Lantz of NASA-Lewis throughout this research program are much appreciated.

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## SUMMARY

Described in this report are two user-oriented computer programs, JET 5A and CIVM-JET 5B to predict transient, large, elastic-plastic deflections of single-layer or multilayer (3 layers or less) Bernoulli-Euler structural rings which may be subjected to fragment impact (CIVM-JET 5B), or prescribed externally-applied transient loading, and/or prescribed initial velocity distributions (handled in JET 5A). These structural ring deflections lie essentially in one plane and, hence, are called two-dimensional (2-d). The structural rings may be complete or partial; the former may be regarded as representing a "fragment containment ring" while the latter may be viewed as a 2-d fragment-deflector structure. These two types of "rings" may be either free or supported in various ways (pinned-fixed, locally clamped, elastic-foundation supported, mounting-bracket supported, etc.). The initial geometry of each ring may be circular or arbitrarily curved; uniform-thickness or variable-thickness rings may be analyzed. Strain-hardening and strain-rate effects of initially-isotropic material are taken into account.

An approximate analysis utilizing kinetic energy and momentum conservation relations is used to predict the after-impact velocities of each fragment and of the impact-affected region of the ring; this procedure is termed the collision-imparted velocity method (CIVM) and is used in the CIVM-JET 5B program. This imparted-velocity information is used in conjunction with a finite-element structural response computation code to predict the transient, large-deflection, elastic-plastic responses of the ring. Similarly, the equations of motion for each fragment are solved in small steps in time.

Provisions are made in the CIVM-JET 5B code to analyze structural ring response to impact attack by from 1 to 3 fragments, each with its own size, mass, translational velocity components, and rotational velocity. The effects of friction between each fragment and the impacted ring are included.

## SECTION 1

### INTRODUCTION

The JET 5A and the CIVM-JET 5B computer programs described in this report are additions to the series of computer programs which are intended to be made available to the aircraft industry for possible use in analyzing structural response problems such as containment/deflection (C/D) rings intended to cope with engine-rotor-burst fragments. These computer programs may also be applicable (a) to crashworthiness problems which are of interest to the automobile industry and (b) to nuclear power plant protective structures.

The features and capabilities of both the present computer programs and earlier ones developed under NASA NGR 22-009-339 are given in a convenient informative tabular summary in Appendix C together with supplementary descriptive material. The reader is urged to examine the Appendix C information in order to make an assessment of which one (or more) of these programs might best suit his particular application, since each computer program has its own specific capabilities and limitations. With regard to the type of applications accommodated, only programs CIVM-JET 4B and CIVM-JET 5B pertain to ring structural response induced by fragment impact; the remaining computer programs cited in Appendix C deal with the transient structural responses of rings which are subjected to prescribed (1) transient distributed external loads or (2) a distributed initial velocity field.

The JET 5A and CIVM-JET 5B programs, written in FORTRAN IV, permit one to predict the large-deflection, two-dimensional, elastic-plastic transient Bernoulli-Euler response of a multilayer<sup>a</sup>, multimaterial, hard-bonded<sup>b</sup> ring, which may be either a complete ring or a partial ring. The ring may be subjected to various restraints and supports, including "ring support brackets" (which are treated as "branches") and elastic foundations.

- 
- a: The programs are restricted to 3 or fewer layers but the formulation applies to an arbitrary number of layers.
  - b: This means that the displacements are defined to be continuous at layer interfaces.



The geometrical shape of the structural ring can be simple circular or arbitrarily curved, and each layer may have independently-varying thickness along the circumferential direction. The material behavior of each layer may be elastic, strain-hardening, and/or strain-rate sensitive. Both of these programs employ the spatial finite-element representation of the ring and the temporal finite-difference solution procedure.

The JET 5A computer program is designed to analyze full rings or partial rings subjected to initial impulsive loading and/or prescribed externally-applied time-dependent forces. On the other hand, the CIVM-JET 5B computer program is designed to analyze the transient responses of structural rings subjected only to rigid-fragment impact. These programs were written in parallel and the main body of the program and input were kept the same to ease the transition from one to the other by the user. The following section of the user's guide will first describe the portion of these programs which are the same and then detail any differences. The governing equations and the solution procedures common to both programs are outlined in Appendix A.

In the CIVM-JET 5B code for predicting the transient responses of structural rings subjected to rigid-fragment impact, energy and momentum considerations are employed in an approximate analysis to predict the collision-induced velocities which are imparted to the fragment and to the affected ring segments. The presence of surface friction between the ring and the impacting fragment is taken into account. The pertinent analytical development and the solution methods which are unique to the CIVM-JET 5B program are presented concisely in Appendix B. The reader is invited to consult Refs. 1, 2, 3, and 4 for background information and a more detailed description of this solution procedure.

Section 2 of this report is devoted to describing the general organization and capabilities of each of these programs. The ring structural geometry, supports, elastic restraints, and materials properties accommodated will be described for both programs. The initial-velocity and prescribed external-loading provisions and the associated solution procedure for JET 5A are described. Then the fragment-ring collision-interaction analysis procedure and the associated transient response solution procedure for CIVM-JET 5B are discussed.

Next in Section 3, the main programs and subroutines for both of these programs are described. Since the formulation and solution of these programs is quite similar, many of the subroutines are used interchangeably between the two. These common subroutines are described first and then any subroutines particular to each of the programs are listed. This procedure will be followed throughout the remainder of this user's guide. Included in Section 3 is a partial list and explanation of the variable names used, first those common to both JET 5A and CIVM-JET 5B and then those variable names particular to each separate program.

A discussion of the conventions used in JET 5A and a detailed explanation of the required input and its resulting output follows in Section 4. Section 5 is a similar presentation for CIVM-JET 5B including only that information which differs from that which is common to JET 5A. A complete listing of the FORTRAN IV code for all of the subroutines, first those common to both programs and then those particular to each program, appears in Section 6.

Illustrative examples of the use of JET 5A and CIVM-JET 5B are given in Subsections 7.1 and 7.2, respectively of Section 7. These examples are presented with their associated input and output as illustrations of the capabilities of these programs, and to aid the user in checking the adaptation of these programs to his computer system.

## SECTION 2

### GENERAL DESCRIPTION OF THE JET 5A AND THE CIVM-JET 5B PROGRAM

Both of the cited programs are described briefly in this section. Common to both programs are ring geometry, supports, elastic restraints, and material properties; accordingly these matters are discussed in Subsection 2.1. Features that are unique to the JET 5A code include (a) the initial-velocity and external-loading options and (b) the associated solution procedure; these matters are discussed in Subsections 2.2 and 2.3, respectively. Since CIVM-JET 5B accommodates only structural response to fragment impact, Subsection 2.4 contains a description of the ring-fragment collision-interaction analysis and the associated solution procedure.

#### 2.1 Ring Geometry, Supports, Elastic Restraints, and Material Properties

In the present analysis, the transient structural responses of the ring are assumed to consist of planar (two-dimensional) deformations. Also, the Bernoulli-Euler (or Kirchhoff) hypothesis is employed; that is, transverse shear deformation is excluded.

Both the JET 5A and the CIVM-JET 5B computer programs can treat multilayer structural rings. Each layer may be of different material, but perfect bonding at each interface is assumed and hence the displacement fields are continuous across each interface. In addition, each layer may be of independently-varying thickness; however, the total thickness remains small compared with the circumferential dimension of the ring. The cross section of each layer is assumed to be rectangular in shape, and the centroidal axis of a conveniently-chosen\* layer (see Fig. 1) is employed as the circumferential reference axis of the multilayer ring.

The structure can be either a complete or a partial ring. The geometric shape of the circumferential axis of the ring can be circular or arbitrarily curved. The outward-normal direction is defined in such a manner that as one moves along the circumferential axis in the positive  $\eta$  direction from an arbitrary reference point, the outward-normal direction is always toward one's left as shown in Fig. 2, where XYZ is the global reference Cartesian coordinate system with the X-axis pointing out of the paper. At any point on the circumferential axis,  $\bar{i}$  is a local unit vector defined in the same

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\* See Appendix A.

direction as the +X axis,  $\bar{a}$  is a unit tangent vector along the positive circumferential axis direction, and  $\bar{n}$  is a unit outward-normal vector which is defined by the right-hand rule as  $\bar{n} = \bar{i} \times \bar{a}$ . Once the positive circumferential direction is defined, the outward-normal direction is then determined accordingly (see Fig. 2). For the CIVM-JET 5B code, the positive circumferential direction must be chosen so that the positive outward-normal is directed toward the "outside" of the C/D structure such that fragment impact can occur only on the "inside" of the C/D structure.

In the spatial finite-element analysis, the ring is represented by an assemblage of discrete (or finite) elements compatibly joined at the nodal stations. The geometry and nomenclature of a typical arbitrarily curved ring element are shown in Fig. 3, where the deformation plane is  $\eta, \zeta$  and the coordinates  $\eta$  along, and  $\zeta$  outward-normal to the centroidal axis of a conveniently-chosen layer are employed as the reference coordinates of the multilayer beam element. The nodal number is increased along the positive circumferential direction.

The behavior of each finite-element is characterized by a knowledge of the four generalized displacements:  $v$ ,  $w$ ,  $\psi = (\partial w / \partial \eta) - (v/R)$ , and  $\chi = (\partial v / \partial \eta) + (w/R)$  at each of its nodal stations where  $v$  and  $w$  are the reference plane displacements in the circumferential and the normal direction, respectively;  $R$  is the radius of curvature. The displacement within each finite-element is represented by a cubic polynomial in  $\eta$  for the circumferential displacement  $v$  and a cubic polynomial in  $\eta$  for the normal displacement  $w$ , anchored to the four generalized nodal displacements at each node (see Appendix A and/or Ref. 1 for further details). For application to arbitrarily-curved, variable-thickness, ring structures, the finite elements are described by reading in at each nodal station the global Y and Z coordinates, the slope (the angle between the tangent vector and the +Y axis), and the thickness of each layer. Within each finite element, the slope is approximated by a quadratic function in  $\eta$  and the thickness of each layer is approximated as being piecewise linear between nodes.

As for the support conditions of the structure, these programs include three types of prescribed nodal displacement conditions (see Fig. 4a):

(1) Symmetry\*

$$(v = \psi = 0)$$

---

\* Not accommodated in CIVM-JET 5B

(2) Ideally-Clamped  $(v = w = \psi = 0)$

(3) Smoothly-Hinged, Pinned  $(v = w = 0)$

and two types of elastic restraints (see Fig. 4b):

(a) Point elastically restrained (elastic restoring spring) at given locations (3 directions: normal, tangential, and rotational)

(b) Distributed elastically restrained (elastic foundation) over a given number of elements (3 directions: normal, tangential, and rotational).

A global effective stiffness matrix supplied by the elastic foundation and/or the restoring springs will be evaluated in the program from the virtual-work statement for cases in which the structure is subjected to one or both of these two types of elastic restraints.

The 2-d containment/deflector (C/D) structure may also be regarded as being supported by attachment brackets as depicted, for example, in Fig. 4c. These attachment brackets (or branches) are idealized to behave in the 2-d fashion shown in Fig. 4d. These brackets are modeled as consisting of a single-layer, variable-thickness, 2-d structure of arbitrary initial shape in the plane of the C/D structure, and are connected compatibly with the C/D structure; the other end of each bracket may be supported in any of the common fashions (clamped, pinned, elastic support, etc.). The programs provide for a maximum of five support brackets. In the fragment attack (CIVM-JET 5B) usually only the C/D structure suffers physical impact; however, if the analyst has a physically plausible situation wherein the idealized support bracket could be impacted by a fragment (such a case is depicted in Fig. 4d), the impacted portion must be defined as the main C/D structure since impacts on a branch are not accommodated in the program. It should be noted, however, that the actual brackets in the bracket-supported C/D structure (see Fig. 4c) must undergo 3-d deformation -- this aspect is not accommodated in the present 2-d model. Finally, a support bracket (or branch) may be attached to any nodal station of the main 2-d C/D structure.

Each layer of material can be of elastic, or elastic, perfectly-plastic or elastic-strain-hardening behavior, and the material properties of each

branch can vary from the properties of the main structure. The strain-rate effects of the material can also be taken into account. In the present analysis, the strain-hardening material is accounted for by using the "mechanical sublayer model" (Ref. 1). A useful feature of this model is its inclusion of kinematic hardening and the Bauschinger effect. The strain-rate effect is approximated by assuming that the uniaxial stress-strain curve is affected by strain-rate only by a quasi-steady increase in the yield stress above the "static" value (Ref. 1).

## 2.2 Initial-Velocity Provisions and/or Externally-Applied Forces for JET 5A

### 2.2.1 Initial Velocity Provisions

The initial velocity distribution is specified by reading in the initial nodal velocities. Three ways are available to describe these distributions (see Fig. 5):

- (1) Arbitrary distribution by prescribing nodal initial velocities,  $\dot{v}$ ,  $\dot{w}$ , and  $\dot{\psi}$  at certain nodes of the structure.
- (2) One or more local uniform initial normal velocity values,  $\dot{w}$ , distributed over certain elements of the structure, and/or
- (3) One or more local sine-shaped distributions of initial velocity in the normal direction, distributed over certain elements of the structure.

### 2.2.2 Transient Externally-Applied Prescribed Loads

The transient externally-applied loads,  $F(\eta, t)$  are assumed to be expressible as

$$F(\eta, t) = g(\eta) f(t) \quad (2.1)$$

where  $g(\eta)$  is the prescribed spatial distribution function and  $f(t)$  denotes the amplitude time history. These quantities are described in the program as follows (see Fig. 6):

- (a) The function  $f(t)$  can be arbitrary and is represented by a series of coordinates in time which specify values of characteristic two-component (normal and circumferential) force-versus-time curves.



The program then linearly interpolates between time points to obtain values of forces at intermediate times by:

$$f(t) = f_m + \frac{f_{m+1} - f_m}{T_{m+1} - T_m} (t - T_m) \quad (2.1a)$$

where  $f_m$  and  $f_{m+1}$  are the amplitudes of the forces at some user-specified times  $T_m$  and  $T_{m+1}$ . The quantity  $f(t)$  is found by this interpolation in the time interval  $(T_m \text{ to } T_{m+1})$  linearly in terms of  $f_m$  and  $f_{m+1}$ .

- (b) The spatial distribution of the forces acting on the ring is described through the following three forms:
- (1) One or more concentrated loads prescribed at certain locations.
  - (2) One or more local uniform load distributions specified over given numbers of elements.
  - (3) One or more local half sinusoidal-shape load distributions specified over given numbers of elements (this distribution is approximated as being piecewise linear within each element).

Corresponding to this general distribution of externally-applied loads, a set of virtual-work equivalent (or consistent) nodal loads is evaluated in the program.

### 2.3 Solution Procedure for JET 5A

The spatial finite-element approach is utilized in conjunction with the Principle of Virtual Work and D'Alembert's Principle to obtain the equations of motion of the structural ring which is permitted to undergo large-deflection elastic-plastic transient deformations. In the interest of conciseness and convenience in this report, the user is invited to consult Ref. 1 and/or Appendix A for a detailed derivation and discussion of the equations of motion. For present purposes, it suffices to note that the governing equations of motion for the complete assembled discretized structural ring may be written in the following form:

$$[M^*]\{\ddot{q}^*\} + ([K^*] + [K_s^*])\{q^*\} = \{F^*\} + \{F_q^{*NL}\} + \{F_p^{*L}\} + \{F_p^{*NL}\} \quad (2.2)$$

where

- $\{q^*\}$  and  $\{\ddot{q}^*\}$  are the global generalized displacement and acceleration.
- $[M^*]$  is the consistent mass matrix of the complete structure.
- $[K^*]$  is the usual stiffness matrix of the complete structure.
- $[K^*]_s$  represents the effective stiffness matrix supplied by the elastic foundation and/or the restraining spring.
- $\{F^*\}$  denotes the prescribed externally-applied generalized loading acting on the structure.
- $\{F_q^{*NL}\}$  represents a "generalized loads" vector arising from large deflections and is a function of quadratic and cubic displacement terms -- a nonlinear force contribution.
- $\{F_p^{*L}\}$  is the generalized loads vector arising from the presence of plastic strains, and is associated with the linear terms of the strain-displacement relations.
- $\{F_p^{*NL}\}$  is a generalized loads vector of origin similar to  $\{F_p^{*L}\}$  but is associated with the nonlinear terms of the strain-displacement relations.

The resulting equation of motion, Eq. 2.2, is solved through the use of the Houbolt operator (4-point backward finite-difference operator) whereby one obtains a recurrence equation which provides a solution step-by-step in finite-time increments. In the following, the general solution process is described briefly.

First, information is provided to define the geometry of the ring including its prescribed-displacement conditions and elastic restraints. In addition, the ring material property constants, and the prescribed initial velocity and/or the prescribed applied transient external loading are defined. Also defined are the structural discretization information and numerical integration data. It should be mentioned that Gaussian quadrature is employed in the present analysis to evaluate the element-property matrices -- this requires that the stresses and strains be evaluated at a selected finite number of Gaussian stations over the "spanwise" and depthwise region of each layer of each finite

element. Next, the mass matrix and the stiffness matrix for the entire structure are evaluated by assembling the element mass and stiffness matrices. Then the proper prescribed displacement conditions are imposed and a reduced mass matrix and stiffness matrix are obtained by deleting the corresponding rows and columns associated with those generalized displacements which are prescribed to be zero. Also constructed are the discrete-element property matrices that do not change with time (and remain constant throughout the program), such as the matrices relating strain to the nodal generalized displacements, the equivalent nodal load vector and actual externally-applied load transformation matrices, etc.

Starting from a set of given initial conditions at time  $t_0$  on the generalized nodal displacements, nodal velocities, and externally-applied forces, the generalized nodal displacements and displacement increments are computed for the first time increment  $\Delta t$ . Next, the strain increments developed from  $t_0$  to  $t_1$  at every Gaussian station (or point) required over and depthwise through each finite element are calculated. From a knowledge of the prescribed initial stresses (if any) and the strain increments, one can determine the stress increments, the stresses and/or the plastic strains and the plastic strain increments through the use of the pertinent elastic-plastic stress-strain relations including the plastic yield condition and flow rule. Next, one can calculate the equivalent generalized load vectors arising from large deflections and plastic strains. Also, the prescribed generalized load vector representing the externally-applied loads at the present time step is calculated. Then, the proper recurrence equations, which is the finite-difference representation of the equations of motion, are solved to obtain the nodal generalized displacements and displacement increments of the next time increment. The process then proceeds cyclically for as many time steps as desired. Finally, it should be noted that the triple-matrix-factorization scheme is employed to solve the system of ordinary algebraic equations.

For present purposes, the above general description is considered to be adequate; one may consult Appendix A and Refs. 1-3 for a more detailed discussion of the solution and evaluation process.

#### 2.4 Fragment/Ring Collision-Interaction and Solution Procedure for CIVM-JET 5B

For analyzing the collision-induced transient responses of two-dimensional containment and/or deflector rings and fragment motions, the fragment is idealized as a non-deformable fragment of circular configuration as depicted for

example, in Fig. 7. The modeled-fragment diameter, mass, mass moment of inertia, and velocity components are specified by the user to "correspond" with those of the actual fragment.

The process called the collision-imparted velocity method (CIVM) is used for the collision-interaction analysis in the CIVM-JET 5B program (see Refs. 1-3). In this process, energy and momentum considerations are employed to predict the collision-induced velocities which are imparted to the fragment and to the impact-affected zone of the ring. Also, the following simplifying assumptions are invoked:

- (1) The collision process is instantaneous and involves only the fragment and the impact-affected zone of the target ring. The impact-affected zone is defined as the fraction of the ring that responds to fragment impact instantaneously with momentum changes. The size of the impact-affected zone of the ring can be estimated from the speed of a longitudinal wave or from semi-empirical data.
- (2) In an overall sense, the fragment is treated as being rigid but at the "immediate contact region" between the fragment and the struck ring the collision process is regarded as acting in a perfectly elastic ( $e = 1$ ), perfectly inelastic ( $e = 0$ ), or an intermediate fashion ( $0 < e < 1$ ), where  $e$  represents the coefficient of restitution.
- (3) The colliding surfaces of both the fragment and the target ring may be either perfectly smooth ( $\mu = 0$ ) or may be "rough" ( $\mu \neq 0$ ), where  $\mu$  denotes the coefficient of sliding friction. Hence, respectively, force and/or momentum (or velocities) are transmitted only in the normal-to-surface direction or in both the normal and the tangential direction.
- (4) During the collision, the contact forces are the only ones considered to act on the impact-affected region of the ring and in an anti-parallel fashion on the fragment. Any forces which the ring segment on either side of the impact-affected region may exert\* on that segment as a result of this collision are considered to be negligible because instantaneous momentum transfer to the impact-affected region is assumed.

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\* Such forces are termed "internal forces" as distinguished from the "external impact forces".

- (5) To avoid unduly complicating the analysis and because of the smallness of the arc length of the ring finite elements, each affected ring element is treated as a straight beam segment (see Fig. 8) in the derivation of the impact inspections and equations. However, for modeling of the ring itself for transient response predictions, the ring is treated as being arbitrarily curved and of variable thickness.

An information flow schematic of the CIVM and ring/fragment transient response solution procedure is shown in Fig. 9. Briefly, the analysis procedure indicated in Fig. 9 consists of the following principal steps:

1. Motions and Positions of Bodies

The motions of the fragment and of the containment and/or deflector ring are predicted and the (tentative) region of space occupied by each body at a given instant in time is determined.

Modeling of the C/D ring structure is carried out as already described for the JET 5A analysis, except that a diagonal "lumped" mass matrix is employed (see Appendix B). The justification for the use of lumped mass instead of consistent mass is outlined next. A comparison of numerical results obtained using lumped mass vs. consistent mass, given in Ref. 1, for ring-type structures shows similar results for both mass systems. Reduced storage requirements and additional savings of computation time in each time step because of the simple form of the lumped mass matrix, makes the use of a lumped mass matrix computationally efficient. Finally, in the collision-interaction analysis, the element (and structure) mass properties are assumed to be lumped at the nodal points. Thus, for consistency, the mass properties of the ring structure used in the global timewise solution procedure should also be nodal lumped masses. Also, since no prescribed externally-applied forces act on the ring, the form of the governing equations of motion is given by Eq. 2.2 except that  $\{F^*\} = 0$ .

Prior to fragment-ring impact, the ring structure is assumed to be stationary in its undeformed state and the (one or more) idealized fragment is moving with known translational and rotational velocities toward the ring. The step-by-step solution procedure is carried out in small steps  $\Delta t$  in time by employing Houbolt timewise operator.

## 2. Collision Inspection

Next, an inspection is performed to determine whether a collision has occurred during the small increment ( $\Delta t$ ) in time from the last instant at which the body locations were known to the present instant in time at which the body-location data are sought. If a collision has not occurred during this  $\Delta t$ , one follows the motion of each body for another  $\Delta t$ , etc. However, if a collision has occurred, one proceeds to carry out an (approximate) calculation of the time of fragment-ring contact.

## 3. Contact-Time Calculation

The fragment and ring-node positions, velocities, and accelerations are known at an instant in time prior to ring-fragment collision. Using this information, the (approximate) time of ring-fragment contact (within a small increment,  $\Delta t$ , in time), and the point of contact on the ring are calculated. When this information has been obtained, one then proceeds to carry out a collision-interaction calculation.

## 4. Collision-Interaction Calculation

In this calculation energy and momentum conservation relations are employed in an approximate analysis to compute the collision-induced changes in (a) the velocities  $V_f$  (translation) and  $\omega_f$  (rotational) of the fragment and (b) nodal velocities of the ring impact-affected segments. The coordinates which locate the positions of the fragment and of the affected segments are thereby corrected from their tentative uncorrected-for-impact locations.

One then returns to step 1, and the process is repeated for as many time increments as desired.

The details of this analysis procedure as well as various considerations and simplifying assumptions employed are discussed further in Ref. 4 and Appendix B.



## SECTION 3

### DESCRIPTION OF PROGRAMS AND SUBPROGRAMS

#### 3.1 Program Contents

The following three subsections present a brief description of the subroutines which are common to both the JET 5A and the CIVM-JET 5B program (Subsection 3.1.1). Then the MAIN programs and subroutines unique to each program, JET 5A and CIVM-JET 5B, are presented in Subsections 3.1.2 and 3.1.3, respectively.

##### 3.1.1 Subprograms Common to JET 5A and CIVM-JET 5B

This group consists of the following 14 subprograms:

- |       |   |
|-------|---|
| ASSEF | This subroutine assembles the generalized nodal load vectors (due to large-deflection elastic-plastic effects) of each individual element into a generalized nodal load vector for the structure as a whole.  |
| ASSEM | This subroutine updates the structural mass (and/or stiffness) matrix as the element mass (and/or stiffness) matrices are generated. The components of the assembled structural mass matrix $[M^*]$ , which is a symmetric matrix, are stored in a linear-array form; only the lower triangular part of $[M^*]$ need be and is stored (row-wise) starting with the first nonzero element in the row and ending with the diagonal term. Similar handling of the assembled stiffness matrices ( $[K^*]$ and $[K_g^*]$ ) of the structure is employed. |
| BRAN  | This subroutines reads the geometry, boundary constraints, and elastic restraints for a branch. The global numbering system of the main structure is then modified to include the branches. BRAN establishes arrays which contain information facilitating the rotations required in other subroutines. It also establishes identifier arrays which distinguish between elements of the main structure and elements of the various branches.  |
| ELMPP | This subroutine evaluates the element mass matrix $[m]$ , and element stiffness matrix $[k]$ , for each discrete element, and   |

then performs discrete element assembly to form  $[M^*]$  and  $[K^*]$  for the complete structure with respect to global coordinates. Next, the prescribed displacement conditions (if any) are imposed on  $[M^*]$  and  $[K^*]$  to form restrained matrices. Also evaluated are the transformation matrices between the strain at each spanwise checking (Gaussian) station and the generalized nodal displacement conditions of the element.

ERC	Imposes the proper prescribed displacement conditions to the $[M^*]$ and/or $[K^*]$ matrices by restraining the corresponding rows and columns of the matrices
FAC	FAC factors a symmetric matrix $[B]$ , into a lower triangular matrix $[L]$ , a diagonal matrix $[D]$ , and an upper triangular matrix $[L]^T$ ; $[B] = [L] [D] [L]^T$ .
IDENT	The IDENT subroutine is used to print out the values of certain input parameters at the beginning of the run, and is used to identify the type of run that is being made.
MINV	Performs the matrix inversion; a standard Gauss-Jordan inversion method is used.
ØMULT	Computes various linear arrays (in which a two-dimensional matrix is stored) and vector products. A vector results.
QREM	Evaluates the effective stiffness matrix $[K_s^*]$ , supplied by the elastic foundations and/or the restoring springs, and then imposes the prescribed displacement conditions on $[K_s^*]$ accordingly.
ROTAT	This subroutine generates the transformation matrix necessary to rotate from the global displacement system to the element displacement system. This matrix is then applied to the element $[k]$ matrix, the displacement vector and the equivalent load vector (as required) to perform the rotation for the connecting branch elements and any elements containing discontinuities.

SØLV Performs two back substitutions involving the triple factorization of a matrix to obtain the solution of a matrix equation.

STRESS This subroutine evaluates the generalized load vectors,  $(\{F_q^{*NL}\} + \{F_p^{*L}\} + \{F_p^{*NL}\})$  of Eq. 2.2) arising from the presence of large deflections and plastic strains. First, the stresses and plastic strains are determined at each quadrature station, which involves the use of the strain-displacement relation and the stress-strain relation. The strain-hardening and strain-rate sensitivity effects are taken into consideration. Next, the appropriate Gaussian integration scheme is used to form the element generalized nodal load for each discrete element, and finally, an assembled generalized nodal load vector is calculated.

TSTEP This subroutine is called during each problem run to compute  $\Delta t_{ref}$ . It finds the highest natural frequency,  $\omega_{max}$ , in the mathematical model of a corresponding linear dynamic system  $[M^*] \{\ddot{q}^*\} + [K^*] \{q^*\} = 0$  by using an iteration process, and then calculates a value of  $\Delta t_{ref} = (2/\omega_{max})$ . Will be used to estimate an appropriate  $\Delta t$ .

### 3.1.2 Subprograms Unique to JET 5A

This group consists of the following 4 subprograms:

MAIN Reads the ring geometry, material property data, the structural discretization information, and/or the prescribed displacement conditions and elastic restraints. It computes the quantities that are constant throughout the program and initializes most of the variables used in the subroutines. It controls the logical flow of information supplied by the various subroutines and the overall time cycle.

IMPULS The information for the initial generalized nodal velocities is read in. This subroutine also sets the initial generalized nodal displacements, the initial stresses, and the initial plastic strains to be equal to zero.

**LOADEQ** Computes the transformation matrices between the element generalized (virtual-work equivalent) nodal load vectors and the externally-applied mechanical load which may be concentrated, uniformly distributed, and/or linearly distributed within the element.

**LOADFT** This subroutine reads the data pertaining to the subsequent time-dependent externally-applied loads and uses this data to compute the element generalized load vector; subsequently, an assembled generalized load vector for the whole structure is formed at each step of calculation.

### 3.1.3 Subprograms Unique to CIVM-JET 5B

This group consists of the following 4 subprograms:

**MAIN** Reads the ring geometry, material property data, the structural discretization information, and/or the prescribed displacement conditions and elastic restraints. Also, read in are the fragment geometry parameters and the fragment velocity components. It computes the quantities that are constant throughout the program and initializes most of the variables used in the subroutines. It controls the logical flow of information supplied by the various subroutines and the overall time cycle. Also, the lumped mass matrix  $[M^*]$  is generated by this routine and stored in row form.

**IMPACT** This subroutine is the controlling routine for carrying out the search for impact occurrence involving one of N fragments on each element of the ring for all fragments considered. When it is determined that a fragment-ring collision has taken place, **IMPACT** controls the application of appropriate correction factors to the velocities of the fragment and the nodal points of the affected elements.

**IMPCTE** A slave subroutine of **IMPACT**. This subroutine calculates and applies the appropriate correction factors to the velocities

of the fragment and the nodal points of the elements affected when a fragment-ring collision has occurred.

PENTRN

A slave subroutine of IMPACT. Given the position of the fragment and ring nodes and the geometry of the fragment and idealized ring structure, this subroutine determines whether any "overlapping" (penetration) exists between the fragment geometry and the ring geometry.

### 3.2 Partial List of Variable Names

The following subsections give a brief list and definition of the most important and/or commonly used variable names.

#### 3.2.1 Variables Common to JET 5A and CIVM-JET 5B

A(I,J)	[A], an 8x8 matrix defines the transformation between the element generalized nodal displacements {q} and the parameters { $\beta$ } in the assumed displacement field of each element. It is destroyed in computation and is replaced by its inverse [ $A^{-1}$ ].
AEP(I,J,K)	Transformation matrix which relates strain at Ith additional strain point to the generalized nodal displacements of the element on which it is located.
AL(I)	Element arc length of the Ith element.
AMASS(I)	The lower triangular part of the symmetric structural mass matrix [M*] (stored in a linear-array form of a size ISIZE). Later on, it is destroyed in calculation and is replaced by a lower triangular factorized matrix.
ANB(I)	Same as ANG(I); applies to initial input for branch nodes.
ANG(I)	The slope, which is the angle between the tangent vector and the +Y axis, at the Ith node.
ANGDB	The slope, which is the angle between the tangent vector and the +Y axis, at the Ith slope discontinuity. ANGDB refers to initial input for branches.
ANGDI(I)	
APHA	The angle between the chord connecting the first node of the element to the second node, and the +Y axis.
ASFL(I,J,K,L)	Stress and/or plastic strain weighting factor on the Lth sub-layer in the Kth depthwise Gaussian point at the Jth spanwise Gaussian station of the Ith element.
AXG(I) } AWG(I) }	Input vectors with dimension NOGA: contain Gaussian quadrature constants, $x_i$ , and weights, $w_i$ of



$$\int_0^1 f(x) dx = \sum_i f(x_i) W_i$$

employed in the spanwise integration over each element.

AZET(I)	The location along an element's centroidal axis of the Ith additional strain point.
B(L)	Width of the ring (inches); $L=1$ for main structure; $L \geq 2$ for branches.
BEP(IR,J,I,K)	Transformation matrix which relates the strain at the Jth spanwise Gaussian station to the generalized nodal displacements of the IRth element ( $[D_I]$ , $I = 1, 2, 3$ , see Eq. A.14a).
BI(L)	Same as BIG(L), for largest average nodal strain.
BIG(L)	The largest computed strain at the Gaussian stations for the Lth substructure, up to the present cycle. It should be noted that strains are computed at every cycle. $L=1$ for main structure, $L \geq 2$ for branches.
BIGA(L)	The largest computed strain at the additional strain points, up to the present cycle.
BINP(I,J) BIMP(I,J)	The longitudinal force and the bending moment, respectively, over the cross section at the Jth spanwise Gaussian station of the Ith element (see Eq. A.24).
BINPP(J) BIMPP(J)	
BONE	The highest natural frequency squared of a corresponding linear dynamic system.
BTIM(L)	Same as BTIME(L); applies to nodes.
BITMA(L)	The time at which the largest computed strain occurs at the additional strain points. $L=1$ for main structure, $L \geq 2$ for branches.

BTIME(L)	The time at which the largest computed strain occurs at the Gaussian stations.
CINET	Kinetic energy stored in ring at the present time.
COPY(I) } COPZ(I) }	Current global Y coordinate and Z coordinate, respectively, of the Ith node.
DELD(I)	Vector contains the generalized Ith degree of freedom displacement increment during the current time step.
DELTAT	Time-step size used in the program, $\Delta t$ .
DEP(IR,I,J,K)	Transformation matrix which relates the strain at the Ith node to the generalized nodal displacements of the IRth element.
DENS(M,L)	Density of the Mth material layer of the Lth structural segment. $L=1$ for main structure, $L \geq 2$ for branches ( $\text{lbs-sec}^2/\text{in}^4$ ).
DISP(I)	Vector which contains the generalized Ith degree of freedom displacements at the current time instant.
DROT(L)	Stores information used in rotating a displacement vector into the global system at a point of slope discontinuity.
DS(M,L)	Material constant used in the strain-rate sensitivity formula for the Mth layer. $L=1$ for main structure, $L \geq 2$ for branches.
DUMMY	A dummy argument in the calling statement of Subroutine ROTAT.
ELAST	Total elastic energy present in the structure at the present time instant.
ELK(I,J)	Element stiffness matrix of dimension $8 \times 8$ (Eq. A.24a).
ELMAS(I,J)	Element mass matrix of dimension $8 \times 8$ (Eq. A.18b).
ELRP(I,J)	Element effective stiffness matrix of dimension $8 \times 8$ supplied by elastic restraints.

EPASI	}	Axial strain on the inner and outer surface, respectively, at an additional strain point.
EPASØ		
EPI(I)	}	Axial strain on the inner and outer surface, respectively, at the Ith Gaussian station.
EPØ(I)		
EPS(M,L,J)		Input quantities of abscissa of the uniaxial stress-strain curve for the Jth mechanical sublayer material model of the Mth layer. $L=1$ for main structure, $L \geq 2$ for branches.
EPSI(I)	}	Average axial strain on the inner surface and on the outer surface, respectively, at node I.
EPSØ(I)		
FARE	}	Midplane axial strain and curvature increment, respectively, at the selected spanwise Gaussian station of each element.
FCUR		
FLVA(I)		Assembled generalized load vector corresponding to large deflections and plastic strain presence; it equals $\{F_q^{*NL}\} + \{F_p^{*L}\} + \{F_p^{*NL}\}$ .
FQREF(I)		Assembled generalized load vector supplied by elastic restraints, equals $[K_s^*] \{q^*\}$ of Eq. 2.2.
FREQ		The highest natural frequency of a corresponding linear dynamic system of the ring.
GFL(IR,I,J)		Stress and/or plastic strain weighting factor on the Jth depthwise Gaussian point at the Ith spanwise Gaussian station of the IRth element.
GZETA(IR,I,J)		Distance from the centroidal axis to the Jth depthwise Gaussian point at the Ith spanwise Gaussian station of the IRth element.
H(I,M)		Thickness of the Mth layer at the Ith node.
HB(I)		Same as H(I,M), applies only to initial input for branches.
HTH(L)		The branch thickness for the Lth branch at its connecting node.
IBI(L)		Same as IBIG(L), applies to nodes.
IBIG(L)		The element number whose strain, computed at one of its Gaussian stations, exhibits the largest value during the present computer run. $L=1$ for main structure, $L \geq 2$ for branches.

IBIGA(L)	Same as IBIG(L), applies to additional strain points.
ICØL(I)	Vector, of length NI, contains the column number of the first nonzero entry in the Ith row of the structural mass and/or stiffness matrix.
ICØN	INDICATOR = 0 if last data have been input = 1 if more runs are desired
ICØNT	INDICATOR, if > 0 then the program expects data for a continuation run.
ICP	INDICATOR, which if > 0 indicates that the structure is a complete ring. For a partial ring $ICP \leq 0$ .
IK	Number of discrete elements into which the whole structure is discretized for analysis.
IKK	Total number of nodes.
INUM(I)	Vector of dimension NI contains the corresponding position in the linear-array of the first nonzero entry in the Ith row of the structural mass or stiffness matrix.
IRRUN	A counter: is equal to the number of runs in a single computer submittal.
ISTA(I)	The number of the Gaussian station at which the strain is a maximum.
ISTAA(I)	The number of the additional strain point at which the strain is a maximum.
ISIZE	Number of locations required for the storage of the structural mass or stiffness matrix in linear-array form.
ISUR(L)	Same as ISURF(L), applies to nodes.
ISURA(L)	Same as ISURF(L), applies to additional strain points. L=1 for main structure, $L \geq 2$ for branches.

ISURF(L)      INDICATOR = 1 if largest computed strain occurs on inner surface  
                      = 2 if largest computed strain occurs on outer surface  
                      Refers only to strains calculated at Gaussian stations.

IT              Current time-step (cycle) number.

KROW(I)        The row number of the Ith irregular row in the structural mass  
                      or stiffness matrix.

LATT            Indicates how the branch is attached to the main structure:  
                      = -1   inner surface  
                      = 0   outer surface  
                      = 1,2,3   midsurface of respective layer

LBR(I)          The number of a branch upon which a boundary condition is to  
                      be applied.

LHIT(I)         Indicator array. I = branch number. If LHIT(I)=0, branch is  
                      not to be impacted; in the present program LHIT(I) must be set  
                      equal to zero.

LMT(I)          Array which stores the element numbers of those branch elements  
                      where impact cannot occur.

LREF            The layer number whose centroidal axis is conveniently employed  
                      as the reference axis of the multilayer structure.

MATT(L)        Indicates the node at which the Lth branch is attached.

MK(I)           Vector which contains new nodal numbers for the main structure,  
                      given I as the old nodal number.

MKE(I)          Indicates the substructure to which the Ith element belongs.

MM              Time step (cycle) at which run is to stop.

MNEL(I)        Number of elements in the Ith substructure.

M1              Cycle at which regular printing starts.

M2              Printout will occur every M2 cycles.

MPU	Indicator for punched output: IF MPU = 0, no punched output IF MPU $\neq$ 0, data is punched from last time cycle.
	This card must be physically changed in the MAIN program.
MREAD	} Number for the data input tape unit, printed output tape unit, and the punched output tape unit, respectively. These names must be assigned a number in MAIN corresponding to the user's computing facility requirements.
MWRITE	
MPUNCH	
NASP	Number of additional strain points.
NBC(I)	The prescribed-displacement condition identification number.
NBCB(I)	Same as NBC(I), applies to initial input for branches.
NBC $\emptyset$ NB	The number of nodes at which the prescribed displacement condition is to be specified: refers only to branches.
NBC $\emptyset$ ND	The number of nodes at which the prescribed displacement conditions are to be specified.
NBR	Indicates the number of branches that are to be added to main structure (not to exceed 5).
NDEX(I)	The corresponding position in the linear-array of the first nonzero entry in the Ith irregular row.
NDI	Number of branch elements containing a slope discontinuity.
NDIS	The number of elements containing a slope discontinuity.
NEDI(I)	The main structure element number of the Ith element containing a slope discontinuity.
NEDIB(I)	The branch element number of the Ith branch element containing a slope discontinuity.
NELT(I)	Number of elements in the Ith branch.
NFL	The number of depthwise Gaussian points through the thickness of each layer for the numerical evaluation of stress resultants

(axial forces and bending moment) at each spanwise Gaussian station.

NI            Total number of degrees of freedom (unrestrained); it equals the number of nodes times 4. Also, it is the number of rows in the assembled structural mass or stiffness matrix.

NIRREG       Number of irregular rows in the assembled structural mass or stiffness matrix.

NLAY         The number of layers used in the hard-bonded composite ring.

NØDBB(I)     The node number along branch (I) at which a boundary condition is to be applied.

NØDEB(I)     The node number at which the prescribed displacement condition NBC(I) is to be specified.

NØDP(I)      Nodal number (from main structure numbering system) at which the Ith branch starts.

NØGA         The number of Gaussian stations to be employed for the spanwise numerical integration of the element properties over each element.

NØRP }        The number of point elastic restraints (elastic restoring  
NØRU }        springs) and the number of locally distributed elastic restraints, respectively, which are to be specified over the structure.

NQR          Indicator, which if > 0 indicates that this structure is subjected to elastic restraints (point and/or distributed).

NREADF       Dummy variable which controls the reading in of force-time data.

NREL(I)      The element number at which the Ith point elastic restraint is to be specified.

NRST(I) }     The first element and the number of elements, respectively,  
NREU(I) }     over which the Ith distributed elastic restraint is to be specified.

NSFL(M,L) Equals the number of mechanical sublayers in the strain-hardening material model; also is the number of coordinate pairs defining the piecewise linear stress-strain curve of the substructure's material. M = material layer number.

L = 1 for main structure, L  $\geq$  2 for branches.

NV1 } User specified dimension sizes for number of elements, number  
 NV2 } of total depthwise Gaussian stations, and number of mechanical  
 NV3 } sublayers, respectively.

NVEC(I,J) Array containing nodal numbers which form the end points of the Ith element. J = 1 or 2 [First or second node, number clockwise for main structure, outwards for branches, and inwards for a branch attached to node 1 of a partial ring.]

P(M,L) Constant used in the strain-rate sensitivity formula for the Mth layer.

L = 1 for main structure, L  $\geq$  2 for branches.

PIE Represents  $\pi = 3.141592653589793$ .

PLAST Total plastic work done on the structure up to the current time step (mechanical work dissipated during plastic flow).

REX(I) The length coordinate along the centroidal axis from the node NREL(I) at which the Ith point elastic restraint is to be specified.

RFACTR Strain rate factor used in the stress calculation.

ROT(I,J) Array which contains information needed to rotate a stiffness matrix.

I = Number of branch  
 J = 1 or 2

ROT(I,1) = 0.0 if Ith branch connects to first node of main structure. Equals 1.0 for all other connecting points. ROT(I,2) = Angle of rotation.

RWORK Total energy stored in ring up to the current time.



SCTP } SCTY }	The tangential and normal translational restoring spring elastic constants, respectively.
SCRp	The rotational restoring spring elastic constant.
SCTU } SCTW }	Tangential and normal translational elastic foundation stiffness constants, respectively.
SCRU	Elastic foundation modulus in torsion.
SIG(M,L,J)	Input quantities for the ordinate of the uniaxial static stress-strain curve for the Jth mechanical sublayer material model of the Mth layer.  L = 1 for main structure; L $\geq$ 2 for branches.
SNØ(M,N,L)	Uniaxial static yield stress of the Nth mechanical sublayer material model, for the Mth structural layer.  L = 1 for main structure; L $\geq$ 2 for branches.
SNP(I,J,K,L)	The total plastic strain of the Lth mechanical sublayer at the Kth depthwise Gaussian point at the Jth spanwise Gaussian station of the Ith element.
SNS(I,J,K,L)	Axial stress of the Lth mechanical sublayer at the Kth depthwise Gaussian point at the Jth spanwise Gaussian station of the Ith element.
SNY	Uniaxial yield stress of the mechanical sublayer, taking strain-rate sensitivity into account.
SOL(I)	Contains the solution vector of a series of matrix equations.
SPDEN	Total energy stored in the elastically-restoring springs and/or the elastic foundations at the current time instant.
SPRIN(I)	The assembled effective stiffness matrix supplied by elastic restraints (stored in a linear array form).
STIFK(I)	Assembled structural elastic stiffness matrix, stored in a linear-array form.
TIME	Current time (IT*DELTAT).

TRAN(I,J) Transformation matrix, used to rotate displacement vector and element stiffness matrices into global coordinates. Used for branch connection and slope discontinuities.

TWG(I) }  
TXG(I) } Input vectors with dimension NFL; contain Gaussian quadrature constants  $x_i$  and weights,  $w_i$  of

$$\int_{-1}^{+1} f(x) dx = \sum_i f(x_i) w_i$$

used in the numerical integration of stresses and/or plastic strains through the thickness.

XDIST(I) Distance from reference axis to attachment point of the Ith branch.

YK(I) A general work vector. It is finally used to store either the number 1 or 0 for each element (I) to indicate whether a transformation is necessary. YK(I) is used together with ROT(I,J) to identify and aid in rotating an element's stiffness matrix.

YOUNG(M,L) Elastic (Young's) modulus for the Mth structural layer (the slope of the 1st segment in the piecewise linear approximation of the uniaxial stress-strain curve).

$L = 1$  for main structure;  $L \geq 2$  for branches.

Y(I) }  
Z(I) } Initial Y coordinate and Z coordinate, respectively, of the Ith node.

YB(I) }  
ZB(I) } Same as Y(I) and Z(I); applies only to branch nodal input.

### 3.2.2 Variables Unique to JET 5A

AMPLFV }  
AMPLFW } Initial nominal amplitudes (at time TBEGIN) of the externally-applied forces in the tangential and the normal direction, respectively.

AMP2FV } AMP2FW }	Nominal force amplitudes, in the tangential and the normal direction, respectively, of each succeeding point on the force-versus-time curve to be prescribed.
AMPFV } AMPFW }	The linearly-interpolated values of the nominal force amplitudes in the tangential and the normal direction, respectively, at the current time instant.
ANGV	Initial angular velocity, $\dot{\psi} = (\partial \dot{w} / \partial \eta - \dot{v} / R)$ at time zero.
ANGV1 } ANGV2 }	Initial angular velocities at the two edge nodes of the local uniform initial normal velocity distributed over certain elements of the structure.
APDEN	Total work done on the structure by externally-applied forces up to the present time step.
CINETØ	Initial kinetic energy imparted to the structure.
CINETT	Total work done by all external agencies (externally-applied forces and initial imported kinetic energy) up to the current time step.
ETA(I)	Equals the length coordinate along the centroidal axis from the node JELEM(I) at which the Ith concentrated load is to be specified on element JELEM(I).
FMECH(I)	Assembled generalized load vector due to externally-applied forces.
IE1 } IE2 }	The first element and the number of elements, respectively, over which the local uniform initial normal velocity is to be prescribed.
IØTA	Number of local uniform initial normal velocity distributions.
IØTB	Number of nodes at which the initial generalized nodal velocity components are to be prescribed.
IØTC	Number of local sine-shaped initial normal velocity distributions.

IS1 } IS2 }	The first element and the number of elements, respectively, over which the local sine-shaped initial normal velocity is to be prescribed.
JELEM(I)	The element number at which the Ith concentrated load is to be specified.
NELF2(I)	The number of elements over which the Ith local uniformly distributed externally-applied load is to be specified.
NELF3(I)	The number of elements over which the Ith local sine-shaped distributed externally-applied load is to be specified.
NLOAD	Equal to 1 means external forces are acting during the current time step; equal to 2 means the forces are not acting.
NODEV	The node number at which the initial generalized nodal velocity components are to be specified.
NØFT1 } NØFT2 } NØFT3 }	The number of concentrated loads, the number of local uniform load distributions, and the number of local sine-shaped load distributions, respectively, which are to be prescribed over the structure.
NREADF	Dummy variable which controls the reading-in of force-time data.
NSTF2(I)	The first element number at which the Ith local uniform load distribution is to be specified.
NSTF3(I)	The first element number at which the Ith local sine-shaped load distribution is to be specified.
NV	Indicator, which if > 0 indicates that initial velocity distributions are to be specified over the structure.
RTØV(I)	The normalized values of the Ith concentrated load with respect
RTØW(I)	to the nominal amplitudes in the tangential and the normal direction, respectively.

RTØ2V(I) } RTØ2W(I) }	The normalized values of the Ith local uniform load distribution with respect to the nominal amplitudes in the tangential and the normal direction, respectively.
RTØ3V(I) } RTØ3W(I) }	The normalized values of the Ith sine-shaped load distribution with respect to the nominal amplitudes in the tangential and the normal direction, respectively.
SLØPEV } SLØPEW }	Slopes of the piecewise-linear segment approximation of nominal force versus time curve in the tangential and the normal direction, respectively, at the current time instant.
T1 } T2 }	Times at which a linear segment of the force-versus-time curve starts acting and stops acting, respectively.
TBEGIN } TFINAL }	Times when overall externally-applied forcing function starts acting and stops acting, respectively.
VRAD	The value of the initial tangential velocity to be specified at the node of the element.
WRAD	The value of initial normal velocity to be specified for the local uniform initial normal velocity; also is the peak value of the sine-shaped initial normal velocity distribution.
WRAD1 } WRAD2 }	The values of the initial normal velocity at the two edge nodes of the local uniform initial normal velocity distributed over certain elements of the structure.

### 3.2.3 Variables Unique to CIVM-JET 5B

ADØT(J)	The angular velocity of the Jth fragment (rad/sec). Positive sign denotes counter-clockwise rotation.
AINT	Relative normal velocity between the ring impact-affected nodes and an impacting fragment.
ALFA(I)	Angular rotation of fragment (I) (rad).
APN	Fragment-induced impulse normal to the impacted ring element surface.

APT            Fragment-induced impulse tangential to the impacted ring element surface.

CINETF (J)    Kinetic energy stored in Jth fragment up to the present time.

CR (J)        Coefficient of restitution between the Jth fragment and the impacted ring surface.

DALFA (J)     Impact-corrected angular displacement increment of the Jth fragment at the current time step.

DCRTE        Critical distance used in calculating where a positive penetration has occurred between a fragment and a ring element. It is equal to the fragment radius plus one half the mean element thickness.

DDELD (I)     Stores DELD(I) from the previous time step.

DELTR        Equal to time step  $\Delta t$ . Used in impact inspection and correction calculations.

DFCGU (J)     Impact-corrected Y-direction displacement increment applied to the position of fragment J.

DFCGW (J)     Impact-corrected Z-direction displacement increment applied to the position of fragment J.

EFLN (L)      The effective impact length of the ring (inches).  $L=1$  for main structure.  $L \geq 2$  for branches.

FACTFN       Impact-induced correction factor applied to the normal-to-impact displacement increment of the attacking fragment at the time of contact.

FACTFT       Impact-induced correction factor applied to the tangential-to-impact displacement increment of the attacking fragment at the time of contact.

FACTFØ       Impact-induced correction factor applied to the rotational displacement increment of the attacking fragment at the time of contact.

FACTN        Impact-induced correction factor applied to the normal-to-impact displacement increment of each affected node.

FACTT	Impact-induced correction factor applied to the tangential-to-impact displacement increment of each affected node.
FCGU(J)	The global Y coordinate of the centroid of the Jth fragment.
FCGW(J)	The global Z coordinate of the centroid of the Jth fragment.
FH(J)	The diameter of the circular disk model of fragment J.
FKT(J)	Initial kinetic energy of fragment J.
FMASS(J)	The mass of the Jth fragment ( $\text{lb-sec}^2/\text{in}$ ).
FMØI(J)	The mass moment of inertia of the Jth fragment ( $\text{lb-sec}^2\text{-in}$ ).
IFLAG(I,J)	A flagging matrix which indicates whether element I has been impacted by fragment J during a given time step, $\Delta t$ .
IMCØ	Indicates the occurrence of an impact in the previous time step.
IMCØU	Indicates the number of impacts up to the present time instant.
JF	The fragment number which is involved in the ring segment impact.
KII	Number of nodes included in the impact-affected region.
MIRP	Indicates the first fragment that is released at a time after the initial impact.
NE	The number of fragments considered to be impacting the ring.
NPP	The number of positive penetrations during time DELTR.
PAL	Fractional distance from point of impact to the first node of the impacted element
PAX	Fractional distance from point of impact to the second node of the impacted element.
QACL(I)	Vector which contains the generalized DOF accelerations for the current time step.

QVEL(I)	Vector which contains the generalized DOF velocities at the current time instant.				
RCOS(I) } RSIN(I) }	Cosine and sine, respectively of the angle that element I makes with the global Y axis. Used in transformation from impact to local and local to global coordinate systems.				
RL(I)	Straight line length of ring element I used in the collision inspection and correction analysis.				
RMASS(I) } RMX(I) }	Lumped mass and moment of inertia values, respectively, at ring structure node I.				
SINT	Relative tangential velocity between the ring impact-affected nodes and an impacting fragment.				
TAII	Time of initial impact.				
TANX	Boundary between rolling and sliding friction.				
TNJ(J)	Indicates whether or not fragment J has been released before the start of calculations.				
TPRIM(J)	Length of time that fragment J has been traveling prior to initial impact of the <u>first</u> fragment.				
TU(I) } TW(I) }	Trial Y and Z coordinates, respectively, of the Ith node during impact calculations.				
UDOT(J)	The velocity component of the Jth fragment parallel to the global Y axis.				
UNK(J)	Coefficient of friction for the Jth fragment.				
VELFA(J) } VELFU(J) } VELFW(J) }	<table border="0"> <tr> <td>Same as ADOT(J)</td> <td rowspan="3">} used in impact calculations.</td> </tr> <tr> <td>" " UDOT(J)</td> </tr> <tr> <td>" " WDOT(J)</td> </tr> </table>	Same as ADOT(J)	} used in impact calculations.	" " UDOT(J)	" " WDOT(J)
Same as ADOT(J)	} used in impact calculations.				
" " UDOT(J)					
" " WDOT(J)					
WDOT(J)	The velocity component of the Jth fragment parallel to the global Z axis.				



## SECTION 4

### USE OF THE JET 5A PROGRAM

#### 4.1 Guidelines for User-Prepared Array Dimensions

The JET 5A program is capable of handling multilayer structures with up to three layers, up to fifty elements, and up to five "mechanical sublayers" to represent the stress-strain behavior of the material. Inherent with this capability is a large computer core requirement. In order to make the program more flexible for the user with a limited budget or a limited computer core, the largest dimensioned arrays are to be user dimensioned in the MAIN program and will be variably dimensioned throughout the subroutines. The user must, therefore, insert his own dimension statements for these arrays at the beginning of the MAIN program, before running the JET 5A computer code. Once the user has set the dimension limits for these arrays, it is unnecessary to change these dimension statements until a run is submitted in which one or more of the dimensions will be exceeded. The user must be warned, however, that the upper limit for the dimensions (as mentioned earlier in this subsection) can not be exceeded, as other dimensioned variables are fixed at these maximum values. It is hoped that with a minimum of interaction between the user and the computer deck, the user will be able to save fifty to sixty percent of the maximum required core, when jobs are run with only one or two layers, or with a few elements.

Listed below are the cards that the user is required to change in the MAIN program:

Dimension	ASFL(IK,3,K,NSFL), GZETA(IK,3,K), SNJ(IK, 3,K,NSFL), SNP(IK,3,K,NSFL), AEP(IK,3,8), DEP(IK,2,3,8)
Dimension	STIFK(L), SPRIN(L), AMASS(L), QDD(M), REACM(L), REACK(L), REAL(L), REAFM(M), REAFK(M)

NV1 = IK

NV2 = K

NV3 = NSFL

MPU = J

where

IK	The number of elements.
K	Number of layers times the number of depthwise Gaussian stations, NFL.
NSFL	The number of mechanical sublayers.
L	The number of nodes times 26 plus ten. If there are branches attached to the middle of the main structure, add a cushion of at least 100 to L.
M	The number of nodes times four plus one.
J	Equals 0 if no continuation cards are desired. Equals 1 if continuation cards are to be punched.

#### 4.2 Input Information and Procedure

The information required to punch a set of data cards for a run of the program is presented in a step-by-step manner in this section. The variables to be punched on the  $n$ th data card are outlined, and to the right is the format to be used for that card; the definition of and some restrictions for each variable are given directly below. This is done for each card, in turn, until all are described.

Cards 1 through 16 are used to describe the ring geometry, material properties, the finite-element modeling, and the prescribed displacement conditions and/or elastic restraints. Cards 17-27 are used to describe the initial impulsive loads and/or the externally-applied force distributions.

Card 1	<u>Format</u>
IK, ICP, NLAY, LREF, NOGA, NFL, MM, M1, M2, ICON	10I5

where

IK	The number of finite elements used to model the whole ring structure. This number cannot exceed 50 (however, this limitation may be relaxed by a changing of the appropriate dimension statements of the program).
ICP	Indicator, which if $>0$ indicates that the structure is a complete ring. For a partial ring, $ICP \leq 0$ .

NLAY	The number of layers used in the hard-bonded composite ring. This number cannot be greater than 3.
LREF	The layer number whose centroidal axis is conveniently employed as the reference axis of the multilayer ring. The first layer of the maximum of 3 layers is defined to be the inside layer of the ring.
NOGA	The number of spanwise Gaussian stations to be used for the spanwise numerical integration over each element in evaluating the element property matrices. NOGA=3 is used in JET 5A.
NFL	The number of depthwise Gaussian points to be used for the numerical integration through the thickness of each layer at each spanwise Gaussian station. This number cannot exceed 6.
MM	The cycle number at which the run is to stop.
M1	The cycle number at which the regular printout is to begin. M1 must not equal 0.
M2	The number of cycles between regular printout (i.e., print every M2 cycles).
ICON	Integer that controls the stopping of the entire program: = 0   The program will stop after all the required printouts are made for a particular run. = 1   The program will expect a new set of Cards 1-27 for another ring problem.

Card 2

NSFL(1,1) ---- NSFL(NLAY,1) 3I5

where

NSFL(1,1)      The number of material mechanical sublayers in the strain-hardening material model for the first layer of the main structure, and equals the number of coordinate pairs

defining the polygonal approximation of the stress-strain curve for that material. NSFL(1,1) can not exceed 5.

Continue until NSFL(NLAY,1) is specified, where NLAY is the total number of layers in the multilayer ring, and NSFL(M,1) can not exceed 5. [M=1, NLAY].

#### Card 3A

DENS(1,1), DS(1,1), P(1,1)

3D15.6

where

DENS(1,1) The mass density of the first layer material (lb-sec<sup>2</sup>/in<sup>4</sup>) of the main structure (first substructure).

DS(1,1) } The values of the constants D and p, respectively used in  
P(1,1) } the Cowper-Symonds [7] strain-rate sensitivity formula:\*

$$\sigma_{yk} = \sigma_{ok} \left( 1 + \left| \frac{\dot{\epsilon}}{D} \right|^{\frac{1}{p}} \right)$$

for the first layer of the multilayer ring, where DS=(1/sec),  $\sigma_{ok}$  is the static yield stress of the kth mechanical sub-layer, and  $\sigma_{yk}$  is the corresponding rate dependent yield stress. If the material of ring layer 1 does not exhibit strain-rate sensitivity, set DS(1,1)=0.0 and P(1,1)=0.0.

#### Card 4AA

EPS(1,1,1), SIG(1,1,1), EPS(1,2,1), SIG(1,2,1)

4D15.6

where

EPS(1,1,1) } The first coordinate pair of strain,  $\epsilon$ , and stress,  $\sigma$ , for  
SIG(1,1,1) } the first ring layer, which is used to define the polygonal approximation of the first layer's stress-strain diagram. The stress-strain diagram from which these values and those following are obtained must be upwardly-convex with non-negative slopes. ( $\epsilon(M,L)$  = in/in, and  $\sigma(M,L)$  = lb/in.) (This is for the main structure which is termed the first substructure.)

\* See Ref. 8 wherein values cited for aluminum, for example, are  $D = 6500 \text{ sec}^{-1}$  and  $p = 4$ ; for mild steel  $D = 40.4 \text{ sec}^{-1}$  and  $p = 5$ . For other materials, the user will need to seek appropriate strain rate data from sources such as the Air Force Materials Laboratory, the General Motors Research Laboratory, etc. [7-13] and to deduce approximate values for D and p by data fitting studies.

$\left. \begin{array}{l} \text{EPS}(1,2,1) \\ \text{SIG}(1,2,1) \end{array} \right\}$  The second coordinate pair of the polygonal approximate strain and stress in the first ring layer, of the main structure.

Additional Cards 4AB and 4AC are punched in exactly the same manner as Card 4AA until the number of coordinate pairs equals NSFL(1,1) punched on Card 2 for layer 1. The total number of coordinate pairs must not exceed 5 for any layer. Do not include any unneeded (blank) cards.

Cards 3 through 4 are repeated for each additional layer in the multilayer ring until the number of sets of cards equals NLAY (given in Card 1). The total number of card sets must not exceed 3.

Card 5

B(1), DELTAT 2D15.6

where

B(1) The width of the multilayer main structure (inches).  
 DELTAT The time step,  $\Delta t$  (seconds) to be employed for the Houbolt timewise integration operator. If the value of  $\Delta t$  is set equal to zero on this card, the program will compute the largest natural frequency,  $\omega_{\max}$ , of the corresponding linear system and will then choose a value  $\Delta t = 2\Delta t_{\max}^{\text{CD}}$ , where  $\Delta t_{\max}^{\text{CD}}$  is the maximum  $\Delta t$  allowed for a linear system using the central difference operator:  

$$\Delta t_{\max}^{\text{CD}} = 2/\omega_{\max}$$

Card 6A

Y(1), Z(1), ANG(1) 3D15.6

where

$\left. \begin{array}{l} \text{Y}(1) \\ \text{Z}(1) \end{array} \right\}$  Initial Y and Z coordinate, respectively, of the first node (inches).  
 ANG(1) The slope (degrees) which is the angle between the tangent vector and the +Y axis at the first node. An angle from the +Y axis to the tangent vector in a counter-clockwise direction is defined as the positive direction (see Fig. 3).

Additional Cards 6B, 6C, ... are punched in exactly the same format as Card 6A until the total number of No. 6 cards equals (IK+1) for a partial ring and equals IK for a complete ring, where IK is the value appearing on Card 1. Also, the following two conditions must be satisfied by ANG(I) (where I is the node number):

- (1)  $-180^{\circ} < \text{ANG}(I) \leq +180^{\circ}$
- (2) An element cannot have a change in slope between its first node and its second node that is greater than  $15^{\circ}$ . This refers only to the shape of one element (see Fig. 3); slope discontinuities between two elements are handled on Card 8.

Note that for bookkeeping purposes, the nodal slope is defined to be identified with the first end (left-hand end) of the element at that node for structures with continuous slopes. However, where a slope discontinuity occurs on the main structure, a node must be used and two slopes must be given: (1) one given on Card 6A associated with the second end (right-hand end) of the pertinent element and (2) one associated with "end one" (L-H end) of the next element; the item (2) situation is dealt with by Cards 8A, 8BA, 8BB, 8BC, etc.

#### Card 7A

H(1,1), ... H(1, NLAY), H(2,1) .. 5D15.6

where

H(1,1)	The thickness of the first layer of the ring at node 1 (inches)
H(1,M)	The thickness of the Mth layer of the ring at node 1 (inches)

Card(s) 7B, 7C, ... are repeated in the same format until the thicknesses of each layer of the ring at every nodal station are defined. The total number of data on Cards 7 (with 5 data on each card) should be equal to NLAY\*IK for a complete ring and equal to NLAY\*(IK+1) for a partial ring.

#### Card 8A

NDIS I5

where

NDIS            The total number of elements in the main structure having a slope discontinuity at the first node of the element.

If there are no slope discontinuities on the main structure, set NDIS=0 and go to Card 9.

Card 8BA

NEDI (I), ANGDI (I) 4 (I5,D15.6)

where

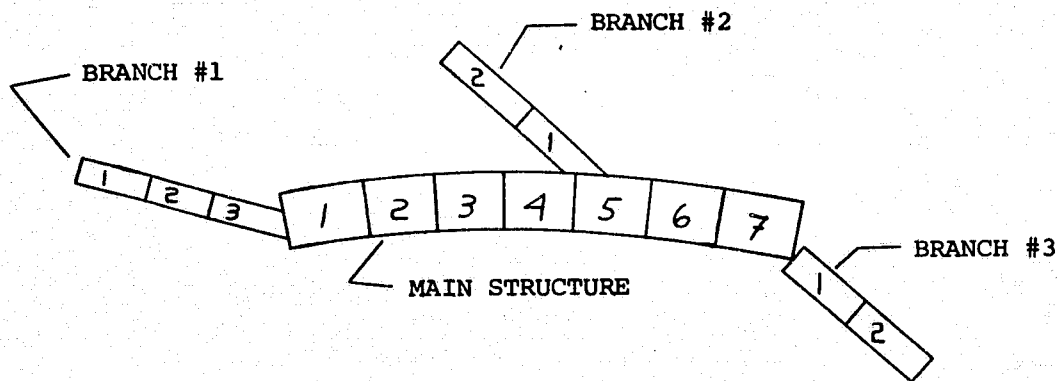
I = 1, NDIS

NEDI(I)            The element (on the main structure) at which the Ith slope discontinuity appears on the element's first node.

ANGDI(I)      The appropriate slope (degrees) for the Ith slope discontinuity; the slope is measured between the tangent vector to the element at the station in question and the +Y axis (see Card 6a ANG(1) for a description of the measurement system).

Additional Cards 8BB, 8BC, etc. are used until all of the "slope discontinuities" are described. (See Fig. 10 for a further description of the discontinuity option.)

The sequence of cards starting with Card 9 and going through Card 9DB contains all of the data for the single layer branches to be applied to the main structure except that elastic restraints must be handled as one unit on Card 16. If no branches are to be applied, Card 9 has NBR=0; then proceed to Card 10. Only 5 branches are allowed, with a maximum of 10 elements in any one branch. A branch may not be connected to another branch. Branches may be attached to any node on the main structure, or to the inner or outer surface of the main structure at any node but only one branch may be connected to a given main-structure node. Note that if a complete ring primary structure is specified, no branch may connect to node 1 of the primary structure. The following sketch shows typical permissible arrangements of the single layer branches:



Note the difference in the numbering schemes for branch 1 compared with branches 2 and 3; the last geometry input card for a branch pertains to its junction with the main structure. Numbering of the primary structure is done independent of any branches. Typical branch numbering is given in the above sketch. Note that all numbering in the above sketch is done in each sub-structure's system. The program will renumber (in a clockwise manner) the entire finite element system.

The following describes the sequence of Cards (9A through 9DB) needed to accommodate branches (these cards are nested in such a way that each branch's material and geometric properties are specified, branch by branch, followed by slope-discontinuity information for all branches, followed by boundary condition information for all branches):

Card 9

NBR

Format

I5

where

NBR

The number of individual branches being added to the main structure ( $NBR \leq 5$ ).

If  $NBR=0$ , go to Card 10

Card 9A

NSFL(1,L), B(L), DENS(1,L), DS(1,L), P(1,L)

I5, 4D15.6

where

$L=2, NBR+1$

The branch number is  $(L-1)$ ; the values of these variables when  $L=1$  are equal to the main structure's material.



NSFL(1,L)      The number of mechanical sublayers in the strain-hardening model of the material of the (L-1) branch, and is equal to the number of coordinate pairs defining the polygonal approximation of the stress-strain curve of the material (NSFL(L)  $\leq$  5).

B(L)      Width of the (L-1) branch (inches).

DENS(1,L)      Mass density of the (L-1) branch (lb-sec<sup>2</sup>)/in<sup>4</sup>.

DS(1,L) }      See Card 3A.  
P(1,L) }      (L-1) Branch.

#### Card 9AA

EPS(1,J,L), SIG(1,J,L)      4D15.6

where

J =      coordinate pair number  $\leq$  5

(L-1) =      branch number  $\leq$  5

EPS(1,J,L) }      See Card 4AA for definition of quantities.  
SIG(1,J,L) }

Additional Cards 9AB and 9AC are punched in exactly the same manner as Card 9AA until the number of coordinate pairs equals NSFL(L) punched on Card 9A. Do not include any unneeded (blank) cards.

#### Card 9B

NELT(I), NODP(I), LHIT(I), LATT(I)      4(I5)

where

I = 1,NBR      is the branch number

NELT(I)      number of elements in Ith branch (NELT(I)  $\leq$  10)

NODP(I)      Node of main structure (in original numbering system) at which Ith branch is attached. See figure on page 42.

LHIT(I)      Determines whether or not branch can be impacted:

LHIT(I)=0      No impact

LHIT(I)=1      Impact

LATT (I)

LATT(I) = -1      inner surface

1,2,3 midsurface of respective layer

YB(I,J), ZB(I,J), ANB(I,J), HB(I,J)

where

YB(I,J)            Y coordinate of node (inches)

ZB(I,J)            Z coordinate of node (inches)

ANB(I,J)      Tangent angle measured to Y axis (degrees); see Fig. 3.

HB(I,J)            Thickness at node J

Note: See Card 6A [ANG(1)] for sign convention used for ANB(I,J).

45

particular only to the branch, and node (NELT+1) is the common node with the primary structure. The subroutine BRAN automatically updates IK (the total number of elements), IKK (number of nodes), and NI (D.O.F.). Therefore, the initial input (Cards 1-8 and 10-15) is punched as though the branches did not exist.

Cards 9BB, 9BC, etc., are punched until (NELT+1) nodes have been described.

Card 9C

NDISB I5

where

NDISB The number of elements in the branches having a discontinuity at their first node. (Do not count the discontinuities due to the attachment of the branch to the main structure.)

If there are no discontinuities on the branches, set NDISB=0 and go to Card 9D.

Card 9CA

NEDIB, NBDI, ANGB 2I5,D15.6

where

NEDIB The element number (along a branch) at which the discontinuity occurs.

NBDI The branch in which the element NEDIB is contained.

ANGB The slope (degrees); See Card 6A [ANG(1)] for sign convention used for ANGB.

Cards 9CB, 9CC, etc. follow until the information for all NDISB branch slope-discontinuities has been given.

Card 9D

NBCONB I5

where

NBCONB The number of boundary conditions applied only to the branches. (Total B.C.'s on structure  $\leq$  7).

If Card 9D = 0 go to Card 10.

Card 9DA

NBCB(I), NODBB(I), LBR(I)

4(3I5)

where

I = 1, NBCONB

NBCB(I) Type of boundary condition. See Card 15 for description.

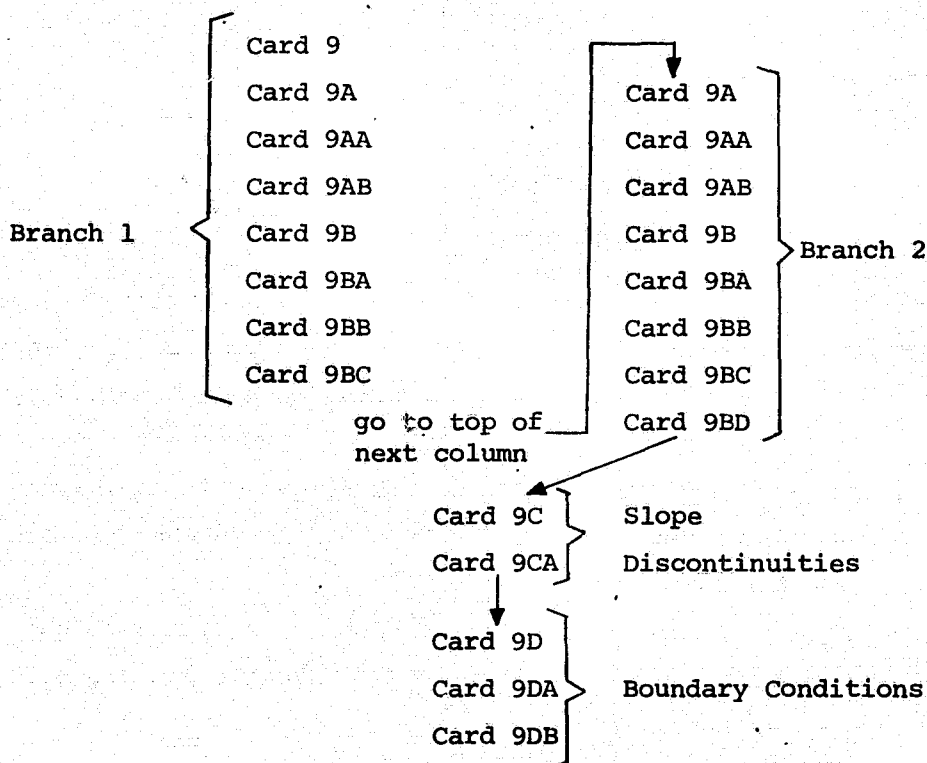
NODBB(I) The node number of the particular branch on which the B.C. is being applied (see sketch prior to Card 9 description).

LBR(I) The branch number on which the B.C. is being applied (see sketch).

A total of seven boundary conditions is allowed, including the primary structure and all branches. Therefore, Card 9DB is punched if more than 4 B.C.'s are to be applied to the branches.

The cards grouped under the number 9 contain the complete description of all branches (except for elastic restraints). These cards are nested branch by branch, such that a branch's material and geometric layout are completely described before starting the next branch. After all branches have been described, and the branch slope-discontinuity information has been given, then the boundary conditions are applied to all branches. It should be noted that branches may contain only one material layer.

An example is given below for a main structure containing two branches, each of a different material, and five boundary conditions on the branches. For each material a three mechanical sublayer model is used. The first branch contains two elements, while the second branch has three elements. The first has one slope-discontinuity, the second branch has none. The following list gives the card number (described in this section) in the order they would appear in the input deck:



Card 10

NOP, NASP, NTERF

315

where

NOP

Indicates the type of strain output desired (given at inner and outer surface)

- = 0            Average strain at node
- = 1            Average strain at each node plus strain at each Gaussian station
- = 2            Average strain at each node plus strain at designated additional points
- = 3            Strain for all three of the above options

NASP

Number of additional strain points requested;  $NASP \leq 50$

NTERF

Indicates whether strain information for the boundary of two material layers is to be printed. If  $NTERF=0$  this

strain information will not be printed. If there are three structural layers in the main structure, then the strains at each of the two interfaces will be printed for each element. If there are only two layers present, then the strains for the one interface will be listed and strains along the reference axis will be listed instead of strains at a second interface. The actual output is governed by the indicator NOP; interface strains are printed for each Gaussian station and for any additional strain points as specified by the value of NOP on Card 10.

If NOP  $\neq$  2 or 3, go to Card 11.

Note: It is suggested that the user use NOP=1 or NOP=3 in order to obtain a complete set of strain output for a first run of a problem. NOP=0 or 2 can be used for additional runs of the same problem in order to reduce output costs.

#### Card 10A

NSBS(I), NSEL(I), AZET(I)

2I5,D15.6

where

I = 1, NASP

NSBS(I)	Number of the substructure on which the additional strain point is requested: NSBS = 1 main structure; if NSBS > 1 the substructure is a branch whose number is (NSBS - 1)
NSEL(I)	The element along the NSBS substructure on which additional strain point is requested. No more than 10 additional strain points are allowed on any one element.
AZET(I)	The $\bar{s}$ coordinate of the additional strain point measured from the first node of the element ( $\bar{s}$ is a fractional length (in/in) of the element itself).

Cards 10B, 10C, etc. are used until all the additional strain points have been described.

Card 11

AXG(1), AXG(2), AXG(3)

3D25.16

Card 12

AWG(1), AWG(2), AWG(3)

3D25.16

where

AXG(I) }  
AWG(I) }

Vectors, of dimension NOGA, contain Gaussian quadrature constants,  $x_i$  and weights,  $W_i$ , respectively, for the numerical evaluation of

$$\int_0^1 f(x) dx = \sum_i f(x_i) W_i$$

The following data appear on Card 11, since NOGA=3:

0.1127016653792585D+00 0.5000000000000000D+00

0.8872983346207415D+00 and the data 0.2777777777777778D+00

0.4444444444444444D+00 0.2777777777777778D+00 on Card 12.

Card 13A

TXG(1), TXG(2), TXG(3)

3D25.16

Card 13B

TXG(4)

3D25.16

Card 14A

TWG(1), TWG(2), TWG(3)

3D25.16

Card 14B

TWG(4)

D25.16

Note: If  $NFL \leq 3$ , Cards 13B and 14B are eliminated.

If  $NFL > 4$  the extra terms are added to Cards 13B and 14B.

where

TXG(I)

Vectors of dimension NFL, contain Gaussian quadrature constants,  $x_i$ , and weights,  $W_i$  respectively, for the numerical integration of

$$\int_{-1}^1 f(x) dx = \sum_i f(x_i) W_i$$

If NFL=4, for example, then the following data appear on Cards 13A, and 13B:

-0.8611363115940530D+00 -0.3399810435848560D+00

0.3399810435848560D+00 0.8611364115940530D+00

and the data

0.3478548451374540D+0 0.6521451548625460D+00

0.6521451548625460D+00 0.3478548451374540D+0

appear on Cards 14A and 14B.

#### Card 15

NBCOND, NBC(1), NODEB(1), NBC(2), NODEB(2), ... NBC(7), NODEB(7) 1015

where

NBCOND            The number of prescribed displacement conditions to be specified on the structure. This number must not exceed 7.

NBC(1)        }    The identification number and the node number, respectively,  
NODEB(1)       }    for which the first prescribed displacement condition is  
                 to be imposed.

NBC(2)        }    The second data group of the identification number and  
NODEB(2)       }    node number, respectively, for which the second prescribed  
                 displacement condition is to be imposed.

The appropriate form of the data group NBC(I) and NODEB(I) should be repeated NBCOND times. If NBCOND=0, that means there is no prescribed displacement condition to be imposed on the structure; then, leave NBC(I) and NODEB(I) blank.

The prescribed displacement condition identification number can be equal to 1, 2, or 3, depending upon the type of the prescribed displacement condition. Its description follows:

NBC(I)=1        Symmetry displacement condition, setting the degrees of freedom  $v$  and  $\psi$  at the node NODEB(I) to zero.

NBC(I)=2        Ideally clamped condition, setting  $v$ ,  $w$ , and  $\psi$  at node NODEB(I) to zero.



NBC(I)=3            Smoothly-hinged condition, setting v and w at node NODEB(I) to zero.

Card 16

NQR, NORP, NORU

3I5

where

NQR            Indicator, which if > 0 indicates that the structure is subjected to elastic restraints (point and/or distributed).

NORP           The number of point elastic restraints (elastic restoring springs) which are to be prescribed over the structure. This number must not exceed 4.

NORU           The number of local distributed elastic restraints (elastic foundations) which are to be prescribed over the structure. This number must not exceed 4.

If there are no prescribed elastic restraints on the structure, set NQR=0 and leave NORP and NORU blank.

Card 16A and Card 16B are included only if NQR > 0 on Card 16. If NORP=0, skip to Card 16B.

Card 16A

SCTP, SCTY, SCRP

3D15.6

Card 16AA

NREL(1), REX(1), NREL(2), REX(2) ... NREL(4), REX(4)

4(I5,D15.6)

where

SCTP           The translational tangential restoring spring elastic constant (lb/in).

SCTY           The translational radial restoring spring elastic constant (lb/in).

SCRP           The torsional restoring spring elastic constant (in-lb/radian).

NREL(I) }       The element number and the length coordinate along the  
 REX(I) }       reference axis from the node NREL(I) of the element,

respectively, at which the Ith point elastic restraint is to be specified.

The data group NREL(I), REX(I) should be repeated NORP times.

If NORU=0 in Card 16, omit Card 16, and Card 17 follows directly.

Card 16B

SCTU, SCTW, SCRU 3D15.6

Card 16BB

NRST(1), NREU(1), ... NRST(4), NREU(4) 8I5

where

SCTU Elastic foundation modulus in translation along the circumferential direction (lb/in<sup>2</sup>).

SCTW Elastic foundation modulus in translation along the normal direction (lb/in<sup>2</sup>).

SCRU Elastic foundation modulus in torsion (in-lb)/(rad-in).

NRST(1) } The first element and the number of elements, respectively,  
NREU(1) } over which the first elastic foundation is to be specified  
(the first elastic foundation is distributed to element NRST(1), through and including element (NRST(1)+NREU(1)-1).

Note: The element numbers used here must be those defined after branches have been added. See Fig. 12c.

NRST(2) } The first element and the number of elements over which  
NREU(2) } the second elastic foundation is to be specified.

Data group NRST(I) and NREU(I) are repeated NORU times.

Cards 17 through 20 are used to describe the initial velocity distributions.

Card 17

NV, IOTA, IOTB, IOTC 4I5

where

NV Indicator, which if > 0 indicates that the initial velocities are to be prescribed over the structure.

IOTA Number of local uniform initial normal velocity distributions.



of  $v$ ,  $w$ ,  $\psi$ , and  $\chi$  at boundary nodes of each element with neighboring elements is required).

If  $IOTB > 0$  in Card 17, the following No. 19 Card(s) must be included; otherwise, skip to Card 20.

#### Card 19

NODEV, VRAD, WRAD, ANGV

I5, 3D15.6

where

NODEV	The node number at which the initial generalized nodal velocity components are to be prescribed.
VRAD	The initial tangential velocity $\dot{v}_0$ (in/sec), normal velocity $\dot{w}_0$ (in/sec), and the angular velocity, $\dot{\psi}_0$ (rad/sec), respectively, which are to be prescribed on node NODEV.
WRAD	
ANGV	

Additional Card(s) 19A, 19B, ... are punched in the same format until the total number of cards specified equals IOTB in Card 16.

Card(s) 20, 20A, 20B ... are included only if  $IOTC > 0$  in Card 16.

#### Card 20

IS1, IS2, WRAD

2I5,D15.6

where

IS1	The first element and the number of elements over which the first local sine-shaped initial normal velocity distribution is to be prescribed.
IS2	
WRAD	The peak value $\dot{w}_0$ (in/sec) of the first sine-shaped initial normal velocity distribution.

Card(s) 20A, 20B ... are punched in the same manner, until the total number of No. 20 cards equals IOTC on Card 17.

The remaining Cards (21 through 25 and 27) specify the amplitude, direction, and distribution of the subsequent time-dependent externally-applied forcing function.

Card 21

TBEGIN, TFINAL, AMPLFV, AMPLFW

4D15.6

where

TBEGIN	}	Times (seconds) which define the beginning and the end, respectively, of the complete externally-applied forcing function; i.e., the complete forcing function starts at TBEGIN and ends at TFINAL.
TFINAL		

AMPLFV	}	The circumferential and the normal components, respectively, of the normal force (amplitudes of the forcing function) (lbs) versus time history at time TBEGIN.
AMPLFW		

If there is no externally-applied forcing function during the run, set both TBEGIN and TFINAL equal to zero and leave AMPLFV, AMPLFW blank; if no forcing function is to be prescribed, go to Card 26.

Card 22

NOFT1, NOFT2, NOFT3

3I5

where

NOFT1	The number of concentrated loads which are to be prescribed (NOFT1 $\leq$ 4).
NOFT2	The number of local uniform load distributions which are to be prescribed (NOFT2 $\leq$ 4).
NOFT3	The number of local sine-shaped load distributions which are to be prescribed (NOFT3 $\leq$ 4).

Omit data group 23 if NOFT1=0 on Card 22.

Card 23

JELEM(1), ETA(1), RTOV(1), RTOW(1)

I5,3D.15.6

where

JELEM(1)	}	The element number and the length coordinate along the reference axis from node JELEM(1), respectively, at which the first concentrated load is to be prescribed.
ETA(1)		

$\left. \begin{array}{l} \text{RTOV}(1) \\ \text{RTOW}(1) \end{array} \right\}$  The normalized values of the first concentrated load with respect to the nominal forces in the circumferential and the normal directions, respectively, (lb/lb).

Card(s) 23A, 23B, ... are repeated in the same format, until the total number of No. 23 cards equals NOFT1 given in Card 22.

Skip data group Card(s) 24 to Card 25 if NOFT2=0 on Card 22.

Card 24

$\text{NSTF2}(1), \text{NELF2}(1), \text{RTO2V}(1), \text{RTO2W}(1)$  2I5,2D15.6

where

$\left. \begin{array}{l} \text{NSTF2}(1) \\ \text{NELF2}(1) \end{array} \right\}$  The first element and the number of elements, respectively, over which the first local uniform load is to be distributed.

$\left. \begin{array}{l} \text{RTO2V}(1) \\ \text{RTO2W}(1) \end{array} \right\}$  The normalized values of the first local uniform load distribution with respect to the nominal amplitudes in the circumferential and the normal directions, respectively, (lb-in/lb-in).

Card(s) 24A, 24B, ... are repeated in the same format until the total number of No. 24 cards equals NOFT2 on Card 22.

Card(s) 25 are included only if NOFT3>0; otherwise, skip to Card 26.

Card 25

$\text{NSTF3}(1), \text{NELF}(3), \text{RTO3V}(1), \text{RTO3W}(1)$  2I5,2D15.6

where

$\left. \begin{array}{l} \text{NSTF3}(1) \\ \text{NELF3}(1) \end{array} \right\}$  The first element and the number of elements, respectively, over which the first local sine-shaped forcing function is to be distributed.

$\left. \begin{array}{l} \text{RTO3V}(1) \\ \text{RTO3W}(1) \end{array} \right\}$  The normalized values of the first local sine-shaped forcing function with respect to the nominal amplitudes in the circumferential and the normal directions, respectively (lb-in/lb-in).

Card(s) 25A, 25B, ... are repeated until the total number of No. 25 cards equals NOFT3 on Card 22.

Card 26

ICONT

I5

where

ICONT

Integer which if greater than 0 indicates that this is a continuation run. In order to use this option, it is necessary to obtain the following continuation cards from a previously-run job. To do this, set the variable MPU=1 at the beginning of the MAIN routine. This will cause the following set of data cards 26A through 26 NA to be punched. When using this deck, set ICONT=1 and use the same data cards as used before, except to change the values of MM and M1 on Card 1 and to modify Card 27.

If ICONT=0, skip Cards 26A-26NA and go to Card 27.

If the indicator ICONT is greater than zero, the continuation deck produced from the output of the previous run follows immediately. The continuation deck contains the following information:

Card 26A

IT, TIME, T1, T2

I5,3D20.13

where (L=1 for main structure; L=2, NBR+1 for branches):

IT           The number of the time cycle at which the previous run had stopped, and is the beginning time cycle of the present continuation run.

TIME        The absolute time at which the previous run stopped, and is the beginning time of the present continuation run.

T1 }        Times at which the present linear segment of the force  
T2 }        versus time curve starts and stops acting, respectively.

Card 26B

AMP1FV, AMP1FW, AMP2FV, AMP2FW

4D20.13

where

AMP1FV	}	Nominal force amplitudes in the tangential and normal directions, respectively, at the beginning (1) and end (2) of the present linear segment of the force versus time curve.
AMP1FW		
AMP2FV		
AMP2FW		

Card 26C

SLOPEV, SLOPEW, APDEN, CINETO 4D20.13

where

SLOPEV	}	Slopes of the piecewise linear segment approximation of the present nominal force versus time curve in the tangential and the normal direction, respectively.
SLOPEW		
APDEN		Total work done on the structure by externally-applied forces up to the present time step.
CINETO		Initial kinetic energy imparted to the structure.

Card 26D

IBIGA(L), ISTAA(L), BIGA(L), BTIMA(L), ISURA(L) 2I5,2D20.13,I5

where (L=1 for main structure; L=2, NBR+1 for branches):

IBIGA	}	Information for maximum "additional-point strain". Same as their counterparts on Card 26E.
ISTAA		
BIGA		
BTIMA		
ISURA		

Card 26E

IBIG(L), ISURF(L), ISTA(L), BIG(L), BTIME(L) 3I5,2D20.13

where (L=1 for main structure; L=2, NBR+1 for branches):

IBIG(L)	The element number whose computed tensile strain exhibits the largest value during the previous run.
ISURF(L)	Equals 1 means largest computed tensile strain occurs on the inner surface; equals 2 means on the outer surface.
ISTA(L)	The Gaussian station at which the maximum strain occurred.
BIG(L)	The largest computed tensile strain during the previous run.





FMECH(I)      Assembled generalized load vector due to externally-applied forces at degree of freedom I.

FLVA (I) 4D20.13

FLVA(J)      Assembled generalized load vector due to large deflections  
and elastic plastic strains at each degree of freedom I.

Card 26MA

SNS (IR, J, K, L) 4D20.13

SNS(IR,J,K,L) The axial stress on the Lth mechanical sublayer at the Kth depthwise Gaussian point at the Jth spanwise Gaussian station of the IRth element at time cycle IT.

SNP (IR, J, K, L) 4D20.13

SMP(IR,J,K,L) The total plastic strain of the Lth mechanical sublayer at the Kth depthwise Gaussian point at the Jth spanwise Gaussian station of the IRth element.

Card 27

T2, AMP2FV, AMP2FW 3D15.6

T2            The time (seconds) of the second point to be specified on the normal force versus time curve.

AMP2FV } The nominal circumferential and normal force amplitudes,  
AMP2FW } respectively, of the second point to be specified (lbs).

Cards 27A, 27B, ... have the same format as Card 27 and read successive values of T2, AMP2FV, and AMP2FW. T2, AMP2FV, and AMP2FW on each card give the coordinates of each succeeding point on the force versus time curve. There is no limit to the number of No. 27 cards that can be used when specifying the total forcing function by coordinates of the force versus time curve. However, it is important that the final No. 27 card specify the nominal force at a time which must be equal to or greater than TFINAL specified on Card 21; otherwise, computation will stop.

**\*Note:** If ICONT $\neq$ 0 on Card 26 and this is a continuation run, the only No. 27 cards to be included are those with a T2 greater than the starting time of this continuation run.

#### 4.3 Input for Special Cases

While the JET 5A program is capable of analyzing the large-deformation, elastic-plastic response of a container/deflector structure, there will be instances when the user will wish to analyze only the elastic response of a material, or analyze the response of a membrane material. The JET 5A program is capable of performing these analyses with the following input and internal modifications.

##### 4.3.1 Special Cases of the General Stress-Strain Relations

In the following the specific input data for three special cases of the general elastic, strain hardening constitutive relation handled by the computer program are given. Only the relevant data are noted. (L=1 for main structure; L=2 to NBR+1 for the NBR branches; M=1 to NLAY):

##### 1. Purely Elastic Case

Set NSFL(M,L)=1 on Card 2 and Card 9A, and make EPS(M,1,L) and SIG(M,1,L) on Card 4AA and Card 9AA sufficiently high so that no plastic deformation occurs; for example EPS(M,1,L)=1.0, SIG(M,1,L)=ES(M,1,L), where ES(M,1,L) equals the elastic (Young's) modulus.

##### 2. Elastic, Perfectly-Plastic Case

Set NSFL(M,L)=1 on Card 2 and Card 9A, and make EPS(M,1,L)=SIG(M,1,L)/ES(M,1,L) on Card 4AA and Card 9AA.

### 3. Elastic, Linear Strain-Hardening Case

Set NSFL(M,L)=2 on Card 2 and Card 9A and set  $EPS(M,1,L)=SIG(M,J,L)/ES(M,1,L)$ . Also  $EPS(M,2,L)$  and  $SIG(M,2,L)$  on Card 4AA and Card 9AA are taken sufficiently high in order to avoid plastic deformation in the second sublayer. For example,  $EPS(M,2,L)=1.0$ , and  $SIG(M,2,L)=(1.0-EPS(M,1,L))*ES(M,2,L)+SIG(M,1,L)$ , where  $ES(M,2,L)$  is the slope of the segment in the plastic range.

#### 4.3.2 Membrane Analysis

If the user wishes to analyze a membrane (a structure with no appreciable bending stiffness), there are five basic steps to be undertaken.

1. Set NFL = 1 on Card 1
2. Set TXG(1) = 0.0 on Card 13A
3. Set TWG(1) = 2.0 on Card 14A
4. Set NTERF = 0 on Card 10
5. This step requires an internal change to the MAIN program of JET 5A. At the appropriate locations in the MAIN program, during the strain calculations for printout, comment cards are present to instruct the user as to which terms should be changed or zeroed out. These changes eliminate the bending terms present in Eq. A.12.

#### 4.4 Description of the Output

The printed output begins with a partial reiteration of the program input which identifies the problem being solved. This output includes information on: (1) initial geometry, (2) the nodal and element numbering system originally assigned by the user, (3) the new updated nodal and element system generated internally by the program if branches are present, (4) the branch attachment points, (5) the material properties for each layer of the main structure and for each branch, (6) the boundary conditions and elastic restraints as input, (7) the initial velocity locations and magnitudes, (8) the externally applied force locations, magnitude and timewise distribution, (9) the Gaussian stations and weights used in the program, (10) the assembled

After the initial printout has been completed, the following information is printed out after cycle M1 has been completed, and at every M2 cycles thereafter (see Subsection 4.2, Card 1). In addition, for JET 5A runs, a printout is made before and after the first cycle to confirm the proper implementation of the user's designated initial velocity information.

2

3

SUBSTRUCTURE	MSTR	ELE	TIME	STA
--------------	------	-----	------	-----

1

2

SUBSTRUCTURE	LARGEST ADD. PT. STRAIN	ELEM	ADD. PT.	TIME
--------------	-------------------------	------	----------	------

1

2

SUBSTRUCTURE	LARGEST NODAL STRAIN	NODE	SURF	TIME
--------------	----------------------	------	------	------

1

2

REACTIONS AT NODE	RV (LBS)	RW (LBS)	RM (IN-LBS)
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where

IT = Cycle number

TIME = Elapsed time corresponding to the end of cycle IT (sec.)

CINETT = Total work imparted to the structural ring up to the present time by the external loadings (in-lb).

CINET = The current value of kinetic energy present in the structural ring\* (includes both the rigid body and the relative kinetic energies) (in-lb).

ELAST = Total elastic strain energy stored in the entire structural ring at the present time instant (in-lb).

PLAST = Total plastic work\*\* done on the structural ring (mechanical work dissipated during plastic flow) (in-lb).

SPDEN = Total energy stored in the elastic-restoring springs and/or the elastic foundations at the current time instant (in-lb), if the presence of elastic restraints is specified.

SI = Strain  $\gamma_{11}$  (same as  $\tilde{\epsilon}$  of Eq. A.12) at the inner surface of the ring

SO = Strain  $\gamma_{11}$  at the outer surface of the ring

Note: If the strains at the interfaces of a multilayer structure are to be printed out, every other line will be strain at the inner and outer surface (starting with line one) and the second, fourth, sixth, etc. lines will be strains at interface one and two (going from the inner to

---

\* It should be noted that the rigid body part of the kinetic energy, which is used to accelerate the "rigid body" mass of the structure, can be extracted and identified separately. However, for the present program dealing with rather general structural geometries and with various support/restraint conditions, it would be very unwieldy (but not impossible) to identify these separate kinetic energies; hence, the total kinetic energy is calculated and printed out.

\*\* The plastic work done on the ring is estimated by subtracting the sum of the elastic and kinetic energies present in the ring from the total input energy (due to the externally-applied load and the initially-imparted kinetic energy); i.e.,  $CINETT = CINET + ELAST + PLAST + SPDEN$ . It should be mentioned that the approximate nature of this numerical calculation will sometimes yield impossible results such as negative values of plastic work or values greater than zero when the ring has not yet reached a plastic condition; thus, the value of plastic work should be considered only approximate, and spurious results as noted above should be ignored.

the outer surface). If there is only one interface, the strain corresponding to the second interface will be the strain along the reference axis. This will be true for both strains at Gaussian stations and at additional strain points.

STAL	}	= Spanwise Gaussian Station at which strain was calculated.
STA2		
STA3		
EI	}	= Relative elongation at inner or outer surface, respectively, at the additional strain points; obtained from
EO		
		$E_1 = \sqrt{1+2\gamma_{11}} - 1.$
I		= Node number. For a partial ring, the value of the total number of nodes equals the value of the total number of elements plus one. For a complete ring, the value of the total number of elements plus one. For a complete ring, the value of the total number of nodes equals the value of the total number of elements.
V		= The middle plane axial displacement at node I (in).
W		= The middle plane transverse displacement at node I (in).
PSI		= The generalized nodal displacement $\psi = (\partial v / \partial \eta) - v/R$ at node I (rad).
CHI		= The generalized nodal displacement $\chi = (\partial v / \partial \eta) + w/R$ at node I (rad).
COPY		= The Y-location of node I in the global (inertial) coordinate system (in).
COPZ		= The Z-location of node I in the global coordinate system (in).
L		= Axial internal force resultant over the cross section at the midspan point of <u>element</u> I (lb).
M		= Internal bending moment of the cross section at the midspan point of <u>element</u> I (lb).



STRAIN(IN) = Average strain on the inner surface at node I.\*  
 STRAIN(OUT) = Average strain on the outer surface at node I.\*  
 SUBSTRUCTURE = The portion of the ring being considered.  
     1 = main structure  
     2 = 1st branch  
     3 = 2nd branch  
     .  
     .  
     .  
 MSTR = Maximum strain on the substructure at a Gaussian station.  
 ELE = Element on which max. tension strain occurred.  
 TIME = Time at which max. tension strain occurred.  
 STA = Gaussian station at which max. tension strain occurred  
       on element ELE.  
 NODE = Node at which largest average value of tension strain  
       occurred.  
 ELEM = Element on which largest value of tension strain occurred  
       at an additional strain point.  
 ADD. PT. = Additional Point Number.  
 TIME = Time at which the max. tension strain occurred.  
 REACTIONS AT NODE = The node number of a constrained node.  
 RV = The tangential reaction force (lbs).  
 RW = The normal reaction force (lbs).  
 RM = The reaction moment (in-lbs).

Note: Checks for largest average nodal strain and largest additional-point strain are made only at printout cycles. Check for largest Gaussian-station strain is made at each cycle.

---

\* At nodes on the main structure where a branch connection occurs, the contribution of strain from the branch is not included in the nodal averaging process.

At the conclusion of the run, a final update of the maximum strain occurring on each substructure (main structure and each branch) and for the additional strain points on the main structure and each branch is printed out. Also, a note as to whether or not continuation cards were punched is made.

#### 4.5 Guidelines and Restrictions for Code Usage

##### 4.5.1 General Instructions

The JET 5A computer code is capable of handling a wide variety of transient, large-deflection structural response problems involving external loadings. This capability is beneficial to the user since it is contained in one computer program; however, it can be unnecessarily costly to run the program if all of the options included are carried along but are not being used.

In order to save storage locations and, therefore, save computer costs on each run, several subroutines can be removed when they are not used during that particular job submittal.

The following is a list of subroutines which must be included in every run of the JET 5A program:

MAIN	FAC	PRINT
ASSEF	IDNT	SOLV
ASSEM	IMPULS	STRESS
ELMPP	MINV	
ERC	OMULT	

The remaining subroutines: BRAN, LOADEQ, LOADFT, QREM, ROTAT, and TSTEP may be left out depending upon the type of problem being solved.

Subroutine TSTEP may be optional when the user desires (i.e. when the user does not specify DELTAT = 0.0 on Card 5). The user merely has to omit the TSTEP subroutine, and only inputs the following three cards instead of TSTEP:

```
SUBROUTINE  TSTEP  (AMASS, STIFK, DELTAT)
RETURN
END
```

In like manner, if the user does not wish to apply any branches to the

main structure, the BRAN subroutine becomes optional. If no branches are used, BRAN is input as follows:

```
SUBROUTINE BRAN (NBR)
RETURN
END
```

Thus, for any subroutine that is not being used for a particular run, just submit the first card of the subroutine (the name card) and the RETURN and END cards. This will save the user input costs, compilation costs, and storage costs. The same procedure is used for QREM if no elastic restraints are defined, for ROTAT if no branches or slope discontinuities are used, and for LOADEQ and LOADFT if no external forcing functions are specified.

Finally, it should be noted that if the various layers of the multi-layer structure consist of the same material and if a branch is attached and consists of a different material, unreliable results can be expected because the present element assembly logic does not accommodate this situation properly.

#### 4.5.2 Comments on Strain Calculations

In the present JET 5A program, options are available which allow the user to obtain strain printout at the spanwise Gaussian stations (which include the element midspan location), and/or at additional points on the structure specified by the user. Nodal average strains are given automatically at each regular printout cycle. This flexibility can be of great value to the user, but certain precautions should be taken by the user in interpreting the strain results.

The strain-displacement relation employed in the present curved beam elements is given by Eq. A.12. An examination of this equation shows that nonlinear terms are included only in the membrane behavior, and only linear terms are included in the bending behavior. Thus, the membrane nonlinearities have been assumed to be more significant than the bending nonlinearities. The calculated distribution of strain may be quite different from element to element, and the strain distribution within each element will, in general, not be the same as the "exact" distribution. This behavior corresponds to the fact that in the present finite-element model the predicted strain distribution

approximates the actual strain distribution in an average (integral) sense, and not in a pointwise sense. Although the calculated distribution may be the same as the "exact" distribution at some points within the element, the choice of a "best" point (or points) for strain evaluation within an element is not obvious. The choice of  $v, w, \psi$ , and  $\chi$  as generalized nodal parameters assures membrane strain continuity at the nodes, but in general the bending strain will not be continuous at the nodes; thus, the predicted strains at the inner and outer surface of an element will not, in general, be continuous at the nodes.

Because of these facts, certain precautions should be taken by the user when assessing strain distributions in space and/or time. If detailed strain distributions are required over a portion of the structure at a particular time instant, it is suggested that several printout points be chosen in each element (e.g. Gaussian stations and nodal averaged points) in the region of interest. When these calculated values are plotted, the analyst can then make a reasonable "faired" estimate of the "proper" distribution. It should be noted that severe strain gradients within an element do not necessarily indicate poor behavior of the solution; however, it is in these regions where the analyst must exercise the greatest caution in making a reasonable faired estimate of the proper distribution. Although not conclusive, experience to date with the present JET 5A computer code suggests that these regions of predicted severe strain gradients are most often observed near clamped boundaries.

If strain time-history information is required at various points on the structure, these points can be specified as additional strain points and the time histories may be obtained directly. In addition, it is recommended that spatial distributions near these points of interest be obtained at several time instants to assess whether or not the strain at the point of interest is in reasonable agreement with the curve-fitted (or faired) distribution in that region of the structure. If these steps are followed, a reasonable engineering assessment of strain information should be obtained.

The equations in Appendix A have been developed within the assumption of large deflections but small strains. Thus, reliable results may not be obtained in localized regions where large strains are predicted. However, the actual strain level at which the "small strain" assumption becomes invalid is

not known. Thus, the limitations of the present analysis, for practical engineering problems, cannot be clearly stated; further study of the limitations of the present analysis versus appropriate well-defined experimental data is required. In the future it is recommended that models which can accommodate arbitrarily large strain be developed for both two-dimensional (planar) and three-dimensional (non-planar) deformations. In the meantime, however, it is believed that the capabilities of the present JET 5A analysis and program can provide useful engineering estimates.

#### 4.5.3 Comments on Code Use on Other Computer Systems

The JET 5A computer code has been exercised largely on an IBM 370/168 computer system at the MIT Information Processing Center with MIT's version of IBM's G compiler (including all updated IBM modifications). The example problem results given in Subsection 7.1.3 were obtained from this system.

Each user will need to assess what kind of computer code statement changes need to be made (if any) to the FORTRAN IV source code given in this report in order to adapt the code to his particular computer facility. The user should be aware of the fact that the use of different compilers at a given computer facility can produce somewhat different transient response predictions. For example, the use of a TSS compiler with an IBM 360 system at the NASA Lewis Research Center led to slightly different transient strain predictions and significantly different support reactions than given in the solution results of Subsections 7.1.3 and 7.2.3 (for CIVM-JET 5B) with code modifications included to adapt to that NASA system. However, subsequently, the "modified adapted" code was used on that IBM 360 system with NASA's H-extended compiler; the results agreed exactly with those given in the present report. For the two example problems (see Subsections 7.1 and 7.2), some results obtained with several computing systems and compilers at NASA-Lewis and MIT are given in the table on page 297.

## SECTION 5

### USE OF THE CIVM-JET 5B PROGRAM

The CIVM-JET 5B program has been designed to be as similar to the JET 5A program as possible. This will aid the user in adapting from one program to the other. The user is encouraged to read Section 4 before using Section 5, because this section depends on information already covered in Section 4. Subsections 4.1 and 4.4 hold equally well for both JET 5A and CIVM-JET 5B and are not repeated in this section.

#### 5.1 Input Information and Procedure

The input information required for CIVM-JET 5B is very similar to that just described in Subsection 4.2 for JET 5A, except for some slight modifications. The data cards are listed in the following. To avoid needless repetition, only variables which newly appear and/or have different definitions are described.

	FORMAT
Card 1	
IK, ICP, NLAY, LREF, NOGA, NFL, MM, M1, M2, ICON	10I5
Card 2	
NSFL(1,1) .... NSFL(NLAY, 1)	3I5
Card 3A	
DENS(1,1), DS(1,1), P(1,1)	3D15.6
Card 4AA	
EPS(1,1,1), SIG(1,1,1), EPS(1,2,1), SIG(1,2,1)	4D15.6

Additional Cards 4AB and 4AC are punched in exactly the same manner as Card 4AA until the number of coordinate pairs equals NSFL(1,1) punched on Card 2 for layer 1. The total number of coordinate pairs must not exceed 5 for any layer. Do not include any unneeded (blank) cards.

Cards 3 through 4 are repeated for each additional layer in the multi-layer ring until the number of sets of cards equals NLAY (given on Card 1). The total number of card sets must not exceed 3.

Card 5

B(1), DELTAT 2D15.6

Card 5A

Y(1), Z(1), ANG(1) 3D15.6

Additional Cards 6B, 6C ... are punched in exactly the same format as Card 6A until the total number of No. 6 cards equals (IK+1) for a partial ring and equals IK for a complete ring, where IK is the value appearing on Card 1. See Card 6A, Subsection 4.2, for further restrictions.

Card 7A

H(1,1), ... H(1, NLAY), H(2,1)... 5D15.6

Card(s) 7B, 7C, ... are repeated in the same format until the thicknesses of each layer of the ring at every nodal station are defined. The total number of data on Cards 7 (with 5 data on each card) should be equal to NLAY\*IK for a complete ring and equal to NLAY\*(IK+1) for a partial ring.

Card 8A

NDIS 15

If there are no slope discontinuities on the main structure, set NDIS=0 and go to Card 9.

Card 8BA

NEDI(I), ANGDI(I) 4(I5,D15.6)

Additional Cards 8BB, 8BC, etc. are used until all of the "slope discontinuities" are described. See Fig. 10 for a further description of the discontinuity option.

The sequence of cards starting with Card 9 and going through Card 9DB contains all the data for the single layer branches to be applied to the main structure except that elastic restraints must be handled as one unit on Card 16. See Subsection 4.2 for a complete explanation of the branch option.

Card 9

NBR 15

If NBR=0 Go to Card 10.

Card 9A

NSFL(1,L), B(L), DENS(1,L), DS(1,L), P(1,L)

I5, 4D15.6

Card 9AA

EPS(1,J,L), SIG(1,J,L)

4D15.6

Additional Cards 9AB and 9AC are punched in exactly the same manner as Card 9AA until the number of coordinate pairs equals NSFL(1,L) punched on Card 9A. Do not include any unneeded (blank) cards.

Card 9B

NELT(I), NODP(I), LHIT(I), LATT(I)

4I5

where

I                      Number of branch      I=1, NBR

LHIT(I)                Determines whether or not branch can be impacted:

LHIT(I)=0              No impact

LHIT(I)=1              Impact

Note: While it may be useful to allow branches to be impacted at some future time, at present branch impact is not allowed. Set LHIT(I)=0 for all CIVM-JET 5B computer runs.

LATT(I)                Determines where branch is to be attached.

LATT(I)= -1      inner surface

0      outer surface

1 }  
2 } midsurface of respective layer.  
3 }

Card 9BA

YB(I,J), ZB(I,J), ANB(I,J), HB(I,J)

4D15.6

where

I = branch number, J = node number

See Subsection 4.2 for further restrictions.

Cards 9BB, 9BC, etc., are punched until (NELT+1) nodes have been described.



Card 9C

NDISB

I5

If there are no discontinuities on the branches, set NDISB=0 and go to Card 9D.

Card 9CA

NEDIB, NBDI, ANGB

2I5,D15.6

Cards 9CB, 9CC, etc., follow until the information for all NDISB branch slope-discontinuities has been given.

Card 9D

NBCONB

I5

If NBCONB=0 go to Card 10.

Card 9DA

NBCB(I), NODBB(I), LBR(I)

4(3I5)

where

I=1, NBCONB

See Subsection 4.2 for further remarks about the branch input.

Card 10

NOP, NASP, NTERF

3I5

If NOP  $\neq$  2 or 3, go to Card 11.

Card 10A

NSBS(I), NSEL(I), AZET(I)

2I5,D15.6

where

I=1, NASP

Cards 10B, 10C, etc. are used until all the additional strain points have been described.

Card 11

AXG(1), AXG(2), AXG(3)

3D25.16

Card 12

AWG(1), AWG(2), AWG(3)

3D25.16

Card 13A		
	TXG(1), TXG(2), TXG(3)	3D25.16
Card 13B		
	TXG(4)	3D25.16
Card 14A		
	TWG(1), TWG(2), TWG(3)	3D25.16
Card 14B		
	TWG(4)	3D25.16
	See Subsection 4.2 for further instructions.	
Card 15		
	NBCOND, NBC(1), NODEB(1), NBC(2), NODEB(2), ... NBC(7), NODEB(7)	9I5
	See Subsection 4.2 for a full explanation of the above boundary conditions.	
Card 16		
	NQR, NORP, NORU	3I5
	If NQR=0 go to Card 17.	
	If NORP=0, Skip to Card 16B	
Card 16A		
	SCTP, SCTY, SCRP	3D15.6
Card 16AA		
	NREL(1), REX(1), NREC(2), REX(2), ... NREL(4), REX(4)	4(I5,D15.6)
	If NORU=0 in Card 16, omit Card 16B, and Card 17 follows directly.	
Card 16B		
	SCTU, SCTW, SCRUI	3D15.6
Card 16BB		
	NRST(1), NREU(1), ... NRST(4), NREU(4)	8I5
	Cards 17 and 18 contain the input data concerning the attacking fragment(s).	
Card 17		
	NF, EFLN(1)	I5,D15.6

where

NF            The number of fragments considered to be impacting the structure. This number cannot exceed 3.

EFLN(1)      The "effective length" of the impact-affected zone. The user can select an "appropriate" value for this quantity; or, if EFLN(1)=0, the program will choose a value for EFLN(1) given by  $EFLN(1) = \Delta t \sqrt{E/\rho}$  where E = Young's modulus and  $\rho$  = the mass density of a layer. The largest EFLN(1) calculated for each layer, will be the "effective length" employed for the entire structure.

Card 18AA

FH(I), FCG(I), FCGX(I), FMASS(I), FMOI(I) 5D15.6

Card 18AB

UNK (I) D15.6

Card 18AC

UDOT(I), WDOT(I), ADOT(I), TPRIM(I), CR(I) 5D15.6

where  $I$  = number of fragment.  $I < 3$

FH(I)            The diameter of the circular disk model of the Ith fragment  
                  (inches).

FCG(I)            The Z coordinate of the centroid of the Ith fragment before and at the time of its release. The positive direction represents a location above the global Y axis (inches).

FCGX(I)      The Y coordinate of the centroid of the Ith fragment before and at the time of its release. The positive direction represents a location to the right of the global Z axis (inches).

FMASS(I)      The mass of the Ith fragment (lb-sec<sup>2</sup>/in).

FMOI(I)      The mass moment of inertia of the Ith fragment (lb-sec<sup>2</sup>-in).

UNK(I)      Coefficient of friction between the Ith fragment and the ring inner surface.

UDOT(I)      The velocity component of the Ith fragment parallel to the global Y axis before initial impact (in/sec). Positive UDOT(I) represents a fragment traveling to the right.

WDOT(I)      The velocity component of the Ith fragment parallel to the global Z axis before initial impact. The positive direction denotes a fragment traveling in an upward (+Z) direction (in/sec).

ADOT(I)      The initial angular velocity of the Ith fragment (rad/sec). Positive sign denotes counterclockwise rotation.

TPRIM(I)      Time (seconds) that the fragment is allowed to travel before program starts to track its location. One usage of TPRIM(I) allows fragments to be released after the first fragment has impacted and calculations have begun.

The fragments should be ordered as follows to allow proper use of the TPRIM capability: Fragment 1 should be the fragment that will make first contact with the ring. Time zero is the time of release of this fragment. The second group of fragments includes all of the fragments that will be released before the first fragment impacts. The fragments can be placed in any order within their group. The third group contains those fragments released after the first fragment impacts; these must be ordered such that the first fragment to be released is first and so on within this group.  $TPRIM(1) = \text{Time of impact of first fragment} - \text{time of release}$ . Since time of release of fragment one is equal to 0,  $TPRIM(1)$  equals time of first impact. Actually,  $TPRIM(1)$  must be less than the time of first impact to guarantee a proper impact solution.

$TPRIM(I)$  where  $I = 2, NF$  equals  $TPRIM(1)$  minus time of release of the Ith fragment. Thus,  $TPRIM$ , for those fragments released after the first fragment impacts, will be negative.  $TPRIM(I)$  must be a multiple of the  $\Delta t$  used.

CR(I)            Coefficient of restitution between the Ith fragment and the impacted ring inner surface ( $0 \leq CR \leq 1$ ); equals 1 for perfectly elastic, 0 for perfectly inelastic,  $0 < CR < 1$  for intermediate. CR=1 is usually recommended.

Cards 18BA, 18BB, 18BC, 18CA, 18CB, 18CC, ... should follow (in blocks of three cards) until the information for all NF fragments has been completely specified.

Card 19

ICONT

I5

where

ICONT            Integer which if greater than 0 indicates that this is a continuation run. In order to use this option, it is necessary to obtain the following continuation cards from a previously run job. To do this, set the variable MPU=1 at the beginning of the MAIN routine. This will cause the following set of data cards 19A through 19NA to be punched. When using this deck, set ICONT=1 and use the same data cards as used before, except to change the values of MM and M1 on Card 1.

If ICONT=0, skip Cards 19A-19NA. If the indicator ICONT is greater than zero, the continuation deck produced from the output of the previous run follows immediately. The continuation deck contains the following information:

Card 19A

IT, TIME, IMOU, TAIL

2(I5,D20.13)

where

IMOU            The number of impacts up to the end of the last run.

TAIL            Time of initial impact.

Card 19BA

IBIGA(L), ISTAA(L), BIGA(L), BTIMA(L), ISURA(L)

2I5,2D20.13,I5

Card 19CA

IBIG(L), ISURF(L), ISTA(L), BIG(L), BTIME(L)

3I5,2D20.13

Card 19DA

IBI(L), ISUR(L), BI(L), BTIM(L)

2I5, 2D20.13

Card 19E

MIRP, TNJ(1), ... , TNJ(NF)

I5, 3D20.13

where

NF            Number of fragments impacting structure.

MIRP            Number of next fragment waiting to be released.

TNJ(J)            Indicates whether or not the Jth fragment has been  
released:

TNJ(J)=0.0            not released

TNJ(J)=1.0            released

Card 19FA

DISP(I)

4D20.13

Card 19GA

DELD(I)

Card 19HA

DELDML(I)

4D20.13

Card 19IA

FLVA(I)

4D20.13

Card 19JA

QVEL(I)

4D20.13

where

QVEL(I)            The velocity at the present instant of time for the Ith  
degree of freedom.

Card 19KA

QACL(I)

4D20.13

where

QACL(I)            The acceleration at the present instant of time for the Ith  
degree of freedom.

Card 19MA

SNP (IR,J,K,L)

4D20.13

Card 19NA

FCGU(J), FCGW(J), ALFA(J), UDOT(J), WDOT(J), ADOT(J)

4D20.13

where

FCGU(J)      The centroidal position of the Jth fragment in the Y direction at time cycle IT (inches).

FCGW(J)      The centroidal position of the Jth fragment in the Z direction at time cycle IT (inches).

ALFA(J)      The total angular displacement of the Jth fragment at time cycle IT (radians).

UDOT(J) }  
WDOT(J) }      Fragment velocities at time cycle IT (in/sec); see Card 18AC  
ADOT(J) }      for more details.

J=1, NF

## 5.2 Description of the Output

The output for CIVM-JET 5B is exactly the same as the output generated by the JET 5A program (described in Subsection 4.4), except for two places where data are given for the attacking fragments.

After each printout cycle (designated by the user on Card 1), an update of the fragments locations and velocities is given as follows:

FRAG NO.	FCGU	FCGW	ALFA	FRUV	FRWV	FRAV
1						
2						
.						
.						
.						

where

FCGU      = Global Y coordinate of the centroid of the fragment at the current time instant (in).

PCGW = Global Z coordinate of the centroid of the fragment at the current time instant (in).

ALFA = Angular rotation of the fragment to the current time instant (rad).

FRUV = The current velocity component of the fragment in the Y direction (in/sec).

FRWV = The current velocity component of the fragment in the Z direction (in/sec).

FRAV = The current angular velocity of the fragment (rad/sec). Positive sign denotes counter-clockwise rotation.

In addition to the above information, whenever there is an impact, the following information is printed out:

IMPACT NO.	TIME =	DURING CYCLE =	ELEM =
FRAG =	DISTANCE =		
FRAG[J]	TE =	RE =	TOE =

where

DISTANCE	The ratio of the distance from the first node of the element to the point of impact divided by the straight line distance from node 1 to node 2.
J	The J'th fragment
TE	Translational kinetic energy of fragment J immediately following the impact.
RE	Rotational kinetic energy of fragment J immediately following the impact.
TOE	Total kinetic energy of fragment J immediately following the impact. TOE=TE+RE.

### 5.3 Guidelines and Restrictions for Code Usage\*

#### 5.3.1 General Instructions

The following is a list of subroutines which must be included in every run of the CIVM-JET 5B program:

---

\* The remarks given in Subsection 4.5.3 concerning use of JET 5A on various computer systems apply also to CIVM-JET 5B.



ASSEF	FAC	MAIN	PRINT
ASSEM	IDNT	MINV	SOLV
ELMPP	IMPACT	OMULT	STRESS
ERC	IMPCTE	PENTRN	

The remaining subroutines: BRAN, QREM, ROTAT, and TSTEP may be left out depending upon the type of problem being solved. See Subsection 4.5.1 for a detailed explanation.

### 5.3.2 Use of Branches vs. Use of Discontinuities

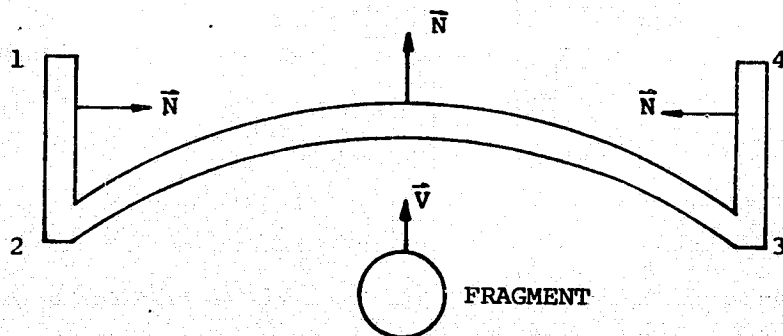
In the present CIVM-JET 5B program, both branches attached to and slope-discontinuities in the main structure can be accommodated. Because of the way in which these two features are handled in the program logic and, in particular, for determining ring-fragment collision, certain general guidelines should be followed by the user for more efficient use of the computer code.

The dominant consideration involves the determination of ring-fragment collision. In the present code, impact on a branch is not accommodated, so that if branch impact is an important consideration for a particular problem, then the slope-discontinuity option must be used in place of the branch option, thus, identifying this region not as a branch but as a part of the main structure. Note, however, that in all cases where three elements are to be connected at a single nodal point (such as in the case of a branch at the midspan of a beam), one of the elements must be defined as a branch. In general, at any node where three elements are joined, one of these elements (and all subsequent elements in that portion of the structure) must be defined as branch elements. However, two branches may not start at the same node of the main structure.

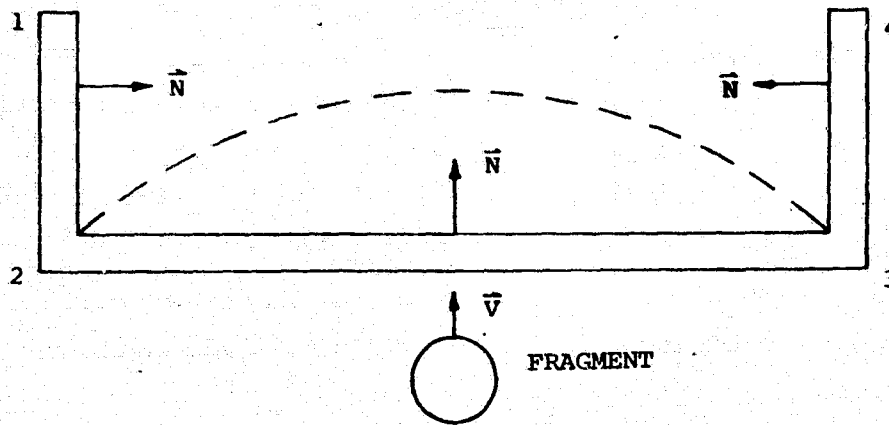
During each increment in time,  $\Delta t$ , a collision inspection is carried out for each element on the main structure for each of the N fragments considered, but no collision inspection is carried out for elements defined as branch elements. This fact can be used to reduce the total computation time; if the user knows a priori that no collisions will occur in certain regions of the structure, then those regions should be defined as branches wherever possible (note that branches cannot be specified to be attached to another branch).

It should be noted that complete nodal generalized displacement compatibility at a junction between a branch and the main structure is contained in the program logic regardless of whether the main structure and the branch are composed of the same or different materials. In the latter case this leads to results at and near the junction which are somewhat inconsistent physically; improved results could be expected if one were to require nodal compatibility only for  $v$ ,  $w$ , and  $\psi$  (rather than for  $v$ ,  $w$ ,  $\psi$ , and  $\chi$  where  $\chi = \frac{\partial v}{\partial \eta} + \frac{w}{R}$ ).

As noted in Section 2, the positive  $\eta$  direction must be chosen in such a way that the outward normal for each element is directed toward the outside of the structure, where the fragments are considered to be in the inside of the structure. In some special (but plausible) cases, the outside region of a portion of the structure may overlap with the inside region of another portion of the structure either in the initial structural configuration or after some deformation of the structure has occurred. Within the current collision inspection program logic, such overlapping regions cannot be accommodated. Consider the following initial structural configuration:



With the positive normal directions  $\bar{N}$  as shown (and considering the entire structure as a main structure, using the slope-discontinuity option), the outside regions of segments 1-2 and 3-4 would overlap with the inside region of segment 2-3. To accommodate such a configuration, segments 1-2 and 3-4 must be defined as branches so that no collision inspection is performed for those segments. Consider now the following initial structural configuration:



For the initial configuration (solid lines), no inside-outside overlapping occurs. However, after deformation of segment 2-3 (dashed line, assuming fragment impact is as depicted above), the outside regions of segments 1-2 and 3-4 will overlap with the inside region of segment 2-3. Again, in this case, segments 1-2 and 3-4 must be defined as branches.

### 5.3.3 Impact at or Near a Constrained Node

In the present CIVM-JET 5B program, the case of fragment impact on or near a constrained node is handled in an approximate fashion. The nature of this approximation is discussed briefly here as a guide to the user in interpreting results when impact occurs on or near a constrained node.

The assumption used is as follows: when impact occurs near a constrained node, the only nodes which can respond with impact-induced velocity changes are those nodes which lie within the impact-affected region and which are located on the impacted side of the constrained node. In essence, no impact-induced information is allowed to propagate past the constrained node (for the purpose of impact corrections), and a portion of the impact-induced impulse is "absorbed" by the constraint. Although no impact-induced information is allowed to propagate past the constrained node for the purpose of impact-induced velocity, the impact-induced information will filter through the constrained node in the global timewise solution if the constrained node is smoothly hinged.

If the node is ideally clamped, no impact-induced information will filter past the constrained node in the global timewise solution. It should also be noted that as the point of ring-fragment impact approaches the constrained node, the impact-induced ring response approaches zero; when impact occurs directly on a constrained node, the fragment simply rebounds and no impact-induced structural response occurs.

For a more thorough discussion of this topic, the reader is referred to Appendix B.

#### 5.3.4 Comments on Space Mesh Sizing

In the present CIVM-JET 5B program, considerable flexibility is given to the user in terms of defining the size and number of elements to be used for a particular structural geometry. However, certain guidelines should be followed in the selection of a finite-element mesh for the present impact analysis. It is recommended that a uniform mesh be employed for all analyses, the only exception being in regions where structural detail dictates the use of nonuniform elements. Clearly this recommendation is justified for the general case where the point of initial (and subsequent) impact is not known a priori. Now consider the special (limiting) case where it is known a priori that all ring-fragment impacts will occur at (approximately) the same point on the structure (e.g. initially straight, uniform thickness, doubly clamped beam with the only nonzero component of the fragment velocity being normal to the beam midsurface, and initial impact occurring at the midspan of the beam). A uniform mesh is again recommended for this special case, based on the following considerations. One estimate\* of the impact-affected length,  $L_{eff}$ , is  $L_{eff} = \sqrt{\frac{E}{\rho}} \Delta t$ ; when using the central difference operator, the allowable time step,  $\Delta t$ , is inversely related to the highest natural frequency,  $\omega_{max}$ , of the assembled structure. If the element size in the region of impact is decreased, then  $\omega_{max}$  is increased and  $\Delta t$  and, thus,  $L_{eff}$  are decreased. In the limit, as the element size is decreased, the impact-induced "loading" will become concentrated at the point of impact and unreasonably high strain predictions may be found near this region of concentrated loading. It is believed (based on experience to date with the present CIVM-JET 5B program) that the choice of a uniform mesh for this case will yield the most reliable predictions.

---

\* Basically, however,  $L_{eff}$  must be independent of  $\Delta t$  since various  $\Delta t$  sizes are permissible with different finite-difference time operators. From considerations of through-the-thickness stress wave propagation and accompanying imparted particle velocities, one might estimate  $L_{eff} = nh$  where  $h$  is the total wall thickness and  $n$  is some number typically  $2 \lesssim n \lesssim 4$ .

## SECTION 6

### COMPLETE FORTRAN IV LISTINGS OF THE PROGRAMS

#### 6.1 Subroutines Common to both JET 5A and CIVM-JET 5B

These fourteen (14) subroutines consist of:

ASSEF	MINV
ASSEM	ØMULT
BRAN	QREM
ELMPP	RØTAT
ERC	SØLV
FAC	STRESS
IDENT	TSTEP

and are listed in the following:

```

SUBROUTINE ASSEF(IR,IK,ELFP,FLVA,ICP)
  IMPLICIT REAL*8(A-H,O-Z)
  DIMENSION NN(8),FLVA(1),ELFP(1)
  COMMON /BR/ NVEC(51,2), LMT(51)
  J1 = NVEC(IR,1)*4
  NN(1)=J1-3
  NN(2)=J1-2
  NN(3)=J1-1
  NN(4)=J1
  IF(ICP.LE.0) GO TO 121
  IF(IR-1K) 121,122,122
121 J2 = NVEC(IR,2)*4
  NN(5)=J2-3
  NN(6)=J2-2
  NN(7)=J2-1
  NN(8)=J2
  GO TO 123
68 122 NN(5)=1
  NN(6)=2
  NN(7)=3
  NN(8)=4
123 DO 101 I=1,8
  M=NN(I)
  FLVA(M)=FLVA(M)+ELFP(I)
101 CONTINUE
  RETURN
END

```

```

ASSF0010
ASSF0020
ASSF0030
ASSF0040
ASSF0050
ASSF0060
ASSF0070
ASSF0080
ASSF0090
ASSF0100
ASSF0110
ASSF0120
ASSF0130
ASSF0140
ASSF0150
ASSF0160
ASSF0170
ASSF0180
ASSF0190
ASSF0200
ASSF0210
ASSF0220
ASSF0230
ASSF0240
ASSF0250
ASSF0260
ASSF0270

```

SUBROUTINE ASSEM(IR,IK,ELMAS,STIFM,ICP,INUM)  
 IMPLICIT REAL\*8(A-H,O-Z)  
 DIMENSION ELMAS(8,8),NN(8),STIFM(1),INUM(1)  
 COMMON /BR/ NVEC(51,2), LMT(51)  
 J1 = NVEC(IR,1)\*4  
 NN(1)=J1-3  
 NN(2)=J1-2  
 NN(3)=J1-1  
 NN(4)=J1  
 IF(ICP.LE.0) GO TO 203  
 IF(IR-1K) 203,204,204  
 203 J2 = NVEC(IR,2)\*4  
 NN(5)=J2-3  
 NN(6)=J2-2  
 NN(7)=J2-1  
 NN(8)=J2  
 GO TO 202  
 204 NN(5)=1  
 NN(6)=2  
 NN(7)=3  
 NN(8)=4  
 202 DO 402 I=1,8  
 M=NN(I)  
 DO 402 J=1,8  
 N=NN(J)  
 IF(M-N) 402,403,403  
 403 L=N+INUM(M)  
 STIFM(L)=STIFM(L)+ELMAS(I,J)  
 402 CONTINUE  
 RETURN  
 END

ASSM0010  
 ASSM0020  
 ASSM0030  
 ASSM0040  
 ASSM0050  
 ASSM0060  
 ASSM0070  
 ASSM0080  
 ASSM0090  
 ASSM0100  
 ASSM0110  
 ASSM0120  
 ASSM0130  
 ASSM0140  
 ASSM0150  
 ASSM0160  
 ASSM0170  
 ASSM0180  
 ASSM0190  
 ASSM0200  
 ASSM0210  
 ASSM0220  
 ASSM0230  
 ASSM0240  
 ASSM0250  
 ASSM0260  
 ASSM0270  
 ASSM0280  
 ASSM0290  
 ASSM0300  
 ASSM0310

ORIGINAL PAGE IS  
 OF POOR  
 QUALITY

C-2

```

      SUBROUTINE BRAN(NBR,DENS,EPS,SIG,B)
      IMPLICIT REAL*8(A-H,O-Z)
      DIMENSION SLB(5)
      DIMENSION DENS(3,6),B(6),EPS(3,5,6),SIG(3,5,6)
      DIMENSION LBR(7),ZK(51),HK(51,3),ANGK(51),LATT(6),LHIT(6)
      DIMENSION YB(5,11),ZB(5,11),ANB(5,11),HB(5,11),NELT(6)
      COMMON /PG/ IK,IKK,ICP,LREF,NOGA,NFL,NI,ICOL(205),INUM(205)
      *,NBCOND,NBC(7),NODEB(7),KROW(8),NDEX(8),NIRREG
      COMMON /TAPE/ MREAD,MWRITE,MPUNCH
      COMMON /THI/ HTH(5)
      COMMON/MAT/YOUNG(3,6),DS(3,6),SNO(3,5,6),NSFL(3,6),P(3,6),NLAY
      COMMON/FC/ Y(51),Z(51),ANG(51),H(51,3)
      COMMON/BOUN/YK(51),NBCONB,NBCB(7),NODBB(7),MK(51),ROT(5,2)
      *,XDIST(6),DROT(50),NODP(6)
      COMMON /ML/ MNEL(6),MATT(6)
      COMMON/DIS/ ANGDI(50),NEDI(50),NDIS
      COMMON /BR/ NVEC(51,2),LMT(51)
      COMMON /TAM/ MKE(51)
      C  RENUMBER NODES AND ELEMENTS
      EXANG= 360.0
      IF (ICP.LE.0) EXANG= 0.0
      NS = IKK
      NNS = NS
      NIK = IK
      PIE= 3.141592653589793D+00
      DO 5301 J= 1,6
      NELT(J) = 0
      5301 NODP(J) = 0
      DO 5302 K = 1,NS
      YK(K) = Y(K)
      ZK(K) = Z(K)
      DO 5303 L=1,NLAY
      5303 HK(K,L) = H(K,L)
      5302 ANGK(K) = ANG(K)
      DO 5313 I = 1,NBR
      IB = I+1

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BRAN0010
BRAN0020
BRAN0030
BRAN0040
BRAN0050
BRAN0060
BRAN0070
BRAN0080
BRAN0090
BRAN0100
BRAN0110
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BRAN0140
BRAN0150
BRAN0160
BRAN0170
BRAN0180
BRAN0190
BRAN0200
BRAN0210
BRAN0220
BRAN0230
BRAN0240
BRAN0250
BRAN0260
BRAN0270
BRAN0280
BRAN0290
BRAN0300
BRAN0310
BRAN0320
BRAN0330
BRAN0340
BRAN0350
BRAN0360

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5500	READ (MREAD,5500) NSFL(1,IB),B(1B),DENS(1,IB),DS(1,IB),P(1,IB)	BRAN0370
	FORMAT(15,4D15.6)	BRAN0380
	L= NSFL(1,IB)	BRAN0390
	READ (MREAD,5510) (EPS(1,J,IB),SIG(1,J,IB),J=1,L)	BRAN0400
5510	FORMAT(4D15.6)	BRAN0410
	READ (MREAD,5300) NELT(I),NODP(I),LHIT(I),LATT(I)	BRAN0420
5300	FORMAT(14I5)	BRAN0430
	MNEL(I+1) = NELT(I)	BRAN0440
	NODPH= NODP(I)	BRAN0450
	IF (LATT(I)) 6010,6015,6020	BRAN0460
6010	IF (LREF-2) 6011,6012,6013	BRAN0470
6011	XDIST(I) = +H(NODPH,1)/2.0	BRAN0480
	GOTO 6001	BRAN0490
6012	XDIST(I) = (H(NODPH,1)+H(NODPH,2)/2.0)	BRAN0500
	GOTO 6001	BRAN0510
6013	XDIST(I) = (H(NODPH,1)+H(NODPH,2)+H(NODPH,3)/2.0)	BRAN0520
	GOTO 6001	BRAN0530
6015	IF(LREF-2) 6016,6017,6018	BRAN0540
6016	XDIST(I) = -(H(NODPH,1)/2.0 + H(NODPH,2) + H(NODPH,3))	BRAN0550
	GOTO 6001	BRAN0560
6017	XDIST(I) = -(H(NODPH,2)/2.0 + H(NODPH,3))	BRAN0570
	GOTO 6001	BRAN0580
6018	XDIST(I) = -H(NODPH,3)/2.0	BRAN0590
	GOTO 6001	BRAN0600
6020	IF(LREF.NE.LATT(I)) GO TO 6025	BRAN0610
	XDIST(I) = 0.0	BRAN0620
	GOTO 6001	BRAN0630
6025	LRA= LATT(I) -LREF	BRAN0640
	LSIGN=-1	BRAN0650
	IF (LRA.LT.0) LSIGN= 1	BRAN0660
	LRAA = IABS(LRA)	BRAN0670
	NNNN= LATT(I)	BRAN0680
	IF(LRAA.EQ.2) GO TO 6030	BRAN0690
	XDIST(I) = ((H(NODPH,LREF)+H(NODPH,NNNN))/2.0)*LSIGN	BRAN0700
	GOTO 6001	BRAN0710
6030	XDIST(I) = ((H(NODPH,LREF)+H(NODPH,NNNN))/2.0+H(NODPH,LRAA))*LSIGN	BRAN0720

6001	CONTINUE	BRAN0730
	NO1 = NELT(I) + 1	BRAN0740
	DO 5310 J = 1, NO1	BRAN0750
	READ (MREAD, 5305) YB(I, J), ZB(I, J), ANB(I, J), HB(I, J)	BRAN0760
5305	FORMAT(4D15.6)	BRAN0770
	ANB(I, J) = ANB(I, J) * PIE / 180.0	BRAN0780
5310	CONTINUE	BRAN0790
	HTH(I) = HB(I, NO1)	BRAN0800
	SLB(I) = ANB(I, NO1)	BRAN0810
	NS = NS + NELT(I)	BRAN0820
	IK = IK + NELT(I)	BRAN0830
	IKK = NS	BRAN0840
5313	CONTINUE	BRAN0850
	DO 5200 K = 1, NS	BRAN0860
	MK(K) = 0	BRAN0870
5200	LMT(K) = 0	BRAN0880
	DO 5270 I = NIK, IK	BRAN0890
5270	MKE(I) = 1	BRAN0900
	WRITE(MWRITE, 5311) IK, NS	BRAN0910
5311	FORMAT('OTHER ARE ', I3, ' ELEMENTS AND ', I3, ' NODES')	BRAN0920
	WRITE(MWRITE, 5312) NBR, (NODP(M), M=1, NBR)	BRAN0930
5312	FORMAT('OTHER ARE ', I3, ' BRANCHES AND THEY ARE AT NODES', 5I6)	BRAN0940
	WRITE(MWRITE, 8500) (SLB(K), K=1, NBR)	BRAN0950
8500	FORMAT('OTHE GLOBAL SLOPE (RAD) AT EACH BRANCH CONNECTION:', 5D15.6)	BRAN0960
	WRITE(MWRITE, 5250) NBR	BRAN0970
5250	FORMAT('OTHE ATTACHMENT POINT CODE FOR THE ', I4, ' BRANCHES IS AS	BRAN0980
	@ FOLLOWS:')	BRAN0990
	WRITE(MWRITE, 5260) (LATT(L), L=1, NBR)	BRAN1000
5260	FORMAT(' ', 5I8)	BRAN1010
	WRITE(MWRITE, 5261)	BRAN1020
5261	FORMAT(' WHERE -1= INNER AND 0 = OUTER SURFACES. 1, 2, 3 INDICATE	MBRAN1030
	@ IDSURFACE OF CORRESPONDING LAYER.')	BRAN1040
	NODP(NBR+1) = NNS	BRAN1050
	NELTT = 0	BRAN1060
	DO 5316 J = 1, NBR	BRAN1070
	NELTT = NELTT + NELT(I)	BRAN1080

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NO1 = NODP(I) + 1  
 NOD=NODP(I+1)  
 DO 5315 J = NO1,NOD  
 KN= J+NELTT  
 Y(KN) = YK(J)  
 Z(KN) = ZK(J)  
 DO 5401 L=1,NLAY  
 5401 H(KN,L) = HK(J,L)  
 ANG(KN) = ANGK(J)  
 MK(J) = KN  
 5315 CONTINUE  
 5316 CONTINUE  
 IF(NODP(1).NE.1) GOTO 5320  
 KN= 1+NELT(1)  
 Y(KN) = YK(1)  
 Z(KN) = ZK(1)  
 DO 5410 L=1,NLAY  
 5410 H(KN,L) = HK(1,L)  
 ANG(KN) = ANGK(1)  
 MK(1) = KN  
 NEL = NELT(1)  
 DO 5325 I= 1,NEL  
 Y(I) = YB(1,I)  
 Z(I) = ZB(1,I)  
 ANG(I) = ANB(1,I)  
 H(I,1) = HB(1,I)  
 IF(NLAY.EQ.1) GO TO 5325  
 DO 6455 MT=2,NLAY  
 6455 H(I,MT) = 0.0  
 5325 CONTINUE  
 GOTO 5322  
 5320 NO1= NODP(1)  
 DO 5321 J = 1,NO1  
 5321 MK(J) = J  
 5322 NELTT=0  
 DO 5330 I= 1,NBR

BRAN1090  
 BRAN1100  
 BRAN1110  
 BRAN1120  
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 BRAN1190  
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 BRAN1420  
 BRAN1430  
 BRAN1440

IF (NODP(I).EQ.1) GOTO 5334  
 NEL = NELT(I)  
 DO 5335 J= 1,NEL  
 KN= J+ NODP(I) + NELTT  
 Y(KN) = YB(I,J)  
 Z(KN) = ZB(I,J)  
 ANG(KN) = ANB(I,J)  
 H(KN,1) = HB(I,J)  
 IF(NLAY.EQ.1) GO TO 5335  
 DO 6450 MT=2,NLAY  
 6450 H(KN,MT) = 0.0  
 5335 CONTINUE  
 5334 NELTT= NELTT + NELT(I)  
 5330 CONTINUE  
 NZB = 0  
 NYB = 0  
 LTIME= 0  
 LELT = 1  
 DO 5100 J = 1,NS  
 NXB = J + NYB  
 IF( NXB.EQ.MK(J) ) GO TO 5100  
 MKL = 0  
 LTIME= LTIME+1  
 MXX = NXB-2  
 NYB= NYB+ NELT(LTIME)  
 IF (LHIT(LTIME).NE.0) GO TO 5140  
 NZB = NZB+NELT(LTIME)  
 IF (J.EQ.1) MXX=0  
 MKL=MKL+MXX  
 DO 5130 I= LELT,NZB  
 MKL=MKL+1  
 5130 LMT(I) = MKL  
 LELT = NZB+1  
 5140 IF (LTIME.EQ.NBR) GOTO 5145  
 5100 CONTINUE  
 5145 CONTINUE

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 BRAN1800

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96  
 LElt=0  
 NYB=0  
 LTIME = 0  
 DO 5275 J= 1, NS  
 NXB=J+NYB  
 IF (NXB.EQ.MK(J)) GO TO 5275  
 LTIME=LTIME+1  
 MXX = NXB-2  
 NYB=NYB+NELT(LTIME)  
 IF (J.EQ. 1) MXX=0  
 LElt=MXX+1  
 NZB= MXX+NELT(LTIME)  
 DO 5280 I=LElt, NZB  
 5280 MKE(I) = LTIME+1  
 IF (LTIME.EQ.NBR) GO TO 5285  
 5275 CONTINUE  
 5285 CONTINUE  
 NODP(NBR+1) = IK  
 NT= NELT(1) + NODP(2) + NELT(2) -1  
 NTT= NELT(1) + NELT(2)  
 IF (NBR.EQ.1) NT = IK  
 IF (NODP(1).EQ.1) GO TO 5340  
 NT= NODP(1) + NELT(1) - 1  
 NTT= NELT(1)  
 5340 DO 5345 I= 1, NT  
 NVEC(I,1) = I  
 5345 NVEC(I,2) = I+1  
 NO = 2  
 IF(NODP(1) - 1) 5350, 5355, 5350  
 5355 IF(NBR.EQ.1) GO TO 5350  
 NO= 3  
 5350 NB1 = NBR+1  
 DO 5360 I = NO, NB1  
 IF (NT.EQ.IK) GO TO 5400  
 NT= NT+1  
 NVEC(NT, 1) = NT-NELT(I-1)

BRAN1810  
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 BRAN1950  
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 BRAN2100  
 BRAN2110  
 BRAN2120  
 BRAN2130  
 BRAN2140  
 BRAN2150  
 BRAN2160

NVEC (NT,2) = NT+1	BRAN2170
NT = NT+1	BRAN2180
NTT= NTT+ NELT(I)	BRAN2190
NOO = NTT+ NODP(I) - 1	BRAN2200
IF (NODP(I).EQ.IK) NOO=IK	BRAN2210
DO 5365 J=NT,NOO	BRAN2220
NVEC (J,1) = J	BRAN2230
5365 NVEC (J,2) = J+1	BRAN2240
NT = NOO	BRAN2250
5360 CONTINUE	BRAN2260
5400 CONTINUE	BRAN2270
IF (EXANG.EQ.360.0) NVEC (IK,2) = 1	BRAN2280
WRITE (MWRITE,110)	BRAN2290
110 FORMAT(//, ' PRESENT ELEM. NO.',5X,'NODE1',5X,'NODE2',5X,'SUBSTRUCT	BRAN2300
@URE',5X,'SUBST. ELEM. NO.')	BRAN2310
JEL = 0	BRAN2320
JL=0	BRAN2330
DO 115 IR=1,IK	BRAN2340
IF (MKE (IR).NE.1) GO TO 120	BRAN2350
JL=0	BRAN2360
JEL=JEL+1	BRAN2370
JELE=JEL	BRAN2380
GO TO 125	BRAN2390
120 JL=JL+1	BRAN2400
JELE=JL	BRAN2410
125 WRITE (MWRITE,126) IR,NVEC (IR,1),NVEC (IR,2),MKE (IR),JELE	BRAN2420
126 FORMAT(' ',4X,I5,11X,I5,5X,I5,7X,I5,13X,I5)	BRAN2430
115 CONTINUE	BRAN2440
WRITE (MWRITE,130)	BRAN2450
130 FORMAT ('OTHE UPDATED NODE NUMBERS FOR THE MAIN STRUCTURE, GIVEN IN	BRAN2460
@ THEIR ORIGINAL NUMBERING ORDER:')	BRAN2470
WRITE (MWRITE,5323) (MK(L),L=1,NNS)	BRAN2480
5323 FORMAT ('0',25I5)	BRAN2490
WRITE (MWRITE,1010)	BRAN2500
1010 FORMAT(//, ' NOTE: THE ELEMENT NUMBERS REFERRED TO BELOW ARE PRESE	BRAN2510
@NT ELEMENT NUMBERS',//)	BRAN2520

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WRITE (MWRITE,2110)	BRAN2530
WRITE (MWRITE,2100) (LMT(N),N=1,NS)	BRAN2540
2100 FORMAT(' ',10I5)	BRAN2550
2110 FORMAT('ELEMENTS THAT CAN NOT BE IMPACTED:')	BRAN2560
READ(MREAD,5300) NDISB	BRAN2570
IF (NDISB.EQ.0) GO TO 8100	BRAN2580
DO 8101 I=1,NDISB	BRAN2590
READ(MREAD,8102) NEDIB,NBDI,ANGDB	BRAN2600
8102 FORMAT(2I5,D15.6)	BRAN2610
ANGDB= ANGDB*PIE/180.0	BRAN2620
NDIS= NDIS+1	BRAN2630
ANGDI(NDIS) = ANGDB	BRAN2640
L= NODP(NBDI)	BRAN2650
K=MK(L)	BRAN2660
IF (L.EQ.1) K=1	BRAN2670
8103 NEDI(NDIS) = NEDIB +K -1	BRAN2680
8101 CONTINUE	BRAN2690
8100 CONTINUE	BRAN2700
C ESTABLISH BOUNDARY CONDITIONS	BRAN2710
C VECTOR YK(51) NOW CONTAINS ACTUAL NODE NUMBER OF ORIGINAL DEFLECTO	BRAN2720
READ(MREAD,5300) NBCONB	BRAN2730
IF (NBCONB.EQ.0) GOTO 5376	BRAN2740
READ(MREAD,5300) (NBCB(L),NODBB(L),LBR(L),L=1,NBCONB)	BRAN2750
DO 5370 L = 1,NBCONB	BRAN2760
NNNN= LBR(L)	BRAN2770
NO1= NODP(NNNN)	BRAN2780
NELTT= 0	BRAN2790
LB= LBR(L)-1	BRAN2800
DO 5375 J= 1,LB	BRAN2810
5375 NELTT= NELTT + NELT(J)	BRAN2820
IF (LB.NE.0) GOTO 5371	BRAN2830
NELTT = 0	BRAN2840
IF (NODP(1).EQ.1) GO TO 5370	BRAN2850
5371 NODBB(L) = NODBB(L) + NO1 + NELTT	BRAN2860
5370 CONTINUE	BRAN2870
5376 CONTINUE	BRAN2880

C DETERMINE LEADING NON ZERO TERM IN EACH ROW

DO 15 I= 1,8  
 15 ICOL(I) = 1  
 IKM1 = IK-1  
 NI = NS\*4  
 IF(EXANG.NE.360.0) GO TO 210  
 DO 16 I = 2,IKM1  
 J= (I+1)\*4  
 ICOL(J) = NVEC(I,1) \* 4 - 3  
 ICOL(J-1) = NVEC(I,1) \* 4 - 3  
 ICOL(J-2) = NVEC(I,1) \* 4 - 3  
 ICOL(J-3) = NVEC(I,1) \* 4 - 3  
 16 CONTINUE  
 ICOL(IK\*4) = 1  
 ICOL(IK\*4-1) = 1  
 ICOL(IK\*4-2) = 1  
 ICOL(IK\*4-3) = 1  
 GO TO 218  
 210 DO 211 I= 2,IK  
 J= (I+1)\*4  
 ICOL(J) = NVEC(I,1) \* 4 - 3  
 ICOL(J-1) = NVEC(I,1) \* 4 - 3  
 ICOL(J-2) = NVEC(I,1) \* 4 - 3  
 ICOL(J-3) = NVEC(I,1) \* 4 - 3  
 211 CONTINUE  
 218 CONTINUE  
 DO 5341 M= 1,IK  
 5341 YK(M) = 0.0  
 DO 5342 M = 1,NBR  
 IF (NODP(M).NE.1) GO TO 5343  
 NNNN= NELT(M)  
 YK(NNNN) = 1.0  
 ROT(M,1) = 0.0  
 MKS = NELT(M) + 1  
 ROT(M,2) = ANB(M,MKS) - ANGK(1)  
 GO TO 5342

BRAN2890  
 BRAN2900  
 BRAN2910  
 BRAN2920  
 BRAN2930  
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 BRAN2950  
 BRAN2960  
 BRAN2970  
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 BRAN2990  
 BRAN3000  
 BRAN3010  
 BRAN3020  
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 BRAN3110  
 BRAN3120  
 BRAN3130  
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 BRAN3160  
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 BRAN3190  
 BRAN3200  
 BRAN3210  
 BRAN3220  
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 BRAN3240

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5343 N= NODP(M)  
NM= MK (N)  
YK(NM) = 1.0  
ROT(M,1) = 1.0  
MKS = NELT(M) + 1  
ROT(M,2) = ANB(M,MKS) - ANG(NM)  
5342 CONTINUE  
RETURN  
END

BRAN3250  
BRAN3260  
BRAN3270  
BRAN3280  
BRAN3290  
BRAN3300  
BRAN3310  
BRAN3320  
BRAN3330

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SUBROUTINE  ELMPP (AMASS,STIFK,ISIZE,AEP,DEP,NV1,REACK,REACH,ELMPB) ELMP0010
C    TO FIND THE MASS MATRIX STIFFNESS MATRIX AND STRAIN NODAL ELMP0020
C    DISPLACEMENT TRANSFORMATION MATRICES ELMP0030
    IMPLICIT REAL*8 (A-H,C-Z) ELMP0040
    DIMENSION REACK(1),REACH(1) ELMP0050
    DIMENSION AEP(NV1,3,8),DEP(NV1,2,3,8) ELMP0060
    DIMENSION AE1(3,8), DUMMY(8),BX(2) ELMP0070
    DIMENSION TR(4,4),TRAN(8,8) ELMP0080
    DIMENSION A(8,8),LMI(8),MMI(8),D(8,8),ELM(8,8), ELMP0090
    *ELMAS(8,8),AMASS(1),E(8,8),EK1(8,8),ELK(8,8),STIFK(1), ELMP0100
    *BE1(3,3,8),BNG(51) ELMP0110
    *,D1(3,8),D2(3,3),D3(3,8),D4(8,8),E1(2,8),E2(2,2),E3(2,8),E4(8,8) ELMP0120
    COMMON/MAT/YOUNG(3,6),DS(3,6),SNO(3,5,6),NSFL(3,6),P(3,6),NLAY ELMP0130
    COMMON /FG/ IK,IKK,ICP,LREF,NOGA,NFL,NI,ICOL(205),INUM(205) ELMP0140
    *,NBCOND,NBC(7),NODEB(7),KROW(8),NDEX(8),NIRREG ELMP0150
    COMMON/FC/ Y(51),Z(51),ANG(51),H(51,3) ELMP0160
    COMMON/BA/ BEP(50,3,3,8),AL(50),AXG(3),AWG(3),WET(50,3), ELMP0170
    *CE1(50,3),CE2(50,3),CE3(50,3),CM1(50,3),CM2(50,3),CM3(50,3) ELMP0180
    COMMON /TAPE/ MREAD,MWRITE,MPUNCH ELMP0190
    COMMON/ADSP/ AZET(50),ASP(50),YSP(50),ZSP(50),LKK(50,11) ELMP0200
    COMMON/BCUN/YK(51),NBCONE,NBCB(7),NODBB(7),MK(51),RCT(5,2) ELMP0210
    *,XDIST(6),DROT(50),NODP(6) ELMP0220
    COMMON /BR/ NVEC(51,2), LMT(51) ELMP0230
    COMMON /TAM/ MKE(51) ELMP0240
    SIN(Q)=DSIN(Q) ELMP0250
    COS(Q)=DCOS(Q) ELMP0260
    ATAN(Q)=DATAN(Q) ELMP0270
    SQRT(Q)=DSQRT(Q) ELMP0280
    DO 18 L=1,ISIZE ELMP0290
    STIFK(L)=0.0 ELMP0300
    18  AMASS(L)=0.0 ELMP0310
    50  DO 101 IR=1,IK ELMP0320
    K1 = NVEC(IR,1) ELMP0330
    K2 = NVEC(IR,2) ELMP0340
    L= MKE(IR) -1 ELMP0350
    P5=Z(K2)-Z(K1) ELMP0360

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P6=Y(K2)-Y(K1)	ELMP0370
P7=ANG(K2)-ANG(K1)	ELMP0380
IF(YK(IR).EQ.1.0) P7=ANG(K2)-ROT(L,2)-ANG(K1)	ELMP0390
IF(YK(IR).EQ.1.0.AND.ROT(L,1).EQ.0.0) P7=ROT(L,2)+ANG(K2)-ANG(K1)	ELMP0400
IF(YK(IR).EQ.2.0) P7=ANG(K2)-DROT(IR)-ANG(K1)	ELMP0410
IF(YK(IR).EQ.3.0) P7=ROT(L,2)+ANG(K2)-DROT(IR)-ANG(K1)	ELMP0420
PIE= 3.141592653589793D+00	ELMP0430
PIE2= 2.0*PIE	ELMP0440
PIE32= 1.5 *PIE	ELMP0450
ANG2=ANG(K2)	ELMP0460
ANG1=ANG(K1)	ELMP0470
IF(YK(IR).EQ.1.0.AND.ROT(L,1).EQ.0.0) ANG(K2)=ROT(L,2)+ANG(K2)	ELMP0480
IF(YK(IR).EQ.1.0.AND.ROT(L,1).EQ.1.0) ANG(K1)=ROT(L,2)+ANG(K1)	ELMP0490
IF(YK(IR).EQ.2.0) ANG(K1)=DROT(IR)+ANG(K1)	ELMP0500
IF(YK(IR).EQ.3.0) ANG(K1)=DROT(IR)+ANG(K1)	ELMP0510
IF(YK(IR).EQ.3.0) ANG(K2)=ROT(L,2)+ANG(K2)	ELMP0520
APHA = PIE / 2.0	ELMP0530
IF(P5.LT.0.0) APHA= -APHA	ELMP0540
IF(P6.NE.0.0) APHA= ATAN(P5/P6)	ELMP0550
IF(P6.LT.0.0.AND.P5.LT.0.0) APHA=APHA-PIE	ELMP0560
IF(P6.LT.0.0.AND.P5.GE.0.0) APHA=APHA+PIE	ELMP0570
IF(P7.EQ.0.0) GO TO 60	ELMP0580
AL(IR)=P7*SQRT(P5**2+P6**2)/SIN(P7/2.)/2.	ELMP0590
IF(P7.GT.PIE32) AL(IR)=(P7-PIE2)*SQRT(P5**2+P6**2)/SIN(P7/2.-PIE)	ELMP0600
*/2.0	ELMP0610
IF(P7.LT.(-PIE32)) AL(IR)=(P7+PIE2)*SQRT(P5**2+P6**2)	ELMP0620
*/SIN(P7/2.+PIE)/2.	ELMP0630
GO TO 61	ELMP0640
60 AL(IR)=SQRT(P5**2+P6**2)	ELMP0650
61 BNG(IR+1)=ANG(K2)	ELMP0660
BNG(IR)=ANG(K1)	ELMP0670
IF(P7.GT.(PIE32).AND.APHA.LT.0.0) BNG(IR+1)=ANG(K2)-PIE2	ELMP0680
IF(P7.GT.(PIE32).AND.APHA.GT.0.0) BNG(IR)=ANG(K1)+PIE2	ELMP0690
IF(P7.LT.(-PIE32).AND.APHA.GT.0.0) BNG(IR+1)=ANG(K2)+PIE2	ELMP0700
IF(P7.LT.(-PIE32).AND.APHA.LT.0.0) BNG(IR)=ANG(K1)-PIE2	ELMP0710
BZER=BNG(IR)-APHA	ELMP0720

102

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B1=(-2.*BNG(IR+1)-4.*BNG(IR)+6.*APHA)/AL(IP)
B2=(3.*BNG(IR+1)+3.*BNG(IR)-6.*APHA)/AL(IR)**2
ANG(K2)=ANG2
ANG(K1)=ANG1
DO 102 I=1,8
DO 102 J=1,8
A(I,J)=0.0
E(I,J)=0.0
D(I,J)=0.0
A(1,1)=COS(BNG(IR)-APHA)
A(1,2)=SIN(BNG(IR)-APHA)
A(2,1)=-SIN(BNG(IR)-APHA)
A(2,2)=COS(BNG(IR)-APHA)
A(3,3)=1.
A(5,1)=COS(BNG(IR+1)-APHA)
A(5,2)=SIN(BNG(IR+1)-APHA)
A(5,3)=P6*SIN(BNG(IR+1))-P5*COS(BNG(IR+1))
A(6,1)=-SIN(BNG(IR+1)-APHA)
A(6,2)=COS(BNG(IR+1)-APHA)
A(6,3)=P6*CCS(BNG(IR+1))+P5*SIN(BNG(IR+1))
A(7,3)=1.
A(4,4)=1.
A(5,4)=AL(IR)
A(5,7)=AL(IR)**2
A(5,8)=AL(IR)**3
A(6,5)=AL(IR)**2
A(6,6)=AL(IR)**3
P8=B1+2.*B2*AL(IR)
A(7,4)=AL(IR)*P8
A(7,5)=2.*AL(IR)
A(7,6)=3.*AL(IR)**2
A(7,7)=AL(IR)**2*P8
A(7,8)=AL(IR)**3*P8
A(8,4)=1.
A(8,5)=-AL(IR)**2*P8
A(8,6)=-AL(IR)**3*P8

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ELMP0730
ELMP0740
ELMP0750
ELMP0760
ELMP0770
ELMP0780
ELMP0790
ELMP0800
ELMP0810
ELMP0820
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ELMP0840
ELMP0850
ELMP0860
ELMP0870
ELMP0880
ELMP0890
ELMP0900
ELMP0910
ELMP0920
ELMP0930
ELMP0940
ELMP0950
ELMP0960
ELMP0970
ELMP0980
ELMP0990
ELMP1000
ELMP1010
ELMP1020
ELMP1030
ELMP1040
ELMP1050
ELMP1060
ELMP1070
ELMP1080

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A(8,7)=2.*AL(IR)
A(8,8)=3.*AL(IR)**2
CALL MINV(A,8,DET,LMI,MMI)
DO 103 J=1,NOGA
WET(IR,J)=AL(IR)*AWG(J)
ZET=AL(IR)*AXG(J)
PHIP=B1+2.*B2*ZET
PHI=BZER+B1*ZET+B2*ZET**2
YZET= 0.0
ZZET=0.0
DO 104 JJ=1,NOGA
P2=BZER+B1*ZET*AXG(JJ)+B2*(ZET*AXG(JJ))**2+APHA
YZET=YZET+COS(P2)*ZET*AWG(JJ)
104 ZZET=ZZET+SIN(P2)*ZET*AWG(JJ)
P3=YZET*SIN(PHI+APHA)-ZZET*COS(PHI+APHA)
P4=YZET*COS(PHI+APHA)+ZZET*SIN(PHI+APHA)
DO 201 M=1,3
DO 201 N=1,8
201 BE1(J,M,N)=0.0
BE1(J,1,4)=1.
BE1(J,1,5)=-ZET**2*PHIP
BE1(J,1,6)=-ZET**3*PHIP
BE1(J,1,7)=2.*ZET
BE1(J,1,8)=3.*ZET**2
BE1(J,2,3)=1.
BE1(J,2,4)=ZET*PHIP
BE1(J,2,5)=2.*ZET
BE1(J,2,6)=3.*ZET**2
BE1(J,2,7)=ZET**2*PHIP
BE1(J,2,8)=ZET**3*PHIP
BE1(J,3,4)=-PHIP-ZET*2.*B2
BE1(J,3,5)=-2.
BE1(J,3,6)=-6.*ZET
BE1(J,3,7)=-2.*ZET*PHIP-ZET**2*2.*B2
BE1(J,3,8)=-3.*ZET**2*PHIP-ZET**3*2.*B2
DO 202 M=1,3

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ELMP1090
ELMP1100
ELMP1110
ELMP1120
ELMP1130
ELMP1140
ELMP1150
ELMP1160
ELMP1170
ELMP1180
ELMP1190
ELMP1200
ELMP1210
ELMP1220
ELMP1230
ELMP1240
ELMP1250
ELMP1260
ELMP1270
ELMP1280
ELMP1290
ELMP1300
ELMP1310
ELMP1320
ELMP1330
ELMP1340
ELMP1350
ELMP1360
ELMP1370
ELMP1380
ELMP1390
ELMP1400
ELMP1410
ELMP1420
ELMP1430
ELMP1440

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DO 202 N=1,8  
 BEP (IR,J,M,N)=0.0  
 DO 202 K=1,8  
 202 BEP (IR,J,M,N)=BEP (IR,J,M,N)+BE1 (J,M,K)\*A (K,N)  
 DO 115 K=1,3  
 DO 115 L=1,8  
 115 D1 (K,L)=0.0  
 DO 116 K=1,2  
 DO 116 L=1,8  
 116 E1 (K,L)=0.0  
 D1 (1,1)=COS (PHI)  
 D1 (1,2)=SIN (PHI)  
 D1 (1,3)=P3  
 D1 (1,4)=ZET  
 D1 (1,7)=ZET\*\*2  
 D1 (1,8)=ZET\*\*3  
 D1 (2,1)=-SIN (PHI)  
 D1 (2,2)=COS (PHI)  
 D1 (2,3)=P4  
 D1 (2,5)=ZET\*\*2  
 D1 (2,6)=ZET\*\*3  
 D1 (3,3)=1.  
 D1 (3,4)=ZET\*PHIP  
 D1 (3,5)=2.\*ZET  
 D1 (3,6)=3.\*ZET\*\*2  
 D1 (3,7)=ZET\*\*2\*PHIP  
 D1 (3,8)=ZET\*\*3\*PHIP  
 D2 (1,1)=CM1 (IR,J)  
 D2 (1,2)=0.0  
 D2 (1,3)=CM2 (IR,J)  
 D2 (2,1)=0.0  
 D2 (2,2)=CM1 (IR,J)  
 D2 (2,3)=0.0  
 D2 (3,1)=CM2 (IR,J)  
 D2 (3,2)=0.0  
 D2 (3,3)=CM3 (IR,J)

ELMP1450  
 ELMP1460  
 ELMP1470  
 ELMP1480  
 ELMP1490  
 ELMP1500  
 ELMP1510  
 ELMP1520  
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 ELMP1550  
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 ELMP1570  
 ELMP1580  
 ELMP1590  
 ELMP1600  
 ELMP1610  
 ELMP1620  
 ELMP1630  
 ELMP1640  
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 ELMP1660  
 ELMP1670  
 ELMP1680  
 ELMP1690  
 ELMP1700  
 ELMP1710  
 ELMP1720  
 ELMP1730  
 ELMP1740  
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 ELMP1760  
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 ELMP1780  
 ELMP1790  
 ELMP1800

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E1(1,4)=1.
E1(1,5)=-ZET**2*PHIP
E1(1,6)=-ZET**3*PHIP
E1(1,7)=2.*ZET
E1(1,8)=3.*ZET**2
E1(2,4)=-PHIP-ZET*2.*B2
E1(2,5)=-2.
E1(2,6)=-6.*ZET
E1(2,7)=-2.*ZET*PHIP-ZET**2*2.*B2
E1(2,8)=-3.*ZET**2*PHIP-ZET**3*2.*B2
E2(1,1)=CE1(IR,J)
E2(1,2)=CE2(IR,J)
E2(2,1)=CE2(IR,J)
E2(2,2)=CE3(IR,J)
DO 110 K=1,3
DO 110 L=1,8
D3(K,L)=0.0
DO 110 M=1,3
110 D3(K,L)=D3(K,L)+D2(K,M)*D1(M,L)
DO 111 K=1,8
DO 111 L=1,8
D4(K,L)=0.0
DO 111 M=1,3
111 D4(K,L)=D4(K,L)+D1(M,K)*D3(M,L)
DO 113 K=1,2
DO 113 L=1,8
E3(K,L)=0.0
DO 113 M=1,2
113 E3(K,L)=E3(K,L)+E2(K,M)*E1(M,L)
DO 114 K=1,8
DO 114 L=1,8
E4(K,L)=0.0
DO 114 M=1,2
114 E4(K,L)=E4(K,L)+E1(M,K)*E3(M,L)
DO 112 K=1,8
DO 112 L=1,K

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ELMP1810
ELMP1820
ELMP1830
ELMP1840
ELMP1850
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ELMP1870
ELMP1880
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ELMP1900
ELMP1910
ELMP1920
ELMP1930
ELMP1940
ELMP1950
ELMP1960
ELMP1970
ELMP1980
ELMP1990
ELMP2000
ELMP2010
ELMP2020
ELMP2030
ELMP2040
ELMP2050
ELMP2060
ELMP2070
ELMP2080
ELMP2090
ELMP2100
ELMP2110
ELMP2120
ELMP2130
ELMP2140
ELMP2150
ELMP2160

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112 F(K,L)=I(K,L)+F4(K,L)\*WET(IR,J)  
 112 D(K,L)=I(K,L)+D4(K,L)\*WEL(IR,J)  
 103 CONTINUE  
 DO 105 I=1,7  
 IP1=I+1  
 DO 105 J=IP1,8  
 E(I,J)=E(J,I)  
 105 D(I,J)=L(J,I)  
 DO 106 I=1,8  
 DO 106 J=1,8  
 EK1(I,J)=0.0  
 ELM(I,J)=0.0  
 DO 106 K=1,8  
 EK1(I,J)=EK1(I,J)+A(K,I)\*E(K,J)  
 106 ELM(I,J)=ELM(I,J)+A(K,I)\*D(K,J)  
 DO 107 I=1,8  
 DO 107 J=1,8  
 ELK(I,J)=0.0  
 ELMAS(I,J)=0.0  
 DO 107 K=1,8  
 ELK(I,J)=ELK(I,J)+EK1(I,K)\*A(K,J)  
 107 ELMAS(I,J)=ELMAS(I,J)+ELM(I,K)\*A(K,J)  
 IF(YK(IR).EQ.0.0) GOTO 504  
 CALL ROTAT(3,ELK,DUMMY,IR)  
 CALL ROTAT(3,ELMAS,DUMMY,IR)  
 504 CONTINUE  
 IF(FIMPB.EQ.0.0) GOTO 8320  
 DO 1000 I=1,4  
 IF(I.EQ.3.OR.I.EQ.4) GOTO 1000  
 ELMAS(I,1)=ELMAS(I,1)+ELMAS(I,I+4)  
 1000 CONTINUE  
 DO 1030 I=5,6  
 ELMAS(I,1)=ELMAS(I,1)+ELMAS(I,I-4)  
 1030 CONTINUE  
 DO 1010 I=1,8  
 DO 1010 J=1,8

ELMP2170  
 ELMP2180  
 ELMP2190  
 ELMP2200  
 ELMP2210  
 ELMP2220  
 ELMP2230  
 ELMP2240  
 ELMP2250  
 ELMP2260  
 ELMP2270  
 ELMP2280  
 ELMP2290  
 ELMP2300  
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 ELMP2320  
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 ELMP2400  
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 ELMP2420  
 ELMP2430  
 ELMP2440  
 ELMP2450  
 ELMP2460  
 ELMP2470  
 ELMP2480  
 ELMP2490  
 ELMP2500  
 ELMP2510  
 ELMP2520

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IF (I.EQ.J) GOTO 1010  
 ELMAS(I,J) = 0.0  
 1010 CONTINUE  
 WRITE(MWRITE,1020) ((ELMAS(I,J),J=1,8),I=1,8)  
 1020 FORMAT(' ',F15.6)  
 8320 CONTINUE  
 502 CALL ASSEM(IR,IK,EIK,STIFK,ICP,INUM)  
 CALL ASSEM(IR,IK,ELMAS,AMASS,ICP,INUM)  
 IF (IKK(IR,1) .EQ.0) GOTO 8200  
 NPE= IKK(IR,1)  
 DO 8210 NO=1,NPE  
 MO = NO+1  
 M= IKK(IR,MO)  
 ZET= AZET(M) \* AL(IR)  
 PHIP= B1+2.0\*B2\*ZET  
 DO 8240 I=1,3  
 DO 8240 N=1,8  
 8240 AE1(I,N) = 0.0  
 AE1(1,4) = 1.0  
 AE1(1,5) = -ZET\*\*2\*PHIP  
 AE1(1,6) = -ZET\*\*3\*PHIP  
 AE1(1,7) = 2.\*ZET  
 AE1(1,8) = 3.\*ZET\*\*2  
 AE1(2,3) = 1.0  
 AE1(2,4) = ZET\*PHIP  
 AE1(2,5) = AE1(1,7)  
 AE1(2,6) = AE1(1,8)  
 AE1(2,7) = -AE1(1,5)  
 AE1(2,8) = -AE1(1,6)  
 AE1(3,4) = -PHIP-ZET\*2.\*P2  
 AE1(3,5) = -2.0  
 AE1(3,6) = -6.\*ZET  
 AE1(3,7) = -2.0\*ZET\*PHIP-ZET\*\*2\*2.0\*B2  
 AE1(3,8) = -3.\*ZET\*\*2\*PHIP-ZET\*\*3\*2.0\*B2  
 DO 8245 I=1,3  
 DO 8245 N= 1,8

ELMP2530  
 ELMP2540  
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 ELMP2590  
 ELMP2600  
 ELMP2610  
 ELMP2620  
 ELMP2630  
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 ELMP2670  
 ELMP2680  
 ELMP2690  
 ELMP2700  
 ELMP2710  
 ELMP2720  
 ELMP2730  
 ELMP2740  
 ELMP2750  
 ELMP2760  
 ELMP2770  
 ELMP2780  
 ELMP2790  
 ELMP2800  
 ELMP2810  
 ELMP2820  
 ELMP2830  
 ELMP2840  
 ELMP2850  
 ELMP2860  
 ELMP2870  
 ELMP2880

AEP(M,I,N) = 0.0  
 DO 8245 K= 1,8  
 8245 AEP(M,I,N) = AEP(M,I,N) +AE1(I,K)\*A(K,N)  
 8210 CONTINUE  
 8200 CONTINUE  
 BX(1) =0.0  
 BX(2) = 1.0  
 DO 303 J=1,2  
 ZET= AL(IR)\* PX(J)  
 PHIP= B1+2.0\*B2\*ZET  
 DO 301 M=1,3  
 DO 301 N= 1,8  
 301 BE1(J,M,N) = 0.0  
 BE1(J,1,4)=1.  
 BE1(J,1,5)=-ZET\*\*2\*PHIP  
 BE1(J,1,6)=-ZET\*\*3\*PHIP  
 BE1(J,1,7)=2.\*ZET  
 BE1(J,1,8)=3.\*ZET\*\*2  
 BE1(J,2,3)=1.  
 BE1(J,2,4)=ZET\*PHIP  
 BE1(J,2,5)=2.\*ZET  
 BE1(J,2,6)=3.\*ZET\*\*2  
 BE1(J,2,7)=ZET\*\*2\*PHIP  
 BE1(J,2,8)=ZET\*\*3\*PHIP  
 BE1(J,3,4)=-PHIP-ZET\*2.\*B2  
 BE1(J,3,5)=-2.  
 BE1(J,3,6)=-6.\*ZET  
 BE1(J,3,7)=-2.\*ZET\*PHIP-ZET\*\*2\*2.\*B2  
 BE1(J,3,8)=-3.\*ZET\*\*2\*PHIP-ZET\*\*3\*2.\*B2  
 DO 302 M=1,3  
 DO 302 N=1,8  
 DEP(IR,J,M,N) =0.0  
 DO 302 K=1,8  
 302 DEP(IR,J,M,N) = DEP(IR,J,M,N)+BE1(J,M,K)\*A(K,N)  
 303 CONTINUE  
 101 CONTINUE

ELMP2890  
 ELMP2900  
 ELMP2910  
 ELMP2920  
 ELMP2930  
 ELMP2940  
 ELMP2950  
 ELMP2960  
 ELMP2970  
 ELMP2980  
 ELMP2990  
 ELMP3000  
 ELMP3010  
 ELMP3020  
 ELMP3030  
 ELMP3040  
 ELMP3050  
 ELMP3060  
 ELMP3070  
 ELMP3080  
 ELMP3090  
 ELMP3100  
 ELMP3110  
 ELMP3120  
 ELMP3130  
 ELMP3140  
 ELMP3150  
 ELMP3160  
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 ELMP3190  
 ELMP3200  
 ELMP3210  
 ELMP3220  
 ELMP3230  
 ELMP3240

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DO 8300 I=1,ISTZE
PEACK(I) = STIFK(I)
8300 REACH(I) = AMASS(I)
  IF (NBCOND .EQ. 0) RETURN
  DO 91 I=1,NBCOND
    JT4=NODEB(I)*4
    JT4M3=JT4-3
    JT4M2=JT4-2
    JT4M1=JT4-1
    IF (ELMPB.NE.C.0) GOTO 8310
    CALL ERC(JT4M3,AMASS,NI,ICOL,INUM)
    IF (NBC(I).EQ.1.OR.NBC(I).EQ.2) CALL ERC(JT4M1,AMASS,NI,ICOL,INUM)
    IF (NBC(I).EQ.2.OR.NBC(I).EQ.3) CALL ERC(JT4M2,AMASS,NI,ICOL,INUM)
8310 CONTINUE
    CALL ERC(JT4M3,STIFK,NI,ICOL,INUM)
    IF (NBC(I).EQ.1.OR.NBC(I).EQ.2) CALL ERC(JT4M1,STIFK,NI,ICOL,INUM)
    IF (NBC(I).EQ.2.OR.NBC(I).EQ.3) CALL ERC(JT4M2,STIFK,NI,ICOL,INUM)
91 CONTINUE
  RETURN
END

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ELMP3250
ELMP3260
ELMP3270
ELMP3280
ELMP3290
ELMP3300
ELMP3310
ELMP3320
ELMP3330
ELMP3340
ELMP3350
ELMP3360
ELMP3370
ELMP3380
ELMP3390
ELMP3400
ELMP3410
ELMP3420
ELMP3430
ELMP3440

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C      SUBROUTINE ERC(II,STIFM,NI,ICOL,INUM)
      FOR ELIMINATING ROWS AND COLUMNS IN STIFM
      IMPLICIT REAL*8 (A-H,O-Z)
      DIMENSION STIFM(1),ICOL(1),INUM(1)
      IC=ICOL(II)
      DO 101 J=IC,II
        L=J+INUM(II)
101    STIFM(L)=0.
      DO 102 I=II,NI
        IC1=ICOL(I)
        IF(II-IC1) 102,103,103
103    L=II+INUM(I)
        STIFM(L)=0.
102    CONTINUE
        L=II+INUM(II)
        STIFM(L)=1.
      RETURN
      END

```

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ERC 0010
ERC 0020
ERC 0030
ERC 0040
ERC 0050
ERC 0060
ERC 0070
ERC 0080
ERC 0090
ERC 0100
ERC 0110
ERC 0120
ERC 0130
ERC 0140
ERC 0150
ERC 0160
ERC 0170
ERC 0180

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	SUBROUTINE FAC (STIFM,NCOL,KROW,NDEX,IDET,NTAPE6,NROWS,NIRREG,IC)	FACT0010
C	LOWER TRIANGULAR FACTOR OF STIFM MATRIX IS COMPUTED AND STORED	FACT0020
	IMPLICIT REAL*8 (A-H,O-Z)	FACT0030
	DIMENSION STIFM(1),NCOL(1),KROW(1),NDEX(1),IC(1)	FACT0040
	ABS(Q)=DABS(Q)	FACT0050
C	STIFM	FACT0060
C	PROCESS COLUMN 1	FACT0070
	I=1	FACT0080
	IDET=0	FACT0090
	IF (STIFM(1)) 152,122,101	FACT0100
152	IDET=IDET+1	FACT0110
101	INDEX=0	FACT0120
	IROW=1	FACT0130
	TEST=1.0	FACT0140
	KN=1	FACT0150
	DO 103 I=2,NROWS	FACT0160
	KN=KN+I-NCOL(I)	FACT0170
	IF (NCOL(I)-1) 103,102,103	FACT0180
102	STIFM(KN)=STIFM(KN)/STIFM(1)	FACT0190
103	CONTINUE	FACT0200
	DO 121 I=2,NROWS	FACT0210
	IP1=I+1	FACT0220
	IM1=I-1	FACT0230
	SUM=0.0	FACT0240
	NCK=0	FACT0250
	III=NCOL(I)	FACT0260
	INDEX=INDEX+I-III	FACT0270
	IF (IM1-III) 150,140,140	FACT0280
C	DIAGONAL TERMS	FACT0290
140	DO 104 J=III,IM1	FACT0300
	IJ=INDEX+J	FACT0310
104	SUM=SUM+STIFM(IJ)*STIFM(IJ)*STIFM(IC(J)+J)	FACT0320
150	II=INDEX+I	FACT0330
	SUM=STIFM(II)-SUM	FACT0340
	IF (SUM) 151,122,105	FACT0350
151	IDET= IDET +1	FACT0360

113

```

105  TES= ABS (SUM/STIFM (II))
      IF (TES-TEST) 106,107,107
106  TEST=IES
      IROW=I
107  STIFM (II)= SUM
C    OFF DIAGONAL TERMS
      IF (I-NROWS) 108,121,121
108  KNDEX=INDEX
109  DO 116 K=IP1,NROWS
      KK=NCOL (K)
      KNDEX=KNDEX+K-KK
      SUM=0.0
      IF (KK-III) 110,130,130
110  KK=III
130  IF (IM1-KK) 112,131,131
131  DO 111 J=KK,IM1
      IJ=INDEX+J
      KJ=KNDEX+J
111  SUM=SUM+STIFM (IJ)*STIFM (KJ)*STIFM (IC (J) +J)
112  IF (I-KK) 114,115,115
114  IF (NIRREG .LE. 0) GO TO 121
      IF (NIRREG .GT. NROWS /2) GO TO 116
      GO TO 190
115  KI=KNDEX+I
      STIFM (KI)=(STIFM (KI) -SUM)/STIFM (II)
116  CONTINUE
      GO TO 121
190  NCK=NCK+1
      IF (NIRREG .LT. NCK) GO TO 121
      IP1=KROW (NCK)
      IF (I .LT. NCOL (IP1)) GO TO 190
      IF (IP1 .LT. K) GO TO 190
      KNDEX=NDEX (NCK)
      GO TO 109
121  CONTINUE
      RETURN

```

```

FACT0370
FACT0380
FACT0390
FACT0400
FACT0410
FACT0420
FACT0430
FACT0440
FACT0450
FACT0460
FACT0470
FACT0480
FACT0490
FACT0500
FACT0510
FACT0520
FACT0530
FACT0540
FACT0550
FACT0560
FACT0570
FACT0580
FACT0590
FACT0600
FACT0610
FACT0620
FACT0630
FACT0640
FACT0650
FACT0660
FACT0670
FACT0680
FACT0690
FACT0700
FACT0710
FACT0720

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122	WRITE (NTAPE6,1001) I	FACT0730
	IDET=-I	FACT0740
1001	FORMAT (37H1 MATRIX NOT POSITIVE DEFINITE IN ROW,I4)	FACT0750
	WRITE (NTAPE6,1002) SUM	FACT0760
1002	FORMAT (27H0SQUARE OF DIAGONAL TERM = ,E15.8,/28H0PARTIALLY FACTOR	FACT0770
	ED K MATRIX,//)	FACT0780
	RETURN	FACT0790
	END	FACT0800

	SUBROUTINE IDENT(NQR,B,DENS,EPS,SIG,NBR)	IDNT0010
	IMPLICIT REAL*8(A-H,O-Z)	IDNT0020
	DIMENSION DENS(3,6),EPS(3,5,6),SIG(3,5,6),B(6)	IDNT0030
	COMMON/MAT/YOUNG(3,6),DS(3,6),SNO(3,5,6),NSFL(3,6),P(3,6),NLAY	IDNT0040
	COMMON /FG/ IK,IKK,ICP,LREF,NOGA,NFL,NI,ICOL(205),INUM(205)	IDNT0050
	*,NBCOND,NBC(7),NODEB(7),KROW(8),NDEX(8),NIRREG	IDNT0060
	COMMON /ML/ MNEL(6)	IDNT0070
	COMMON/FC/ Y(51),Z(51),ANG(51),H(51,3)	IDNT0080
	COMMON /TAPE/ MREAD,MWRITE,MPUNCH	IDNT0090
	COMMON /TAM/ MKE(51)	IDNT0100
	IF(ICP.GT.0) GO TO 31	IDNT0110
	WRITE(MWRITE,2)	IDNT0120
2	FORMAT('***** A SPATIAL FINITE ELEMENT AND HOUBOLT TEMPORA	IDNT0130
	*L OPERATOR PROGRAM',/, ' USED TO CALCULATE THE NONLINEAR RESPON	IDNT0140
	*ES OF A VARIABLE THICKNESS MULTILAYER ',/, ' ARBITRARILY CURVED	IDNT0150
	* PARTIAL RING WITH THE FOLLOWING PARAMETERS ',//)	IDNT0160
	GO TO 30	IDNT0170
31	WRITE(MWRITE,1)	IDNT0180
1	FORMAT('***** A SPATIAL FINITE ELEMENT AND HOUBOLT TEMPORA	IDNT0190
	*L OPERATOR PROGRAM',/, ' USED TO CALCULATE THE NONLINEAR RESPON	IDNT0200
	*ES OF A VARIABLE THICKNESS MULTILAYER ',/, ' ARBITRARILY CURVED	IDNT0210
	* COMPLETE RING WITH THE FOLLOWING PARAMETERS ',//)	IDNT0220
30	CONTINUE	IDNT0230
	NBR1 = NBR+1	IDNT0240
	DO 600 LSUB=1,NBR1	IDNT0250
	IF(LSUB.EQ.1) GOTO 100	IDNT0260
	LSUB1 = LSUB-1	IDNT0270
	WRITE(MWRITE,115) LSUB1	IDNT0280
115	FORMAT('--PROPERTIES OF BRANCH NUMBER',I4,' :')	IDNT0290
	GOTO 110	IDNT0300
100	WRITE(MWRITE,105)	IDNT0310
105	FORMAT('--PROPERTIES OF THE MAIN STRUCTURE:')	IDNT0320
110	CONTINUE	IDNT0330
	NLAP=NLAY	IDNT0340
	IF(LSUB.GT.1) NLAP = 1	IDNT0350
	WRITE(MWRITE,3) B(LSUB),MNEL(LSUB),NOGA,NFL,NLAP,LREF	IDNT0360



3	FORMAT(' WIDTH OF RING (IN)	=',E15.6,/,	IDNT0370
*	NUMBER OF ELEMENTS	=',I5,/,	IDNT0380
*	NUMBER OF SPANWISE GAUSSIAN POINTS	=',I5,/,	IDNT0390
*	NUMBER OF DEPTHWISE GAUSSIAN POINTS	=',I5,/,	IDNT0400
*	NUMBER OF LAYERS	=',I5,/,	IDNT0410
*	REFERENCE SURFACE IS THE MIDDLE SURFACE OF LAYER=' ,I5,/,		IDNT0420
	DO 32 M=1,NLAP		IDNT0430
	WRITE (MWRITE,33) M,DENS(M,LSUB),NSFL(M,LSUB)		IDNT0440
33	FORMAT(' MATERIAL PROPERTIES OF LAYER	=',I5,/,	IDNT0450
*	DENSITY(LB-SEC**2/IN**4)	=',E15.6,/,	IDNT0460
*	NUMBER OF MECHANICAL SUBLAYERS	=',I5,/,	IDNT0470
	NSFLM= NSFL(M,LSUB)		IDNT0480
	WRITE(MWRITE,40)		IDNT0490
40	FORMAT(19X,' STRAIN STRESS ')		IDNT0500
	WRITE(MWRITE,41) (L,EPS(M,L,LSUB),SIG(M,L,LSUB),L=1,NSFLM)		IDNT0510
41	FORMAT(14X,I5,2E15.6)		IDNT0520
	IF(DS(M,LSUB).LE.0.0) GO TO 34		IDNT0530
	WRITE(MWRITE,35) DS(M,LSUB),P(M,LSUB)		IDNT0540
35	FORMAT(9X,' MATERIAL IS STRAIN RATE SENSITIVE WITH ',/,		IDNT0550
	*19X,' D =',E15.6,' P = ',E15.6,/,		IDNT0560
	GO TO 32		IDNT0570
34	WRITE(MWRITE,36)		IDNT0580
36	FORMAT(9X,' MATERIAL IS STRAIN RATE INSENSITIVE ',/,		IDNT0590
32	CONTINUE		IDNT0600
600	CONTINUE		IDNT0610
	IF(NBCOND .EQ. 0) GO TO 5		IDNT0620
	DO 14 I=1,NBCOND		IDNT0630
	IF(NBC(I) .EQ. 1) WRITE(MWRITE,15) NODEB(I)		IDNT0640
	IF(NBC(I) .EQ. 2) WRITE(MWRITE,16) NODEB(I)		IDNT0650
	IF(NBC(I) .EQ. 3) WRITE(MWRITE,17) NODEB(I)		IDNT0660
14	CONTINUE		IDNT0670
15	FORMAT(' SYMMETRY DISPLACEMENT CONDITION AT NODE =' ,I5)		IDNT0680
16	FORMAT(' CLAMPED DISPLACEMENT CONDITION AT NODE =' ,I5)		IDNT0690
17	FORMAT(' HINGED DISPLACEMENT CONDITION AT NODE =' ,I5)		IDNT0700
	GO TO 18		IDNT0710
5	WRITE(MWRITE,13)		IDNT0720

13	FORMAT(/,' THERE IS NO PRESCRIBED DISPLACEMENT CONDITION')	IDNT0730
18	IF(NOR .EQ. 0) GO TO 19	IDNT0740
	WRITE(MWRITE,20)	IDNT0750
20	FORMAT(/,' CONSTRAINTS (ELASTIC FOUNDATION/SPRING) AS DESCRIBED	IDNT0760
	* BY INPUT ',//)	IDNT0770
	GO TO 23	IDNT0780
19	WRITE(MWRITE,21)	IDNT0790
21	FORMAT(/,' THERE ARE NO ELASTIC SPRING CONSTRAINTS',//)	IDNT0800
23	CONTINUE	IDNT0810
	WRITE(MWRITE,47)	IDNT0820
47	FORMAT(10X,' NODE NO        Y COORD(IN)        Z COORD(IN)        SLOPE (	IDNT0830
	*RAD)        RING THICKNESS(IN) ',//,70X,'        LAYER 1        LAYER	IDNT0840
	* 2        LAYER 3 ',//)	IDNT0850
	DO 45 I=1,IKK	IDNT0860
45	WRITE(MWRITE,46) I,Y(I),Z(I),ANG(I),(H(I,M),M=1,NLAY)	IDNT0870
46	FORMAT(10X,I5,4X,6E17.6)	IDNT0880
	RETURN	IDNT0890
	END	IDNT0900

SUBROUTINE MINV(A,N,DET,L,M)  
 INVERT MATRIX A  
 IMPLICIT REAL\*8(A-H,O-Z)  
 DIMENSION A(1),L(1),M(1)  
 ABS(Q)=DABS(Q)

SEARCH FOR LARGEST ELEMENT

DET=1.0  
 NK=-N  
 DO 80 K=1,N  
 NK=NK+N  
 L(K)=K  
 M(K)=K  
 KK=NK+K  
 BIGA=A(KK)  
 DO 20 J=K,N  
 IZ=N\*(J-1)  
 DO 20 I=K,N  
 IJ=IZ+I

10 IF(ABS(BIGA)-ABS(A(IJ)))15,20,20

15 BIGA=A(IJ)  
 L(K)=I  
 M(K)=J

20 CONTINUE

INTERCHANGE ROWS

J=L(K)  
 IF(J-K) 35,35,25  
 25 KI=K-N  
 DO 30 I=1,N  
 KI=KI+N  
 HOLD=-A(KI)  
 JI=KI-K+J  
 A(KI)=A(JI)

MINV0000  
 MINV0010

MINV0020

MINV0030

MINV0040

MINV0050

MINV0060

MINV0070

MINV0080

MINV0090

MINV0100

MINV0110

MINV0120

MINV0130

MINV0140

MINV0150

MINV0160

MINV0170

MINV0190

MINV0200

MINV0210

MINV0220

MINV0230

MINV0240

MINV0250

MINV0260

MINV0270

MINV0280

MINV0290

MINV0300

MINV0310

MINV0320

MINV0330

30 A(JI) =HOLD

C  
C  
C

INTERCHANGE COLUMNS

35 I=M(K)

IF(I-K) 45,45,38

38 JP=N\*(I-1)

DO 40 J=1,N

JK=NK+J

JI=JP+J

HOLD=-A(JK)

A(JK)=A(JI)

40 A(JI) =HOLD

C  
C  
C  
C

DIVIDE COLUMN BY MINUS PIVOT (VALUE OF PIVOT ELEMENT IS  
CONTAINED IN BIGA)

45 IF(BIGA) 48,46,48

46 DET=0.0

RETURN

48 DO 55 I=1,N

IF(I-K) 50,55,50

50 IK=NK+I

A(IK)=A(IK)/(-BIGA)

55 CONTINUE

C  
C  
C

REDUCE MATRIX

DO 65 I=1,N

IK=NK+I

HOLD=A(IK)

IJ=I-N

DO 65 J=1,N

IJ=IJ+N

IF(I-K) 60,65,60

60 IF(J-K) 62,65,62

MINV0340

MINV0350

MINV0360

MINV0370

MINV0380

MINV0390

MINV0400

MINV0410

MINV0420

MINV0430

MINV0440

MINV0450

MINV0460

MINV0470

MINV0480

MINV0490

MINV0500

MINV0510

MINV0520

MINV0530

MINV0540

MINV0550

MINV0560

MINV0570

MINV0580

MINV0590

MINV0600

MINV0610

MINV0620

MINV0630

MINV0640

MINV0650

MINV0660

MINV0670

MINV0680

MINV0690

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62 KJ=IJ-I+K
   A(IJ)=HOLD*A(KJ)+A(IJ)
65 CONTINUE

```

```

C
C   DIVIDE ROW BY PIVOT
C

```

```

   KJ=K-N
   DO 75 J=1,N
   KJ=KJ+N
   IF(J-K) 70,75,70
70  A(KJ)=A(KJ)/BIGA
75  CONTINUE

```

```

C
C   PRODUCT OF PIVOTS
C
   DET=DET*BIGA

```

```

C
C   REPLACE PIVOT BY RECIPROCAL
C

```

```

   A(KK)=1.0/BIGA
80  CONTINUE

```

```

C
C   FINAL ROW AND COLUMN INTERCHANGE
C

```

```

   K=N
100 K=(K-1)
   IF(K) 150,150,105
105 I=L(K)
   IF(I-K) 120,120,108
108 JQ=N*(K-1)
   JR=N*(I-1)
   DO 110 J=1,N
   JK=JQ+J
   HOLD=A(JK)
   JI=JR+J
   A(JK)=-A(JI)

```

```

MINV0700
MINV0710
MINV0720
MINV0730
MINV0740
MINV0750
MINV0760
MINV0770
MINV0780
MINV0790
MINV0800
MINV0810
MINV0820
MINV0830
MINV0840
MINV0850
MINV0860
MINV0870
MINV0880
MINV0890
MINV0900
MINV0910
MINV0920
MINV0930
MINV0940
MINV0950
MINV0960
MINV0970
MINV0980
MINV0990
MINV1000
MINV1010
MINV1020
MINV1030
MINV1040
MINV1050

```

```
110 A(JI) =HOLD
120 J=M(K)
    IF(J-K) 100,100,125
125 KI=K-N
    DO 130 I=1,N
        KI=KI+N
        HOLD=A(KI)
        JI=KI-K+J
        A(KI)=-A(JI)
130 A(JI) =HOLD
    GO TO 100
150 RETURN
    END
```

```
MINV1060
MINV1070
MINV1080
MINV1090
MINV1100
MINV1110
MINV1120
MINV1130
MINV1140
MINV1150
MINV1160
MINV1170
MINV1180
```

	SUBROUTINE DMULT(SQVCT,RWVCT,NCOL,NROWS,ACC,KROW,NDEX,NIRREG)	DMUT0000
C	TO FIND ACC OF (SQVCT)*(RWVCT)=(ACC)	DMUT0010
	IMPLICIT REAL*8(A-H,O-Z)	
	DIMENSION SQVCT(1),RWVCT(1),NCOL(1),ACC(1),KROW(1),NDEX(1)	DMUT0020
	INDEX=0	DMUT0030
	NROWM=NROWS-1	DMUT0040
	IF (NIRREG .GT. 0) GO TO 200	DMUT0050
C	HIGH SPEED PRODUCT FOR REGULAR MATRICES	DMUT0060
	DO 100 NN=1,NROWM	DMUT0070
	SUM=0.0	DMUT0080
	IP1=NN+1	DMUT0090
	KST=NCOL(NN)	DMUT0100
	INDEX=INDEX+NN-KST	DMUT0110
	DO 101 KPL=KST,NN	DMUT0120
	IJ=INDEX+KPL	DMUT0130
101	SUM=SUM+SQVCT(IJ)*RWVCT(KPL)	DMUT0140
C	NOW FOR THE COLUMN ELEMENTS	DMUT0150
	JNDEX=IJ	DMUT0160
	DO 102 KPL=IP1,NROWS	DMUT0170
	IF(NN.LT.NCOL(KPL))GO TO 100	DMUT0180
	JNDEX=JNDEX+KPL-NCOL(KPL)	DMUT0190
102	SUM=SUM+SQVCT(JNDEX)*RWVCT(KPL)	DMUT0200
100	ACC(NN)=ACC(NN)+SUM	DMUT0210
C	NOW FOR THE LAST ROW	DMUT0220
104	KADD=NCOL(NROWS)	DMUT0230
	SUM=0.0	DMUT0240
	INDEX=INDEX+NROWS-KADD	DMUT0250
	DO 103 KPL=KADD,NROWS	DMUT0260
	IJ=INDEX+KPL	DMUT0270
103	SUM=SUM+SQVCT(IJ)*RWVCT(KPL)	DMUT0280
	ACC(NROWS)=ACC(NROWS)+SUM	DMUT0290
	RETURN	DMUT0300
C	MEDIUM SPEED PRODUCT FOR NIRREG .LE. NROWS/2	DMUT0310
200	IF (NIRREG .GT. NROWS/2) GO TO 201	DMUT0320
	DO 105 NN=1,NROWM	DMUT0330
	IP1=NN+1	DMUT0340

```

KST=NCOL(NN)
INDEX=INDEX+NN-KST
SUM=0.0
DO 106 KPL=KST,NN
  IJ=INDEX+KPL
106  SUM=SUM+SQVCT(IJ)*RWVCT(KPL)
  NCK=0
  JINDEX=IJ
107  DO 108 KPL=IP1,NROWS
    IF(NN .LT. NCOL(KPL)) GO TO 109
    JINDEX=JINDEX+KPL-NCOL(KPL)
108  SUM=SUM+SQVCT(JINDEX)*RWVCT(KPL)
    GO TO 105
109  NCK=NCK+1
    IF (NCK .GT. NIRREG) GO TO 105
    IF (KPL .GE. KROW(NCK)) GO TO 109
    IP1=KROW(NCK)
    JINDEX=NDEX(NCK)+NN
    GO TO 107
105  ACC(NN)=ACC(NN)+SUM
    GO TO 104
201  DO 503 NN=1,NROWM
    IP1=NN+1
    K=NCOL(NN)
    INDEX=INDEX+NN-K
    SUM=0.0
    DO 502 KRX=K,NN
      IJ=INDEX+KRX
502  SUM=SUM+SQVCT(IJ)*RWVCT(KRX)
      JINDEX=IJ
      DO 504 KRX=IP1,NROWS
        K=NCOL(KRX)
        JINDEX=JINDEX+KRX-K
        IF (NN .LT. K) GO TO 504
        SUM=SUM+SQVCT(JINDEX)*RWVCT(KRX)
504  CONTINUE

```

```

OMUT0350
OMUT0360
OMUT0370
OMUT0380
OMUT0390
OMUT0400
OMUT0410
OMUT0420
OMUT0430
OMUT0440
OMUT0450
OMUT0460
OMUT0470
OMUT0480
OMUT0490
OMUT0500
OMUT0510
OMUT0520
OMUT0530
OMUT0540
OMUT0550
OMUT0560
OMUT0570
OMUT0580
OMUT0590
OMUT0600
OMUT0610
OMUT0620
OMUT0630
OMUT0640
OMUT0650
OMUT0660
OMUT0670
OMUT0680
OMUT0690
OMUT0700

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503 ACC(NN)=ACC(NN)+SUM  
GO TO 104  
END

OMUT0710  
OMUT0720  
OMUT0730

C	SUBROUTINE QREM(AL,AXG,AWG,SPRIN) TO FIND EFFECTIVE STIFFNESS MATRIX DUE TO ELASTIC RESTRAINTS IMPLICIT REAL*8(A-H,O-Z) DIMENSION DUMMY(8) DIMENSION AL(1),AXG(1),AWG(1),BNG(51),SPRIN(1) *,ELR(8,8),ELRR(8,8),ELRP(8,8),A(8,8),LMI(8),MMI(8) COMMON/MAT/YOUNG(3,6),DS(3,6),SNC(3,5,6),NSFL(3,6),P(3,6),NLAY COMMON /FG/ IK,IKK,ICP,LREF,NOGA,NFL,NI,ICOL(205),INUM(205) *,NBCOND,NBC(7),NODEB(7),KROW(8),NDEX(8),NIRREG COMMON/FC/ Y(51),Z(51),ANG(51),H(51,3) COMMON /ELFU/ FQREF(205),REX(4),NQR,NORP,NORU *,NREL(4),NREST(4),NREU(4) COMMON/BOUN/ YK(51),NBCONB,NBCB(7),NODBB(7),MK(51),ROT(5,2) *,XDIST(6),DROT(50),NODP(6) COMMON /TAM/ MKE(51) COMMON /TAPE/ MREAD,MWRITE,MPUNCH COMMON /BR/ NVEC(51,2), LMT(51) SIN(Q)=DSIN(Q) COS(Q)=DCOS(Q) ATAN(Q)=DATAN(Q) ABS(Q)=DABS(Q) SQRT(Q)=DSQRT(Q) 777 FORMAT(/,10X,'THE VALUE OF THE TANGENTIAL SPRING CONSTANT IS =',E15.6,/, *5.6,/,10X,'THE VALUE OF THE RADIAL SPRING CONSTANT IS =',E15.6,/, *10X,'THE VALUE OF THE TORSIONAL SPRING CONSTANT IS =',E15.6,/ IF (NORP .EQ. 0) GO TO 1 READ(MREAD,2) SCTP,SCTY,SCRIP,(NREL(I),REX(I),I=1,NORP) 2 FORMAT(3D15.6/(4(I5,D15.6))) WRITE(MWRITE,1100) NORP 1100 FORMAT(/,,' THE CONSTANTS FOR',I3,' ELASTIC POINT CONSTRAINTS ARE @: ') WRITE(MWRITE,777) SCTP,SCTY,SCRIP WRITE(MWRITE,1140) 1140 FORMAT(/,10X,'ELEMENT',10X,'S COORDINATE') WRITE(MWRITE,1145) (NREL(I),REX(I),I=1,NORP) 1145 FORMAT(' ',10X,I3,13X,D13.6)	QREM0010 QREM0020 QREM0030 QREM0040 QREM0050 QREM0060 QREM0070 QREM0080 QREM0090 QREM0100 QREM0110 QREM0120 QREM0130 QREM0140 QREM0150 QREM0160 QREM0170 QREM0180 QREM0190 QREM0200 QREM0210 QREM0220 QREM0230 QREM0240 QREM0250 QREM0260 QREM0270 QREM0280 QREM0290 QREM0300 QREM0310 QREM0320 QREM0330 QREM0340 QREM0350 QREM0360
---	---	--

DO 10 IQ=1,NORP  
 SL=REX(IQ)  
 NE=NREL(IQ)  
 L= MKE(NE) -1  
 K1 = NVEC(NE,1)  
 K2 = NVEC(NE,2)  
 P5=Z(K2)-Z(K1)  
 P6=Y(K2)-Y(K1)  
 P7=ANG(K2) -ANG(K1)  
 IF(YK(NE).EQ.1.0) P7=ANG(K2) - ROT(L,2)-ANG(K1)  
 IF(YK(NE).EQ.1.0.AND.ROT(L,1).EQ.0.0) P7=ROT(L,2)+ANG(K2)-ANG(K1)  
 IF(YK(NE).EQ.2.0) P7= ANG(K2)- DROT(NE) - ANG(K1)  
 IF(YK(NE).EQ.3.0) P7=ROT(L,2)+ANG(K2)-DROT(NE)-ANG(K1)  
 PIE= 3.141592653589793D+00  
 PIE2= 2.0\*PIE  
 PIE32= 1.5 \*PIE  
 ANG2=ANG(K2)  
 ANG1=ANG(K1)  
 IF(YK(NE).EQ.1.0.AND.ROT(L,1).EQ.0.0) ANG(K2)=ROT(L,2)+ANG(K2)  
 IF(YK(NE).EQ.1.0.AND.ROT(L,1).EQ.1.0) ANG(K1)=ROT(L,2)+ANG(K1)  
 IF(YK(NE).EQ.2.0) ANG(K1)= DROT(NE) + ANG(K1)  
 IF(YK(NE).EQ.3.0) ANG(K2)= ROT(L,2)+ANG(K2)  
 IF(YK(NE).EQ.3.0) ANG(K1)= DROT(NE) + ANG(K1)  
 APHA = PIE / 2.0  
 IF(P5.LT.0.0) APHA= -APHA  
 IF(P6.NE.0.0) APHA= ATAN(P5/P6)  
 IF(P6.LT.0.0.AND.P5.LT.0.0) APHA=APHA-PIE  
 IF(P6.LT.0.0.AND. P5.GE.0.0) APHA=APHA+PIE  
 BNG(NE+1)=ANG(K2)  
 BNG(NE)=ANG(K1)  
 IF(P7.GT.(PIE32).AND.APHA.LT.0.0) BNG(NE+1)=ANG(K2) -PIE2  
 IF(P7.GT.(PIE32).AND.APHA.GT.0.0) BNG(NE)=ANG(K1)+PIE2  
 IF(P7.LT.(-PIE32).AND.APHA.GT.0.0) BNG(NE+1)=ANG(K2) +PIE2  
 IF(P7.LT.(-PIE32).AND.APHA.LT.0.0) BNG(NE)=ANG(K1)-PIE2  
 BZER=BNG(NE)-APHA  
 B1=(-2.\*BNG(NE+1)-4.\*BNG(NE)+6.\*APHA)/AL(NE)

QREM0370  
 QREM0380  
 QREM0390  
 QREM0400  
 QREM0410  
 QREM0420  
 QREM0430  
 QREM0440  
 QREM0450  
 QREM0460  
 QREM0470  
 QREM0480  
 QREM0490  
 QREM0500  
 QREM0510  
 QREM0520  
 QREM0530  
 QREM0540  
 QREM0550  
 QREM0560  
 QREM0570  
 QREM0580  
 QREM0590  
 QREM0600  
 QREM0610  
 QREM0620  
 QREM0630  
 QREM0640  
 QREM0650  
 QREM0660  
 QREM0670  
 QREM0680  
 QREM0690  
 QREM0700  
 QREM0710  
 QREM0720

```

      B2=(3.*BNG (NE+1)+3.*BNG (NE)-6.*APHA)/AL (NE) **2
      ANG (K2)= ANG2
      ANG (K1)= ANG1
      DO 400 I=1,8
      DO 400 J=1,8
400   A (I,J)=0.0
      A (1,1)= COS (BNG (NE)-APHA)
      A (1,2)= SIN (BNG (NE)-APHA)
      A (2,1)=-SIN (BNG (NE)-APHA)
      A (2,2)= COS (BNG (NE)-APHA)
      A (3,3)=1.
      A (5,1)=COS (BNG (NE+1)-APHA)
      A (5,2)=SIN (BNG (NE+1)-APHA)
      A (5,3)=P6*SIN (BNG (NE+1)) -P5*COS (BNG (NE+1))
      A (6,1)=-SIN (BNG (NE+1)-APHA)
      A (6,2)=COS (BNG (NE+1)-APHA)
      A (6,3)=P6*COS (BNG (NE+1)) +P5*SIN (BNG (NE+1))
      A (7,3)=1.
      A (4,4)=1.
      A (5,4)=AL (NE)
      A (5,7)=AL (NE) **2
      A (5,8)=AL (NE) **3
      A (6,5)=AL (NE) **2
      A (6,6)=AL (NE) **3
      P8=B1+2.*B2*AL (NE)
      A (7,4)=AL (NE) *P8
      A (7,5)=2.*AL (NE)
      A (7,6)=3.*AL (NE) **2
      A (7,7)=AL (NE) **2*P8
      A (7,8)=AL (NE) **3*P8
      A (8,4)=1.
      A (8,5)=-AL (NE) **2*P8
      A (8,6)=-AL (NE) **3*P8
      A (8,7)=2.*AL (NE)
      A (8,8)=3.*AL (NE) **2
      CALL MINV (A,8,DET,LMI,MMI)

```

```

QREM0730
QREM0740
QREM0750
QREM0760
QREM0770
QREM0780
QREM0790
QREM0800
QREM0810
QREM0820
QREM0830
QREM0840
QREM0850
QREM0860
QREM0870
QREM0880
QREM0890
QREM0900
QREM0910
QREM0920
QREM0930
QREM0940
QREM0950
QREM0960
QREM0970
QREM0980
QREM0990
QREM1000
QREM1010
QREM1020
QREM1030
QREM1040
QREM1050
QREM1060
QREM1070
QREM1080

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104

```

PHI=BZER+B1*SL+B2*SL**2
PHIP=B1+2.*B2*SL
YZET=0.0
ZZET=0.0
DO 104 JJ=1,NOGA
P2=BZER+B1*SL*AXG(JJ)+B2*(SL*AXG(JJ))**2+APHA
YZET=YZET+COS(P2)*SL*AWG(JJ)
ZZET=ZZET+SIN(P2)*SL*AWG(JJ)
P3=YZET*SIN(PHI+APHA)-ZZET*COS(PHI+APHA)
P4=YZET*COS(PHI+APHA)+ZZET*SIN(PHI+APHA)
ELR(1,1)=SCTP*COS(PHI)**2+SCTY*SIN(PHI)**2
ELR(2,1)=(SCTP-SCTY)*COS(PHI)*SIN(PHI)
ELR(3,1)=P3*COS(PHI)*SCTP-P4*SIN(PHI)*SCTY
ELR(4,1)=SL*COS(PHI)*SCTP
ELR(5,1)=-SL**2*SIN(PHI)*SCTY
ELR(6,1)=-SL**3*SIN(PHI)*SCTY
ELR(7,1)=SL**2*COS(PHI)*SCTP
ELR(8,1)=SL**3*COS(PHI)*SCTP
ELR(2,2)=SCTP*SIN(PHI)**2+SCTY*COS(PHI)**2
ELR(3,2)=P3*SIN(PHI)*SCTP+P4*COS(PHI)*SCTY
ELR(4,2)=SL*SIN(PHI)*SCTP
ELR(5,2)=SL**2*COS(PHI)*SCTY
ELR(6,2)=SL**3*COS(PHI)*SCTY
ELR(7,2)=SL**2*SIN(PHI)*SCTP
ELR(8,2)=SL**3*SIN(PHI)*SCTP
ELR(3,3)=P3**2*SCTP+P4**2*SCTY+SCRIP
ELR(4,3)=P3*SI*SCTP+SL*PHIP*SCRIP
ELR(5,3)=P4*SL**2*SCTY+2.*SL*SCRIP
ELR(6,3)=P4*SL**3*SCTY+3.*SL**2*SCRIP
ELR(7,3)=(P3*SCTP+PHIP*SCRIP)*SL**2
ELR(8,3)=(P3*SCTP+PHIP*SCRIP)*SL**3
ELR(4,4)=(SCTP+PHIP**2*SCRIP)*SL**2
ELR(5,4)=2.*SL**2*PHIP*SCRIP
ELR(6,4)=3.*SL**3*PHIP*SCRIP
ELR(7,4)=(SCTP+PHIP**2*SCRIP)*SL**3
ELR(8,4)=(SCTP+PHIP**2*SCRIP)*SL**4

```

```

QREM1090
QREM1100
QREM1110
QREM1120
QREM1130
QREM1140
QREM1150
QREM1160
QREM1170
QREM1180
QREM1190
QREM1200
QREM1210
QREM1220
QREM1230
QREM1240
QREM1250
QREM1260
QREM1270
QREM1280
QREM1290
QREM1300
QREM1310
QREM1320
QREM1330
QREM1340
QREM1350
QREM1360
QREM1370
QREM1380
QREM1390
QREM1400
QREM1410
QREM1420
QREM1430
QREM1440

```

```

ELR(5,5)=SL**4*SCTY+4.*SL**2*SCR
ELR(6,5)=SL**5*SCTY+6.*SL**3*SCR
ELR(7,5)=2.*SL**3*PHIP*SCR
ELR(8,5)=2.*SL**4*PHIP*SCR
ELR(6,6)=SL**6*SCTY+9.*SL**4*SCR
ELR(7,6)=3.*SL**4*PHIP*SCR
ELR(8,6)=3.*SL**5*PHIP*SCR
ELR(7,7)=(SCTP+PHIP**2*SCR)*SL**4
ELR(8,7)=(SCTP+PHIP**2*SCR)*SL**5
ELR(8,8)=(SCTP+PHIP**2*SCR)*SL**6
DO 12 I=1,7
IP1=I+1
DO 12 J=IP1,8
12 ELR(I,J)=ELR(J,I)
DO 13 I=1,8
DO 13 J=1,8
ELRR(I,J)=0.0
DO 13 K=1,8
13 ELRR(I,J)=ELPR(I,J)+ELR(I,K)*A(K,J)
DO 14 I=1,8
DO 14 J=1,8
ELRP(I,J)=0.0
DO 14 K=1,8
14 ELRP(I,J)=ELRP(I,J)+A(K,I)*ELRR(K,J)
IF(YK(NE).EQ.0.0) GOTO 201
CALL ROTAT(3,ELRP,DUMMY,NE)
201 CONTINUE
CALL ASSEM(NE,IK,ELRP,SPRIN,ICP,INUM)
10 CONTINUE
1 IF(NORU.EQ.0) GO TO 4
READ(MREAD,3) SCTU,SCTW,SCRU,(NRST(I),NREU(I),I=1,NORU)
3 FORMAT(3D15.6/(8I5))
WRITE(MWRITE,1120) NORU
1120 FORMAT(//,' THE CONSTANTS FOR',I3,' ELASTIC FOUNDATIONS ARE:')
WRITE(MWRITE,777) SCTU,SCTW,SCRU
WRITE(MWRITE,1150)

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QREM1450  
QREM1460  
QREM1470  
QREM1480  
QREM1490  
QREM1500  
QREM1510  
QREM1520  
QREM1530  
QREM1540  
QREM1550  
QREM1560  
QREM1570  
QREM1580  
QREM1590  
QREM1600  
QREM1610  
QREM1620  
QREM1630  
QREM1640  
QREM1650  
QREM1660  
QREM1670  
QREM1680  
QREM1690  
QREM1700  
QREM1710  
QREM1720  
QREM1730  
QREM1740  
QREM1750  
QREM1760  
QREM1770  
QREM1780  
QREM1790  
QREM1800

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1150 FORMAT(/,10X,'FIRST ELEMENT',10X,'NUMBER OF ELEMENTS')  
 WRITE(MWRITE,1155) (NRST(I),NREU(I),I=1,NORU)

1155 FCRMAT(' ',13X,I3,24X,I3)

DO 15 IQ=1,NORU

NSTAT=NRST(IQ)

NEND=NREU(IQ)

DO 16 IR=1,NEND

NE=(NSTAT-1)+IR

IF(NE.GT.IK) NE=NE-1K

L= MKE(NE) -1

K1 = NVEC(NE,1)

K2 = NVEC(NE,2)

P5=Z(K2)-Z(K1)

P6=Y(K2)-Y(K1)

P7=ANG(K2) -ANG(K1)

IF(YK(NE).EQ.1.0) P7=ANG(K2) - ROT(L,2) -ANG(K1)

IF(YK(NE).EQ.1.0.AND.ROT(L,1).EQ.0.0) P7=ROT(L,2)+ANG(K2)-ANG(K1)

IF(YK(NE).EQ.2.0) P7= ANG(K2)- DROT(NE) - ANG(K1)

IF(YK(NE).EQ.3.0) P7=ROT(L,2)+ANG(K2)-DROT(NE)-ANG(K1)

PIE= 3.141592653589793D+00

PIE2= 2.0\*PIE

PIE32= 1.5 \*PIE

ANG2=ANG(K2)

ANG1=ANG(K1)

IF(YK(NE).EQ.1.0.AND.ROT(L,1).EQ.0.0) ANG(K2)=ROT(L,2)+ANG(K2)

IF(YK(NE).EQ.1.0.AND.ROT(L,1).EQ.1.0) ANG(K1)=ROT(L,2)+ANG(K1)

IF(YK(NE).EQ.2.0) ANG(K1)= DROT(NE) + ANG(K1)

IF(YK(NE).EQ.3.0) ANG(K2)= ROT(L,2)+ANG(K2)

IF(YK(NE).EQ.3.0) ANG(K1)= DROT(NE) + ANG(K1)

APHA = PIE / 2.0

IF(P5.LT.0.0) APHA= -APHA

IF(P6.NE.0.0) APHA= ATAN(P5/P6)

IF(P6.LT.0.0.AND.P5.LT.0.0) APHA=APHA-PIE

IF(P6.LT.0.0 .AND. P5.GE.0.0) APHA=APHA+PIE

BNG(NE+1)=ANG(K2)

BNG(NE)=ANG(K1)

QREM1810

QREM1820

QREM1830

QREM1840

QREM1850

QREM1860

QREM1870

QREM1880

QREM1890

QREM1900

QREM1910

QREM1920

QREM1930

QREM1940

QREM1950

QREM1960

QREM1970

QREM1980

QREM1990

QREM2000

QREM2010

QREM2020

QREM2030

QREM2040

QREM2050

QREM2060

QREM2070

QREM2080

QREM2090

QREM2100

QREM2110

QREM2120

QREM2130

QREM2140

QREM2150

QREM2160

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IF (P7.GT. (PIE32 ).AND.APHA.LT.0.0) BNG (NE+1)=ANG (K2)  -PIE2
IF (P7.GT. (PIE32 ).AND.APHA.GT.0.0) BNG (NE)=ANG (K1)+PIE2
IF (P7.LT. (-PIE32 ).AND.APHA.GT.0.0) BNG (NE+1)=ANG (K2)  +PIE2
IF (P7.LT. (-PIE32 ).AND.APHA.LT.0.0) BNG (NE)=ANG (K1)-PIE2
  BZER=BNG (NE)-APHA
  B1=(-2.*BNG (NE+1)-4.*BNG (NE)+6.*APHA)/AL (NE)
  B2=(3.*BNG (NE+1)+3.*BNG (NE)-6.*APHA)/AL (NE)**2
ANG (K2)= ANG2
ANG (K1)= ANG1
DO 401 I=1,8
DC 401 J=1,8
401  A (I,J)=0.0
      A (1,1)= COS (BNG (NE)-APHA)
      A (1,2)= SIN (BNG (NE)-APHA)
      A (2,1)=-SIN (BNG (NE)-APHA)
      A (2,2)= COS (BNG (NE)-APHA)
      A (3,3)=1.
      A (5,1)=COS (BNG (NE+1)-APHA)
      A (5,2)=SIN (BNG (NE+1)-APHA)
      A (5,3)=P6*SIN (BNG (NE+1) )-P5*COS (BNG (NE+1) )
      A (6,1)=-SIN (BNG (NE+1)-APHA)
      A (6,2)=COS (BNG (NE+1)-APHA)
      A (6,3)=P6*COS (BNG (NE+1) )+P5*SIN (BNG (NE+1) )
      A (7,3)=1.
      A (4,4)=1.
      A (5,4)=AL (NE)
      A (5,7)=AL (NE) **2
      A (5,8)=AL (NE) **3
      A (6,5)=AL (NE) **2
      A (6,6)=AL (NE) **3
      P8=B1+2.*B2*AL (NE)
      A (7,4)=AL (NE) *P8
      A (7,5)=2.*AL (NE)
      A (7,6)=3.*AL (NE) **2
      A (7,7)=AL (NE) **2*P8
      A (7,8)=AL (NE) **3*P8

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QREM2170
QREM2180
QREM2190
QREM2200
QREM2210
QREM2220
QREM2230
QREM2240
QREM2250
QREM2260
QREM2270
QREM2280
QREM2290
QREM2300
QREM2310
QREM2320
QREM2330
QREM2340
QREM2350
QREM2360
QREM2370
QREM2380
QREM2390
QREM2400
QREM2410
QREM2420
QREM2430
QREM2440
QREM2450
QREM2460
QREM2470
QREM2480
QREM2490
QREM2500
QREM2510
QREM2520

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A(8,4)=1.  
 A(8,5)=-AL(NE)\*\*2\*P8  
 A(8,6)=-AL(NE)\*\*3\*P8  
 A(8,7)=2.\*AL(NE)  
 A(8,8)=3.\*AL(NE)\*\*2  
 CALL MINV(A,8,DET,LMI,MMI)  
 DO 102 I=1,8  
 DO 102 J=1,8  
 102 ELR(I,J)=0.0  
 DO 103 J=1,NOGA  
 ZET=AL(NE)\*AXG(J)  
 PHIP=B1+2.\*B2\*ZET  
 PHI=BZER+B1\*ZET+B2\*ZET\*\*2  
 WET=AL(NE)\*AWG(J)  
 YZET=0.0  
 ZZET=0.0  
 DO 105 JJ=1,NOGA  
 P2=BZER+B1\*ZET\*AXG(JJ)+B2\*(ZET\*AXG(JJ))\*\*2+APHA  
 YZET=YZET+COS(P2)\*ZET\*AWG(JJ)  
 105 ZZET=ZZET+SIN(P2)\*ZET\*AWG(JJ)  
 P3=YZET\*SIN(PHI+APHA)-ZZET\*COS(PHI+APHA)  
 P4=YZET\*COS(PHI+APHA)+ZZET\*SIN(PHI+APHA)  
 ELR(1,1)=ELR(1,1)+(SCTU\*COS(PHI)\*\*2+SCTW\*SIN(PHI)\*\*2)\*WET  
 ELR(2,1)=ELR(2,1)+((SCTU-SCTW)\*SIN(PHI)\*COS(PHI))\*WET  
 ELR(3,1)=ELR(3,1)+(P3\*SCTU\*COS(PHI)-P4\*SCTW\*SIN(PHI))\*WET  
 ELR(5,1)=ELR(5,1)-(ZET\*\*2\*SCTW\*SIN(PHI))\*WET  
 ELR(6,1)=ELR(6,1)-(ZET\*\*3\*SCTW\*SIN(PHI))\*WET  
 ELR(2,2)=ELR(2,2)+(SCTU\*SIN(PHI)\*\*2+SCTW\*COS(PHI)\*\*2)\*WET  
 ELR(3,2)=ELR(3,2)+(P3\*SCTU\*SIN(PHI)+P4\*SCTW\*COS(PHI))\*WET  
 ELR(5,2)=ELR(5,2)+(ZET\*\*2\*SCTW\*COS(PHI))\*WET  
 ELR(6,2)=ELR(6,2)+(ZET\*\*3\*SCTW\*COS(PHI))\*WET  
 ELR(3,3)=ELR(3,3)+(P3\*\*2\*SCTU+P4\*\*2\*SCTW+SCRU)\*WET  
 ELR(5,3)=ELR(5,3)+(P4\*SCTW\*ZET\*\*2+2.0\*SCRU\*ZET)\*WET  
 ELR(6,3)=ELR(6,3)+(P4\*SCTW\*ZET\*\*3+3.0\*SCRU\*ZET\*\*2)\*WET  
 ELR(5,5)=ELR(5,5)+(ZET\*\*4\*SCTW+4.0\*ZET\*\*2\*SCRU)\*WET  
 ELR(6,5)=ELR(6,5)+(ZET\*\*5\*SCTW+6.0\*ZET\*\*3\*SCRU)\*WET

QREM2530  
 QREM2540  
 QREM2550  
 QREM2560  
 QREM2570  
 QREM2580  
 QREM2590  
 QREM2600  
 QREM2610  
 QREM2620  
 QREM2630  
 QREM2640  
 QREM2650  
 QREM2660  
 QREM2670  
 QREM2680  
 QREM2690  
 QREM2700  
 QREM2710  
 QREM2720  
 QREM2730  
 QREM2740  
 QREM2750  
 QREM2760  
 QREM2770  
 QREM2780  
 QREM2790  
 QREM2800  
 QREM2810  
 QREM2820  
 QREM2830  
 QREM2840  
 QREM2850  
 QREM2860  
 QREM2870  
 QREM2880

ELR(6,6)=ELR(6,6)+(ZET\*\*6\*SCTW+9.0\*ZET\*\*4\*SCRU)\*WET  
 ELR(4,1)=ELR(4,1)+ZET\*COS(PHI)\*SCTU\*WET  
 ELR(7,1)=ELR(7,1)+ZET\*\*2\*COS(PHI)\*SCTU\*WET  
 ELR(8,1)=ELR(8,1)+ZET\*\*3\*COS(PHI)\*SCTU\*WET  
 ELR(4,2)=ELR(4,2)+ZET\*SIN(PHI)\*SCTU\*WET  
 ELR(7,2)=ELR(7,2)+ZET\*\*2\*SIN(PHI)\*SCTU\*WET  
 ELR(8,2)=ELR(8,2)+ZET\*\*3\*SIN(PHI)\*SCTU\*WET  
 ELR(4,3)=ELR(4,3)+(P3\*SCTU+PHIP\*SCRU)\*ZET\*WET  
 ELR(7,3)=ELR(7,3)+(P3\*SCTU+PHIP\*SCRU)\*ZET\*\*2\*WET  
 ELR(8,3)=ELR(8,3)+(P3\*SCTU+PHIP\*SCRU)\*ZET\*\*3\*WET  
 ELR(4,4)=ELR(4,4)+(SCTU+PHIP\*\*2\*SCRU)\*ZET\*\*2\*WET  
 ELR(5,4)=ELR(5,4)+2.\*ZET\*\*2\*PHIP\*SCRU\*WET  
 ELR(6,4)=ELR(6,4)+3.\*ZET\*\*3\*PHIP\*SCRU\*WET  
 ELR(7,4)=ELR(7,4)+(SCTU+PHIP\*\*2\*SCRU)\*ZET\*\*3\*WET  
 ELR(8,4)=ELR(8,4)+(SCTU+PHIP\*\*2\*SCRU)\*ZET\*\*4\*WET  
 ELR(7,5)=ELR(7,5)+2.\*ZET\*\*3\*PHIP\*SCRU\*WET  
 ELR(8,5)=ELR(8,5)+2.\*ZET\*\*4\*PHIP\*SCRU\*WET  
 ELR(7,6)=ELR(7,6)+3.\*ZET\*\*4\*PHIP\*SCRU\*WET  
 ELR(8,6)=ELR(8,6)+3.\*ZET\*\*5\*PHIP\*SCRU\*WET  
 ELR(7,7)=ELR(7,7)+(SCTU+PHIP\*\*2\*SCRU)\*ZET\*\*4\*WET  
 ELR(8,7)=ELR(8,7)+(SCTU+PHIP\*\*2\*SCRU)\*ZET\*\*5\*WET  
 ELR(8,8)=ELR(8,8)+(SCTU+PHIP\*\*2\*SCRU)\*ZET\*\*6\*WET  
 103 CONTINUE  
 DO 5 I=1,7  
 IP1=I+1  
 DO 5 J=IP1,8  
 5 ELR(I,J)=ELR(J,I)  
 DO 6 I=1,8  
 DO 6 J=1,8  
 ELRR(I,J)=0.0  
 DO 6 K=1,8  
 6 ELRR(I,J)=ELRR(I,J)+ELR(I,K)\*A(K,J)  
 DO 7 I=1,8  
 DO 7 J=1,8  
 ELRP(I,J)=0.0  
 DO 7 K=1,8

QREM2890  
 QREM2900  
 QREM2910  
 QREM2920  
 QREM2930  
 QREM2940  
 QREM2950  
 QREM2960  
 QREM2970  
 QREM2980  
 QREM2990  
 QREM3000  
 QREM3010  
 QREM3020  
 QREM3030  
 QREM3040  
 QREM3050  
 QREM3060  
 QREM3070  
 QREM3080  
 QREM3090  
 QREM3100  
 QREM3110  
 QREM3120  
 QREM3130  
 QREM3140  
 QREM3150  
 QREM3160  
 QREM3170  
 QREM3180  
 QREM3190  
 QREM3200  
 QREM3210  
 QREM3220  
 QREM3230  
 QREM3240

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7      ELRP(I,J)=ELRP(I,J)+A(K,I)*ELRR(K,J)
      IF(YK(NE).EQ.0.0) GOTO 202
      CALL ROTAT(3,ELRP,DUMMY,NE)
202    CONTINUE
16      CALL ASSEM(NE,IK,ELRP,SPRIN,ICP,INUM)
15      CONTINUE
      4 RETURN
      END

```

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QREM3250
QREM3260
QREM3270
QREM3280
QREM3290
QREM3300
QREM3310
QREM3320

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	SUBROUTINE ROTAT(IND,ELM,ELV,IR)	ROTA0010
C	THIS SUBROUTINE TRANSFORMS MATRICES FROM ELEMENT SYSTEMS TO THE	ROTA0020
C	GLOBAL SYSTEM AND VICE-VERSA. IND = 1 FOR GLOBAL VECTOR INTO	ROTA0030
C	ELEMENT VECTOR, IND=2 FOR ELEMENT VECTOR INTO GLOBAL VECTOR, IND = 3	ROTA0040
C	FOR ELEMENT MATRIX INTO GLOBAL SYSTEM	ROTA0050
C	ELM IS THE MATRIX TO BE TRANSFORMED, ELV IS THE VECTOR TO BE	ROTA0060
C	TRANSFORMED, WHILE IR IS THE ELEMENT NUMBER YK,ROT,AND DROT USED	ROTA0070
C	BELOW, INDICATE WHETHER A BRANCH OR A DISCONTINUITY IS BEING CON-	ROTA0080
C	SIDERED AND WHAT THE ANGLE OF ROTATION IS.	ROTA0090
	IMPLICIT REAL*8(A-H,O-Z)	ROTA0100
	DIMENSION ELM(8,8),ELV(8),TR(4,4),TRAN(8,8),WORK(8),ELRR(8,8)	ROTA0110
	COMMON /BOUN/ YK(51),NBCONB,NBCB(7),NODBB(7),MK(51),RCT(5,2)	ROTA0120
	*,XDIST(6),DROT(50),NCDP(6)	ROTA0130
	COMMON /TAM/ MKE(51)	ROTA0140
	COMMON /BR/ NVEC(51,2), LMT(51)	ROTA0150
	COMMON /TAPE/ MREAD,MWRITE,MPUNCH	ROTA0160
	COMMON /TIME/ IT	ROTA0170
	SIN(Q)=DSIN(Q)	ROTA0180
	COS(Q)=DCOS(Q)	ROTA0190
	ATAN(Q)=DATAN(Q)	ROTA0200
	ABS(Q)=DABS(Q)	ROTA0210
	SQRT(Q)=DSQRT(Q)	ROTA0220
	DO 1100 I=1,4	ROTA0230
	DO 1100 J = 1,4	ROTA0240
1100	TR(I,J) = 0.0	ROTA0250
	TR(3,3) = 1.0	ROTA0260
	TR(4,4) = 1.0	ROTA0270
	MOP = MKE(IR) -1	ROTA0280
	DO 1110 J = 1,8	ROTA0290
	DO 1110 K = 1,8	ROTA0300
1110	TRAN(J,K) = 0.0	ROTA0310
	DO 1115 J= 1,8	ROTA0320
1115	TRAN(J,J) = 1.0	ROTA0330
	ANGK= DROT(IR)	ROTA0340
	IF(YK(IR).EQ.1.0.OR.YK(IR).EQ.3.0) ANGK=ROT(MOP,2)	ROTA0350
	TR(1,1) = DCOS(ANGK)	ROTA0360

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TR(1,2) = DSIN(ANGK)
TR(2,1) = -DSIN(ANGK)
TR(2,2) = DCOS(ANGK)
IF(YK(IR).EQ.2.0) GO TO 1120
IF (ROT(MOP,1).NE.0.0) GO TO 1120
DO 1130 J = 5,8
DO 1130 K = 5,8
1130 TRAN(J,K) = TR(J-4,K-4)
TRAN(5,7) = XDIST(MOP) * TR(1,1)
TRAN(6,7) = XDIST(MOP) * TR(2,1)
GOTO 1150
1120 DO 1140 J = 1,4
DO 1140 K = 1,4
1140 TRAN(J,K) = TR(J,K)
IF(YK(IR).EQ.2.0) GO TO 1150
TRAN(1,3) = XDIST(MOP) * TR(1,1)
TRAN(2,3) = XDIST(MOP) * TR(2,1)
1150 CONTINUE
IF(YK(IR).NE.3.0) GOTO 3000
ANGZ=DROT(IR)
TRAN(1,1) = DCCS(ANGZ)
TRAN(1,2) = DSIN(ANGZ)
TRAN(2,1) = -DSIN(ANGZ)
TRAN(2,2) = DCOS(ANGZ)
3000 CONTINUE
IF(IND.EQ.3) GOTO 800
IF(IND.EQ.1) GOTO 100
DO 210 I=1,8
DO 210 J=1,8
210 ELRR(I,J) = TRAN(J,I)
DO 215 I=1,8
DO 215 J= 1,8
215 TRAN(I,J) = ELRR(I,J)
100 CONTINUE
110 CONTINUE
DO 1160 I = 1,8

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```

ROTA0370
ROTA0380
ROTA0390
ROTA0400
ROTA0410
ROTA0420
ROTA0430
ROTA0440
ROTA0450
ROTA0460
ROTA0470
ROTA0480
ROTA0490
ROTA0500
ROTA0510
ROTA0520
ROTA0530
ROTA0540
ROTA0550
ROTA0560
ROTA0570
ROTA0580
ROTA0590
ROTA0600
ROTA0610
ROTA0620
ROTA0630
ROTA0640
ROTA0650
ROTA0660
ROTA0670
ROTA0680
ROTA0690
ROTA0700
ROTA0710
ROTA0720

```

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      WORK(I) = 0.0
      DO 1160 J = 1,8
1160  WORK(I) = WORK(I) + TRAN(I,J) * ELV(J)
      DO 1170 I= 1,8
1170  ELV(I) = WORK(I)
      RETURN
800  CONTINUE
      DO 2160 I = 1,8
      DO 2160 J = 1,8
      ELRR(I,J) = 0.0
      DO 2160 K = 1,8
2160  ELRR(I,J) = ELRR(I,J) + ELM(I,K)*TRAN(K,J)
      DO 2170 I= 1,8
      DO 2170 J= 1,8
      ELM(I,J) = 0.0
      DO 2170 K = 1,8
2170  ELM(I,J) = ELM(I,J) + TRAN(K,I) * ELRR(K,J)
      RETURN
      END

```

```

ROTA0730
ROTA0740
ROTA0750
ROTA0760
ROTA0770
ROTA0780
ROTA0790
ROTA0800
ROTA0810
ROTA0820
ROTA0830
ROTA0840
ROTA0850
ROTA0860
ROTA0870
ROTA0880
ROTA0890
ROTA0900
ROTA0910

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SUBROUTINE SOLV (STIFM,G,SOL,NCOL,KROW,NDEX,NROWS,NIRREG)
C SOLVE (LL*) (SCL)=(FORCE) FOR DISPLACEMENTS (SCL)
  IMPLICIT REAL*8 (A-H,O-Z)
  DIMENSION STIFM(1),G(1),SOL(1), NCOL(1),KROW(1),NDEX(1)
C INTERMEDIATE SOLUTION USING THE LOWER TRIANGLE
100 INDEX=0
  SOL(1)=G(1)
  DO 104 I=2,NROWS
    IM1=I-1
    SUM=0.0
    K=NCOL(I)
    INDEX=INDEX+I-K
    IF (IM1-K) 103,101,101
101 DO 102 J=K,IM1
    IJ=INDEX+J
    SU=SOL(J)
102 SUM=SUM+STIFM(IJ)*SU
103 II=INDEX+I
104 SOL(I)= G(I)-SUM
C SOL CONTAINS THE INTERMEDIATE SOLUTION
C COMPLETE THE SOLUTION USING THE UPPER TRIANGLE
  SOL(NROWS)=SOL(NROWS)/STIFM(II)
  INDEX=INDEX-NROWS+NCOL(NROWS)
  IF (NIRREG .GT. 0) GO TO 111
  DO 109 KK=2,NROWS
    I=NROWS+1-KK
    IP1=I+1
    SUM=0.0
    JNDEX=INDEX+I
    DO 107 J=IP1,NROWS
      K=NCOL(J)
      IF (I-K) 108,106,106
106 JNDEX=JNDEX+J-K
      SU=SOL(J)
107 SUM=SUM+STIFM(JNDEX)*SU
108 II=INDEX+I

```

```

SOLV0010
SOLV0020
SOLV0030
SOLV0040
SOLV0050
SOLV0060
SOLV0070
SOLV0080
SOLV0090
SOLV0100
SOLV0110
SOLV0120
SOLV0130
SOLV0140
SOLV0150
SOLV0160
SOLV0170
SOLV0180
SOLV0190
SOLV0200
SOLV0210
SOLV0220
SOLV0230
SOLV0240
SOLV0250
SOLV0260
SOLV0270
SOLV0280
SOLV0290
SOLV0300
SOLV0310
SOLV0320
SOLV0330
SOLV0340
SOLV0350
SOLV0360

```

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      SOL(I) = SOL(I)/STIFM (II) -SUM
109  INDEX=INDEX-I+NCOL(I)
      RETURN
111  IF (NIRREG-NROWS /2) 116,116,112
C    TOO MANY IRREGULAR ROWS FOR ACCELERATED SOLUTION
112  DO 115 KK=2,NROWS
      I=NROWS+1-KK
      IP1=I+1
      JNDEX=INDEX+I
      SUM=0.0
      JNDEX=INDEX+I
      DO 114 J=IP1,NROWS
      K=NCOL(J)
      JNDEX=JNDEX+J-K
      IF (I-K) 114,113,113
113  SU=SOL(J)
      SUM=SUM+STIFM(JNDEX)*SU
114  CONTINUE
      II=INDEX+I
      SOL(I) = SOL(I)/STIFM(II) -SUM
115  INDEX=INDEX-I+NCOL(I)
      RETURN
C    ACCELERATED SOLUTION FOR CASE WITH IRREGULAR ROWS
116  DO 125 KK=2,NROWS
      I=NROWS+1-KK
      IP1=I+1
      SUM=0.0
      NCK=0
      JNDEX=INDEX+I
117  DO 119 J=IP1,NROWS
      K=NCOL(J)
      IF (I-K) 120,118,118
118  JNDEX=JNDEX+J-K
      SU=SOL(J)
119  SUM=SUM+STIFM(JNDEX)*SU
      GO TO 124

```

```

SOLV0370
SOLV0380
SOLV0390
SOLV0400
SOLV0410
SOLV0420
SOLV0430
SOLV0440
SOLV0450
SOLV0460
SOLV0470
SOLV0480
SOLV0490
SOLV0500
SOLV0510
SOLV0520
SOLV0530
SOLV0540
SOLV0550
SOLV0560
SOLV0570
SOLV0580
SOLV0590
SOLV0600
SOLV0610
SOLV0620
SOLV0630
SOLV0640
SOLV0650
SOLV0660
SOLV0670
SOLV0680
SOLV0690
SOLV0700
SOLV0710
SOLV0720

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120 NCK=NCK+1  
IF (NIRREG-NCK) 124,121,121  
121 IP1=KROW(NCK)  
IF (I-NCOL(IP1)) 120,122,122  
122 IF (IP1-J) 120,123,123  
123 JNDEX=NDEX(NCK)+I  
GO TO 117  
124 II=INDEX+I  
SOL(I) = SOL(I)/STIFM(II) -SUM  
125 INDEX=INDEX-I+NCOL(I)  
RETURN  
END

SOLV0730  
SOLV0740  
SOLV0750  
SOLV0760  
SOLV0770  
SOLV0780  
SOLV0790  
SOLV0800  
SOLV0810  
SOLV0820  
SOLV0830  
SOLV0840

	SUBROUTINE STRESS(DELTA,ASFL,GZETA,SNS,SNP,NV1,NV2,NV3)	STRS0010
C	TO EVALUATE GENERALIZED NODAL LOAD VECTOR DUE TO LARGE DEFLECTION	STRS0020
C	AND ELASTIC-PLASTIC STRAIN	STRS0030
	IMPLICIT REAL*8(A-H,O-Z)	STRS0040
	DIMENSION ASFL(NV1,3,NV2,NV3),GZETA(NV1,3,NV2),SNS(NV1,3,NV2,NV3)	STRS0050
	,SNP(NV1,3,NV2,NV3)	STRS0060
	DIMENSION DISM(8),DELM(8),DUMMY(8,8)	STRS0070
	DIMENSION ELFP(8),BEPS(3),CEPS(3,3),BINPW(3),BIMPW(3),HWB(3,3),	STRS0080
	*PN(8),PM(8),HNL(8),BINPP(3),BIMPP(3)	STRS0090
	COMMON /FG/ IK,IKK,ICP,LREF,NOGA,NFL,NI,ICOL(205),INUM(205)	STRS0100
	*,NBCOND,NBC(7),NODEB(7),KROW(8),NDEX(8),NIRREG	STRS0110
	COMMON /TAPE/ MREAD,MWRITE,MPUNCH	STRS0120
	COMMON/MAT/YOUNG(3,6),DS(3,6),SNO(3,5,6),NSFL(3,6),P(3,6),NLAY	STRS0130
	COMMON/VQ/ FLVA(205),DISP(205),DELD(205),BINP(50,3),BIMP(50,3)	STRS0140
	COMMON/BA/ BEP(50,3,3,8),AL(50),AXG(3),AWG(3),WET(50,3),	STRS0150
	*CE1(50,3),CE2(50,3),CE3(50,3),CM1(50,3),CM2(50,3),CM3(50,3)	STRS0160
	COMMON/BOUN/YK(51),NBCONB,NBCB(7),NODBB(7),MK(51),ROT(5,2)	STRS0170
	*,XDIST(6),DROT(50),NODP(6)	STRS0180
	COMMON/BR/ NVEC(51,2), LMT(51)	STRS0190
	COMMON /TAM/ MKE(51)	STRS0200
	ABS(0)=DABS(0)	STRS0210
	DO 502 IR=1,IK	STRS0220
	K1= NVEC(IR,1)	STRS0230
	K2= NVEC(IR,2)	STRS0240
	DO 8000 K=1,8	STRS0250
	INDEX= (K1-1)*4+K	STRS0260
	IF(K.GT.4) INDEX= (K2-1)*4+K-4	STRS0270
	DISM(K) = DISP(INDEX)	STRS0280
	DELM(K) = DELD(INDEX)	STRS0290
8000	CONTINUE	STRS0300
	IF(YK(IR).EQ.0.0) GOTO 1010	STRS0310
	CALL ROTAT(1,DUMMY,DISM,IR)	STRS0320
	CALL ROTAT(1,DUMMY,DELM,IR)	STRS0330
1010	CONTINUE	STRS0340
	IP=MKE(IR)	STRS0350
	NIAP=NLAY	STRS0360

```

IF (MKE (IR) .GT. 1) NLAP=1
DO 503 J=1, NOGA
BINP (IR, J)=0.
BIMP (IR, J)=0.
BINPP (J)=0.0
BIMPP (J)=0.0
202 DO 402 I=1, 3
BEP (I)=0.
DO 402 K=1, 8
402 BEP (I)=BEP (I)+BEP (IR, J, I, K)*DELM (K)
DO 403 I=1, 3
CEP (J, I)=0.0
DO 403 K=1, 8
403 CEP (J, I)=CEP (J, I)+BEP (IR, J, I, K)*DISM (K)
205 FARE=BEP (1)+CEP (J, 2)*BEP (2)-BEP (2)**2/2.
*+CEP (J, 1)*BEP (1)-BEP (1)**2/2.
FCUR=BEP (3)
DO 151 M=1, NLAP
NSFLM= NSFL (M, IP)
DO 151 N=1, NFL
K=N+(M-1)*NFL
BFNP=0.
BFNPP=0.0
BEPX=FARE+GZETA (IR, J, K)*FCUR
RFACTR=1.
IF (DS (M, IP).EQ.0.0) GO TO 1000
S1 = 1.0/P (M, IP)
S2 = 1.0/DS (M, IP)/DELTAT
RFACTR = 1.0 + (S2*ABS (BEPX))**S1
1000 CONTINUE
DO 35 L=1, NSFLM
DESNP=0.0
SNS (IR, J, K, L) = SNS (IR, J, K, L) + YOUNG (M, IP)*BEPX
SNY=SNQ (M, L, IP)*RFACTR
IF (SNS (IR, J, K, L)-SNY) 30, 301, 20
20 DESNP=SNP (IR, J, K, L)-SNY

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```

STRS0370
STRS0380
STRS0390
STRS0400
STRS0410
STRS0420
STRS0430
STRS0440
STRS0450
STRS0460
STRS0470
STRS0480
STRS0490
STRS0500
STRS0510
STRS0520
STRS0530
STRS0540
STRS0550
STRS0560
STRS0570
STRS0580
STRS0590
STRS0600
STRS0610
STRS0620
STRS0630
STRS0640
STRS0650
STRS0660
STRS0670
STRS0680
STRS0690
STRS0700
STRS0710
STRS0720

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	SNS (IR,J,K,L) =SNY	STRS0730
	GO TO 301	STRS0740
30	IF (SNS (IR,J,K,L) +SNY) 40,301,301	STRS0750
40	DESNP=SNS (IR,J,K,L) +SNY	STRS0760
	SNS (IR,J,K,L) =-SNY	STRS0770
301	BFNP=BFNP+SNS (IR,J,K,L) *ASFL (IR,J,K,L)	STRS0780
	SNP (IR,J,K,L) =SNP (IR,J,K,L) +DESNP	STRS0790
	BFNPP=BFNPP+SNP (IR,J,K,L) *ASFL (IR,J,K,L)	STRS0800
35	CONTINUE	STRS0810
	BINP (IR,J) =BINP (IR,J) +BFNP	STRS0820
	BIMP (IR,J) =BIMP (IR,J) +BFNP*GZETA (IR,J,K)	STRS0830
	BINPP (J) =BINPP (J) +BFNPP	STRS0840
	BIMPP (J) =BIMPP (J) +BFNPP*GZETA (IR,J,K)	STRS0850
151	CONTINUE	STRS0860
503	CONTINUE	STRS0870
107	DO 101 J=1,NOGA	STRS0880
	BINPW (J) = (CE1 (IR,J) * (CEPS (J,1) **2/2.+CEPS (J,2) **2/2.)	STRS0890
	*-BINPP (J) ) *WET (IR,J)	STRS0900
	BIMPW (J) = (CE2 (IR,J) * (CEPS (J,1) **2/2.+CEPS (J,2) **2/2.)	STRS0910
	*-BIMPP (J) ) *WET (IR,J)	STRS0920
	HWB (J,1) = (CE1 (IR,J) * (CEPS (J,1) +CEPS (J,2) **2/2.+CEPS (J,1) **2/2.)	STRS0930
	*+CE2 (IR,J) *CEPS (J,3) -BINPP (J) ) *CEPS (J,1) *WET (IR,J)	STRS0940
	HWB (J,2) = (CE1 (IR,J) * (CEPS (J,1) +CEPS (J,2) **2/2.+CEPS (J,1) **2/2.)	STRS0950
	*+CE2 (IR,J) *CEPS (J,3) -BINPP (J) ) *CEPS (J,2) *WET (IR,J)	STRS0960
101	CONTINUE	STRS0970
	DO 102 I=1,8	STRS0980
	PN (I) =0.	STRS0990
	PM (I) =0.	STRS1000
	HNL (I) =0.0	STRS1010
	DO 102 J=1,NOGA	STRS1020
	PN (I) =PN (I) +BEP (IR,J,1,I) *BINPW (J)	STRS1030
	PM (I) =PM (I) +BEP (IR,J,3,I) *BIMPW (J)	STRS1040
102	HNL (I) =HNL (I) +BEP (IR,J,2,I) *HWB (J,2) +BEP (IR,J,1,I) *HWB (J,1)	STRS1050
200	DO 105 I=1,8	STRS1060
105	ELFP (I) =PN (I) +PM (I) +HNL (I)	STRS1070
	IF ( YK (IR) .EQ.0.0) GO TO 502	STRS1080

CALL ROTAT(2,DUMMY,ELFP,IR)  
502 CALL ASSEF(IR,IK,ELFP,FLVA,ICP)  
RETURN  
END

STRS1090  
STRS1100  
STRS1110  
STRS1120

	SUBROUTINE TSTEP (AMASS, STIFK, DELTAT)	TSTP0010
C	TO FIND DELTAT IF IT IS NOT SPECIFIED	TSTP0020
	IMPLICIT REAL*8 (A-H, O-Z)	TSTP0030
	DIMENSION AMASS (1), STIFK (1), TRIAL (205), VMULT (205), VECTR (205)	TSTP0040
	COMMON /FG/ IK, IKK, ICP, LREF, NOGA, NFL, NI, ICOL (205), INUM (205)	TSTP0050
	*, NBCOND, NBC (7), NODEB (7), KROW (8), NDEX (8), NIRREG	TSTP0060
	COMMON /MAT/ YOUNG (3, 6), DS (3, 6), SNC (3, 5, 6), NSFL (3, 6), P (3, 6), NLAY	TSTP0070
	COMMON /TAPE/ MREAD, MWRITE, MPUNCH	TSTP0080
	ABS (Q) = DABS (Q)	TSTP0090
	SQRT (Q) = DSQRT (Q)	TSTP0100
	INT (Q) = IDINT (Q)	TSTP0110
	DO 3 K=1, NI	TSTP0120
3	TRIAL (K) = 1.0	TSTP0130
	IF (NBCOND .EQ. 0) GO TO 90	TSTP0140
	DO 91 I=1, NBCCND	TSTP0150
	JT4 = NODEB (I) * 4	TSTP0160
	JT4M3 = JT4 - 3	TSTP0170
	JT4M2 = JT4 - 2	TSTP0180
	JT4M1 = JT4 - 1	TSTP0190
	TRIAL (JT4M3) = 0.0	TSTP0200
	IF (NBC (I) .EQ. 1 .OR. NBC (I) .EQ. 2) TRIAL (JT4M1) = 0.0	TSTP0210
	IF (NBC (I) .EQ. 2 .OR. NBC (I) .EQ. 3) TRIAL (JT4M2) = 0.0	TSTP0220
91	CONTINUE	TSTP0230
90	MRANK = NI	TSTP0240
	BONE = 0.	TSTP0250
	EPSLN = 1.0E-07	TSTP0260
2	BOLD = 1.0	TSTP0270
	DO 14 KKK=1, 4	TSTP0280
	DO 12 LLL=1, 50	TSTP0290
	DO 4 I=1, MRANK	TSTP0300
4	VMULT (I) = 0.0	TSTP0310
	CALL OMULT (STIFK, TRIAL, ICOL, NI, VMULT, KROW, NDEX, NIRREG)	TSTP0320
	CALL SOLV (AMASS, VMULT, VECTR, ICOL, KROW, NDEX, NI, NIRREG)	TSTP0330
	BNEW = -1.	TSTP0340
	DO 6 K=1, MRANK	TSTP0350
	IF (BNEW - ABS (VECTR (K))) 60, 60, 6	TSTP0360

60	BNEW= ABS (VECTR (K))	TSTP0370
6	CONTINUE	TSTP0380
	DO 7 K=1, MRANK	TSTP0390
	IF (BNEW- ABS (VECTR (K))) 7, 8, 7	TSTP0400
7	CONTINUE	TSTP0410
8	MROW=K	TSTP0420
	BNEW=VECTR (K)	TSTP0430
	DO 9 K=1, MRANK	TSTP0440
9	TRIAL (K)=VECTR (K) /BNEW	TSTP0450
	IF ( ABS (BNEW/BOLD-1.0)-EPSLN) 15, 15, 10	TSTP0460
C	ITERATION	TSTP0470
10	BKTH=BOLD	TSTP0480
	BOLD=BNEW	TSTP0490
12	CONTINUE	TSTP0500
	EPSLN=EPSLN*10.	TSTP0510
14	CONTINUE	TSTP0520
C	NOT CONVERGING AFTER LL*KK ITERATIONS	TSTP0530
	EPSLN=1.0	TSTP0540
	BONE=BNEW	TSTP0550
	GO TO 32	TSTP0560
C	EIGEN VALUE FOUND	TSTP0570
15	BONE=BNEW	TSTP0580
32	CONTINUE	TSTP0590
	FREQ= SQRT (BONE)	TSTP0600
	FACTCL=1.	TSTP0610
	DELTAN=FACTCL*2./FREQ	TSTP0620
	MP=0	TSTP0630
20	DELTAN=DELTAN*10.	TSTP0640
	MP=MP+1	TSTP0650
	IF (DELTAN.LT.10.) GO TO 20	TSTP0660
	DELTAN= INT (DELTAN) *10.** (-MP)	TSTP0670
	WRITE (MWRITE, 25) FREQ	TSTP0680
25	FORMAT (/, ' HIGHEST NATURAL FREQUENCY (RAD/SEC) =', E17.8)	TSTP0690
	WRITE (MWRITE, 500) DELTAN	TSTP0700
500	FORMAT ('DELTAT SHOULD BE EQUAL TO OR LESS THAN', D15.6)	TSTP0710
	IF (DELTAT.EQ.0.0) DELTAT =DELTAN	TSTP0720

RETURN  
END

TSTP0730  
TSTP0740

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## 6.2 Additional Subroutines Needed for JET 5A

These five (5) subroutines consist of:

MAIN  
IMPULS  
LOADAQ  
LOADFT  
PRINT

and are listed in the following:

C	(C) COPYRIGHT 1978 MASSACHUSETTS INSTITUTE OF TECHNOLOGY	MAIN0010
C	JET 5A MAIN PROGRAM FOR VARIABLE THICKNESS ARBITRARILY CURVED	MAIN0020
C	MULTILAYER RING	MAIN0030
C	JET 5A HOUBOLT OPERATOR	MAIN0040
	IMPLICIT REAL*8 (A-H,O-Z)	MAIN0050
	DIMENSION ASFL(20,3,8,3), GZETA(20,3,8), SNS(20,3,8,3),	MAIN0060
	@ SNP(20,3,8,3), AEP(20,3,8), DEP(20,2,3,8)	MAIN0070
	DIMENSION STIFK(1400), SPRIN(1400), AMASS(1400), QDD(204), PEACH(1400)	MAIN0080
	@, REACK(1400), REAC(21), REAFM(205), REAFK(205)	MAIN0090
	DIMENSION EPL2(3), EPL1(3), DISM3(205)	MAIN0100
	DIMENSION TXG(6), TWG(6), ES(3,6,6), FMECH(205)	MAIN0110
	DIMENSION DDELD(205), DISUM(205), DIS(205), DISM1(205), DISM2(205),	MAIN0120
	*FLR(205), FLN(205), FLVM(205)	MAIN0130
	*BMASS(1400), RH(3), HZ(3), HREF(50,3,3)	MAIN0140
	DIMENSION BEPS(3,3), EPI(3), EPO(3)	MAIN0150
	DIMENSION HDIF(3)	MAIN0160
	DIMENSION HNIN(51), RMASS(51), UDOT(3), WDOT(3), ADOT(3)	MAIN0170
	DIMENSION EFLN(6)	MAIN0180
	DIMENSION DENS(3,6), B(6), EPS(3,5,6), SIG(3,5,6)	MAIN0190
	DIMENSION NSBS(50), NSEL(50), AEPS(3)	MAIN0200
	DIMENSION DISM(8), DELM(8), DUMMY(8,8)	MAIN0210
	DIMENSION BIGA(6), BTIMA(6), IBIGA(6), ISTAA(6), ISURA(6)	MAIN0220
	DIMENSION BI(6), BTIM(6), IBI(6), ISUR(6), ITHR(51)	MAIN0230
	COMMON/SC/ BIG(6), BTIME(6), IBIG(6), ISURF(6), ISTA(6)	MAIN0240
	COMMON/MAT/YOUNG(3,6), DS(3,6), SNO(3,5,6), NSFL(3,6), P(3,6), NLAY	MAIN0250
	COMMON/ADSP/ AZET(50), ASP(50), YSP(50), ZSP(50), LKK(50,11)	MAIN0260
	COMMON/VQ/ FLVA(205), DISP(205), DELD(205), BINP(50,3), BIMP(50,3)	MAIN0270
	COMMON /FG/ IK, IKK, ICP, LREF, NOGA, NFL, NI, ICOL(205), INUM(205)	MAIN0280
	*NBCOND, NBC(7), NODEB(7), KROW(8), NDEX(8), NIRREG	MAIN0290
	COMMON /EP/ EPSI(50), EPSO(50)	MAIN0300
	COMMON /TAPE/ MREAD, MWRITE, MPUNCH	MAIN0310
	COMMON/FC/ Y(51), Z(51), ANG(51), H(51,3)	MAIN0320
	COMMON/BA/ BEP(50,3,3,8), AL(50), AXG(3), AWG(3), WET(50,3),	MAIN0330
	*CE1(50,3), CE2(50,3), CE3(50,3), CM1(50,3), CM2(50,3), CM3(50,3)	MAIN0340
	COMMON /FORCE/ T1, AMP1FV, AMP1FW, T2, AMP2FV, AMP2FW, SLOPEV, SLOPEW,	MAIN0350
	*AMPFV, AMPFW, ETA(4), RTOV(4), RTOW(4), RTO2V(4), RTO2W(4), RTO3V(4),	MAIN0360

*RTO3W(4),FM1(4,8,2),FM2(2,4,8,2),FM3A(2,4,8,2),FM3B(2,4,8,2),	MAIN0370
*NOFT1,NOFT2,NOFT3,JELEM(4),NSTF2(4),NELF2(4),NSTF3(4),NELF3(4)	MAIN0380
COMMON /ELFU/ FQREF(205),REX(4),NQR,NORP,NORU	MAIN0390
*,NREL(4),NRST(4),NREU(4)	MAIN0400
COMMON /ML/ MNEL(6),MATT(6)	MAIN0410
COMMON /FRAG/ PH(3),FMASS(3),FMOI(3),UNK(3),CR(3),FCGU(3),FCGW(3)	MAIN0420
*,ALFA(3),DFCGU(3),DFCGW(3),DALFA(3),TREL,PKT(3),DELTAT,NP,MIMP	MAIN0430
COMMON/BOUN/YK(51),NBCONB,NBCB(7),NODBB(7),MK(51),ROT(5,2)	MAIN0440
*,XDIST(6),DROT(50),NODP(6)	MAIN0450
COMMON /TIME/ IT	MAIN0460
COMMON/DIS/ ANGDI(50),NEDI(50),NDIS	MAIN0470
COMMON /BR/ NVEC(51,2), LMT(51)	MAIN0480
COMMON /TAM/ MKE(51)	MAIN0490
COMMON /THI/ HTH(5)	MAIN0500
SIN(Q)=DSIN(Q)	MAIN0510
COS(Q)=DCOS(Q)	MAIN0520
ATAN(Q)=DATAN(Q)	MAIN0530
SQRT(Q)=DSQRT(Q)	MAIN0540
MREAD=5	MAIN0550
MWRITE=6	MAIN0560
MPUNCH=7	MAIN0570
NV1= 20	MAIN0580
NV2= 8	MAIN0590
NV3= 3	MAIN0600
1 FORMAT(10I5)	MAIN0610
2 FORMAT(3D15.6)	MAIN0620
3 FORMAT(3D25.16)	MAIN0630
4 FORMAT(3D15.6/(4D15.6))	MAIN0640
5 FORMAT(5D15.6)	MAIN0650
301 FORMAT(I5,2D15.6)	MAIN0660
303 FORMAT(5D15.6)	MAIN0670
IRRUN = 1	MAIN0680
5555 WRITE(MWRITE,5556) IRRUN	MAIN0690
5556 FORMAT('1THIS IS RUN NUMBER',I3,' FOR THIS JET 5A SUBMITTAL')	MAIN0700
READ(MREAD,1) IK,ICP,NLAY,LREF,NOGA,NFL,MM,M1,M2,ICON	MAIN0710
READ(MREAD,1) (NSFL(M,1),M=1,NLAY)	MAIN0720

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DO 201 M=1,NLAY
NSFLM= NSFL(M,1)
201 READ(MREAD,4) DENS(M,1),DS(M,1),P(M,1),(EPS(M,L,1),SIG(M,L,1)
*,L=1,NSFLM)
READ(MREAD,2) B(1),DELTAT
MNEL(1) = IK
IKP1=IK+1
IKK=IKP1
IF(ICP.GT.0) IKK=IK
NS= IKK
MPU=1
C IF A CONTINUATION DECK IS DESIRED, REMOVE THE FOLLOWING CARD: MPU=0
MPU=0
PIE= 3.141592653589793D+00
NPZ1 = M1
DO 7100 I=1,IKK
DO 7100 J= 1,3
7100 H(I,J) = 0.0
C GEOMETRY GENERATION PERFORMED HERE
READ(MREAD,2) (Y(I),Z(I),ANG(I),I=1,IKK)
READ(MREAD,5) ((H(I,M),M=1,NLAY),I=1,IKK)
DO 111 I=1,IKK
111 ANG(I)=ANG(I)*PIE/180.0
IF(ICP.LE.0) GO TO 202
Y(IKP1)=Y(1)
Z(IKP1)=Z(1)
ANG(IKP1)=ANG(1)
DO 203 M=1,NLAY
203 H(IKP1,M)=H(1,M)
202 CONTINUE
READ(MREAD,5300) NDIS
NDI = NDIS
IF(NDIS.EQ.0) GO TO 8100
READ(MREAD,8101) (NEDI(I),ANGDI(I),I=1,NDIS)
8101 FORMAT (4(I5,D15.6))
DO 8102 I=1,NDIS

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MAIN1070
MAIN1080

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8102	ANGDI(I) = (ANGDI(I)*PIE)/180.0	MAIN1090
8100	CONTINUE	MAIN1100
	READ(MREAD,5300) NBR	MAIN1110
5300	FORMAT(2I5)	MAIN1120
	MNSFL= NSFL(1,1)	MAIN1130
	DO 5666 I=1,NLAY	MAIN1140
	IF(MNSFL.LT.NSFL(I,1)) MNSFL=NSFL(I,1)	MAIN1150
5666	CONTINUE	MAIN1160
	DO 5305 I= 1,IK	MAIN1170
	MKE(I) = 1	MAIN1180
	LMT(I) = 0	MAIN1190
	YK(I) = 0.0	MAIN1200
	MK(I)= I	MAIN1210
	NVEC(I,2) = I+1	MAIN1220
5305	NVEC(I,1) = I	MAIN1230
	IF(ICP.GT.0) NVEC(IK,2) = 1	MAIN1240
	IF(ICP.LE.0) MK(IK+1) = IK+1	MAIN1250
	IF(NBR.NE.0) GOTO 1112	MAIN1260
	WRITE(MWRITE,1113)	MAIN1270
1113	FORMAT('/', ' THERE ARE NO BRANCHES CONNECTED TO THE MAIN STRUCTURE	MAIN1280
	@, THEREFORE', '/', ' THE NUMBERING SYSTEM FOR NODES AND ELEMENTS REMAIN	MAIN1290
	@S UNCHANGED')	MAIN1300
1112	CONTINUE	MAIN1310
	IF(NBR.EQ.0) GO TO 5310	MAIN1320
	CALL BRAN(NBR,DENS,EPS,SIG,B)	MAIN1330
	DO 8888 I=1,NBR	MAIN1340
	IF(MNSFL.LT.NSFL(1,I+1)) MNSFL= NSFL(1,I+1)	MAIN1350
8888	CONTINUE	MAIN1360
5310	CONTINUE	MAIN1370
	LGSP= 0	MAIN1380
	LSPP=0	MAIN1390
	READ(MREAD,8200) NOP,NASP,NTERF	MAIN1400
8200	FORMAT(3I5)	MAIN1410
	DO 8215 I=1,IK	MAIN1420
	DO 8215 J=1,2	MAIN1430
8215	LKK(I,J) = 0	MAIN1440

IF(NOP.EQ.0) GO TO 8220	MAIN1450
IF(NOP.NE.2) LGSP=1	MAIN1460
IF(NOP.NE.1) LSPP=1	MAIN1470
IF(LSPP.NE.1) GO TO 8220	MAIN1480
READ(MREAD,8210) (NSBS(I),NSEL(I),AZET(I),I=1,NASP)	MAIN1490
8210 FORMAT(2I5,D15.6)	MAIN1500
WRITE(MWRITE,156)	MAIN1510
156 FORMAT('0ADDITIONAL STRAIN POINT',5X,'ELEMENT',5X,'S COORDINATE')	MAIN1520
DO 8216 J= 1,NASP	MAIN1530
IF(NSBS(J).NE.1) GO TO 8217	MAIN1540
M= NSEL(J) + 1	MAIN1550
IF(ICP.GT.0.AND.NSEL(J).EQ.IK) MK(M) = IK+1	MAIN1560
N= MK(M) - 1	MAIN1570
LKK(N,1) = 1 + LKK(N,1)	MAIN1580
NO = LKK(N,1) + 1	MAIN1590
LKK(N,NO) = J	MAIN1600
GOTO 1400	MAIN1610
8217 NNNN = NSBS(J)-1	MAIN1620
IF(NODP(NNNN).EQ.1) GOTO 8218	MAIN1630
NNNN= NODP(NNNN)	MAIN1640
N= MK(NNNN) + NSEL(J)- 1	MAIN1650
GO TO 8219	MAIN1660
8218 N= NSEL(J)	MAIN1670
8219 LKK(N,1) = 1 + LKK(N,1)	MAIN1680
NO = LKK(N,1) + 1	MAIN1690
LKK(N,NO) = J	MAIN1700
1400 WRITE(MWRITE,145) J,N,AZET(J)	MAIN1710
145 FORMAT(' ',9X,I5,13X,I5,7X,D15.6)	MAIN1720
8216 CONTINUE	MAIN1730
8220 CONTINUE	MAIN1740
IF(NDIS.EQ.0) GO TO 8140	MAIN1750
IF(NBR.EQ.0) GOTO 8145	MAIN1760
IF(NDI.EQ.0) GOTO 8145	MAIN1770
DO 8146 J= 1,NDI	MAIN1780
M= NEDI(J) + 1	MAIN1790
N = MK(M) - 1	MAIN1800

NEDI(J) = N	MAIN1810
8146 CONTINUE	MAIN1820
8145 WRITE(MWRITE,8111)	MAIN1830
WRITE(MWRITE,8120) (NEDI(I),I=1,NDIS)	MAIN1840
8111 FORMAT(' EACH OF THE FOLLOWING ELEMENTS HAS A SLOPE DISCONTINUITY	MAIN1850
AT ITS FIRST NODE')	MAIN1860
8120 FORMAT(' ', 25I5)	MAIN1870
WRITE(MWRITE,8112) (ANGDI(L),L=1,NDIS)	MAIN1880
8112 FORMAT(' THE GLOBAL SLOPE (RAD.) AT EACH DISCONTINUITY EQUALS:',/,	MAIN1890
@ (8D15.6) )	MAIN1900
DO 8130 I= 1,NDIS	MAIN1910
M=NEDI(I)	MAIN1920
YK(M) = 2.0 + YK(M)	MAIN1930
L1= NVEC(M,1)	MAIN1940
DROT(M) = ANGDI(I) - ANG(L1)	MAIN1950
8130 CONTINUE	MAIN1960
8140 CONTINUE	MAIN1970
READ(MREAD,3) (AXG(K),K=1,NOGA)	MAIN1980
READ(MREAD,3) (AWG(K),K=1,NOGA)	MAIN1990
READ(MREAD,3) (TXG(K),K=1,NFL)	MAIN2000
READ(MREAD,3) (TWG(K),K=1,NFL)	MAIN2010
C FOR MEMBRANE SET TXG=0.0 AND TWG=2.0 FOR ONE DEPTHWISE STATION	MAIN2020
READ(MREAD,1) NBCOND, (NBC(I),NODEB(I),I=1,NBCOND)	MAIN2030
IF (NBR.EQ.0) GO TO 748	MAIN2040
NIT = NBCOND+ 1	MAIN2050
NIT1 = NIT - 1	MAIN2060
NBCOND= NBCOND+NBCONB	MAIN2070
IF (NBCONB.EQ.0) GO TO 751	MAIN2080
DO 750 LOP= 1,NBCONB	MAIN2090
NBC(NIT1 + LOP) = NBCB(LOP)	MAIN2100
750 NODEB(NIT1 + LOP) = NODBB(LOP)	MAIN2110
751 IF (NIT1.EQ.0) GO TO 748	MAIN2120
DO 753 LOP = 1,NIT1	MAIN2130
NTI = NODEB(LOP)	MAIN2140
753 NODEB(LOP) = MK(NTI)	MAIN2150
748 CONTINUE	MAIN2160

READ (MREAD,1) NQR,NORP,NORU  
 NI=IKK\*4  
 CALL IDENT(NQR,B,DENS,EPS,SIG,NBR)  
 WRITE(MWRITE,402)  
 402 FORMAT(///,' GAUSSIAN STATIONS AND WEIGHTS:')  
 WRITE(MWRITE,400) (L,AXG(L),L,AWG(L),L=1,NOGA)  
 WRITE(MWRITE,401) (L,TXG(L),L,TWG(L),L=1,NFL)  
 400 FORMAT(' ',12X,'AXG',I3,2X,'=',F20.15,8X,'AWG',I3,2X,'=',F20.15)  
 401 FORMAT(' ',12X,'TXG',I3,2X,'=',F20.15,8X,'TWG',I3,2X,'=',F20.15)  
 NBR1 = NBR+1  
 DO 651 K=1,NBR1  
 NLAP= NLAY  
 IF (K.GT.1) NLAP=1  
 DO 76 M=1,NLAP  
 NSFLM=NSFL(M,K)  
 ES(M,1,K) = SIG(M,1,K) /EPS(M,1,K)  
 IF (NSFLM-1) 77,77,79  
 78 DO 79 L=2,NSFLM  
 79 ES(M,L,K) = (SIG(M,L,K) -SIG(M,L-1,K)) / (EPS(M,L,K) -EPS(M,L-1,K))  
 77 ES(M,NSFLM+1,K) = 0.0  
 DO 80 L=1,NSFLM  
 80 SNO(M,L,K) = ES(M,1,K) \*EPS(M,L,K)  
 YOUNG(M,K) = ES(M,1,K)  
 76 CONTINUE  
 651 CONTINUE  
 IC = 0  
 DO 70 IR=1,IK  
 IF (YK(IR).EQ.1.0.OR.YK(IR).EQ.3.0) IC=IC+1  
 L1= NVEC(IR,1)  
 L2 = NVEC(IR,2)  
 NLAP= NLAY  
 IF (MKE(IR).GT.1) NLAP=1  
 DO 70 J=1,NOGA  
 DO 71 M=1,NLAP  
 IF (YK(IR).NE.1.0.AND.YK(IR).NE.3.0) GOTO 600  
 IF (ROT(IC,1).EQ.0.0) GO TO 610

MAIN2170  
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RH (M) = HTH (IC) \* (1.0-AXG (J)) + H (L2,M) \*AXG (J)  
 GO TO 71  
 610 RH (M) = H (L1,M) \* (1.0-AXG (J)) + HTH (IC) \*AXG (J)  
 GO TO 71  
 600 RH (M) = H (L1,M) \* (1.0-AXG (J)) + H (L2,M) \*AXG (J)  
 71 CONTINUE  
 HZ (1) =RH (1) /2.  
 IF (NLAP.EQ.1) GO TO 72  
 DO 73 M=2,NLAY  
 73 HZ (M) =HZ (M-1) + (RH (M) +RH (M-1)) /2.  
 72 CONTINUE  
 CM1 (IR,J) =0.0  
 CM2 (IR,J) =0.0  
 CM3 (IR,J) =0.0  
 CE1 (IR,J) =0.0  
 CE2 (IR,J) =0.0  
 CE3 (IR,J) =0.0  
 I= MKE (IP)  
 DO 74 M=1,NLAP  
 HREF (IR,J,M) =HZ (M) -HZ (LREF)  
 CM1 (IR,J) =CM1 (IR,J) +DENS (M,I) \*B (I) \*RH (M)  
 CM2 (IR,J) =CM2 (IR,J) -DENS (M,I) \*B (I) \*RH (M) \*HREF (IR,J,M)  
 CM3 (IR,J) =CM3 (IR,J) +DENS (M,I) \*B (I) \* (RH (M) \*\*3/12.  
 \*+HREF (IR,J,M) \*\*2 \*RH (M) )  
 C FOR MEMBRANE SET CE2 AND CE3 = 0.0  
 CE1 (IR,J) =CE1 (IR,J) +YOUNG (M,I) \*B (I) \*RH (M)  
 CE2 (IR,J) = CE2 (IR,J) +YOUNG (M,I) \*B (I) \*RH (M) \*HREF (IR,J,M)  
 CE3 (IR,J) = CE3 (IR,J) +YOUNG (M,I) \*B (I) \* (RH (M) \*\*3/12.0  
 \*+HREF (IR,J,M) \*\*2 \*RH (M) )  
 NSPLM=NSFL (M,I)  
 DO 75 N=1,NFL  
 K=N+ (M-1) \*NFL  
 GFL=RH (M) \*TWG (N) \*B (I) /2.0  
 GZETA (IR,J,K) =RH (M) \*TXG (N) /2. +HREF (IR,J,M)  
 DO 75 L=1,NSFLM  
 ASFL (IR,J,K,L) = GFL \* (ES (M,L,I) -ES (M,L+1,I)) /ES (M,1,I)

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 MAIN2880

75 CONTINUE  
 74 CONTINUE  
 70 CONTINUE  
 IF (NBR.NE.0) GOTO 218  
 DO 15 I=1,8  
 15 ICOL(I)=1  
 IKM1=IK-1  
 IF (ICP.GT.0) GO TO 17  
 DO 16 I=3,IKP1  
 IK4=I\*4  
 IK3=IK4-1  
 IK2=IK4-2  
 IK1=IK4-3  
 JJ=(I-1)\*4-3  
 ICOL(IK1)=JJ  
 ICOL(IK2)=JJ  
 ICOL(IK3)=JJ  
 ICOL(IK4)=JJ  
 16 CONTINUE  
 GO TO 19  
 17 DO 18 I=3,IKM1  
 IK4=I\*4  
 IK3=IK4-1  
 IK2=IK4-2  
 IK1=IK4-3  
 JJ=(I-1)\*4-3  
 ICOL(IK1)=JJ  
 ICOL(IK2)=JJ  
 ICOL(IK3)=JJ  
 ICOL(IK4)=JJ  
 18 CONTINUE  
 ICOL(IK\*4)=1  
 ICOL(IK\*4-1)=1  
 ICOL(IK\*4-2)=1  
 ICOL(IK\*4-3)=1  
 19 CONTINUE

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MAIN2890  
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218	INUM(1)= 1	MAIN3250
	DO 99 I=2,NI	MAIN3260
99	INUM(I)=I-ICOL(I-1)+INUM(I-1)	MAIN3270
	DO 990 I=1,NI	MAIN3280
990	INUM(I)=INUM(I)-ICOL(I)	MAIN3290
	NIRREG=0	MAIN3300
	INDEX=0	MAIN3310
	ISSET=1	MAIN3320
	DO 116 I=1,NI	MAIN3330
	L=ICOL(I)	MAIN3340
	IF (ICOL(I)-ISSET) 117,116,119	MAIN3350
119	ISSET=ICOL(I)	MAIN3360
	GO TO 116	MAIN3370
117	NIRREG=NIRREG+1	MAIN3380
	IF (NIRREG-NI/2) 711,711,90	MAIN3390
711	KROW(NIRREG)=I	MAIN3400
	NDEX(NIRREG)=INDEX	MAIN3410
116	INDEX=INDEX+I-L	MAIN3420
90	ISIZE=NI+INUM(NI)	MAIN3430
	WRITE(MWRITE,91) ISIZE	MAIN3440
91	FORMAT(/,' SIZE OF ASSEMBLED MASS OR STIFFNESS MATRIX=',I5)	MAIN3450
	IF (ISIZE.LE.2060) GOTO 6012	MAIN3460
	WRITE(MWRITE,6011)	MAIN3470
6011	FORMAT('OTHER SIZE OF THE STIFFNESS MATRIX HAS EXCEEDED 2060. THIS	MAIN3480
	② RUN HAS BEEN TERMINATED. CHANGE DIMENSION OF STIPK IN',/, ' MAIN	MAIN3490
	②,ELMPP,AND TSTEP. ALSO CHANGE DIMENSIONS FOR AMASS,BMASS,AND SPRIMAIN	MAIN3500
	②N')	MAIN3510
	GOTO 150	MAIN3520
6012	CONTINUE	MAIN3530
	ELMPB=0.0	MAIN3540
	CALL ELMPP(AMASS,STIFK,ISIZE,ALP,DEP,NV1,REACK,REACH,ELMPB)	MAIN3550
	DO 23 L=1,ISIZE	MAIN3560
	BMASS(L)=AMASS(L)	MAIN3570
23	SPRIN(L)=0.0	MAIN3580
	LLL=(IK-1)*26+36	MAIN3590
	WRITE(MWRITE,9030)	MAIN3600

WRITE(MWRITE,9035)	(BMASS(I),I=1,LLL)	MAIN3610
WRITE(MWRITE,9040)		MAIN3620
WRITE(MWRITE,9035)	(STIFK(I),I=1,LLL)	MAIN3630
9030	FORMAT('OBMASS =')	MAIN3640
9035	FORMAT(' ', 8D16.8)	MAIN3650
9040	FORMAT('OSTIFK =')	MAIN3660
	CALL FAC(AMASS,ICOL,KROW,NDEX,IDET,MWRITE,NI,NIRREG,INUM)	MAIN3670
	CALL TSTEP(AMASS,STIFK,DELTAT)	MAIN3680
	IF (NQR.EQ.0) GO TO 22	MAIN3690
	CALL QREM(AL,AXG,AWG,SPRIN)	MAIN3700
	DO 8612 I=1,ISIZE	MAIN3710
8612	REACK(I) = REACK(I) + SPRIN(I)	MAIN3720
	IF (NBCOND.EQ.0) GOTO 93	MAIN3730
	DO 92 I=1,NBCOND	MAIN3740
	JT4=NODEB(I)*4	MAIN3750
	JT4M3=JT4-3	MAIN3760
	JT4M2=JT4-2	MAIN3770
	JT4M1=JT4-1	MAIN3780
	CALL ERC(JT4M3,SPRIN,NI,ICOL,INUM)	MAIN3790
	IF (NBC(I).EQ.1.OR.NBC(I).EQ.2) CALL ERC(JT4M1,SPRIN,NI,ICOL,INUM)	MAIN3800
	IF (NBC(I).EQ.2.OR.NBC(I).EQ.3) CALL ERC(JT4M2,SPRIN,NI,ICOL,INUM)	MAIN3810
92	CONTINUE	MAIN3820
93	CONTINUE	MAIN3830
22	CONTINUE	MAIN3840
	DO 8951 J=1,NOGA	MAIN3850
8951	EPL2(J)= 0.0	MAIN3860
	EPAS2= 0.0	MAIN3870
	BIGL= 0.0	MAIN3880
	BIGAL=0.0	MAIN3890
	M= NBR+1	MAIN3900
	DO 10005 J= 1,M	MAIN3910
	BIG(J) = 0.0	MAIN3920
	BIGA(J) = 0.0	MAIN3930
	BI(J) = 0.0	MAIN3940
	IBIGA(J) = 0	MAIN3950
	IBIG(J) = 0	MAIN3960

	IBI(J) = 0	MAIN3970
	ISTA(J) = 0	MAIN3980
	ISTAA(J) = 0	MAIN3990
	BTIME(J) = 0.0	MAIN4000
	BTIMA(J) = 0.0	MAIN4010
	BTIM(J) = 0.0	MAIN4020
10005	CONTINUE	MAIN4030
	DTSQ=DELTAT**2	MAIN4040
	C2= 1./ (2.*DELTAT**2)	MAIN4050
	MCRIT=0	MAIN4060
	IT= 0	MAIN4070
	TIME=0.0	MAIN4080
	CALL IMPULS(NV,DELTAT,AL,SNS,SNP,NV1,NV2,NV3)	MAIN4090
	READ(MREAD,5) TBEGIN,TFINAL,AMP1FV,AMP1FW	MAIN4100
	IF(TFINAL.EQ. 0.0) WRITE(MWRITE,48)	MAIN4110
48	FORMAT('0 THERE IS NO TIME DEPENDENT FORCE DISTRIBUTION DURING THIS RUN')	MAIN4120
	IF(TFINAL.EQ. 0.0) GO TO 49	MAIN4130
	CALL LOADEQ(AL,AXG,AWG,TBEGIN,TFINAL)	MAIN4140
49	APDEN=0.0	MAIN4150
	CINETO=0.0	MAIN4160
	NREADF=0	MAIN4170
	T1=TBEGIN	MAIN4180
	NLOAD=2	MAIN4190
	DO 34 I=1,NI	MAIN4200
34	FMECH(I)=0.0	MAIN4210
	IF(TBEGIN.GT.0.0 .OR. TFINAL.EQ.0.0) GO TO 30	MAIN4220
	NLOAD=1	MAIN4230
	CALL LOADFT(TIME,NREADF,FMECH,AL)	MAIN4240
	DO 25 L=1,ISIZE	MAIN4250
25	AMASS(L)=BMASS(L)	MAIN4260
	CALL FAC(AMASS,ICOL,KROW,NDEX,IDET,MWRITE,NI,NIRREG,INUM)	MAIN4270
	CALL SOLV(AMASS,FMECH,DDELD,ICOL,KROW,NDEX,NI,NIRREG)	MAIN4280
	GO TO 31	MAIN4290
30	DO 32 I=1,NI	MAIN4300
32	DDELD(I)=0.0	MAIN4310
		MAIN4320

31 DO 33 I=1,NI  
 33 DISUM(I)=2.\*DTSQ\*DDELD(I)+6.\*DELD(I)+6.\*DISP(I)  
 MLOAD=NLOAD  
 DO 35 I=1,NI  
 FLR(I)=FMECH(I)  
 35 FLVM(I)=0.0  
 CALL OMULT(BMASS,DISUM,ICOL,NI,FLVM,KROW,NDEX,NIRREG)  
 DO 37 L=1,ISIZE  
 37 AMASS(L)=6.\*BMASS(L)+DTSQ\*(STIFK(L)+SPRIN(L))  
 CALL FAC(AMASS,ICOL,KROW,NDEX,IDET,MWRITE,NI,NIRREG,INUM)  
 ITT=1  
 TIME=ITT\*DELTAT  
 NLOAD=2  
 DO 69 I=1,NI  
 FLVA(I)=0.0  
 69 FMECH(I)=0.0  
 IF(TIME.LT.TBEGIN .OR. TIME.GT.TFINAL) GO TO 38  
 NLOAD=1  
 CALL LOADFT(TIME,NREADF,FMECH,AL)  
 38 DO 39 I=1,NI  
 39 FLVM(I)=DTSQ\*FMECH(I)+FLVM(I)  
 CALL SOLV(AMASS,FLVM,DIS,ICOL,KROW,NDEX,NI,NIRREG)  
 DO 61 I=1,NI  
 61 DELD(I)=DIS(I)-DISP(I)  
 330 DO 376 I=1,NI  
 DIS(I)=DISP(I)+DELD(I)  
 DISM1(I)=DTSQ\*DDELD(I)-DIS(I)+2.\*DISP(I)  
 376 CONTINUE  
 DO 100 L=1,ISIZE  
 100 AMASS(L)=2.\*BMASS(L)+DTSQ\*(STIFK(L)+SPRIN(L))  
 CALL FAC(AMASS,ICOL,KROW,NDEX,IDET,MWRITE,NI,NIRREG,INUM)  
 IF(MLOAD.EQ.2) GO TO 333  
 APD=0.0  
 DO 46 I=1,NI  
 46 APD=APD+FLR(I)\*DELD(I)  
 APDEN=APDEN+APD

MAIN4330  
 MAIN4340  
 MAIN4350  
 MAIN4360  
 MAIN4370  
 MAIN4380  
 MAIN4390  
 MAIN4400  
 MAIN4410  
 MAIN4420  
 MAIN4430  
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 MAIN4670  
 MAIN4680

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333  CONTINUE
      DO 1020 I=1,IKK
      EPSI (I) = 0.0
1020  EPSO (I) =0.0
      WRITE (MWRITE,8255) M2,NOP
8255  FORMAT('0THE FOLLOWING IS THE TIME SOLUTION OF AN EXTERNALLY LOADEMAIN4740
      @D STRUCTURE.',/,,' OUTPUT WILL BE PRINTED EVERY',I5,' CYCLES USINGMAIN4750
      @OUTPUT OPTION',I3,'.',/,,' REACTION FORCES APPLIED TO THE STRUCTUREMAIN4760
      @ WILL BE PRINTED AT EACH OUTPUT CYCLE',/,,' FOR NODES AT WHICH BOUNMAIN4770
      @DARY CONDITIONS ARE SPECIFIED. D.O.F. THAT ARE',/,,' NOT RESTRAINEDMAIN4780
      @D AT THAT NODE WILL HAVE A REACTION FORCE = 0.0.')
```

MAIN4790

```

      TIME = 0.0
      CALL PRINT (IT,TIME,HINN,HOUT,APDEN,SPRIN,BMASS,C2,
      @NQR,CINETO,BEP,WET,NV,ES,ASFL,SNS,NV1,NV2,NV3)
```

MAIN4800

```

1280  FORMAT(I5,3D20.13)
1281  FORMAT(4D20.13)
1282  FORMAT(3I5,2D20.13)
1283  FORMAT(2I5,2D20.13)
1284  FORMAT(4D20.13)
      READ(MREAD,1) ICONT
      IF(ICONT.NE.0) GOTO 127
      GOTO 120
```

MAIN4810  
MAIN4820  
MAIN4830  
MAIN4840  
MAIN4850  
MAIN4860  
MAIN4870  
MAIN4880  
MAIN4890  
MAIN4900  
MAIN4910

```

127  M=1+NBR
C  THESE ARE THE VALUES OF THE FOLLOWING VARIABLES TAKEN FROM A
C  PREVIOUS RUN OF THIS PROBLEM. THIS DATA WILL ALLOW A CONTINUATION
C  RUN TO BE MADE.
```

MAIN4920  
MAIN4930  
MAIN4940  
MAIN4950  
MAIN4960  
MAIN4970  
MAIN4980  
MAIN4990

```

      READ (MREAD,1280) ITT,TIME,T1,T2
      READ (MREAD,1281) AMP1FV,AMP1FW,AMP2FV,AMP2FW
      READ (MREAD,1281) SLOPEV,SLOPEW,APDEN,CINETO
      READ ( MREAD,1282) (IBIGA(L),ISTAA(L),ISURA(L),BIGA(L),BTIMA(L),L
      @=1,M)
      READ ( MREAD,1282) (IBIG(L),ISURF(L),ISTA(L),BIG(L),BTIME(L),L=1,M)
      READ ( MREAD,1283) (IBI(L),ISUR(L),BI(L),BTIM(L),L=1,M)
      READ ( MREAD,1284) (DISP(I),I=1,NI)
      READ ( MREAD,1284) (DELD(I),I=1,NI)
      READ ( MREAD,1284) (DIS (I),I=1,NI)
```

MAIN5000  
MAIN5010  
MAIN5020  
MAIN5030  
MAIN5040

READ( MREAD,1284) (DISM1(I),I=1,NI)	MAIN5050
READ( MREAD,1284) (FMECH(I),I=1,NI)	MAIN5060
READ( MREAD,1284) (FLVA(I),I=1,NI)	MAIN5070
READ( MREAD,1284) (((SNS(IR,J,K,L),L=1,MNSFL),K=1,NV2),J=1,NOGA)	MAIN5080
@,IR=1,IK)	MAIN5090
READ( MREAD,1284) (((SNP(IR,J,K,L),L=1,MNSFL),K=1,NV2),J=1,NOGA)	MAIN5100
@,IR=1,IK)	MAIN5110
WRITE(MWRITE,8611)	MAIN5120
8611 FORMAT('0 THIS IS A CONTINUATION RUN.')	MAIN5130
C START OF TIME SOLUTION	MAIN5140
120 ITT=ITT+1	MAIN5150
TIME=ITT*DELTAT	MAIN5160
45 DO 121 I=1,NI	MAIN5170
DISM3(I) = DISM2(I)	MAIN5180
DISM2(I) = DISM1(I)	MAIN5190
DISM1(I) = DISP(I)	MAIN5200
DISP(I) = DIS(I)	MAIN5210
FLR(I) = FMECH(I)	MAIN5220
FLN(I) = FLVA(I)	MAIN5230
FLVA(I) = 0.0	MAIN5240
FMECH(I) = 0.0	MAIN5250
FLVM(I) = 0.0	MAIN5260
121 DISUM(I) = 5.*DISP(I) - 4.*DISM1(I) + DISM2(I)	MAIN5270
IF(ICP.LE.0) GO TO 1277	MAIN5280
DO 128 K=1,4	MAIN5290
DISP(IK*4+K) = DISP(K)	MAIN5300
128 DELD(IK*4+K) = DELD(K)	MAIN5310
1277 CONTINUE	MAIN5320
345 CONTINUE	MAIN5330
MLOAD=NLOAD	MAIN5340
CALL STRESS(DELTAT,ASFL,GZETA,SNS,SNP,NV1,NV2,NV3)	MAIN5350
CALL OMULT(BMASS,DISUM,ICOL,NI,FLVM,KROW,NDEX,NIRREG)	MAIN5360
NLOAD=2	MAIN5370
IF(TIME.LT.TBEGIN .OR. TIME.GT.TFINAL) GO TO 122	MAIN5380
NLOAD=1	MAIN5390
CALL LOADPT(TIME,NREADF,FMECH,AL)	MAIN5400



122	DO 123 I=1,NI	MAIN5410
123	FLVM(I) = (FMECH(I) - (2.*FLVA(I) - FLN(I))) *DTSQ+FLVM(I)	MAIN5420
	IF(NBCOND.EQ. 0) GO TO 124	MAIN5430
	DO 125 I=1,NBCOND	MAIN5440
	JT4=NCDEB(I)*4	MAIN5450
	FLVM(JT4-3)=0.0	MAIN5460
	IF(NBC(I).EQ.1.OR. NBC(I).EQ.2) FLVM(JT4-1)=0.0	MAIN5470
	IF(NBC(I).EQ.2 .OR. NBC(I).EQ.3) FLVM(JT4-2)=0.0	MAIN5480
125	CONTINUE	MAIN5490
124	CALL SOLV(AMASS,FLVM,DIS,ICOL,KROW,NDEX,NI,NIRREG)	MAIN5500
	DO 126 I=1,NI	MAIN5510
126	DELD(I)=DIS(I)-DISP(I)	MAIN5520
	IF(MLOAD.EQ. 2) GO TO 41	MAIN5530
	APD=0.0	MAIN5540
	DO 42 I=1,NI	MAIN5550
42	APD=APD+FLR(I)*DELD(I)	MAIN5560
	APDEN=APDEN+APD	MAIN5570
41	IT=ITT-1	MAIN5580
	TIME=IT*DELTAT	MAIN5590
	DO 6701 I=1,IKK	MAIN5600
	ITHR(I) = 0	MAIN5610
	EPSI(I) = 0.0	MAIN5620
6701	EPSO(I) = 0.0	MAIN5630
	MIZ=0	MAIN5640
	NPZ= IT-NPZ1	MAIN5650
	IF(NPZ.NE.0) GOTO 6700	MAIN5660
	MIZ= 1	MAIN5670
	NPZ1 = NPZ1+M2	MAIN5680
	IF(LGSP.EQ.0) GOTO 6700	MAIN5690
	WRITE(MWRITE,11100)	MAIN5700
	WRITE(MWRITE,6705) IT	MAIN5710
6705	FORMAT('0 CYCLE=' , I8)	MAIN5720
	WRITE(MWRITE,6707)	MAIN5730
6707	FORMAT(' ELEMENT',9X,'SI',4X,'STA 1',4X,'SO',21X,'SI',4X,'STA 2',	MAIN5740
	* 4X,'SO',21X,'SI',4X,'STA 3', 4X,'SO')	MAIN5750
C	GAUSSIAN STATION STRAIN CALCULATION	MAIN5760

6700 DO 7161 IR=1,IK  
       K1= NVEC (IR,1)  
       K2= NVEC (IR,2)  
       LSS= MKE (IR)  
       DO 8018 K=1,8  
       INDEX= (K1-1)\*4+K  
       IF (K.GT.4) INDEX= (K2-1)\*4+K-4  
       DISM (K) = DISP (INDEX)  
 8018 CONTINUE  
       IF (YK (IR).EQ.0.0) GOTO 901  
           CALL ROTAT (1,DUMMY,DISM,IR)  
 901 CONTINUE  
       DO 604 I=1,NOGA  
       DO 604 J=1,3  
       BEPS (I,J) = 0.0  
       DO 604 K=1,8  
 604 BEPS (I,J)=BEPS (I,J)+BEP (IR,I,J,K)\* DISM (K)  
       NLAP= NLAY  
       IF (MKE (IR).GT.1) NLAP =1  
       H1= H (K1,1)  
       H2 = H (K2,1)  
       N=MKE (IR)-1  
       IF (YK (IR).EQ.1.0.AND.ROT (N,1).EQ.1.0) H (K1,1) = HTH (N)  
       IF (YK (IR).EQ.1.0.AND.ROT (N,1).EQ.0.0) H (K2,1) = HTH (N)  
       DO 8908 LM= 1,NLAP  
 8908 HDIF (LM) = H (K2,LM) - H (K1,LM)  
       DO 60 M=1,NOGA  
       HINN=0.0  
       HOUT = 0.0  
       IF (NLAY.EQ.1) GOTO 8931  
       IF (LREF-2) 8935,8936,8937  
 8935 HL1= (H (K1,1)+HDIF (1)\*AXG (M))/2.0  
       HL2= HL1+H (K1,2)+HDIF (2)\*AXG (M)  
       GOTO 8938  
 8936 HL1= -(H (K1,2)+HDIF (2)\*AXG (M))/2.0  
       HL2 = -HL1

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      IF (NLAP.EQ.2) HL2=0.0
      GOTO 8938
8937 HL2=- (H(K1,3)+HDIF(3)*AXG(M))/2.0
      HL1= HL2- (H(K1,2)+HDIF(2)*AXG(M))
8938 CONTINUE
      DO 8909 LM= 1,LREF
      DIVI= 1.0
      IF (LM.EQ.LREF) DIVI=2.0
      HINN= HINN+ (H(K1,LM)+ HDIF(LM)*AXG(M)) / DIVI
8909 CONTINUE
      DO 8911 LM= LREF,NLAP
      DIVI= 1.0
      IF (LM.EQ.LREF) DIVI=2.0
      HOUT= HOUT+ (H(K1,LM)+ HDIF(LM)* AXG(M)) / DIVI
8911 CONTINUE
      GOTO 8932
8931 HINN= (H(K1,1)+ HDIF(1)*AXG(M)) /2.0
      HOUT = HINN
      HL1= 0.0
      HL2= 0.0
8932 CONTINUE
      FARE= BEPS(M,1)+BEPS(M,2)**2/2.0
      *+BEPS(M,1)**2/2.
      IF (NTERF.EQ.0) GOTO 8939
      IF (NLAP.EQ.1) GOTO 8939
C   FOR MEMBRANE SET HL1 AND HL2 =0.0
      EPL1(M) = FARE+HL1*BEPS(M,3)
      EPL2(M) = FARE+HL2*BEPS(M,3)
      IF (NLAP.EQ.2) EPL2(M) = 0.0
      IF (EPL1(M).LE.BIGL) GOTO 8940
      BIGL= EPL1(M)
      IBIGL= IR
      ISTAL= M
      ISURFL=1
      BTIMEL= TIME
8940 IF (NLAY.EQ.2) GOTO 8939

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MAIN6130
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MAIN6460
MAIN6470
MAIN6480

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IF (EPL2(M).LE.BIGL) GOTO 8939  
 BIGL= EPL2(M)  
 IBIGL= IR  
 ISTAL= M  
 ISURFL=2  
 BTIMEL= TIME  
 8939 CONTINUE  
 C FOR MEMBRANE SET HINN AND HOUT =0.0  
 EPI(M) = FARE- HINN\*BEPS(M,3)  
 EPO(M) = FARE+HOUT\*BEPS(M,3)  
 IF(EPI(M).LE.BIG(LSS)) GO TO 591  
 BIG(LSS) = EPI(M)  
 IBIG(LSS) = IR  
 ISTA(LSS) = M  
 ISURF(LSS) = 1  
 BTIME(LSS) = TIME  
 591 IF (EPO(M).LE.BIG(LSS)) GO TO 1200  
 BIG(LSS) = EPO(M)  
 IBIG(LSS) = IR  
 ISTA(LSS) = M  
 ISURF(LSS) = 2  
 BTIME(LSS) = TIME  
 1200 CONTINUE  
 60 CONTINUE  
 C AVERAGE NODAL STRAIN CALCULATION  
 C AT A NODE WHERE A BRANCH ATTACHES TO THE MAIN STRUCTURE,  
 C THE BRANCH'S NODAL STRAIN IS NOT AVERAGED IN  
 DO 6604 I=1,2  
 DO 6604 J=1,3  
 BEPS(I,J) = 0.0  
 DO 6604 K=1,8  
 6604 BEPS(I,J) = BEPS(I,J) +DEP(IR,I,J,K) \* DISM(K)  
 FAR1 =BEPS(1,1)+BEPS(1,2)\*\*2/2.0 +BEPS(1,1)\*\*2/2.0  
 FAR2 =BEPS(2,1)+BEPS(2,2)\*\*2/2.0 +BEPS(2,1)\*\*2/2.0  
 NKE = MKE(IR)  
 NLAP = NLAY

MAIN6490  
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      IF (NKE.GT.1) NLAP=1
      IF (NLAP.EQ.1) GOTO 6631
      THI1= 0.0
      THO1 =0.0
      THI2= 0.0
      THO2= 0.0
      DO 6619 L=1, LREF
      DIVI= 1.0
      IF (L.EQ.LREF) DIVI=2.0
      THI1= THI1 + H(K1,L)/DIVI
6619  THI2= THI2+ H(K2,L)/DIVI
      DO 6620 L= LREF,NLAP
      DIVI=1.0
      IF (L.EQ.LREF) DIVI= 2.0
      THO1= THO1+ H(K1,L)/DIVI
6620  THO2= THO2+ H(K2,L)/DIVI
      GOTO 6622
6631  THI1= H(K1,1)/2.0
      THI2= H(K2,1)/2.0
      THO1= THI1
      THO2= THI2
6622  CONTINUE
      IF (NKE.EQ.1) GOTO 6605
      IF (MATT(NKE-1).EQ.K1) GOTO 6606
6605  ADEN = 1.0
      IF (ITHR(K1).GT.0) ADEN=2.0
      ITHR(K1) = 1
C   FOR MEMBRANE SET THI1,THO1,THI2,THO2=0.0
      EPSI(K1)=(EPSI(K1) + FAR1- THI1*BEPS(1,3)/2.0) /ADEN
      EPSO(K1) =(EPSO(K1) + FAR1+ THO1*BEPS(1,3)/2.0) /ADEN
      IF (NKE.EQ.1) GOTO 6606
      IF (MATT(NKE-1).EQ.K2) GOTO 6607
6606  ADEN = 1.0
      IF (ITHR(K2).GT.0) ADEN=2.0
      ITHR(K2) = 1
      EPSI(K2) =(EPSI(K2) + FAR2- THI2*BEPS(2,3)/2.0) /ADEN

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MAIN6850
MAIN6860
MAIN6870
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MAIN6990
MAIN7000
MAIN7010
MAIN7020
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MAIN7090
MAIN7100
MAIN7110
MAIN7120
MAIN7130
MAIN7140
MAIN7150
MAIN7160
MAIN7170
MAIN7180
MAIN7190
MAIN7200

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EPSO (K2) = (EPSO (K2) + FAR2+ THO2 \* BEPS(2,3) /2.0 ) /ADEN  
 6607 CONTINUE  
 H(K1,1) = H1  
 H(K2,1) = H2  
 IF (MIZ.NE.1) GO TO 7161  
 IF (LGSP.EQ.0) GO TO 7161  
 7940 WRITE(MWRITE,6710) IR, (EPI(L),EPO(L),L=1,3)  
 6710 FORMAT(' ',I3,2X,3(3X,D15.8,3X,D15.8,3X))  
 IF (NLAP.EQ.1) GOTO 7161  
 IF (NTERF.EQ.0) GOTO 7161  
 WRITE(MWRITE,6609) (EPL1(L),EPL2(L),L=1,3)  
 6609 FORMAT(' ',5X,3(3X,D15.8,3X,D15.8,3X))  
 7161 CONTINUE  
 C FIND LARGEST AVERAGE NODAL STRAIN  
 DO 7170 I= 1,IKK  
 N= 0  
 DO 7171 IR=1,IK  
 IF (NVEC(IR,1).NE.I) GOTO 7172  
 IF (MKE(IR).EQ.1) N= N+1  
 IF (MKE(IR).GT.1) N= N+3  
 IF (MKE(IR).GT.1) NKE=MKE(IR)  
 7172 CONTINUE  
 IF (NVEC(IR,2).NE.I) GOTO 7171  
 IF (MKE(IR).EQ.1) N=N+1  
 IF (MKE(IR).GT.1) N= N+3  
 IF (MKE(IR).GT.1) NKE= MKE(IR)  
 7171 CONTINUE  
 NK=1  
 IF (N.EQ.3.OR.N.EQ.6) NK=NKE  
 IF (EPSI(I).LE.BI(NK)) GOTO 7174  
 BI(NK) = EPSI(I)  
 IBI(NK) = I  
 ISUR(NK) = 1  
 BTIM(NK) = TIME  
 7174 IF (EPSO(I).LE.BI(NK)) GOTO 7170  
 BI(NK) = EPSO(I)

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IBI(NK) = I	MAIN7570
ISUR(NK) = 2	MAIN7580
BTIM(NK) = TIME	MAIN7590
7170 CONTINUE	MAIN7600
7180 CONTINUE	MAIN7610
IF(LSPP.EQ.0) GOTO 8562	MAIN7620
IF(MIZ.NE.1) GOTO 8700	MAIN7630
WRITE(MWRITE,6705) IT	MAIN7640
WRITE(MWRITE,8707)	MAIN7650
8707 FORMAT(' STRAIN AT ADDITIONAL POINTS',10X,'SI',18X,'SO',23X,'EI',	MAIN7660
@18X,'EO')	MAIN7670
8700 DO 8761 IR= 1,IK	MAIN7680
IF(LKK(IR,1).EQ.0) GOTO 8761	MAIN7690
NLAP= NLAY	MAIN7700
IF(MKE(IR).GT.1) NLAP =1	MAIN7710
K1 = NVEC(IR,1)	MAIN7720
K2= NVEC(IR,2)	MAIN7730
DO 8019 K=1,8	MAIN7740
INDEX= (K1-1)*4+K	MAIN7750
IF(K.GT.4) INDEX= (K2-1)*4+K-4	MAIN7760
DISM(K) = DISP(INDEX)	MAIN7770
8019 CONTINUE	MAIN7780
IF(YK(IR).EQ.0.0) GOTO 902	MAIN7790
CALL ROTAT(1,DUMMY,DISM,IR)	MAIN7800
902 CONTINUE	MAIN7810
H1= H(K1,1)	MAIN7820
H2 = H(K2,1)	MAIN7830
L= MKE(IR)	MAIN7840
N=MKE(IR)-1	MAIN7850
IF(YK(IR).EQ.1.0.AND.ROT(N,1).EQ.1.0) H(K1,1) = HTH(N)	MAIN7860
IF(YK(IR).EQ.1.0.AND.ROT(N,1).EQ.0.0) H(K2,1) = HTH(N)	MAIN7870
NO= LKK(IR,1)	MAIN7880
DO 8763 I= 1,NO	MAIN7890
IS = LKK(IR,I+1)	MAIN7900
DO 8604 J=1,3	MAIN7910
AEPS(J) = 0.0	MAIN7920

DO 8604 K= 1,8  
8604 AEPS (J)=AEPS (J) + AEP (IS, J, K) \*DISM(K)  
DO 8918 LM= 1,NLAP  
8918 HDIF (LM) = H (K2, LM) - H (K1, LM)  
HINN=0.0  
HOUT = 0.0  
IF (NLAP.EQ.1) GOTO 8941  
IF (LREF-2) 8735,8736,8737  
8735 HL1= (H (K1, 1)+HDIF (1) \*AXG (M)) /2.0  
HL2= HL1+ H (K1, 2)+HDIF (2) \*AXG (M)  
GOTO 8738  
8736 HL1= - (H (K1, 2) +HDIF (2) \*AXG (M)) /2.0  
HL2= -HL1  
IF (NLAP.EQ.2) HL2= 0.0  
GOTO 8738  
8737 HL2= - (H (K1, 3)+HDIF (3) \*AXG (M)) /2.0  
HL1= HL2- (H (K1, 2) +HDIF (2) \*AXG (M))  
8738 CONTINUE  
DO 8919 LM= 1,LREF  
DIVI= 1.0  
IF (LM.EQ.LREF) DIVI=2.0  
HINN= HINN+ (H (K1, LM) + HDIF (LM) \*AZET (IS)) / DIVI  
8919 CONTINUE  
DO 8921 LM= LREF,NLAP  
DIVI= 1.0  
IF (LM.EQ.LREF) DIVI=2.0  
HOUT= HOUT+ (H (K1, LM) + HDIF (LM) \* AZET (IS)) / DIVI  
8921 CONTINUE  
GOTO 8942  
8941 HINN= (H (K1, 1) +HDIF (1) \*AZET (IS)) / 2.0  
HOUT = HINN  
HL1= 0.0  
HL2= 0.0  
8942 CONTINUE  
FARE= AEPS (1) +AEPS (2) \*\*2/2.0+AEPS (1) \*\*2/2.0  
IF (NTERF.EQ.0) GOTO 8739

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MAIN8080  
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IF(NLAP.EQ.1) GOTO 8739  
 C FOR MEMBRANE SET HL1 AND HL2 =0.0  
 EPAS1= FARE+HL1\* AEPS(3)  
 EPAS2= FARE+HL2\*AEPS(3)  
 IF(NLAP.EQ.2) EPAS2= 0.0  
 IF(EPAS1.LE.BIGAL) GOTO 8740  
 BIGAL= EPAS1  
 IBIGAL= IR  
 ISTAAL= IS  
 BTIMAL= TIME  
 ISURAL= 1  
 8740 IF(NLAY.EQ.2) GOTO 8739  
 IF(EPAS2.LE.BIGAL) GOTO 8739  
 BIGAL= EPAS2  
 IBIGAL= IR  
 ISTAAL= IS  
 BTIMAL= TIME  
 ISURAL = 2  
 8739 CONTINUE  
 C FOR MEMBRANE SET HINN AND HOUT =0.0  
 EPASI = FARE- HINN\*AEPS(3)  
 EPASO = FARE+ HOUT\*AEPS(3)  
 C FIND LARGEST ADDITIONAL POINT STRAIN  
 IF(EPASI.LE.BIGA(L)) GO TO 8591  
 BIGA(L) = EPASI  
 IBIGA(L) = IR  
 ISTAA(L) = IS  
 BTIMA(L) = TIME  
 ISURA(L) = 1  
 8591 IF(EPASO.LE.BIGA(L)) GO TO 8780  
 BIGA(L) = EPASO  
 IBIGA(L) = IR  
 ISTAA(L) = IS  
 BTIMA(L) = TIME  
 ISURA(L) = 2  
 8780 IF(MIZ.NE.1) GO TO 8763

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EI= DSQRT(1.0+2.0\* EPASI) -1.0  
 EO= DSQRT(1.0+2.0\* EPASO) -1.0  
 WRITE(MWRITE,8781) IS,EPASI,EPASO,EI,EO  
 8781 FORMAT(' ',10X,I3,16X,D15.8,4X,D15.8,11X,D15.8,4X,D15.8)  
 IF(NLAP.EQ.1) GOTO 8763  
 IF(NTREF.EQ.0) GOTO 8763  
 WRITE(MWRITE,8609) EPAS1,EPAS2  
 8609 FORMAT(' ',29X,D15.8,4X,D15.8)  
 8763 CONTINUE  
 H(K1,1) = H1  
 H(K2,1) = H2  
 8761 CONTINUE  
 8562 CONTINUE  
 IF(IT.EQ.1) CALL PRINT(IT,TIME,HINN,HOUT,APDEN,SPRIN,BMASS,C2,  
 \*NQR,CINETO,BEP,WET,NV,ES,ASFL,SNS,NV1,NV2,NV3)  
 IF(IT-M1) 131,140,150  
 140 M1=M1+M2  
 CALL PRINT(IT,TIME,HINN,HOUT,APDEN,SPRIN,BMASS,C2,NQR,CINETO,  
 \*BEP,WET,NV,ES,ASFL,SNS,NV1,NV2,NV3)  
 IF(NBCOND.EQ.0) GOTO 1260  
 DO 1276 I=1,NI  
 QDD(I) = (2.0\*DISP(I)-5.0\*DISM1(I)+4.0\*DISM2(I)-DISM3(I))/DTSQ  
 REAFM(I) = 0.0  
 REAFK(I) = 0.0  
 1276 CONTINUE  
 CALL OMULT(REACM,QDD,ICOL,NI,REAFM,KROW,NDEX,NIRREG)  
 CALL OMULT(REACK,DISP,ICOL,NI,REAFK,KROW,NDEX,NIRREG)  
 DO 1261 I=1,21  
 1261 REAC(I) = 0.0  
 DO 1262 I=1,NBCOND  
 J= NODEB(I)\*4  
 K= (I-1)\*3  
 REAC(K+1)= REAFM(J-3)+REAFK(J-3)-(FLR(J-3)-FLVA(J-3))  
 IF(NBC(I).EQ.1.OR.NBC(I).EQ.2) REAC(K+3)=REAFM(J-1)+REAFK(J-1)-  
 @ (FLR(J-1)-FLVA(J-1))  
 IF(NBC(I).EQ.2.OR.NBC(I).EQ.3) REAC(K+2)=REAFM(J-2)+REAFK(J-2)-

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@ (FLR (J-2) -FLVA (J-2))	MAIN9010
1262 CONTINUE	MAIN9020
WRITE (MWRITE,1256)	MAIN9030
1256 FORMAT (' 0',6X,'REACTIONS AT NODE',15X,'RV (LBS)',13X,'RW (LBS)',	MAIN9040
@ 11X,'RM (IN-LBS)')	MAIN9050
DO 1252 I=1,NBCOND	MAIN9060
J= (I-1) *3	MAIN9070
WRITE (MWRITE,1253) NODEB(I), REAC (J+1),REAC (J+2),REAC (J+3)	MAIN9080
1253 FORMAT (' ',18X,I4,5X,3D20.6)	MAIN9090
1252 CONTINUE	MAIN9100
1260 CONTINUE	MAIN9110
M=NR+1	MAIN9120
WRITE (MWRITE,66)	MAIN9130
WRITE (MWRITE,67) (L,BIG (L),IBIG (L),ISURF (L),ISTA (L),BTIME (L),L=1,M)	MAIN9140
IF (NTERF.EQ.0) GOTO 1272	MAIN9150
WRITE (MWRITE,1270) BIGL,IBIGL,ISURFL,ISTAL,BTIMEL	MAIN9160
1270 FORMAT (' INTERFACE',4X,D15.6,1X,I4,4X,I4,4X,I4,4X,D15.6)	MAIN9170
1272 CONTINUE	MAIN9180
IF (LSPP.NE.1) GO TO 8782	MAIN9190
WRITE (MWRITE,6030)	MAIN9200
WRITE (MWRITE,6035) (L,BIGA (L),IBIGA (L),ISTAA (L),BTINA (L),ISURA (L),	MAIN9210
@ L=1,M)	MAIN9220
IF (NTERF.EQ.0) GOTO 1273	MAIN9230
WRITE (MWRITE,1271) BIGAL,IBIGAL,ISTAAL,BTIMAL,ISURAL	MAIN9240
1271 FORMAT (' INTERFACE',14X,D15.6,7X,I3,6X,I5,5X,D15.6,6X,I4)	MAIN9250
1273 CONTINUE	MAIN9260
8782 CONTINUE	MAIN9270
WRITE (MWRITE,7181)	MAIN9280
WRITE (MWRITE,7182) (L,BI (L),IBI (L),ISUR (L),BTIN (L),L=1,M)	MAIN9290
7181 FORMAT (' 0SUBSTRUCTURE',5X,'LARGEST NODAL STRAIN ',5X,'NODE',7X,	MAIN9300
@ 'SURF',11X,'TIME')	MAIN9310
7182 FORMAT (' ',4X,I3,16X,D15.6,7X,I3,6X,I5,5X,D15.6)	MAIN9320
WRITE (MWRITE,11100)	MAIN9330
11100 FORMAT (' 0*****MAIN9340	
@ *****MAIN9350	
@ *****',/)	MAIN9360

131	IF(IT-MM) 120,170,150	MAIN9370
170	CONTINUE	MAIN9380
	WRITE(MWRITE,6002)	MAIN9390
6002	FORMAT(' OTHE LARGEST COMPUTED STRAINS FOR EACH SUBSTRUCTURE--	MAIN9400
	@ MAIN AND BRANCHES -- ARE PRINTED BELOW, 1= INNER 2= OUTER SURF')	MAIN9410
	M= NBR+1	MAIN9420
	WRITE(MWRITE,66)	MAIN9430
	WRITE(MWRITE,67) (L,BIG(L),IBIG(L),ISURF(L),ISTA(L),BTIME(L),L=1,M)	MAIN9440
66	FORMAT(' OSUBSTRUCTURE',8X,'MSTR',7X,'ELE',5X,'SURF',5X,'STA',	MAIN9450
	@ 9X,'TIME')	MAIN9460
67	FORMAT(' ',3X,I4,6X,D15.6,1X,I4,4X,I4,4X,I4,4X,D15.6)	MAIN9470
	IF(NTERF.EQ.0) GOTO 1274	MAIN9480
	WRITE(MWRITE,1270) BIGL,IBIGL,ISURFL,ISTAL,BTIMEL	MAIN9490
1274	CONTINUE	MAIN9500
	IF(LSPP.NE.1) GOTO 149	MAIN9510
	WRITE(MWRITE,6030)	MAIN9520
	WRITE(MWRITE,6035) (L,BIGA(L),IBIGA(L),ISTAA(L),BTIMA(L),ISURA(L),	MAIN9530
	@ L=1,M)	MAIN9540
6030	FORMAT(' OSUBSTRUCTURE',5X,'LARGEST ADD. PT. STRAIN',5X,'ELEM',5X,	MAIN9550
	@ 'ADD. PT.',9X,'TIME',10X,'SURFACE')	MAIN9560
6035	FORMAT(' ',4X,I3,16X,D15.6,7X,I3,6X,I5,5X,D15.6,6X,I4)	MAIN9570
	IF(NTERF.EQ.0) GOTO 1275	MAIN9580
	WRITE(MWRITE,1271) BIGAL,IBIGAL,ISTAML,BTIMAL,ISURAL	MAIN9590
1275	CONTINUE	MAIN9600
149	CONTINUE	MAIN9610
	WRITE(MWRITE,7181)	MAIN9620
	WRITE(MWRITE,7182) (L,BI(L),IBI(L),ISUR(L),BTIM(L),L=1,M)	MAIN9630
150	IF(MPU.EQ.0) GOTO 160	MAIN9640
	M= NBR+1	MAIN9650
	WRITE(MPUNCH,1280) ITT,TIME,T1,T2	MAIN9660
	WRITE(MPUNCH,1281) AMP1FV,AMP1FW,AMP2FV,AMP2FW	MAIN9670
	WRITE(MPUNCH,1281) SLOPEV,SLOPEW,APDEN,CINETO	MAIN9680
	WRITE(MPUNCH,1282) (IBIGA(L),ISTAA(L),ISURA(L),BIGA(L),BTIMA(L),L	MAIN9690
	@ =1,M)	MAIN9700
	WRITE(MPUNCH,1282) (IBIG(L),ISURF(L),ISTA(L),BIG(L),BTIME(L),L=1,M)	MAIN9710
	WRITE(MPUNCH,1283) (IBI(L),ISUR(L),BI(L),BTIM(L),L=1,M)	MAIN9720

WRITE (MPUNCH,1284) (DISP(I),I=1,NI)	MAIN9730
WRITE (MPUNCH,1284) (DELD(I),I=1,NI)	MAIN9740
WRITE (MPUNCH,1284) (DIS (I),I=1,NI)	MAIN9750
WRITE (MPUNCH,1284) (DISM1 (I),I=1,NI)	MAIN9760
WRITE (MPUNCH,1284) (FMECH (I),I=1,NI)	MAIN9770
WRITE (MPUNCH,1284) (FLVA (I) ,I=1,NI)	MAIN9780
WRITE (MPUNCH,1284) ((( (SNS(IR,J,K,L) ,L=1,MNSFL) ,K=1,NV2) ,J=1,NOGA)	MAIN9790
@,IR=1,IK )	MAIN9800
WRITE (MPUNCH,1284) ((( (SNP (IR,J,K,L) ,L=1,MNSFL) ,K=1,NV2) ,J=1,NOGA)	MAIN9810
@,IR=1,IK )	MAIN9820
GOTO 162	MAIN9830
160 WRITE (MWRITE,161)	MAIN9840
161 FORMAT('OTHER ARE NO CARDS PUNCHED FOR CONTINUATION')	MAIN9850
162 IF (ICON.EQ.0) GOTO 151	MAIN9860
IRRUN = IRRUN +1	MAIN9870
GO TO 5555	MAIN9880
151 CALL EXIT	MAIN9890
END	MAIN9900

SUBROUTINE IMPULS(NV,DELTAT,AL,SNS,SNP,NV1,NV2,NV3)  
 IMPLICIT REAL\*8(A-H,O-Z)  
 DIMENSION SNS(NV1,3,NV2,NV3),SNP(NV1,3,NV2,NV3)  
 DIMENSION AL(50)  
 COMMON/MAT/YOUNG(3,6),DS(3,6),SNO(3,5,6),NSFL(3,6),P(3,6),NLAY  
 COMMON /FG/ IK,IKK,ICP,LREF,NOGA,NFL,NI,ICOL(205),INUM(205)  
 \*,NBCOND,NBC(7),NODEB(7),KROW(8),NDEX(8),NIRREG  
 COMMON/VQ/ FLVA(205),DISP(205),DELD(205),BINP(50,3),BIMP(50,3)  
 COMMON /TAPE/ MREAD,MWRITE,MPUNCH  
 COMMON /TAM/ MKE(51)  
 SIN(Q)=DSIN(Q)  
 COS(Q)=DCOS(Q)  
 DO 50 I=1,NI  
 DELD(I)=0.0  
 50 DISP(I)=0.0  
 DO 51 IR=1,IK  
 NLAP= NLAY  
 IF(MKE(IR).GT.1) NLAP=1  
 NO = MKE(IR)  
 DO 51 J=1,NOGA  
 BIMP(IR,J)=0.0  
 BIMP(IR,J)=0.0  
 DO 51 M=1,NLAP  
 NSFLM=NSFL(M,NO)  
 DO 51 N=1,NFL  
 K=N+(M-1)\*NFL  
 DO 51 L=1,NSFLM  
 SNP(IR,J,K,L)=0.0  
 51 SNS(IR,J,K,L)=0.0  
 READ(MREAD,1) NV,IOTA,IOTB,IOTC  
 1 FORMAT(4I5)  
 WRITE(MWRITE,2) DELTAT  
 2 FORMAT(/,' TIME STEP SIZE USED IN PROGRAM (SEC) =',E15.6)  
 IF(NV.EQ.0) WRITE(MWRITE,4)  
 IF(NV.GT.0) WRITE(MWRITE,6)  
 4 FORMAT(/,' THERE IS NO INITIAL IMPULSE ')

IMPU0010  
 IMPU0020  
 IMPU0030  
 IMPU0040  
 IMPU0050  
 IMPU0060  
 IMPU0070  
 IMPU0080  
 IMPU0090  
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 IMPU0200  
 IMPU0210  
 IMPU0220  
 IMPU0230  
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 IMPU0260  
 IMPU0270  
 IMPU0280  
 IMPU0290  
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6   FORMAT(/,'      IMPULSE LOADINGS HAVE BEEN SPECIFIED AS DESCRIBED BYIMPU0370
* INPUT ')                                IMPU0380
    IF(NV .EQ. 0) GO TO 43                  IMPU0390
    IF(IOTA .EQ.0) GO TO 10                 IMPU0400
    WRITE(MWRITE,100) IOTA                  IMPU0410
100  FORMAT('0',I4,'      LOCAL INITIAL NORMAL VELOCITY FIELDS ARE DESCRIBIMPU0420
    @ED BELOW:','//',' FIRST ELEM',5X,'TOTAL ELEMS',10X,'WRAD',15X,'WRAD1IMP
    @',15X,'ANGV1',15X,'WRAD2',15X,'ANGV2') IMPU0440
    DO 20 IM=1,IOTA                        IMPU0450
    READ(MREAD,21) IE1,IE2,WRAD,WRAD1,ANGV1,WRAD2,ANGV2 IMPU0460
21   FORMAT(2I5/5E15.6)                   IMPU0470
    WRITE(MWRITE,105) IE1,IE2,WRAD,WRAD1,ANGV1,WRAD2,ANGV2 IMPU0480
105  FORMAT(' ',I6,13X,I3,9X,D13.6,8X,D13.6,7X,D13.6,7X,D13.6,7X,D13.6) IMPU0490
    IE2M1=IE2-1                            IMPU0500
    DO 22 II=1,IE2M1                      IMPU0510
    I=IE1+II                              IMPU0520
    IF(ICP.LE.0) GO TO 22                  IMPU0530
    IF(I .GT. IK) I=I-IK                  IMPU0540
22   DELD(I*4-2)=DELTAT*WRAD              IMPU0550
    DELD(IE1*4-2)=DELTAT*WRAD1            IMPU0560
    DELD(IE1*4-1)=DELTAT*ANGV1            IMPU0570
    IE2P1=IE1+IE2                         IMPU0580
    IF(ICP.LE. 0) GO TO 23                IMPU0590
    IF(IE2P1 .GT. IK) IE2P1=IE2P1-IK      IMPU0600
23   DELD(IE2P1*4-2)=DELTAT*WRAD2        IMPU0610
    DELD(IE2P1*4-1)=DELTAT*ANGV2        IMPU0620
20   CONTINUE                            IMPU0630
10   IF(IOTB .EQ. 0) GO TO 41              IMPU0640
    WRITE(MWRITE,110) IOTB                IMPU0650
110  FORMAT('0',I4,'      NODAL VELOCITY IMPULSES ARE DESCRIBED BELOW:', IMPU0660
    @//,' NCDE',10X,'VRAD',20X,'WRAD',20X,'ANGV') IMPU0670
    DO 30 IM=1,IOTB                      IMPU0680
    READ(MREAD,31) NODEV,VRAD,WRAD,ANGV IMPU0690
31   FORMAT(I5,3E15.6)                   IMPU0700
    WRITE(MWRITE,115) NODEV,VRAD,WRAD,ANGV IMPU0710
115  FORMAT(' ',I3,6X,D13.6,11X,D13.6,11X,D13.6) IMPU0720

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	DELD(NODEV*4-3)=DELTAT*VRAD	IMPU0730
	DELD(NODEV*4-2)=DELTAT*WRAD	IMPU0740
	DELD(NODEV*4-1)=DELTAT*ANGV	IMPU0750
30	CONTINUE	IMPU0760
41	IF(IOTC.EQ.0) GO TO 60	IMPU0770
	WRITE(MWRITE,120) IOTC	IMPU0780
120	FORMAT('0',I4,' SINE SHAPED VELOCITY FIELDS ARE DESCRIBED BELOW:')	IMPU0790
	@,/,/, ' FIRST ELEM',5X,'TOTAL ELEMS',10X,'WRAD')	IMPU0800
	DO 61 IM=1,IOTC	IMPU0810
	READ(MREAD,62) IS1,IS2,WRAD	IMPU0820
62	FORMAT(2I5,E15.6)	IMPU0830
	WRITE(MWRITE,125) IS1,IS2,WRAD	IMPU0840
125	FORMAT(' ',I6,13X,I3,9X,D13.6)	IMPU0850
	TX=0.0	IMPU0860
	DO 65 NN=1,IS2	IMPU0870
	NE=(IS1-1)+NN	IMPU0880
	IF(NE.GT.IK) NE=NE-IK	IMPU0890
65	TX=TX+AL(NE)	IMPU0900
	PIEP=3.14159265/TX	IMPU0910
	DELD(IS1*4-1)=WRAD*DELTAT*PIEP	IMPU0920
	XX=0.0	IMPU0930
	DO 63 II=1,IS2	IMPU0940
	I=IS1+II	IMPU0950
	NE=I-1	IMPU0960
	IF(ICP.LE.0) GO TO 66	IMPU0970
	IF(I.GT.IK) I=I-IK	IMPU0980
66	IF(NE.GT.IK) NE=NE-IK	IMPU0990
	XX=XX+AL(NE)	IMPU1000
	DELD(I*4-2)=WRAD*DELTAT*SIN(PIEP*XX)	IMPU1010
63	DELD(I*4-1)=WRAD*DELTAT*PIEP*COS(PIEP*XX)	IMPU1020
61	CONTINUE	IMPU1030
60	IF(NBCOND.EQ.0) GO TO 43	IMPU1040
	DO 40 I=1,NBCOND	IMPU1050
	JT4=NODEB(I)*4	IMPU1060
	DELD(JT4-3)=0.0	IMPU1070
	IF(NBC(I).EQ.1.CR. NBC(I).EQ.2) DELD(JT4-1)=0.0	IMPU1080



40 IF (NBC(I).EQ.2 .OR. NBC(I).EQ.3) DELD(JT4-2)=0.0  
CCONTINUE  
43 CONTINUE  
IF(ICP.LE.0) GO TO 45  
DO 44 K=1,4  
DISP(IK\*4+K)=DISP(K)  
44 DELD(IK\*4+K)=DELD(K)  
45 CONTINUE  
RETURN  
END

IMPU1090  
IMPU1100  
IMPU1110  
IMPU1120  
IMPU1130  
IMPU1140  
IMPU1150  
IMPU1160  
IMPU1170  
IMPU1180

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SUBROUTINE LOADEQ(AL,AXG,AWG,TBEGIN,TFINAL)
C   TO FIND GENERALIZED NODAL LOAD AND EXTERNALLY-APPLIED LOAD TRANS-
C   FORMATION MATRICES
IMPLICIT REAL*8(A-H,O-Z)
DIMENSION FM(8,2),AL(1),AXG(1),AWG(1),A(8,8),LMI(8),MMI(8)
*,FMA(8,2),FMB(8,2),BNG(51)
COMMON/MAT/YOUNG(3,6),DS(3,6),SNO(3,5,6),NSFL(3,6),P(3,6),NLAY
COMMON /FG/ IK,IKK,ICP,LREF,NOGA,NFL,NI,ICOL(205),INUM(205)
*,NBCOND,NBC(7),NODEB(7),KROW(8),NDEX(8),NIRREG
COMMON/FC/ Y(51),Z(51),ANG(51),H(51,3)
COMMON /FORCE/ T1,AMP1FV,AMP1FW,T2,AMP2FV,AMP2FW,SLOPEV,SLOPEW,
*AMPFV,AMPFW,ETA(4),RTOV(4),RTOW(4),RTO2V(4),RTO2W(4),RTO3V(4),
*RTO3W(4),FM1(4,8,2),FM2(2,4,8,2),FM3A(2,4,8,2),FM3B(2,4,8,2),
*NOFT1,NOFT2,NOFT3,JELEM(4),NSTF2(4),NELF2(4),NSTF3(4),NELF3(4)
COMMON/BOUN/ YK(51),NBCONB,NBCB(7),NGDBB(7),MK(51),ROT(5,2)
*,XDIST(6),DROT(50),NODEF(6)
COMMON /TAM/ MKE(51)
COMMON /TAPE/ MREAD,MWRITE,MPUNCH
COMMON /BR/ NVEC(51,2) , LMT(51)
SIN(Q)=DSIN(Q)
COS(Q)=DCOS(Q)
ATAN(Q)=DATAN(Q)
IF(TFINAL.EQ.0.0) RETURN
WRITE(MWRITE,47) TBEGIN,TFINAL
47  FORMAT('0  STARTING TIME OF FORCING FUNCTION (SEC) =',E15.6,/,
*  STOPPING TIME OF FORCING FUNCTION (SEC) =',E15.6)
WRITE(MWRITE,440) TBEGIN,AMP1FV,AMP1FW
440  FORMAT('0AT TIME',D15.6,' TANGENTIAL FORCE=',D15.6,5X,' NORMAL FO
@RCE=',D15.6,/)
READ(MREAD,6) NOFT1,NOFT2,NOFT3
6  FORMAT(3I5)
7  FORMAT(I5,3D15.6)
8  FORMAT(2I5,2D15.6)
IF(NOFT1.EQ.0) GO TO 54
WRITE(MWRITE,1001)
1001  FCRMAT('0DESCRIPTION OF POINT FORCES:')

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LODQ0010
LODQ0020
LODQ0030
LODQ0040
LODQ0050
LODQ0060
LODQ0070
LODQ0080
LODQ0090
LODQ0100
LODQ0110
LODQ0120
LODQ0130
LODQ0140
LODQ0150
LODQ0160
LODQ0170
LODQ0180
LODQ0190
LODQ0200
LODQ0210
LODQ0220
LODQ0230
LODQ0240
LODQ0250
LODQ0260
LODQ0270
LODQ0280
LODQ0290
LODQ0300
LODQ0310
LODQ0320
LODQ0330
LODQ0340
LODQ0350
LODQ0360

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WRITE(MWRITE,1005)
1005 FORMAT('OELEMENT',13X,'S COORDINATE',12X,'RTOV',16X,'RTOW')
      READ(MREAD,7) (JELEM(I),ETA(I),RTOV(I),RTOW(I),I=1,NOFT1)
      WRITE(MWRITE,1000) (JELEM(I),ETA(I),RTOV(I),RTOW(I),I=1,NOFT1)
1000 FORMAT(' ',I4,10X,3D20.6)
      DO 100 I=1,NOFT1
        NE=JELEM(I)
        SL=ETA(I)
        I= MKE(NE) -1
        K1 = NVEC(NE,1)
        K2 = NVEC(NE,2)
        P5=Z(K2)-Z(K1)
        P6=Y(K2)-Y(K1)
        P7=ANG(K2) -ANG(K1)
        IF(YK(NE).EQ.1.0) P7=ANG(K2) - ROT(L,2) -ANG(K1)
        IF(YK(NE).EQ.1.0.AND.ROT(L,1).EQ.0.0) P7=ROT(L,2)+ANG(K2)-ANG(K1)
        IF(YK(NE).EQ.2.0) P7= ANG(K2)- DROT(NE) - ANG(K1)
        IF(YK(NE).EQ.3.0) P7=ROT(L,2)+ANG(K2)-DROT(NE)-ANG(K1)
        PIE= 3.141592653589793D+00
        PIE2= 2.0*PIE
        PIE32= 1.5 *PIE
        ANG2=ANG(K2)
        ANG1=ANG(K1)
        IF(YK(NE).EQ.1.0.AND.ROT(L,1).EQ.0.0) ANG(K2)=ROT(L,2)+ANG(K2)
        IF(YK(NE).EQ.1.0.AND.ROT(L,1).EQ.1.0) ANG(K1)=ROT(L,2)+ANG(K1)
        IF(YK(NE).EQ.2.0) ANG(K1)= DROT(NE) + ANG(K1)
        IF(YK(NE).EQ.3.0) ANG(K2)= ROT(L,2)+ANG(K2)
        IF(YK(NE).EQ.3.0) ANG(K1)= DROT(NE)+ANG(K1)
        APHA = PIE / 2.0
        IF(P5.LT.0.0) APHA= -APHA
        IF(P6.NE.0.0) APHA= ATAN(P5/P6)
        IF(P6.LT.0.0.AND.P5.LT.0.0) APHA=APHA-PIE
        IF(P6.LT.0.0 .AND. P5.GE.0.0) APHA=APHA+PIE
        BNG(NE+1)=ANG(K2)
        BNG(NE)=ANG(K1)
        IF(P7.GT.(PIE32).AND.APHA.LT.0.0) BNG(NE+1)=ANG(K2)-PIE2

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LODQ0370
LODQ0380
LODQ0390
LODQ0400
LODQ0410
LODQ0420
LODQ0430
LODQ0440
LODQ0450
LODQ0460
LODQ0470
LODQ0480
LODQ0490
LODQ0500
LODQ0510
LODQ0520
LODQ0530
LODQ0540
LODQ0550
LODQ0560
LODQ0570
LODQ0580
LODQ0590
LODQ0600
LODQ0610
LODQ0620
LODQ0630
LODQ0640
LODQ0650
LODQ0660
LODQ0670
LODQ0680
LODQ0690
LODQ0700
LODQ0710
LODQ0720

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IF (P7.GT. (PIE32 ).AND.APHA.GT.0.0) BNG (NE)=ANG (K1)+PIE2
IF (P7.LT. (-PIE32 ).AND.APHA.GT.0.0) BNG (NE+1)=ANG (K2) +PIE2
IF (P7.LT. (-PIE32 ).AND.APHA.LT.0.0) BNG (NE)=ANG (K1)-PIE2
  BZER=BNG (NE)-APHA
  B1=(-2.*BNG (NE+1)-4.*BNG (NE)+6.*APHA)/AL (NE)
  B2=(3.*BNG (NE+1)+3.*BNG (NE)-6.*APHA)/AL (NE)**2
ANG (K2)= ANG2
ANG (K1)= ANG1
DO 400 K=1,8
  DO 400 J=1,8
400 A (K,J) = 0.0
  A (1,1)= COS (BNG (NE)-APHA)
  A (1,2)= SIN (BNG (NE)-APHA)
  A (2,1)=-SIN (BNG (NE)-APHA)
  A (2,2)= COS (BNG (NE)-APHA)
  A (3,3)=1.
  A (5,1)=COS (BNG (NE+1)-APHA)
  A (5,2)=SIN (BNG (NE+1)-APHA)
  A (5,3)=P6*SIN (BNG (NE+1)) -P5*COS (BNG (NE+1))
  A (6,1)=-SIN (BNG (NE+1)-APHA)
  A (6,2)=COS (BNG (NE+1)-APHA)
  A (6,3)=P6*COS (BNG (NE+1)) +P5*SIN (BNG (NE+1))
  A (7,3)=1.
  A (4,4)=1.
  A (5,4)=AL (NE)
  A (5,7)=AL (NE)**2
  A (5,8)=AL (NE)**3
  A (6,5)=AL (NE)**2
  A (6,6)=AL (NE)**3
  P8=B1+2.*B2*AL (NE)
  A (7,4)=AL (NE)*P8
  A (7,5)=2.*AL (NE)
  A (7,6)=3.*AL (NE)**2
  A (7,7)=AL (NE)**2*P8
  A (7,8)=AL (NE)**3*P8
  A (8,4)=1.

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LODQ0730
LODQ0740
LODQ0750
LODQ0760
LODQ0770
LODQ0780
LODQ0790
LODQ0800
LODQ0810
LODQ0820
LODQ0830
LODQ0840
LODQ0850
LODQ0860
LODQ0870
LODQ0880
LODQ0890
LODQ0900
LODQ0910
LODQ0920
LODQ0930
LODQ0940
LODQ0950
LODQ0960
LODQ0970
LODQ0980
LODQ0990
LODQ1000
LODQ1010
LODQ1020
LODQ1030
LODQ1040
LODQ1050
LODQ1060
LODQ1070
LODQ1080

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	A(8,5)=-AL(NE)**2*P8	LODQ1090
	A(8,6)=-AL(NE)**3*P8	LODQ1100
	A(8,7)=2.*AL(NE)	LODQ1110
	A(8,8)=3.*AL(NE)**2	LODQ1120
	CALL MINV(A,8,DET,LMI,MMI)	LODQ1130
	PHI=BZER+B1*SL+B2*SL**2	LODQ1140
	PHIP=B1+2.*B2*SL	LODQ1150
	YZET=0.0	LODQ1160
	ZZET=0.0	LODQ1170
	DO 101 JJ=1,NGGA	LODQ1180
	P2=BZER+B1*SL*AXG(JJ)+B2*(SL*AXG(JJ))**2+APHA	LODQ1190
	YZET=YZET+COS(P2)*SL*AWG(JJ)	LODQ1200
101	ZZET=ZZET+SIN(P2)*SL*AWG(JJ)	LODQ1210
	P3=YZET*SIN(PHI+APHA)-ZZET*COS(PHI+APHA)	LODQ1220
	P4=YZET*COS(PHI+APHA)+ZZET*SIN(PHI+APHA)	LODQ1230
	FM(1,1)=COS(PHI)	LODQ1240
	FM(2,1)=SIN(PHI)	LODQ1250
	FM(1,2)=-SIN(PHI)	LODQ1260
	FM(2,2)=COS(PHI)	LODQ1270
	FM(3,1)=P3	LODQ1280
	FM(3,2)=P4	LODQ1290
	FM(4,1)=SL	LODQ1300
	FM(4,2)=0.0	LODQ1310
	FM(5,1)=0.0	LODQ1320
	FM(5,2)=SL**2	LODQ1330
	FM(6,1)=0.0	LODQ1340
	FM(6,2)=SL**3	LODQ1350
	FM(7,1)=SL**2	LODQ1360
	FM(7,2)=0.0	LODQ1370
	FM(8,1)=SL**3	LODQ1380
	FM(8,2)=0.0	LODQ1390
	DO 102 M=1,8	LODQ1400
	DO 102 N=1,2	LODQ1410
	FM1(I,M,N)=0.0	LODQ1420
	DO 102 K=1,8	LODQ1430
102	FM1(I,M,N)=FM1(I,M,N)+A(K,M)*FM(K,N)	LODQ1440

100	CONTINUE	LODQ1450
54	IF(NOFT2.EQ. 0) GO TO 55	LODQ1460
	WRITE(MWRITE,1010)	LODQ1470
1010	FORMAT('0DESCRIPTION OF RECTANGULAR SHAPED FORCES:')	LODQ1480
	WRITE(MWRITE,1011)	LODQ1490
1011	FORMAT('0FIRST ELEMENT',5X,'NO. OF ELEMS.',10X,'RTO2V',17X,'RTO2W'	LODQ1500
	@)	LODQ1510
	READ(MREAD,8) (NSTF2(I),NELF2(I),RTO2V(I),RTO2W(I),I=1,NOFT2)	LODQ1520
	WRITE(MWRITE,1015) (NSTF2(I),NELF2(I),RTO2V(I),RTO2W(I),I=1,NOFT2)	LODQ1530
1015	FORMAT(5X,I4,13X,I4,12X,D13.6,10X,D13.6)	LODQ1540
	DO 200 I=1,NOFT2	LODQ1550
	NSTAT=NSTF2(I)	LODQ1560
	NEND=NELF2(I)	LODQ1570
	DO 201 NN=1,NEND	LODQ1580
	NE=(NSTAT-1)+NN	LODQ1590
	IF(NE.GT. IK) NE=NE-1K	LODQ1600
	L= MKE(NE) -1	LODQ1610
	K1 = NVEC(NE,1)	LODQ1620
	K2 = NVEC(NE,2)	LODQ1630
	P5=Z(K2)-Z(K1)	LODQ1640
	P6=Y(K2)-Y(K1)	LODQ1650
	P7=ANG(K2) -ANG(K1)	LODQ1660
	IF(YK(NE).EQ.1.0) P7=ANG(K2) - ROT(L,2) -ANG(K1)	LODQ1670
	IF(YK(NE).EQ.1.0.AND.ROT(L,1).EQ.0.0) P7=ROT(L,2)+ANG(K2)-ANG(K1)	LODQ1680
	IF(YK(NE).EQ.2.0) P7= ANG(K2)- DROT(NE) - ANG(K1)	LODQ1690
	IF(YK(NE).EQ.3.0) P7=ROT(L,2)+ANG(K2)-DROT(NE)-ANG(K1)	LODQ1700
	PIE= 3.141592653589793D+00	LODQ1710
	PIE2= 2.0*PIE	LODQ1720
	PIE32= 1.5 *PIE	LODQ1730
	ANG2=ANG(K2)	LODQ1740
	ANG1=ANG(K1)	LODQ1750
	IF(YK(NE).EQ.1.0.AND.ROT(L,1).EQ.0.0) ANG(K2)=ROT(L,2)+ANG(K2)	LODQ1760
	IF(YK(NE).EQ.1.0.AND.ROT(L,1).EQ.1.0) ANG(K1)=ROT(L,2)+ANG(K1)	LODQ1770
	IF(YK(NE).EQ.2.0) ANG(K1)= DROT(NE) + ANG(K1)	LODQ1780
	IF(YK(NE).EQ.3.0) ANG(K2)= ROT(L,2)+ANG(K2)	LODQ1790
	IF(YK(NE).EQ.3.0) ANG(K1)= DROT(NE)+ANG(K1)	LODQ1800

APHA = PIE / 2.0	LODQ1810
IF (P5.LT.0.0) APHA= -APHA	LODQ1820
IF (P6.NE.0.0) APHA= ATAN (P5/P6)	LODQ1830
IF (P6.LT.0.0.AND.P5.LT.0.0) APHA=APHA-PIE	LODQ1840
IF (P6.LT.0.0 .AND. P5.GE.0.0) APHA=APHA+PIE	LODQ1850
BNG (NE+1)=ANG (K2 )	LODQ1860
BNG (NE)=ANG (K1)	LODQ1870
IF (P7.GT. (PIE32 ) .AND. APHA.LT.0.0) BNG (NE+1)=ANG (K2) -PIE2	LODQ1880
IF (P7.GT. (PIE32 ) .AND. APHA.GT.0.0) BNG (NE)=ANG (K1) +PIE2	LODQ1890
IF (P7.LT. (-PIE32 ) .AND. APHA.GT.0.0) BNG (NE+1)=ANG (K2) +PIE2	LCDQ1900
IF (P7.LT. (-PIE32 ) .AND. APHA.LT.0.0) BNG (NE)=ANG (K1) -PIE2	LODQ1910
BZER=BNG (NE) -APHA	LODQ1920
B1= (-2.*BNG (NE+1) -4.*BNG (NE) +6.*APHA) /AL (NE)	LODQ1930
B2= (3.*BNG (NE+1) +3.*BNG (NE) -6.*APHA) /AL (NE) **2	LODQ1940
ANG (K2)= ANG2	LODQ1950
ANG (K1)= ANG1	LODQ1960
DO 401 K=1,8	LODQ1970
DO 401 J=1,8	LODQ1980
401 A (K,J) = 0.0	LODQ1990
A (1,1)= COS (BNG (NE) -APHA)	LODQ2000
A (1,2)= SIN (BNG (NE) -APHA)	LODQ2010
A (2,1)= -SIN (BNG (NE) -APHA)	LODQ2020
A (2,2)= COS (BNG (NE) -APHA)	LODQ2030
A (3,3)=1.	LODQ2040
A (5,1)=COS (BNG (NE+1) -APHA)	LODQ2050
A (5,2)=SIN (BNG (NE+1) -APHA)	LODQ2060
A (5,3)=P6*SIN (BNG (NE+1) ) -P5*COS (BNG (NE+1) )	LODQ2070
A (6,1)= -SIN (BNG (NE+1) -APHA)	LODQ2080
A (6,2)=COS (BNG (NE+1) -APHA)	LODQ2090
A (6,3)=P6*COS (BNG (NE+1) ) +P5*SIN (BNG (NE+1) )	LODQ2100
A (7,3)=1.	LODQ2110
A (4,4)=1.	LODQ2120
A (5,4)=AL (NE)	LODQ2130
A (5,7)=AL (NE) **2	LODQ2140
A (5,8)=AL (NE) **3	LODQ2150
A (6,5)=AL (NE) **2	LODQ2160

A(6,6)=AL(NE)\*\*3  
 P8=B1+2.\*B2\*AL(NE)  
 A(7,4)=AL(NE)\*P8  
 A(7,5)=2.\*AL(NE)  
 A(7,6)=3.\*AL(NE)\*\*2  
 A(7,7)=AL(NE)\*\*2\*P8  
 A(7,8)=AL(NE)\*\*3\*P8  
 A(8,4)=1.  
 A(8,5)=-AL(NE)\*\*2\*P8  
 A(8,6)=-AL(NE)\*\*3\*P8  
 A(8,7)=2.\*AL(NE)  
 A(8,8)=3.\*AL(NE)\*\*2  
 CALL MINV(A,8,DET,LMI,MMI)  
 DO 202 M=1,8  
 DO 202 N=1,2  
 FM(M,N)=0.0  
 DO 203 J=1,NOGA  
 ZET=AL(NE)\*AXG(J)  
 PHIP=B1+2.\*B2\*ZET  
 PHI=BZER+B1\*ZET+B2\*ZET\*\*2  
 WET=AL(NE)\*AWG(J)  
 YZET=0.0  
 ZZET=0.0  
 DO 204 JJ=1,NOGA  
 P2=BZER+B1\*ZET\*AXG(JJ)+B2\*(ZET\*AXG(JJ))\*\*2+APHA  
 YZET=YZET+COS(P2)\*ZET\*AWG(JJ)  
 ZZET=ZZET+SIN(P2)\*ZET\*AWG(JJ)  
 P3=YZET\*SIN(PHI+APHA)-ZZET\*COS(PHI+APHA)  
 P4=YZET\*COS(PHI+APHA)+ZZET\*SIN(PHI+APHA)  
 FM(1,1)=FM(1,1)+COS(PHI)\*WET  
 FM(1,2)=FM(1,2)-SIN(PHI)\*WET  
 FM(2,1)=FM(2,1)+SIN(PHI)\*WET  
 FM(2,2)=FM(2,2)+COS(PHI)\*WET  
 FM(3,1)=FM(3,1)+P3\*WET  
 FM(4,1)=FM(4,1)+ZET\*WET  
 FM(7,1)=FM(7,1)+ZET\*\*2\*WET

LODQ2170  
 LODQ2180  
 LODQ2190  
 LODQ2200  
 LODQ2210  
 LODQ2220  
 LODQ2230  
 LODQ2240  
 LODQ2250  
 LODQ2260  
 LODQ2270  
 LODQ2280  
 LODQ2290  
 LODQ2300  
 LODQ2310  
 LODQ2320  
 LODQ2330  
 LODQ2340  
 LODQ2350  
 LODQ2360  
 LODQ2370  
 LODQ2380  
 LODQ2390  
 LODQ2400  
 LODQ2410  
 LODQ2420  
 LODQ2430  
 LODQ2440  
 LODQ2450  
 LODQ2460  
 LODQ2470  
 LODQ2480  
 LODQ2490  
 LODQ2500  
 LODQ2510  
 LODQ2520

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	FM(8,1)=FM(8,1)+ZET**3*WET	LODQ2530
	FM(3,2)=FM(3,2)+P4*WET	LODQ2540
	FM(5,2)=FM(5,2)+ZET**2*WET	LODQ2550
	FM(6,2)=FM(6,2)+ZET**3*WET	LODQ2560
203	CONTINUE	LODQ2570
	DO 205 M=1,8	LODQ2580
	DO 205 N=1,2	LODQ2590
	FM2(I,NN,M,N)=0.0	LODQ2600
	DO 205 K=1,8	LODQ2610
205	FM2(I,NN,M,N)=FM2(I,NN,M,N)+A(K,M)*FM(K,N)	LODQ2620
201	CONTINUE	LODQ2630
200	CONTINUE	LODQ2640
55	IF(NOPT3.EQ.0) RETURN	LODQ2650
	WRITE(MWRITE,1020)	LODQ2660
1020	FORMAT('0DESCRIPTION OF SINE SHAPED FORCES:')	LODQ2670
	WRITE(MWRITE,1021)	LODQ2680
1021	FORMAT('0FIRST ELEMENT',5X,'NO. OF ELEMS.',10X,'RTO3V',17X,'RTO3W'	LODQ2690
a)		LODQ2700
	READ(MREAD,8) (NSTF3(I),NELF3(I),RTO3V(I),RTO3W(I),I=1,NOPT3)	LODQ2710
	WRITE(MWRITE,1015) (NSTF3(I),NELF3(I),RTO3V(I),RTO3W(I),I=1,NOPT3)	LODQ2720
	DO 300 I=1,NOPT3	LODQ2730
	NSTAT=NSTF3(I)	LODQ2740
	NEND=NELF3(I)	LODQ2750
	DO 301 NN=1,NEND	LODQ2760
	NE=(NSTAT-1)+NN	LODQ2770
	IF(NE.GT.IK) NE=NE-IK	LODQ2780
	L= MKE(NE) -1	LODQ2790
	K1 = NVEC(NE,1)	LODQ2800
	K2 = NVEC(NE,2)	LODQ2810
	P5=Z(K2)-Z(K1)	LODQ2820
	P6=Y(K2)-Y(K1)	LODQ2830
	P7=ANG(K2) -ANG(K1)	LODQ2840
	IF(YK(NE).EQ.1.0) P7=ANG(K2) - ROT(L,2)-ANG(K1)	LODQ2850
	IF(YK(NE).EQ.1.0.AND.ROT(L,1).EQ.0.0) P7=ROT(L,2)+ANG(K2)-ANG(K1)	LODQ2860
	IF(YK(NE).EQ.2.0) P7= ANG(K2)- DROT(NE) - ANG(K1)	LODQ2870
	IF(YK(NE).EQ.3.0) P7=ROT(L,2)+ANG(K2)-DROT(NE)-ANG(K1)	LODQ2880

PIE= 3.141592653589793D+00

PIE2= 2.0\*PIE

PIE32= 1.5 \*PIE

ANG2=ANG (K2)

ANG1=ANG (K1)

IF (YK (NE) .EQ. 1.0 .AND. ROT (L, 1) .EQ. 0.0) ANG (K2) =ROT (L, 2) +ANG (K2)

IF (YK (NE) .EQ. 1.0 .AND. ROT (L, 1) .EQ. 1.0) ANG (K1) =ROT (L, 2) +ANG (K1)

IF (YK (NE) .EQ. 2.0) ANG (K1) = DROT (NE) + ANG (K1)

IF (YK (NE) .EQ. 3.0) ANG (K2) = ROT (L, 2) +ANG (K2)

IF (YK (NE) .EQ. 3.0) ANG (K1) = DROT (NE) +ANG (K1)

APHA = PIE / 2.0

IF (P5.LT.0.0) APHA= -APHA

IF (P6.NE.0.0) APHA= ATAN (P5/P6)

IF (P6.LT.0.0 .AND. P5.LT.0.0) APHA=APHA-PIE

IF (P6.LT.0.0 .AND. P5.GE.0.0) APHA=APHA+PIE

BNG (NE+1) =ANG (K2 )

BNG (NE) =ANG (K1)

IF (P7.GT. (PIE32 ) .AND. APHA.LT.0.0) BNG (NE+1) =ANG (K2) -PIE2

IF (P7.GT. (PIE32 ) .AND. APHA.GT.0.0) BNG (NE) =ANG (K1) +PIE2

IF (P7.LT. (-PIE32 ) .AND. APHA.GT.0.0) BNG (NE+1) =ANG (K2) +PIE2

IF (P7.LT. (-PIE32 ) .AND. APHA.LT.0.0) BNG (NE) =ANG (K1) -PIE2

BZER=BNG (NE) -APHA

B1= (-2.\*BNG (NE+1) -4.\*BNG (NE) +6.\*APHA) /AL (NE)

B2= (3.\*BNG (NE+1) +3.\*BNG (NE) -6.\*APHA) /AL (NE) \*\*2

ANG (K2) = ANG2

ANG (K1) = ANG1

DO 402 K=1,8

DO 402 J=1,8

402 A (K, J) = 0.0

A (1, 1) = COS (BNG (NE) -APHA)

A (1, 2) = SIN (BNG (NE) -APHA)

A (2, 1) = -SIN (BNG (NE) -APHA)

A (2, 2) = COS (BNG (NE) -APHA)

A (3, 3) =1.

A (5, 1) =COS (BNG (NE+1) -APHA)

A (5, 2) =SIN (BNG (NE+1) -APHA)

LODQ2890

LODQ2900

LODQ2910

LODQ2920

LODQ2930

LODQ2940

LODQ2950

LODQ2960

LODQ2970

LODQ2980

LODQ2990

LODQ3000

LODQ3010

LODQ3020

LODQ3030

LODQ3040

LODQ3050

LODQ3060

LODQ3070

LODQ3080

LODQ3090

LODQ3100

LODQ3110

LODQ3120

LODQ3130

LODQ3140

LODQ3150

LODQ3160

LODQ3170

LODQ3180

LODQ3190

LODQ3200

LODQ3210

LODQ3220

LODQ3230

LODQ3240

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A(5,3)=P6*SIN(BNG(NE+1))-P5*COS(BNG(NE+1))
A(6,1)=-SIN(BNG(NE+1)-APHA)
A(6,2)=COS(BNG(NE+1)-APHA)
A(6,3)=P6*COS(BNG(NE+1))+P5*SIN(BNG(NE+1))
A(7,3)=1.
A(4,4)=1.
A(5,4)=AL(NE)
A(5,7)=AL(NE)**2
A(5,8)=AL(NE)**3
A(6,5)=AL(NE)**2
A(6,6)=AL(NE)**3
P8=B1+2.*B2*AL(NE)
A(7,4)=AL(NE)*P8
A(7,5)=2.*AL(NE)
A(7,6)=3.*AL(NE)**2
A(7,7)=AL(NE)**2*P8
A(7,8)=AL(NE)**3*P8
A(8,4)=1.
A(8,5)=-AL(NE)**2*P8
A(8,6)=-AL(NE)**3*P8
A(8,7)=2.*AL(NE)
A(8,8)=3.*AL(NE)**2
CALL MINV(A,8,DET,LMI,MMI)
DO 302 M=1,8
DO 302 N=1,2
FMA(M,N)=0.0
FMB(M,N)=0.0
DO 303 J=1,NOGA
ZET=AL(NE)*AXG(J)
PHIP=B1+2.*B2*ZET
PHI=BZER+B1*ZET+B2*ZET**2
WET=AL(NE)*AWG(J)
YZET=0.0
ZZET=0.0
DO 304 JJ=1,NOGA
P2=BZER+B1*ZET*AXG(JJ)+B2*(ZET*AXG(JJ))**2+APHA

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LODQ3250
LODQ3260
LODQ3270
LODQ3280
LODQ3290
LODQ3300
LODQ3310
LODQ3320
LODQ3330
LODQ3340
LODQ3350
LODQ3360
LODQ3370
LODQ3380
LODQ3390
LODQ3400
LODQ3410
LODQ3420
LODQ3430
LODQ3440
LODQ3450
LODQ3460
LODQ3470
LODQ3480
LODQ3490
LODQ3500
LODQ3510
LODQ3520
LODQ3530
LODQ3540
LODQ3550
LODQ3560
LODQ3570
LODQ3580
LODQ3590
LODQ3600

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304  YZET=YZET+COS(P2)*ZET*AWG(JJ)
      ZZET=ZZET+SIN(P2)*ZET*AWG(JJ)
      P3=YZET*SIN(PHI+APHA)-ZZET*COS(PHI+APHA)
      P4=YZET*COS(PHI+APHA)+ZZET*SIN(PHI+APHA)
      FMA(1,1)=FMA(1,1)+COS(PHI)*WET
      FMA(2,1)=FMA(2,1)+SIN(PHI)*WET
      FMA(3,1)=FMA(3,1)+P3*WET
      FMA(4,1)=FMA(4,1)+ZET*WET
      FMA(7,1)=FMA(7,1)+ZET**2*WET
      FMA(8,1)=FMA(8,1)+ZET**3*WET
      FMA(1,2)=FMA(1,2)-SIN(PHI)*WET
      FMA(2,2)=FMA(2,2)+COS(PHI)*WET
      FMA(3,2)=FMA(3,2)+P4*WET
      FMA(5,2)=FMA(5,2)+ZET**2*WET
      FMA(6,2)=FMA(6,2)+ZET**3*WET
      FMB(1,1)=FMB(1,1)+COS(PHI)*ZET*WET/AL(NE)
      FMB(2,1)=FMB(2,1)+SIN(PHI)*ZET*WET/AL(NE)
      FMB(3,1)=FMB(3,1)+P3*ZET*WET/AL(NE)
      FMB(4,1)=FMB(4,1)+ZET**2*WET/AL(NE)
      FMB(7,1)=FMB(7,1)+ZET**3*WET/AL(NE)
      FMB(8,1)=FMB(8,1)+ZET**4*WET/AL(NE)
      FMB(1,2)=FMB(1,2)-SIN(PHI)*ZET*WET/AL(NE)
      FMB(2,2)=FMB(2,2)+COS(PHI)*ZET*WET/AL(NE)
      FMB(3,2)=FMB(3,2)+P4*ZET*WET/AL(NE)
      FMB(5,2)=FMB(5,2)+ZET**3*WET/AL(NE)
      FMB(6,2)=FMB(6,2)+ZET**4*WET/AL(NE)
303  CONTINUE
      DO 305 M=1,8
      DO 305 N=1,2
      FM3A(I,NN,M,N)=0.0
      FM3B(I,NN,M,N)=0.0
      DO 305 K=1,8
      FM3A(I,NN,M,N)=FM3A(I,NN,M,N)+A(K,M)*FMA(K,N)
305  FM3B(I,NN,M,N)=FM3B(I,NN,M,N)+A(K,M)*FMB(K,N)
301  CONTINUE
300  CONTINUE
      RETURN
      END

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LODQ3610
LODQ3620
LODQ3630
LODQ3640
LODQ3650
LODQ3660
LODQ3670
LODQ3680
LODQ3690
LODQ3700
LODQ3710
LODQ3720
LODQ3730
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LODQ3940
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LODQ3960
LODQ3970
LODQ3980

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	SUBROUTINE LOADFT (TIME, NREADF, FMECH, AL)	LODT0010
C	TO FIND THE GENERALIZED NODAL LOAD VECTOR EQUIVALENT TO THE	LODT0020
C	EXTERNALLY-APPLIED LOAD	LODT0030
	IMPLICIT REAL*8 (A-H, O-Z)	LODT0040
	DIMENSION DUMMY (8, 8)	LODT0050
	DIMENSION FMECH (205), ELF (8), AL (50)	LODT0060
	COMMON /MAT/ YOUNG (3, 6), DS (3, 6), SNO (3, 5, 6), NSFL (3, 6), P (3, 6), NLAY	LODT0070
	COMMON /FG/ IK, IKK, ICP, LREF, NOGA, NFL, NI, ICOL (205), INUM (205)	LODT0080
	*, NBCOND, NBC (7), NODEB (7), KROW (8), NDEX (8), NIRREG	LODT0090
	COMMON /FORCE/ T1, AMP1FV, AMP1FW, T2, AMP2FV, AMP2FW, SLOPEV, SLOPEW,	LODT0100
	*AMPFV, AMPFW, ETA (4), RTOV (4), RTOW (4), RTO2V (4), RTO2W (4), RTO3V (4),	LODT0110
	*RTO3W (4), FM1 (4, 8, 2), FM2 (2, 4, 8, 2), FM3A (2, 4, 8, 2), FM3B (2, 4, 8, 2),	LODT0120
	*NOFT1, NOFT2, NOFT3, JELEM (4), NSTF2 (4), NELF2 (4), NSTF3 (4), NELF3 (4)	LODT0130
	COMMON /BOUN/ YK (51), NBCONB, NBCB (7), NODBB (7), MK (51), ROT (5, 2)	LODT0140
	*, XDIST (6), DROT (50), NODE (6)	LODT0150
	COMMON /TAPE/ MREAD, MWRITE, MPUNCH	LODT0160
	SIN (Q) = DSIN (Q)	LODT0170
	IF (NREADF .GT. 0) GO TO 50	LODT0180
51	READ (MREAD, 52) T2, AMP2FV, AMP2FW	LODT0190
52	FORMAT (3E15.6)	LODT0200
	WRITE (MWRITE, 400) T2, AMP2FV, AMP2FW	LODT0210
400	FORMAT ('OAT TIME', D15.6, ' TANGENTIAL FORCE=', D15.6, 5X, ' NORMAL FO	LODT0220
	@RCE=', D15.6, /)	LODT0230
	NREADF=1	LODT0240
	SLOPEV = (AMP2FV - AMP1FV) / (T2 - T1)	LODT0250
	SLOPEW = (AMP2FW - AMP1FW) / (T2 - T1)	LODT0260
50	IF (TIME .LE. T2) GO TO 53	LODT0270
	T1=T2	LODT0280
	AMP1FV=AMP2FV	LODT0290
	AMP1FW=AMP2FW	LODT0300
	GO TO 51	LODT0310
53	AMPFV=AMP1FV+ (TIME-T1)*SLOPEV	LODT0320
	AMPFW=AMP1FW+ (TIME-T1)*SLOPEW	LODT0330
	DO 57 I=1, NI	LODT0340
57	FMECH (I) = 0.0	LODT0350
	IF (NOFT1 .EQ. 0) GO TO 54	LODT0360

DO 100 I=1,NOFT1  
 NE=JELEM(I)  
 FMV=AMPFV\*RTOV(I)  
 FMW=AMPFW\*RTOW(I)  
 DO 101 J=1,8  
 101 ELF(J)=FM1(I,J,1)\*FMV+FM1(I,J,2)\*FMW  
 IF(YK(NE).EQ.0.0) GO TO 100  
 CALL ROTAT(2,DUMMY,ELF,NE)  
 100 CALL ASSEF(NE,IK,ELF,FMECH,ICP)  
 54 IF(NCFT2.EQ.0) GO TO 55  
 DO 200 I=1,NCFT2  
 NSTAT=NSTF2(I)  
 NEND=NELF2(I)  
 FMV=AMPFV\*RTC2V(I)  
 FMW=AMPFW\*RTO2W(I)  
 DO 201 NN=1,NEND  
 NE=(NSTAT-1)+NN  
 IF(NE.GT.IK) NE=NE-  
 DO 202 J=1,8  
 202 ELF(J)=FM2(I,NN,J,1)\*FMV+FM2(I,NN,J,2)\*FMW  
 IF(YK(NE).EQ.0.0) GO TO 201  
 CALL ROTAT(2,DUMMY,ELF,NE)  
 201 CALL ASSEF(NE,IK,ELF,FMECH,ICP)  
 200 CONTINUE  
 55 IF(NOFT3.EQ.0) GO TO 90  
 DO 300 I=1,NOFT3  
 NSTAT=NSTF3(I)  
 NEND=NELF3(I)  
 TX=0.0  
 DO 303 NN=1,NEND  
 NE=(NSTAT-1)+NN  
 IF(NE.GT.IK) NE=NE-  
 303 TX=TX+AL(NE)  
 PIEP=3.14159265/TX  
 FMV=AMPFV\*RTO3V(I)  
 FMW=AMPFW\*RTO3W(I)

LODT0370  
 LODT0380  
 LODT0390  
 LODT0400  
 LODT0410  
 LODT0420  
 LODT0430  
 LODT0440  
 LODT0450  
 LODT0460  
 LODT0470  
 LODT0480  
 LODT0490  
 LODT0500  
 LODT0510  
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 LODT0570  
 LODT0580  
 LODT0590  
 LODT0600  
 LODT0610  
 LODT0620  
 LODT0630  
 LODT0640  
 LODT0650  
 LODT0660  
 LODT0670  
 LODT0680  
 LODT0690  
 LODT0700  
 LODT0710  
 LODT0720

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FMW1=0.0
FMV1=0.0
XX=0.0
DO 301 NN=1,NEND
NE=(NSTAT-1)+NN
IF(NE.GT. IK) NE=NE-1K
XX=XX+AL(NE)
X=PIEP*XX
FMW2=SIN(X)*FMW
FMV2=SIN(X)*FMV
AFSW=FMW1
BFSW=(FMW2-FMW1)
AFSV=FMV1
BFSV=FMV2-FMV1
FMW1=FMW2
FMV1=FMV2
DO 302 J=1,8
302  ELF(J)=FM3A(I,NN,J,1)*AFSV+FM3A(I,NN,J,2)*AFSW+
*FM3B(I,NN,J,1)*BFSV+FM3B(I,NN,J,2)*BFSW
IF(YK(NE).EQ.0.0) GO TO 301
CALL ROTAT(2,DUMMY,ELF,NE)
301  CALL ASSEF(NE,IK,ELF,FMECH,ICP)
300  CONTINUE
90   IF(NBCOND.EQ.0) RETURN
DO 91 I=1,NBCOND
JT4=NCDEB(I)*4
FMECH(JT4-3)=0.0
IF(NBC(I).EQ.1.OR. NBC(I).EQ.2) FMECH(JT4-1)=0.0
IF(NBC(I).EQ.2.OR. NBC(I).EQ.3) FMECH(JT4-2)=0.0
91   CONTINUE
56   RETURN
END

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LODT0730
LODT0740
LODT0750
LODT0760
LODT0770
LODT0780
LODT0790
LODT0800
LODT0810
LODT0820
LODT0830
LODT0840
LODT0850
LODT0860
LODT0870
LODT0880
LODT0890
LODT0900
LODT0910
LODT0920
LODT0930
LODT0940
LODT0950
LODT0960
LODT0970
LODT0980
LODT0990
LODT1000
LODT1010
LODT1020
LODT1030
LODT1040

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	SUBROUTINE PRINT(IT,TIME,HINN,HOUT,APDEN,SPRIN,BMASS,C2,NQR,	PRIN0010
	*CINETO,BEP,WET,NV,ES,ASFL,SNS,NV1,NV2,NV3)	PRIN0020
	IMPLICIT REAL*8(A-H,O-Z)	PRIN0030
	DIMENSION ASFL(NV1,3,NV2,NV3),SNS(NV1,3,NV2,NV3)	PRIN0040
	DIMENSION AB(18),ES(3,6,6)	PRIN0050
	DIMENSION COPY(51),COPZ(51),BEPS(3)	PRIN0060
	*,BEP(50,3,3,8),WET(50,3),HINN(50,3),HOUT(50,3),FKTP(3)	PRIN0070
	*,FQREF(204),BMASS(1),CINE(205),SPRIN(1),FAILI(50),FAILO(50)	PRIN0080
	COMMON/VQ/ FLVA(205),DISP(205),DELD(205),BINP(50,3),BIMP(50,3)	PRIN0090
	COMMON/FC/ Y(51),Z(51),ANG(51),H(51,3)	PRIN0100
	COMMON /FRAG/ FH(3),FMASS(3),FMOI(3),UNK(3),CR(3),PCGU(3),PCGW(3)	PRIN0110
	*,ALFA(3),DFCGU(3),DFCGW(3),DALFA(3),TREL,FKT(3),DELTAT,NF,MIMP	PRIN0120
	COMMON /EP/ EPSI(50),EPSC(50)	PRIN0130
	COMMON /FG/ IK,IKK,ICP,LREF,NOGA,NFL,NI,ICOL(205),INUM(205)	PRIN0140
	*,NBCOND,NBC(7),NODEB(7),KROW(8),NDEX(8),NIRREG	PRIN0150
	COMMON/MAT/YOUNG(3,6),DS(3,6),SNO(3,5,6),NSFL(3,6),P(3,6),NLAY	PRIN0160
	COMMON /TAPE/ MREAD,MWRITE,MPUNCH	PRIN0170
	COMMON /TAM/ MKE(51)	PRIN0180
	SIN(Q)=DSIN(Q)	PRIN0190
	COS(Q)=DCOS(Q)	PRIN0200
	DO 700 I=1,NI	PRIN0210
700	CINE(I)=0.0	PRIN0220
	CALL OMULT(BMASS,DELD,ICOL,NI,CINE,KROW,NDEX,NIRREG)	PRIN0230
	CINET=0.0	PRIN0240
	DO 701 I=1,NI	PRIN0250
701	CINET=CINET+DELD(I)*CINE(I)	PRIN0260
	CINET=CINET*C2	PRIN0270
	IF(IT.EQ.0.AND.NV.NE.0) CINETO=CINET	PRIN0280
	ELAST=0.0	PRIN0290
	DO 702 IR=1,IK	PRIN0300
	I=MKE(IR)	PRIN0310
	NLAP = NLAY	PRIN0320
	IF(MKE(IR).GT.1) NLAP = 1	PRIN0330
	DO 703 J=1,NOGA	PRIN0340
	SUM=0.0	PRIN0350
	DO 801 M=1,NLAP	PRIN0360



NSFLM=NSFL(M,I)	PRIN0370
DO 801 N=1,NFL	PRIN0380
STRS=0.0	PRIN0390
K=N+(M-1)*NFL	PRIN0400
DO 802 L=1,NSFLM	PRIN0410
LL= L+1	PRIN0420
AB(K)= (ES(M,L,I)-ES(M,LL,I))/ ES(M,1,I)	PRIN0430
802 STRS=STRS+SNS(IR,J,K,L)* AB(K)	PRIN0440
STRS= STRS**2	PRIN0450
801 SUM = SUM+STRS*ASFL(IR,J,K,NSFLM)/(AB(K)*YOUNG(M,I))	PRIN0460
703 ELAST= ELAST+(SUM*WET(IR,J))/2.0	PRIN0470
702 CONTINUE	PRIN0480
SPDEN=0.0	PRIN0490
IF(NQR.EQ. 0) GO TO 31	PRIN0500
DO 30 I=1,NI	PRIN0510
30 FQREF(I)=0.0	PRIN0520
CALL OMULT(SPRIN,DISP,ICOL,NI,FQREF,KROW,NDEX,NIRREG)	PRIN0530
DO 32 I=1,NI	PRIN0540
32 SPDEN=SPDEN+DISP(I)*FQREF(I)	PRIN0550
SPDEN=SPDEN/2.	PRIN0560
31 ELAST=ELAST/2.	PRIN0570
CFRAG=0.0	PRIN0580
300 CINETT=CINETO+APDEN+CFRAG	PRIN0590
PLAST=CINETT-CINET-ELAST-SPDEN	PRIN0600
WRITE(MWRITE,1) IT,TIME,CINETT,CINET,ELAST,PLAST	PRIN0610
1 FORMAT(' J=',I5,' TIME (SEC.) =',E15.6,/,	PRIN0620
*' WORK INPUT INTO RING (IN.-LB.) =',E15.6,/,	PRIN0630
*' RING KINETIC ENERGY (IN.-LB.) =',E15.6,/,	PRIN0640
*' RING ELASTIC ENERGY (IN.-LB.) =',E15.6,/,	PRIN0650
*' RING PLASTIC WORK (IN.-LB.) =',E15.6)	PRIN0660
IF(NQR.EQ. 0) GO TO 33	PRIN0670
WRITE(MWRITE,34) SPDEN	PRIN0680
34 FORMAT(' ENERGY STORED IN THE ELASTIC RESTRAINTS (IN.-LB.) =',	PRIN0690
*E15.6)	PRIN0700
33 DO 11 I=1,IKK	PRIN0710
COPY(I)=Y(I)+DISP(I*4-3)*COS(ANG(I))-DISP(I*4-2)*SIN(ANG(I))	PRIN0720

11	COPZ(I)=Z(I)+DISP(I*4-3)*SIN(ANG(I))+DISP(I*4-2)*COS(ANG(I))	PRIN0730
	IKP1=IK+1	PRIN0740
	WRITE(MWRITE,2)	PRIN0750
2	FORMAT(/,' I ',5X,'V',11X,'W',9X,'PSI',9X,'CHI',10X,'COPY',	PRIN0760
	*8X,'COPZ',9X,'L',11X,'M',7X,'STRAIN(IN)',4X,'STRAIN(OUT)')	PRIN0770
50	DO 21 I=1,IK	PRIN0780
21	WRITE(MWRITE,22) I,DISP(I*4-3),DISP(I*4-2),DISP(I*4-1),DISP(I*4),	PRIN0790
	*CCPY(I),COPZ(I),BINP(I,2),BIMP(I,2),EPSI(I),EPSO(I)	PRIN0800
22	FORMAT(I5,9E12.4,2X,E12.4)	PRIN0810
	IF(ICP.GT.0) GO TO 57	PRIN0820
	WRITE(MWRITE,24) IKP1,DISP(IKP1*4-3),DISP(IKP1*4-2),	PRIN0830
	*DISP(IKP1*4-1),DISP(IKP1*4),COPY(IKP1),COPZ(IKP1),EPSI(IKP1),	PRIN0840
	@EPSC(IKP1)	PRIN0850
24	FORMAT(I5,6D12.4,24X,D12.4,D14.4)	PRIN0860
57	CONTINUE	PRIN0870
	RETURN	PRIN0880
	END	PRIN0890

### 6.3 Additional Subroutines Needed for CIVM-JET 5B

These five (5) subroutines consist of:

MAIN

IMPACT

IMPCTE

PENTRN

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and are listed in the following:

C	(C) COPYRIGHT 1978 MASSACHUSETTS INSTITUTE OF TECHNOLOGY	MAIN0010
C	CIVM JET 5B MAIN PROGRAM FOR VARIABLE THICKNESS ARBITRARILY CURVED	MAIN0020
C	MULTILAYER RING SUBJECTED TO FRAGMENT IMPACT	MAIN0030
C	CIVM JET 5B HOUBOLT OPERATOR	MAIN0040
	IMPLICIT REAL*8 (A-H,O-Z)	MAIN0050
	DIMENSION ASFL (20,3,3,3), GZETA (20,3,8), SNS (20,3,8,3),	MAIN0060
	@ SNP (20,3,8,3), AEP (20,3,8), DEP (20,2,3,8)	MAIN0070
	DIMENSION STIFK (1140), SPRIN (1140), AMASS (1140), REACK (1140)	MAIN0080
	@, REAFK (205), REACH (1140), REAC (21)	MAIN0090
	DIMENSION BMASS (1140)	MAIN0100
	DIMENSION DISUM (205)	MAIN0110
	DIMENSION EPL2 (3), EPL1 (3)	MAIN0120
	DIMENSION RMX (51), RM (3), RMO (3), CL (3), YCG (3), SOL (205)	MAIN0130
	DIMENSION DELDM1 (205), RH (3), HZ (3), HREF (50,3,3), FLN (205), FLVM (205)	MAIN0140
	@, QACL (205), QVEL (205), TXG (6), TWG (6), ES (3,6,6)	MAIN0150
	DIMENSION CINETF (3), TRANEN (3), ROTEN (3)	MAIN0160
	DIMENSION BEPS (3,3), EPI (3), EPO (3)	MAIN0170
	DIMENSION HDIF (3), DIS (205)	MAIN0180
	DIMENSION HNIN (51), EFLN (6), TPRIM (3)	MAIN0190
	DIMENSION DENS (3,6), B (6), EPS (3,5,6), SIG (3,5,6)	MAIN0200
	DIMENSION NSBS (50), NSEL (50), AEPS (3)	MAIN0210
	DIMENSION DISM (8), DELM (8), DUMMY (8,8)	MAIN0220
	DIMENSION BIGA (6), BTIMA (6), IBIGA (6), ISTAA (6), ISURA (6)	MAIN0230
	DIMENSION BI (6), BTIM (6), IBI (6), ISUR (6), ITHR (51)	MAIN0240
	COMMON /ACC/ QCD (205)	MAIN0250
	COMMON /LEFT/ RMASS (51)	MAIN0260
	COMMON /ADSP/ AZET (50), ASP (50), YSP (50), ZSP (50), LKK (50,11)	MAIN0270
	COMMON /IMPT/ VEL (102), IMCO, JVEL (51)	MAIN0280
	COMMON /TIAT/ TAIL, IMCOU	MAIN0290
	COMMON /HIT/ TNJ (6), MIRP	MAIN0300
	COMMON /ML/ MNEL (6), MATT (6)	MAIN0310
	COMMON /MAT/ YOUNG (3,6), DS (3,6), SNO (3,5,6), NSFL (3,6), P (3,6), NLAY	MAIN0320
	COMMON /FG/ IK, IKK, ICP, LREF, NOGA, NFL, NI, ICOL (205), INUM (205)	MAIN0330
	*, NBCOND, NBC (7), NODEB (7), KROW (8), NDEX (8), NIRREG	MAIN0340
	COMMON /TAPE/ MREAD, MWRITE, MPUNCH	MAIN0350
	COMMON /FC/ Y (51), Z (51), ANG (51), H (51,3)	MAIN0360

COMMON/VQ/ FLVA (205), DISP (205), DELD (205), BINP (50,3), BIMP (50,3)	MAIN0370
COMMON /EP/ EPSI (50), EPSO (50)	MAIN0380
COMMON/BA/ BEP (50,3,3,8), AL (50), AXG (3), AWG (3), WET (50,3),	MAIN0390
*CE1 (50,3), CE2 (50,3), CE3 (50,3), CM1 (50,3), CM2 (50,3), CM3 (50,3)	MAIN0400
COMMON/SC/ BIG (6), BTIME (6), IBIG (6), ISURF (6), ISTA (6)	MAIN0410
COMMON /ELFU/ FQREF (205), REX (4), NOR, NORP, NORU	MAIN0420
* ,NREL (4), NRST (4), NREU (4)	MAIN0430
COMMON /FRAGV/ UDOT (3), WDOT (3), ADOT (3)	MAIN0440
COMMON /FRAG/ FH (3), FMASS (3), FMCI (3), UNK (3), CR (3), FCGU (3), FCGW (3)	MAIN0450
* ,ALFA (3), DFCGU (3), DFCGW (3), DALFA (3), TREL, FKT (3), DELTAT, NF, NIMP	MAIN0460
COMMON/BOUN/YK (51), NBCONB, NBCB (7), NODBB (7), MK (51), ROT (5,2)	MAIN0470
* ,XDIST (6), DROT (50), NODP (6)	MAIN0480
COMMON /BR/ NVEC (51,2), LMT (51)	MAIN0490
COMMON/DIS/ ANGDI (50), NEDI (50), NDIS	MAIN0500
COMMON /TAM/ MKE (51)	MAIN0510
COMMON /THI/ HTH (5)	MAIN0520
COMMON /TIME/ IT	MAIN0530
SIN (Q)=DSIN (Q)	MAIN0540
COS (Q)=DCOS (Q)	MAIN0550
ATAN (Q)=DATAN (Q)	MAIN0560
SQRT (Q)=DSQRT (Q)	MAIN0570
NV1=20	MAIN0580
NV2=8	MAIN0590
NV3=3	MAIN0600
MREAD=5	MAIN0610
MWRITE=6	MAIN0620
MPUNCH=7	MAIN0630
1 FORMAT (10I5)	MAIN0640
2 FORMAT (3D15.6)	MAIN0650
3 FORMAT (3D25.16)	MAIN0660
4 FORMAT (3D15.6/(4D15.6))	MAIN0670
5 FORMAT (5D15.6)	MAIN0680
301 FORMAT (I5,2D15.6)	MAIN0690
303 FORMAT (5D15.6)	MAIN0700
IRRUN = 1	MAIN0710
5555 WRITE (MWRITE,5556) IRRUN	MAIN0720

5556	FORMAT(' THIS IS RUN NUMBER',I5,' FOR THIS CIVM-JET 5B SUBMITTAL	MAIN0730
@')		MAIN0740
	READ(MREAD,1) IK,ICP,NLAY,LREF,NOGA,NFL,MM,M1,M2,ICON	MAIN0750
	READ(MREAD,1) (NSFL(M,1),M=1,NLAY)	MAIN0760
	DO 201 M=1,NLAY	MAIN0770
	NSFLM= NSFL(M,1)	MAIN0780
201	READ(MREAD,4) DENS(M,1),DS(M,1),P(M,1),(EPS(M,L,1),SIG(M,L,1)	MAIN0790
	*,L=1,NSFLM)	MAIN0800
	READ(MREAD,2) B(1),DELTAT	MAIN0810
	MNEL(1)= IK	MAIN0820
	IKP1=IK+1	MAIN0830
	IKK=IKP1	MAIN0840
	IF(ICP.GT.0) IKK=IK	MAIN0850
	NS= IKK	MAIN0860
	NI=IKK*4	MAIN0870
	MPU=1	MAIN0880
201	C IF CONTINUATION CARDS ARE DESIRED REMOVE NEXT CARD MPU=0	MAIN0890
	MPU=0	MAIN0900
	PIE= 3.141592653589793D+00	MAIN0910
	IMCOU= 0	MAIN0920
	IMCO =0	MAIN0930
	NPZ1 = M1	MAIN0940
	DO 7100 I=1,IKK	MAIN0950
	DO 7100 J= 1,3	MAIN0960
	7100 H(I,J) = 0.0	MAIN0970
C	THE FOLLOWING IS THE INPUT OF THE MAIN STRUCTURE'S GEOMETRY, IF THE	MAIN0980
C	USER HAS HIS OWN GENERATING ROUTINE THIS WOULD BE THE APPROPRIATE	MAIN0990
C	SPOT IN THE PROGRAM TO INSERT THE ROUTINE.	MAIN1000
	READ(MREAD,2) (Y(I),Z(I),ANG(I),I=1,IKK)	MAIN1010
	READ(MREAD,5) ((H(I,M),M=1,NLAY),I=1,IKK)	MAIN1020
	DO 111 I=1,IKK	MAIN1030
111	ANG(I)=ANG(I)*PIE/180.0	MAIN1040
	IF(ICP.LE.0) GO TO 202	MAIN1050
	Y(IKP1)=Y(I)	MAIN1060
	Z(IKP1)=Z(I)	MAIN1070
	ANG(IKP1)=ANG(I)	MAIN1080

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DO 203 M=1,NLAY	MAIN1090
203 H(IKP1,M)=H(1,M)	MAIN1100
202 CONTINUE	MAIN1110
READ(MREAD,5300) NDIS	MAIN1120
NDI = NDIS	MAIN1130
IF (NDIS.EQ.0) GO TO 8100	MAIN1140
READ (MREAD,8101) (NEDI(I),ANGDI(I),I=1,NDIS)	MAIN1150
8101 FORMAT (4(I5,D15.6))	MAIN1160
DO 8102 I=1,NDIS	MAIN1170
8102 ANGDI(I) = (ANGDI(I)*PIE)/180.0	MAIN1180
8100 CONTINUE	MAIN1190
READ(MREAD,5300) NBR	MAIN1200
5300 FORMAT (2I5)	MAIN1210
MNSFL= NSFL(1,1)	MAIN1220
DO 5666 I=1,NLAY	MAIN1230
IF (MNSFL.LT. NSFL(I,1)) MNSFL=NSFL(I,1)	MAIN1240
5666 CONTINUE	MAIN1250
DO 5305 I= 1,IK	MAIN1260
MKE(I) = 1	MAIN1270
MK(I) = I	MAIN1280
LMT(I) = 0	MAIN1290
YK(I) = 0.0	MAIN1300
NVEC(I,2) = I+1	MAIN1310
5305 NVEC(I,1) = I	MAIN1320
IF (ICP.GT.0) NVEC(IK,2) = 1	MAIN1330
IF(ICP.LE.0) MK(IK+1) = IK+1	MAIN1340
IF (NBR.NE.0) GOTO 1112	MAIN1350
WRITE(MWRITE,1113)	MAIN1360
1113 FORMAT (//, ' THERE ARE NO BRANCHES CONNECTED TO THE MAIN STRUCTURE	MAIN1370
@,THEREFORE',/, ' THE NUMBERING SYSTEM FOR NODES AND ELEMENTS REMAIN	MAIN1380
@S UNCHANGED')	MAIN1390
1112 CONTINUE	MAIN1400
IF (NBR.EQ.0) GO TO 5310	MAIN1410
CALL BRAN(NBR,DENS,EPS,SIG,B)	MAIN1420
DO 8888 I=1,NBR	MAIN1430
IF(MNSFL.LT. NSFL(1,I+1)) MNSFL= NSFL(1,I+1)	MAIN1440

8888	CONTINUE	MAIN1450
5310	CONTINUE	MAIN1460
	LGSP= 0	MAIN1470
	LSPP=0	MAIN1480
	READ(MREAD,8200) NOP,NASP,NTERR	MAIN1490
8200	FORMAT(3I5)	MAIN1500
	DO 8215 I=1,IK	MAIN1510
	DO 8215 J=1,2	MAIN1520
8215	LKK(I,J) = 0	MAIN1530
	IF(NOP.EQ.0) GO TO 8220	MAIN1540
	IF(NOP.NE.2) LGSP=1	MAIN1550
	IF(NOP.NE.1) LSPP=1	MAIN1560
	IF(LSPP.NE.1) GO TO 8220	MAIN1570
	READ(MREAD,8210) (NSBS(I),NSEL(I),AZET(I),I=1,NASP)	MAIN1580
8210	FORMAT(2I5,D15.6)	MAIN1590
	WRITE(MWRITE,156)	MAIN1600
156	FORMAT('0ADDITIONAL STRAIN POINT',5X,'ELEMENT',5X,'S COORDINATE')	MAIN1610
	DO 8216 J= 1,NASP	MAIN1620
	IF(NSBS(J).NE.1) GO TO 8217	MAIN1630
	M= NSEL(J) +1	MAIN1640
	IF(ICP.GT.0.AND.NSEL(J).EQ.IK) MK(M) = IK+1	MAIN1650
	N= MK(M) -1	MAIN1660
	LKK(N,1) = 1 + LKK(N,1)	MAIN1670
	NO = LKK(N,1) + 1	MAIN1680
	LKK(N,NO) = J	MAIN1690
	GOTO 1400	MAIN1700
8217	NNNN = NSBS(J) -1	MAIN1710
	IF(NODP(NNNN).EQ.1) 3OTO 8218	MAIN1720
	NNNN= NODP(NNNN)	MAIN1730
	N= MK(NNNN)+ NSEL(J)- 1	MAIN1740
	GO TO 8219	MAIN1750
8218	N= NSEL(J)	MAIN1760
8219	LKK(N,1) = 1 + LKK(N,1)	MAIN1770
	NO = LKK(N,1) +1	MAIN1780
	LKK(N,NO) = J	MAIN1790
1400	WRITE(MWRITE,145) J,N,AZET(J)	MAIN1800



145	FORMAT (' ',9X,I5,13X,I5,7X,D15.6)	MAIN1810
8216	CONTINUE	MAIN1820
8220	CONTINUE	MAIN1830
	IF (NDIS.EQ.0) GO TO 8140	MAIN1840
	IF (NBR.EQ.0) GOTO 8145	MAIN1850
	IF (NDI.EQ.0) GOTO 8145	MAIN1860
	DO 8146 J= 1,NDI	MAIN1870
	M= NEDI(J) +1	MAIN1880
	N = MK(M) -1	MAIN1890
	NEDI(J) = N	MAIN1900
8146	CONTINUE	MAIN1910
8145	WRITE(MWRITE,8111)	MAIN1920
	WRITE(MWRITE,8120) (NEDI(I),I=1,NDIS)	MAIN1930
8111	FORMAT('OEACH OF THE FOLLOWING ELEMENTS HAS A SLOPE DISCONTINUITY	MAIN1940
	@AT ITS FIRST NODE')	MAIN1950
8120	FORMAT(' ', 25I5)	MAIN1960
	WRITE(MWRITE,8112) (ANGDI(L),L=1,NDIS)	MAIN1970
8112	FORMAT('OTHE GLOBAL SLOPE (RAD.) AT EACH DISCONTINUITY EQUALS: ',/,	MAIN1980
	@ (8D15.6))	MAIN1990
	DO 8130 I= 1,NDIS	MAIN2000
	M=NEDI(I)	MAIN2010
	YK(M) = 2.0 + YK(M)	MAIN2020
	L1= NVEC(M,1)	MAIN2030
	DROT(M) = ANGDI(I) - ANG(L1)	MAIN2040
8130	CONTINUE	MAIN2050
8140	CONTINUE	MAIN2060
	READ(MREAD,3) (AXG(K),K=1,NOGA)	MAIN2070
	READ(MREAD,3) (AWG(K),K=1,NOGA)	MAIN2080
	READ(MREAD,3) (TXG(K),K=1,NFL)	MAIN2090
	READ(MREAD,3) (TWG(K),K=1,NFL)	MAIN2100
	READ(MREAD,1) NBCOND, (NBC(I),NODEB(I),I=1,NBCOND)	MAIN2110
	IF (NBR.EQ.0) GO TO 748	MAIN2120
	NIT = NBCOND+ 1	MAIN2130
	NIT1 = NIT -1	MAIN2140
	NBCOND= NBCOND+NBCONB	MAIN2150
	IF (NBCONB.EQ.0) GO TO 751	MAIN2160

DO 750 LOP= 1,NBCONE  
 NBC(NIT1 + LOP) = NBCB(LOP)  
 750 NODEB(NIT1 + LOP) = NODBB(LOP)  
 751 IF (NIT1.EQ.0) GO TO 748  
 DO 753 LOP = 1,NIT1  
 NTI = NODEB(LOP)  
 753 NODEB(LOP) = MK(NTI)  
 748 CONTINUE  
 READ(MREAD,1) NQR,NORP,NORU  
 CALL IDENT(NQR,B,DENS,EPS,SIG,NBR)  
 WRITE(MWRITE,402)  
 402 FORMAT(///,' GAUSSIAN STATIONS AND WEIGHTS:')  
 WRITE(MWRITE,400) (L,AXG(L),L,AWG(L),L=1,NOGA)  
 WRITE(MWRITE,401) (L,TXG(L),L,TWG(L),L=1,NFL)  
 400 FORMAT(' ',12X,'AXG',I3,2X,'=',F20.15,8X,'AWG',I3,2X,'=',F20.15)  
 401 FORMAT(' ',12X,'TXG',I3,2X,'=',F20.15,8X,'TWG',I3,2X,'=',F20.15)  
 C FOR MEMBRANE SET TXG=0.0 AND TWG=2.0 FOR ONE DEPTHWISE STATION  
 NBR1 = NBR+1  
 DO 651 K=1,NBR1  
 NLAP= NLAY  
 IF(K.GT.1) NLAP=1  
 DO 76 M= 1,NLAP  
 NSFLM=NSFL(M,K)  
 ES(M,1,K)= SIG(M,1,K)/EPS(M,1,K)  
 IF(NSFLM-1) 77,77,78  
 78 DO 79 L=2,NSFLM  
 79 ES(M,L,K)=(SIG(M,L,K)-SIG(M,L-1,K))/(EPS(M,L,K)-EPS(M,L-1,K))  
 77 ES(M,NSFLM+1,K) = 0.0  
 DO 80 L=1,NSFLM  
 80 SNO(M,L,K) = ES(M,1,K)\*EPS(M,L,K)  
 YOUNG(M,K) = ES(M,1,K)  
 76 CONTINUE  
 651 CONTINUE  
 IC = 0  
 DO 70 IR=1,IK  
 IF(YK(IR).EQ.1.0.OR.YK(IR).EQ.3.0) IC=IC+1

MAIN2170  
 MAIN2180  
 MAIN2190  
 MAIN2200  
 MAIN2210  
 MAIN2220  
 MAIN2230  
 MAIN2240  
 MAIN2250  
 MAIN2260  
 MAIN2270  
 MAIN2280  
 MAIN2290  
 MAIN2300  
 MAIN2310  
 MAIN2320  
 MAIN2330  
 MAIN2340  
 MAIN2350  
 MAIN2360  
 MAIN2370  
 MAIN2380  
 MAIN2390  
 MAIN2400  
 MAIN2410  
 MAIN2420  
 MAIN2430  
 MAIN2440  
 MAIN2450  
 MAIN2460  
 MAIN2470  
 MAIN2480  
 MAIN2490  
 MAIN2500  
 MAIN2510  
 MAIN2520

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L1= NVEC(IR,1)
L2 = NVEC(IR,2)
NLAP= NLAY
IF (MKE(IR).GT.1) NLAP=1
DO 70 J=1,NOGA
DO 71 M=1,NLAP
IF (YK(IR).NE.1.0.AND.YK(IR).NE.3.0) GOTO 600
IF (ROT(IC,1).EQ.0.0) GO TO 610
RH(M)= HTH(IC) * (1.0-AXG(J)) +H(L2,M) *AXG(J)
GO TO 71
610 RH(M)= H(L1,M) * (1.0-AXG(J)) + HTH(IC) *AXG(J)
GO TO 71
600 RH(M) = H(L1,M) * (1.0-AXG(J)) +H(L2,M) *AXG(J)
71 CONTINUE
HZ(1)=RH(1)/2.
IF (NLAP.EQ.1) GO TO 72
DO 73 M=2,NLAY
73 HZ(M)=HZ(M-1) + (RH(M) +RH(M-1)) /2.
72 CONTINUE
CM1(IR,J)=0.0
CM2(IR,J)=0.0
CM3(IR,J)=0.0
CE1(IR,J)=0.0
CE2(IR,J)=0.0
CE3(IR,J)=0.0
I= MKE(IR)
DO 74 M=1,NLAP
HREF(IR,J,M)=HZ(M)-HZ(LREF)
CM1(IR,J)=CM1(IR,J)+DENS(M,I)*B(I)*RH(M)
CM2(IR,J)=CM2(IR,J)-DENS(M,I)*B(I)*RH(M)*HREF(IR,J,M)
CM3(IR,J)=CM3(IR,J)+DENS(M,I)*B(I)*(RH(M)**3/12.
*+HREF(IR,J,M)**2*RH(M))
C FOR MEMBRANE SET CE2 AND CE3 = 0.0
CE1(IR,J)=CE1(IR,J)+YOUNG(M,I)*B(I)*RH(M)
CE2(IR,J) = CE2(IR,J)+YOUNG(M,I)*B(I)*RH(M)*HREF(IR,J,M)
CE3(IR,J) = CE3(IR,J)+YOUNG(M,I)*B(I)*(RH(M)**3/12.0

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MAIN2530
MAIN2540
MAIN2550
MAIN2560
MAIN2570
MAIN2580
MAIN2590
MAIN2600
MAIN2610
MAIN2620
MAIN2630
MAIN2640
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MAIN2660
MAIN2670
MAIN2680
MAIN2690
MAIN2700
MAIN2710
MAIN2720
MAIN2730
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MAIN2750
MAIN2760
MAIN2770
MAIN2780
MAIN2790
MAIN2800
MAIN2810
MAIN2820
MAIN2830
MAIN2840
MAIN2850
MAIN2860
MAIN2870
MAIN2880

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\*+HREF(IR,J,M)\*\*2\*RH(1))

NSFLM=NSFL(M,I)

DO 75 N=1,NFL

K=N+(M-1)\*NFL

GFL=RH(M)\*TWG(N)\*B(I)/2.0

GZETA(IR,J,K)=RH(M)\*TXG(N)/2.+HREF(IR,J,M)

DO 75 L=1,NSFLM

ASFL(IR,J,K,L)=GFL\*(ES(M,L,I)-ES(M,L+1,I))/ES(M,1,I)

75 CONTINUE

74 CONTINUE

70 CONTINUE

IF(NBR.NE.0) GOTO 218

DO 15 I=1,8

15 ICOL(I)=1

IKM1=IK-1

IF(ICP.GT.0) GO TO 17

DO 16 I=3,IKP1

IK4=I\*4

IK3=IK4-1

IK2=IK4-2

IK1=IK4-3

JJ=(I-1)\*4-3

ICOL(IK1)=JJ

ICOL(IK2)=JJ

ICOL(IK3)=JJ

ICOL(IK4)=JJ

16 CONTINUE

GO TO 19

17 DO 18 I=3,IKM1

IK4=I\*4

IK3=IK4-1

IK2=IK4-2

IK1=IK4-3

JJ=(I-1)\*4-3

ICOL(IK1)=JJ

ICOL(IK2)=JJ

MAIN2890

MAIN2900

MAIN2910

MAIN2920

MAIN2930

MAIN2940

MAIN2950

MAIN2960

MAIN2970

MAIN2980

MAIN2990

MAIN3000

MAIN3010

MAIN3020

MAIN3030

MAIN3040

MAIN3050

MAIN3060

MAIN3070

MAIN3080

MAIN3090

MAIN3100

MAIN3110

MAIN3120

MAIN3130

MAIN3140

MAIN3150

MAIN3160

MAIN3170

MAIN3180

MAIN3190

MAIN3200

MAIN3210

MAIN3220

MAIN3230

MAIN3240

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	ICOL (IK3) =JJ	MAIN3250
	ICOL (IK4) =JJ	MAIN3260
18	CONTINUE	MAIN3270
	ICOL (IK*4) =1	MAIN3280
	ICOL (IK*4-1) =1	MAIN3290
	ICOL (IK*4-2) =1	MAIN3300
	ICOL (IK*4-3) =1	MAIN3310
19	CONTINUE	MAIN3320
218	INUM (1) = 1	MAIN3330
	DO 99 I=2, NI	MAIN3340
99	INUM (I) =I-ICOL (I-1) +INUM (I-1)	MAIN3350
	DO 99 I=1, NI	MAIN3360
990	INUM (I) =INUM (I) -ICOL (I)	MAIN3370
	NIRREG=0	MAIN3380
	INDEX=0	MAIN3390
	ISSET=1	MAIN3400
	DO 116 I=1, NI	MAIN3410
	L=ICOL (I)	MAIN3420
	IF (ICOL (I) -ISSET) 117, 116, 119	MAIN3430
119	ISSET=ICOL (I)	MAIN3440
	GO TO 116	MAIN3450
117	NIRREG=NIRREG+1	MAIN3460
	IF (NIRREG-NI/2) 711, 711, 90	MAIN3470
711	KROW (NIRREG) =I	MAIN3480
	NDEX (NIRREG) =INDEX	MAIN3490
116	INDEX=INDEX+I-L	MAIN3500
90	ISIZE=NI+INUM (NI)	MAIN3510
	WRITE (MWRITE, 91) ISIZE	MAIN3520
91	FORMAT (/, ' SIZE OF ASSEMBLED MASS OR STIFFNESS MATRIX=', 15)	MAIN3530
	IF (ISIZE.LE.2060) GOTO 6012	MAIN3540
	WRITE (MWRITE, 6011)	MAIN3550
6011	FORMAT (' THE SIZE OF THE STIFFNESS MATRIX HAS EXCEEDED 2060. THIS	MAIN3560
	@ RUN HAS BEEN TERMINATED. CHANGE DIMENSION OF STIFK IN', //, ' MAIN	MAIN3570
	@, ELMPB, AND TSTEP. ALSO CHANGE DIMENSIONS FOR AMASS, BMASS, AND SPR	MAIN3580
	@N')	MAIN3590
	GOTO 150	MAIN3600

6012	CONTINUE	MAIN3610
	WRITE(MWRITE,7850)	MAIN3620
7850	FORMAT('/', ' LUMPED MASS MATRIX FOR EACH ELEMENT:', '/')	MAIN3630
	ELMPB=1.0	MAIN3640
	CALL ELMP (AMASS, STIFK, ISIZE, AEP, DEP, NV1, REACK, REACH, ELMPB)	MAIN3650
	DO 1261 IR=1, IKK	MAIN3660
	J= IR*4-3	MAIN3670
	K= INUM(J)+J	MAIN3680
	RMASS(IR)= AMASS(K)	MAIN3690
	SOL(J)= AMASS(K)	MAIN3700
	K= INUM(J+1)+J+1	MAIN3710
	SOL(J+1)= AMASS(K)	MAIN3720
	K= INUM(J+2)+J+2	MAIN3730
	SOL(J+2)= AMASS(K)	MAIN3740
	K= INUM(J+3)+J+3	MAIN3750
	SOL(J+3)= AMASS(K)	MAIN3760
1261	CONTINUE	MAIN3770
	WRITE(MWRITE,7836)	MAIN3780
	WRITE(MWRITE,7837) (SOL(L), L=1, NI)	MAIN3790
7836	FORMAT('/', ' THE TRANSLATIONAL AND ROTATIONAL MASSES AT EACH NODE A	MAIN3800
	@RE:')	MAIN3810
7837	FORMAT(' ', 4D25.15)	MAIN3820
	DO 23 L=1, ISIZE	MAIN3830
23	SPRIN(L)=0.0	MAIN3840
	IF (NQR.EQ. 0) GO TO 22	MAIN3850
	CALL QREM(AL, AXG, AWG, SPRIN)	MAIN3860
	DO 360 I=1, ISIZE	MAIN3870
360	REACK(I)= REACK(I)+ SPRIN(I)	MAIN3880
22	CONTINUE	MAIN3890
	IF (NBCOND.EQ.0) GOTO 93	MAIN3900
	DO 92 I=1, NBCOND	MAIN3910
	JT4=NODEB(I)*4	MAIN3920
	JT4M3=JT4-3	MAIN3930
	JT4M2=JT4-2	MAIN3940
	JT4M1=JT4-1	MAIN3950
	CALL ERC(JT4M3, AMASS, NI, ICOL, INUM)	MAIN3960

IF (NBC (I) .EQ. 1. OR. NBC (I) .EQ. 2) CALL ERC (JT4M1, AMASS, NI, ICOL, INUM)	MAIN3970
IF (NBC (I) .EQ. 2. OR. NBC (I) .EQ. 3) CALL ERC (JT4M2, AMASS, NI, ICOL, INUM)	MAIN3980
IF (NQR.EQ. 0) GOTO 92	MAIN3990
CALL ERC (JT4M3, SPRIN, NI, ICOL, INUM)	MAIN4000
IF (NBC (I) .EQ. 1. OR. NBC (I) .EQ. 2) CALL ERC (JT4M1, SPRIN, NI, ICOL, INUM)	MAIN4010
IF (NBC (I) .EQ. 2. OR. NBC (I) .EQ. 3) CALL ERC (JT4M2, SPRIN, NI, ICOL, INUM)	MAIN4020
92 CONTINUE	MAIN4030
93 CONTINUE	MAIN4040
WRITE (MWRITE, 7851)	MAIN4050
7851 FORMAT (//, ' THE ASSEMBLED MASS MATRIX: ', //)	MAIN4060
WRITE (MWRITE, 7852) (AMASS (L), L=1, ISIZE)	MAIN4070
7852 FORMAT (' ', 8D15.6)	MAIN4080
WRITE (MWRITE, 7853)	MAIN4090
7853 FORMAT (//, ' THE ASSEMBLED STIFFNESS MATRIX: ', //)	MAIN4100
WRITE (MWRITE, 7852) (STIFK (L), L=1, ISIZE)	MAIN4110
DO 948 I=1, ISIZE	MAIN4120
948 BMASS (I) = AMASS (I)	MAIN4130
CALL PAC (BMASS, ICOL, KROW, NDEX, IDET, MWRITE, NI, NIRREG, INUM)	MAIN4140
CALL TSTEP (BMASS, STIFK, DELTAT)	MAIN4150
DO 953 I=1, ISIZE	MAIN4160
953 BMASS (I) = AMASS (I)	MAIN4170
WRITE (MWRITE, 52) DELTAT	MAIN4180
52 FORMAT (/, ' TIME STEP SIZE USED IN PROGRAM (SEC) = ', D15.6)	MAIN4190
DO 8951 J=1, NOGA	MAIN4200
3951 EPL2 (J) = 0.0	MAIN4210
EPAS2 = 0.0	MAIN4220
BIGL = 0.0	MAIN4230
BIGAL = 0.0	MAIN4240
IBIGAL = 0	MAIN4250
IBIGL = 0	MAIN4260
ISURFL = 0	MAIN4270
ISURAL = 0	MAIN4280
ISTAL = 0	MAIN4290
ISTAAL = 0	MAIN4300
M = NBR + 1	MAIN4310
DO 10005 J = 1, M	MAIN4320

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BIG(J) = 0.0
BIGA(J) = 0.0
BI(J) = 0.0
IBIGA(J) = 0
IBIG(J) = 0
IBI(J) = 0
ISTA(J) = 0
ISTAA(J) = 0
BTIME(J) = 0.0
BTIMA(J) = 0.0
BTIM(J) = 0.0
10005 CONTINUE
      DTSQ=DELTAT**2
      C2=1./(2.*DELTAT**2)
      MCRIT=0
      IT=0
      TIME=0.0
      DO 50 I=1,NI
      DELD(I) = 0.0
50    DISP(I)=0.0
      DO 51 IR=1,IK
      NLAP=NLAY
      IF (MKE(IR).GT.1) NLAP=1
      NO= MKE(IR)
      DO 51 J=1,NOGA
      BINP(IR,J) = 0.0
      BIMP(IR,J) =0.0
      DO 51 M=1,NLAP
      NSFLM= NSFL(M,NO)
      DO 51 N=1,NFL
      K= N+ (M-1)*NFL
      DO 51 L=1,NSFLM
      SNP(IR,J,K,L) = 0.0
51    SNS(IR,J,K,L) = 0.0
      IF(ICP.LE.0) GOTO 55
      DO 54 K=1,4

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	DISP (IK*4+K) = DISP (K)	MAIN4690
54	DELD (IK*4+K) = DELD (K)	MAIN4700
55	CONTINUE	MAIN4710
	L=1	MAIN4720
	READ (MREAD,301) NF,EFLN (L)	MAIN4730
	IF (EFLN (L) .GT.0.0) GO TO 305	MAIN4740
	EFLN (L)=DELTAT*SQRT (YOUNG (1,1) /DENS (1,1) )	MAIN4750
	IF (NLAY .EQ.1) GO TO 305	MAIN4760
	DO 306 M=2,NLAY	MAIN4770
	BOLD=DELTAT*SQRT (YOUNG (M,1) /DENS (M,1) )	MAIN4780
	IF (EFLN (L) .LT.BOLD) EFLN (L) = BOLD	MAIN4790
306	CONTINUE	MAIN4800
305	CONTINUE	MAIN4810
	IF (NBR.EQ.0) GOTO 308	MAIN4820
	JNBR= NBR+1	MAIN4830
	DO 307 I=2,JNBR	MAIN4840
307	EFLN (I) = DELTAT* SQRT (YOUNG (1,I) /DENS (1,I) )	MAIN4850
308	CONTINUE	MAIN4860
	DO 302 I=1,NF	MAIN4870
	ALFA (I)= 0.0	MAIN4880
	READ (MREAD,303) FH (I) ,FCGW (I) ,FCGU (I) ,FMASS (I) ,FMOI (I)	MAIN4890
	READ (MREAD,303) UNK (I)	MAIN4900
	READ (MREAD,303) UDOT (I) ,WDOT (I) ,ADOT (I) ,TPRIM (I) ,CR (I)	MAIN4910
	FKT (I) = FMASS (I) * (UDOT (I) **2+WDOT (I) **2) +FMOI (I) *ADOT (I) **2	MAIN4920
	FKT (I) = FKT (I) /2.0	MAIN4930
302	CONTINUE	MAIN4940
310	WRITE (MWRITE,312)	MAIN4950
	WRITE (MWRITE,313) NF,EFLN (1)	MAIN4960
312	FORMAT (/, ' FRAGMENT PROPERTIES', /)	MAIN4970
313	FORMAT (10X, 'NO. OF FRAGMENTS', /, I5, /,	MAIN4980
	*10X, 'EFFECTIVE LENGTH OF IMPACT (IN) ON MAIN STRUCTURE =', D15.6 /)	MAIN4990
	WRITE (MWRITE,314) (I, FH (I) ,FMASS (I) ,FMOI (I) ,FCGU (I) ,FCGW (I) ,	MAIN5000
	*ALFA (I) ,UDOT (I) ,WDOT (I) ,ADOT (I) ,CR (I) ,UNK (I) ,FKT (I) ,I=1,NF)	MAIN5010
314	FORMAT (12X, 'FRAG. NO.', /, I5, /,	MAIN5020
	*12X, 'DIAMETER (IN)', /, E15.6, /,	MAIN5030
	*12X, 'WEIGHT (LBS-SEC**2/IN.)', /, E15.6, /,	MAIN5040

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*12X,'MOMENT OF INERTIA (IN-LB-SEC**2)      =' ,E15.6,/,
*12X,' CG Y COORDINATE      (IN)             =' ,E15.6,/,
*12X,' CG Z COORDINATE      (IN)             =' ,E15.6,/,
*12X,'ANGULAR ROTATION (DEG)                 =' ,E15.6,/,
*12X,'VEL IN Y DIR (IN/SEC)                  =' ,E15.6,/,
*12X,'VEL IN Z DIR (IN/SEC)                  =' ,E15.6,/,
*12X,' ANGULAR VEL (DEG/SEC)                 =' ,E15.6,/,
*12X,'COEFF OF RESTITUTION                   =' ,E15.6,/,
*12X,'COEFF OF FRICTION                      =' ,E15.6,/,
*12X,'INITIAL KINETIC ENERGY (IN-LB)        =' ,E15.6,/,

315  CONTINUE
      WRITE(MWRITE,309)  (TPRIM(JK),JK=1,NF)
309  FORMAT(' THE TPRIM FOR EACH FRAGMENT IS:',3X,3D18.6 ,/)
      DO 6111 I=1,NI
      DELDM1(I)= 0.0
      PLVA(I) = 0.0
      FLN(I) = 0.0
      QACL(I) = 0.0
      QCD(I) = 0.0
6111  QVEL(I) = 0.0
      DO 37 L=1,ISIZE
37    AMASS(L)=2.*AMASS(L)+DTSQ*(STIFK(L)+SPRIN(L))
      CALL FAC(AMASS,ICOL,KROW,NDEX,IDET,MWRITE,NI,NIRRES,INUM)
      MIRP=0
      XY= TPRIM(1)/DELTAT
      IT= XY+0.02
      TIME= IT*DELTAT
      DO 1270 NPQ=1,NF
1270  TNJ(NPQ) = 1.0
      IF(NF.EQ.1) GOTO 1280
      DO 1275 NTS=2,NF
      IF(TPRIM(NTS).GE.0.0) GOTO 1275
      MIRP= NTS
      GOTO 1280
1275  CONTINUE
1280  IF(MIRP.EQ.0) GOTO 1286

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DO 1285 NPN= MIRP,NF	MAIN5410
1285 TNJ(NPN) = 0.0	MAIN5420
1286 DO 1287 I=1,NF	MAIN5430
DFCGU(I) = UDOT(I)*DELTAT	MAIN5440
DFCGW(I) = WDOT(I)*DELTAT	MAIN5450
DALFA(I) = ADOT(I)*DELTAT	MAIN5460
FCGU(I) = FCGU(I)+UDOT(I)*TPRIM(I)*TNJ(I)	MAIN5470
FCGW(I)= FCGW(I)+WDOT(I)*TPRIM(I)*TNJ(I)	MAIN5480
1287 ALFA(I) = ADOT(I)*TPRIM(I)*TNJ(I)	MAIN5490
DO 1020 I=1,IKK	MAIN5500
JVEL(I) = 0	MAIN5510
EPSI(I) = 0.0	MAIN5520
1020 EPSO(I) =0.0	MAIN5530
83 FORMAT(2(I5,D20.13))	MAIN5540
387 FORMAT(2I5,2D20.13)	MAIN5550
386 FORMAT(3I5,2D20.13)	MAIN5560
84 FORMAT(4D20.13)	MAIN5570
86 FORMAT(2I5,2D20.13,I5)	MAIN5580
89 FORMAT(I5,6D12.4)	MAIN5590
WRITE(MWRITE,8255) M2,NOP	MAIN5600
8255 FORMAT('0THE FOLLOWING IS THE TIME SOLUTION OF THE FRAGMENT- RING	MAIN5610
@IMPACT' ,/, ' OUTPUT WILL BE PRINTED EVERY',I5,' CYCLES USING	MAIN5620
@OUTPUT OPTION',I3,'.',/, ' REACTION FORCES APPLIED TO THE STRUCTURE	MAIN5630
@ WILL BE PRINTED AT EACH OUTPUT CYCLE',/, ' FOR NODES AT WHICH BOUN	MAIN5640
@DARY CONDITIONS ARE SPECIFIED. D.O.F. THAT ARE',/, ' NOT RESTRAIN	MAIN5650
@D AT THAT NODE WILL HAVE A REACTION FORCE = 0.0.',/, ' ALL IMPACTS	MAIN5660
@WILL BE DESIGNATED AND ALL THE FRAGMENT ENERGIES WILL BE',/, ' LIST	MAIN5670
@ED AFTER EACH IMPACT.')	MAIN5680
NLAYP1= NLAY+1	MAIN5690
IF (NLAYP1.GT.3) GOTO 962	MAIN5700
DO 961 I=1,IKK	MAIN5710
DO 961 J=NLAYP1, 3	MAIN5720
961 H(I,J) =0.0	MAIN5730
962 CONTINUE	MAIN5740
READ(MREAD,1) ICONT	MAIN5750
IF(ICONT.EQ.0) GOTO 120	MAIN5760

READ (MREAD,83) IT,TIME,IMCOU,TAII	MAIN5770
M=NR+1	MAIN5780
READ (MREAD,86) (IBIGA(L),ISTAA(L),BIGA(L),BTIMA(L),ISURA(L),L=1,M)	MAIN5790
READ (MREAD,386) (IBIG(L),JSURF(L),ISTA(L),BIG(L),BTIME(L),L=1,M)	MAIN5800
READ (MREAD,387) (IBI(L),ISUR(L),BI(L),BTIM(L),L=1,M)	MAIN5810
READ (MREAD,89) MIRP, (TNJ(I),I=1,NF)	MAIN5820
READ (MREAD,84) (DISP(I),I=1,NI)	MAIN5830
READ (MREAD,84) (DELD(I),I=1,NI)	MAIN5840
READ (MREAD,84) (DELDM1(I),I=1,NI)	MAIN5850
READ (MREAD,84) (FLVA(I),I=1,NI)	MAIN5860
READ (MREAD,84) (QVEL(I),I=1,NI)	MAIN5870
READ (MREAD,84) (QACL(I),I=1,NI)	MAIN5880
READ (MREAD,84) (((SNS(IR,J,K,L),L=1,MNSFL),K=1,NFL),J=1,NOGA),	MAIN5890
*IR=1,IK)	MAIN5900
READ (MREAD,84) (((SNP(IR,J,K,L),L=1,MNSFL),K=1,NFL),J=1,NOGA),	MAIN5910
*IR=1,IK)	MAIN5920
READ (MREAD,84) (FCGU(J),FCGW(J),ALFA(J),UDOT(J),WDOT(J)	MAIN5930
*,ADOT(J),J=1,NF)	MAIN5940
WRITE (MWRITE,8265)	MAIN5950
8265 FORMAT('THIS IS A CONTINUATION RUN')	MAIN5960
C START OF TIME SOLUTION	MAIN5970
120 IT=IT+1	MAIN5980
TIME=IT*DELTAT	MAIN5990
IF(ICP.LE.0) GO TO 127	MAIN6000
DO 128 K=1,4	MAIN6010
DISP(IK*4+K)=DISP(K)	MAIN6020
128 DELD(IK*4+K)=DELD(K)	MAIN6030
127 CONTINUE	MAIN6040
CALL IMPACT(EPLN,IT,NBR,QACL,QVEL,BMASS,AMASS,FLN)	MAIN6050
45 DO 121 I=1,NI	MAIN6060
FLN(I)=FLVA(I)	MAIN6070
FLVA(I)=0.0	MAIN6080
FLVM(I)=0.0	MAIN6090
121 CONTINUE	MAIN6100
6010 IF(MIRP.GT.NF.OR.MIRP.EQ.0) GOTO 6020	MAIN6110
TI=(IT*DELTAT)-(TPRIM(1)-TPRIM(MIRP))	MAIN6120

IF(DABS(TI).GT.DELTAT) GOTO 6020  
 TNJ(MIRP) = 1.0  
 MIRP= MIRP+1  
 GOTO 6010  
 6020 DO 822 I=1,NF  
     FCGU(I)= FCGU(I)+DFCGU(I)\*TNJ(I)  
     FCGW(I)= FCGW(I)+DFCGW(I)\* TNJ(I)  
 822 ALFA(2)= ALFA(I)+ DALFA(I)\* TNJ(I)  
     DO 122 I=1,NI  
     DISP(I)= DISP(I) + DELD(I)  
 122 CONTINUE  
     CALL STRESS(DELTAT,ASFL,GZETA,SNS,SNP,NV1,NV2,NV3)  
 IF(IMCO.EQ.0) GOTO 333  
 IMCO=0  
 DO 6301 I=1,NF  
     TRANEN(I)= FMASS(I)/2.0\*(UDOT(I)\*\*2+WDOT(I)\*\*2)  
     ROTEI(I)= FMOI(I)/2.0\* ADOT(I)\*\*2  
     CINETF(I)= TRANEN(I) + ROTEN(I)  
 6301 CONTINUE  
     WRITE(MWRITE,6302) (I,TRANEN(I),ROTEI(I),CINETF(I),I=1,NF)  
 6302 FORMAT(' ',2('FRAG',I2,' TE=',D12.4,' RE=',D12.4,' TOE=',  
     'D12.4,4X))  
     DO 332 J=1,IKK  
     QVEL(J\*4-3)= 2.0\*DELD(J\*4-3)/DELTAT-QVEL(J\*4-3)  
     QVEL(J\*4-2)= 2.0\*DELD(J\*4-2)/DELTAT-QVEL(J\*4-2)  
     QVEL(J\*4)= (3.0\*DELD(J\*4)-DELDI1(J\*4))/(2.0\*DELTAT)  
     QVEL(J\*4-1)=(3.0\*DELD(J\*4-1)-DELDI1(J\*4-1))/(2.0\*DELTAT)  
 332 CONTINUE  
     GOTO 356  
 333 CONTINUE  
     DO 355 I=1,NI  
     QVEL(I)= (3.0\*DELD(I)-DELDI1(I))/(2.0\*DELTAT)  
 355 CONTINUE  
 356 CONTINUE  
     DO 340 I=1,NI  
     DELDI1(I) = DELD(I)

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DISUM(I) = 2.0*(DISP(I)+DELTAT*QVEL(I))	MAIN6490
DIS(I) = DISP(I)	MAIN6500
340 CONTINUE	MAIN6510
CALL OMULT(BMASS,DISUM,ICOL,NI,FLVM,KROW,NDEX,NIRREG)	MAIN6520
DO 341 I=1,NI	MAIN6530
FLVM(I) = -(2.0*FLVA(I)-FLN(I)) *DTSQ+FLVM(I)	MAIN6540
341 CONTINUE	MAIN6550
IF(NBCOND.EQ.0) GO TO 124	MAIN6560
DO 125 I=1,NBCOND	MAIN6570
JT4=NODEB(I)*4	MAIN6580
FLVM(JT4-3)=0.0	MAIN6590
IF(NBC(I).EQ.1.OR.NBC(I).EQ.2) FLVM(JT4-1)=0.0	MAIN6600
IF(NBC(I).EQ.2.OR.NBC(I).EQ.3) FLVM(JT4-2)=0.0	MAIN6610
125 CONTINUE	MAIN6620
124 CALL SOLV(AMASS,FLVM,DIS,ICOL,KROW,NDEX,NI,NIRREG)	MAIN6630
DO 430 I=1,NI	MAIN6640
DELD(I) = DIS(I)-DISP(I)	MAIN6650
QACL(I) = 2.0D+00 *(DELD(I)-DELTAT*QVEL(I))	MAIN6660
QCD(I) = (DELD(I)-DELD(I-1))/DTSQ	MAIN6670
430 CONTINUE	MAIN6680
DO 6701 I=1,IKK	MAIN6690
ITHR(I) = 0	MAIN6700
EPSI(I) = 0.0	MAIN6710
6701 EPSO(I) = 0.0	MAIN6720
MIZ=0	MAIN6730
NPZ= IT-NPZ1	MAIN6740
IF(NPZ.NE.0) GOTO 6700	MAIN6750
MIZ= 1	MAIN6760
NPZ1 = NPZ1+M2	MAIN6770
IF(LGSP.EQ.0) GOTO 6700	MAIN6780
WRITE(MWRITE,11100)	MAIN6790
WRITE(MWRITE,6705) IT	MAIN6800
6705 FORMAT('0 CYCLE=' , I8)	MAIN6810
WRITE(MWRITE,6707)	MAIN6820
6707 FORMAT(' ELEMENT',9X,'SI',4X,'STA 1',4X,'SO',21X,'SI',4X,'STA 2',	MAIN6830
* 4X,'SO',21X,'SI',4X,'STA 3', 4X,'SO')	MAIN6840

C GAUSSIAN STATION STRAIN CALCULATION

6700 DO 7161 IR=1,IK  
 K1= NVEC(IR,1)  
 K2= NVEC(IR,2)  
 LSS= MKE(IR)  
 DO 8018 K=1,8  
 INDEX= (K1-1)\*4+K  
 IF (K.GT.4) INDEX= (K2-1)\*4+K-4  
 DISM(K) = DISP(INDEX)  
 8018 CONTINUE  
 IF (YK(IR).EQ.0.0) GOTO 901  
 CALL ROTAT(1,DUMMY,DISM,IR)  
 901 CONTINUE  
 DO 604 I=1,NOGA  
 DO 604 J=1,3  
 BEPS(I,J) = 0.0  
 DO 604 K=1,8  
 604 BEPS(I,J)=BEPS(I,J)+BEP(IR,I,J,K)\*DISM(K)  
 NLAP= NLAY  
 IF(MKE(IR).GT.1) NLAP =1  
 H1= H(K1,1)  
 H2 = H(K2,1)  
 N=MKE(IR)-1  
 IF(YK(IR).EQ.1.0.AND.ROT(N,1).EQ.1.0) H(K1,1)= HTH(N)  
 IF(YK(IR).EQ.1.0.AND.ROT(N,1).EQ.0.0) H(K2,1)= HTH(N)  
 DO 8908 LM= 1,NLAP  
 8908 HDIF(LM) = H(K2,LM) - H(K1,LM)  
 DO 60 M=1,NOGA  
 HINN=0.0  
 HOUT = 0.0  
 IF(NLAY.EQ.1) GOTO 8931  
 IF(IREF-2) 8935,8936,8937  
 8935 HL1= (H(K1,1)+HDIF(1)\*AXG(M))/2.0  
 HL2= HL1+H(K1,2)+HDIF(2)\*AXG(M)  
 GOTO 8938  
 8936 HL1= -(H(K1,2)+HDIF(2)\*AXG(M))/2.0

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      HL2= -HL1
      IF(NLAP.EQ.2) HL2=0.0
      GOTO 8938
8937  HL2=- (H(K1,3)+HDIF(3)*AXG(M))/2.0
      HL1= HL2-(H(K1,2)+HDIF(2)*AXG(M))
8938  CONTINUE
      DO 8909 LM= 1,LREF
      DIVI= 1.0
      IF(LM.EQ.LREF) DIVI=2.0
      HINN= HINN+ (H(K1,LM)+HDIF(LM)*AXG(M)) / DIVI
8909  CONTINUE
      DO 8911 LM= LREF,NLAP
      DIVI= 1.0
      IF(LM.EQ.LREF) DIVI=2.0
      HOUT= HOUT+ (H(K1,LM)+HDIF(LM)*AXG(M)) / DIVI
8911  CONTINUE
      GOTO 8932
8931  HINN= (H(K1,1)+HDIF(1)*AXG(M))/2.0
      HOUT= HINN
      HL1= 0.0
      HL2= 0.0
8932  CONTINUE
      FARE= BEPS(M,1)+BEPS(M,2)**2/2.0
      *+BEPS(M,1)**2/2.
      IF(INTERP.EQ.0) GOTO 8939
      IF(NLAP.EQ.1) GOTO 8939
C    FOR MEMBRANE SET HL1 AND HL2 =0.0
      EPL1(M) = FARE+HL1*BEPS(M,3)
      EPL2(M) = FARE+HL2*BEPS(M,3)
      IF(NLAP.EQ.2) EPL2(M) = 0.0
      IF(EPL1(M).LE.BIGL) GOTO 8940
      BIGL= EPL1(M)
      IBIGL= IR
      ISTAL= M
      ISURFL=1
      BTIMEL= TIME

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8940 IF (NLAY.EQ.2) GOTO 8939
      IF (EPL2(M).LE.BIGL) GOTO 8939
      BIGL= EPL2(M)
      IBIGL= IR
      ISTAL= M
      ISURFL=2
      BTIMEL= TIME
8939 CONTINUE
C   FOR MEMBRANE SET HINN AND HOUT =0.0
      EPI(M)= FARE- HINN*BEPS(M,3)
      EPO(M) = FARE+HOUT*BEPS(M,3)
      IF (EPI(M).LE.BIG(LSS)) GO TO 591
      BIG(LSS) = EPI(M)
      IBIG(LSS)= IR
      ISTA(LSS) = M
      ISURF(LSS) = 1
      BTIME(LSS) = TIME
591  IF (EPO(M).LE.BIG(LSS)) GO TO 1200
      BIG(LSS) = EPO(M)
      IBIG(LSS)= IR
      ISTA(LSS) = M
      ISURF(LSS) = 2
      BTIME(LSS) = TIME
1200 CONTINUE
60   CONTINUE
C   AVERAGE NODAL STRAIN CALCULATION
C   AT A NODE WHERE A BRANCH ATTACHES TO THE MAIN STRUCTURE,
C   THE BRANCH'S NODAL STRAIN IS NOT AVERAGED IN
      DO 6604 I=1,2
      DO 6604 J=1,3
      BEPS(I,J) = 0.0
      DO 6604 K=1,8
6604 BEPS(I,J) = BEPS(I,J) +DEP(IR,I,J,K)* DISM(K)
      FAR1 =BEPS(1,1)+BEPS(1,2)**2/2.0 +BEPS(1,1)**2/2.0
      FAR2 =BEPS(2,1)+BEPS(2,2)**2/2.0 +BEPS(2,1)**2/2.0
      NKE = MKE(IR)

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NLAP = NLAY  
 IF (NKE.GT.1) NLAP=1  
 IF (NLAP.EQ.1) GOTO 6631  
 THI1= 0.0  
 THO1= 0.0  
 THI2= 0.0  
 THO2=0.0  
 DO 6619 L=1,LREF  
 DIVI= 1.0  
 IF (L.EQ.LREF) DIVI=2.0  
 THI1= THI1 + H(K1,L)/DIVI  
 6619 THI2= THI2+ H(K2,L)/DIVI  
 DO 6620 L= LREF,NLAP  
 DIVI=1.0  
 IF (L.EQ.LREF) DIVI= 2.0  
 THO1= THO1+ H(K1,L)/DIVI  
 6620 THO2= THO2+ H(K2,L)/DIVI  
 GOTO 6622  
 6631 THI1= H(K1,1)/2.0  
 THI2= H(K2,1)/2.0  
 THO1= THI1  
 THO2= THI2  
 6622 CONTINUE  
 IF (NKE.EQ.1) GOTO 6605  
 IF (MATT(NKE-1).EQ.K1) GOTO 6606  
 6605 ADEN = 1.0  
 IF (ITHR(K1).GT.0) ADEN=2.0  
 ITHR(K1) = 1  
 C FOR MEMBRANE SET THI1,THO1,THI2,THO2=0.0  
 EPSI(K1)=(EPSI(K1) + FAR1- THI1\*BEPS(1,3)/2.0) /ADEN  
 EPSO(K1) =(EPSO(K1) + FAR1+ THO1\*BEPS(1,3)/2.0) /ADEN  
 IF (NKE.EQ.1) GOTO 6606  
 IF (MATT(NKE-1).EQ.K2) GOTO 6607  
 6606 ADEN = 1.0  
 IF (ITHR(K2).GT.0) ADEN=2.0  
 ITHR(K2) = 1

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      EPSI (K2) = (EPSI (K2) + FAR2- TH12*BEPS (2,3)/2.0) /ADEN
      EPSO (K2) = (EPSO (K2) + FAR2+ TH02 * BEPS (2,3)/2.0) /ADEN
6607  CONTINUE
      H (K1,1) = H1
      H (K2,1) = H2
      IF (M12.NE.1) GO TO 7161
      IF (LGSP.EQ.0) GO TO 7161
7940  WRITE (MWRITE,6710) IR, (EPI (L), EPO (L), L=1,3)
6710  FORMAT (' ',I3,2X,3(3X,D15.8,3X,D15.8,3X))
      IF (NLAP.EQ.1) GOTO 7161
      IF (NTERP.EQ.0) GOTO 7161
      WRITE (MWRITE,6609) (EPL1 (L), EPL2 (L), L=1,3)
6609  FORMAT (' ',5X,3(3X,D15.8,3X,D15.8,3X))
7161  CONTINUE
C     FIND LARGEST AVERAGE NODAL STRAIN
      DO 7170 I= 1,IKK
        N= 0
        DO 7171 IR=1,IK
          IF (NVEC (IR,1).NE.I) GOTO 7172
          IF (MKE (IR).EQ.1) N= N+1
          IF (MKE (IR).GT.1) N= N+3
          IF (MKE (IR).GT.1) NKE=MKE (IR)
7172  CONTINUE
          IF (NVEC (IR,2).NE.I) GOTO 7171
          IF (MKE (IR).EQ.1) N=N+1
          IF (MKE (IR).GT.1) N= N+3
          IF (MKE (IR).GT.1) NKE= MKE (IR)
7171  CONTINUE
          NK=1
          IF (N.EQ.3.OR.N.EQ.6) NK=NKE
          IF (EPSI (I).LE.BI (NK)) GOTO 7174
          BI (NK) = EPSI (I)
          IBI (NK) = I
          ISUR (NK) = 1
          BTIM (NK) = TIME
7174  IF (EPSO (I).LE.BI (NK)) GOTO 7170

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BI(NK) = EPSO(I)  
 IBI(NK) = I  
 ISUR(NK) = 2  
 BTIM(NK) = TIME  
 7170 CONTINUE  
 7180 CONTINUE  
 IF(LSPP.EQ.0) GOTO 8562  
 IF(MIZ.NE.1) GOTO 8700  
 WRITE(MWRITE,6705) IT  
 WRITE(MWRITE,8707)  
 8707 FORMAT(' STRAIN AT ADDITIONAL POINTS',10X,'SI',18X,'SO',23X,'EI',  
 @18X,'EO')  
 8700 DO 8761 IR= 1,IK  
 IF(LKK(IR,1).EQ.0) GOTO 8761  
 NLAP= NLAY  
 IF(MKE(IR).GT.1) NLAP =1  
 K1 = NVEC(IR,1)  
 K2= NVEC(IR,2)  
 DO 8019 K=1,8  
 INDEX= (K1-1)\*4+K  
 IF(K.GT.4) INDEX= (K2-1)\*4+K-4  
 DISM(K) = DISP(INDEX)  
 8019 CONTINUE  
 IF(YK(IR).EQ.0.0) GOTO 902  
 CALL ROTAT(1,DUMMY,DISM,IR)  
 902 CONTINUE  
 H1= H(K1,1)  
 H2 = H(K2,1)  
 L= MKE(IR)  
 N=MKE(IR)-1  
 IF(YK(IR).EQ.1.0.AND.ROT(N,1).EQ.1.0) H(K1,1) = HTH(N)  
 IF(YK(IR).EQ.1.0.AND.ROT(N,1).EQ.0.0) H(K2,1) = HTH(N)  
 NO= LKK(IR,1)  
 DO 8763 I= 1,NO  
 IS = LKK(IR,I+1)  
 DO 8604 J=1,3

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      AEPS(J) = 0.0
      DO 8604 K= 1,8
8604  AEPS(J)=AEPS(J) + AEP(IS,J,K)*DISM(K)
      DO 8918 LM= 1,NLAP
8918  HDIF(LM) = H(K2,LM) - H(K1,LM)
      HINN=0.0
      HOUT = 0.0
      IF(NLAP.EQ.1) GOTO 8941
      IF(LREF-2) 8735,8736,8737
8735  HL1= (H(K1,1)+HDIF(1)*AXG(M))/2.0
      HL2= HL1+ H(K1,2)+HDIF(2)*AXG(M)
      GOTO 8738
8736  HL1= -(H(K1,2)+HDIF(2)*AXG(M))/2.0
      HL2= -HL1
      IF(NLAP.EQ.2) HL2= 0.0
      GOTO 8738
8737  HL2= -(H(K1,3)+HDIF(3)*AXG(M))/2.0
      HL1= HL2-(H(K1,2)+HDIF(2)*AXG(M))
8738  CONTINUE
      DO 8919 LM= 1,LREF
      DIVI= 1.0
      IF(LM.EQ.LREF) DIVI=2.0
      HINN= HINN+ (H(K1,LM) + HDIF(LM)*AZET(IS)) / DIVI
8919  CONTINUE
      DO 8921 LM= LREF,NLAP
      DIVI= 1.0
      IF(LM.EQ.LREF) DIVI=2.0
      HOUT= HOUT+ (H(K1,LM) + HDIF(LM)* AZET(IS)) / DIVI
8921  CONTINUE
      GOTO 8942
8941  HINN= (H(K1,1)+HDIF(1)*AZET(IS))/ 2.0
      HOUT = HINN
      HL1= 0.0
      HL2= 0.0
8942  CONTINUE
      FARE= AEPS(1)+AEPS(2)**2/2.0+AEPS(1)**2/2.0

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      IF (NTERF.EQ.0) GOTO 8739
      IF (NLAP.EQ.1) GOTO 8739
C    THIS IS A CALCULATION OF THE STRAINS AT THE INTERFACES
C    FOR MEMBRANE SET HL1 AND HL2 =0.0
      EPAS1= FARE+HL1* AEPS (3)
      EPAS2= FARE+HL2*AEPS(3)
      IF (NLAP.EQ.2) EPAS2= 0.0
      IF (EPAS1.LE.BIGAL) GOTO 8740
      BIGAL= EPAS1
      IBIGAL= IR
      ISTAAL= IS
      BTIMAL= TIME
      ISURAL= 1
8740 IF (NLAY.EQ.2) GOTO 8739
      IF (EPAS2.LE.BIGAL) GO TO 8739
      BIGAL= EPAS2
      IBIGAL= IR
      ISTAAL= IS
      BTIMAL= TIME
      ISURAL = 2
8739 CONTINUE
C    FOR MEMBRANE SET HINN AND HOUT =0.0
      EPASI = FARE- HINN*AEPS(3)
      EPASO = FARE+ HOUT*AEPS(3)
C    FIND LARGEST ADDITIONAL POINT STRAIN
      IF (EPASI.LE.BIGA(L)) GO TO 8591
      BIGA(L) = EPASI
      IBIGA(L) = IR
      ISTAA(L) = IS
      BTIMA(L) = TIME
      ISURA(L) = 1
8591 IF (EPASO.LE.BIGA(L)) GO TO 8780
      BIGA(L) = EPASO
      IBIGA(L) = IR
      ISTAA(L) = IS
      BTIMA(L) = TIME

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      ISURA(L) = 2
8780 IF(MIZ.NE.1) GO TO 8763
      EI= DSQRT(1.0+2.0* EPASI) -1.0
      EO= DSQRT(1.0+2.0* EPASO) -1.0
      WRITE(MWRITE,8781) IS,EPASI,EPASO,EI,EO
8781 FORMAT(' ',10X,I3,16X,D15.8,4X,D15.8,11X,D15.8,4X,D15.8)
      IF(NLAP.EQ.1) GOTO 8763
      IF(NTERF.EQ.0) GOTO 8763
      WRITE(MWRITE,8609) EPAS1,EPAS2
8609 FORMAT(' ',29X,D15.8,4X,D15.8)
8763 CONTINUE
      H(K1,1) = H1
      H(K2,1) = H2
8761 CONTINUE
8562 CONTINUE
      IF(IT-M1) 131,140,150
140   M1=M1+M2
      CALL PRINT(IT,TIME,HINN,HOUT,APDEN,SPRIN,BMASS,C2,NQR,CINETO,
      *BEP,WET,NV,ES,ASFL,SNS,NV1,NV2,NV3,SOL,QVEL)
      IF(NBCOND.EQ.0) GOTO 260
      DO 276 I=1,NI
      REAFK(I) =0.0
276  CONTINUE
      CALL OMULT(REACK,DISP,ICOL,NI,REAFK,KROW,NDEX,NIRREG)
      DO 261 I=1,21
261  REAC(I) =0.0
      DO 262 I=1,NBCOND
      J= NODEB(I)*4
      K= (I-1)*3
      REAC(K+1) = REAFK(J-3)+FLVA(J-3)
      IF(NBC(I).EQ.1.OR.NBC(I).EQ.2) REAC(K+3)=REAFK(J-1)+FLVA(J-1)
      IF(NBC(I).EQ.2.OR.NBC(I).EQ.3) REAC(K+2)=REAFK(J-2)+FLVA(J-2)
262  CONTINUE
      WRITE(MWRITE,256)
256  FORMAT(' 0',6X,'REACTIONS AT NODE ',15X,'RV(LBS)',13X,'RW(LBS)',
      @11X,'RM(IN-LBS)')

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DO 252 I=1,NBCOND	MAIN0090
J= (I-1) *3	MAIN0100
WRITE(MWRITE,253) NODEB(I),REAC(J+1),REAC(J+2),REAC(J+3)	MAIN0110
253 FORMAT(' ',18X,I4,5X,3D20.6)	MAIN0120
252 CONTINUE	MAIN0130
260 CONTINUE	MAIN0140
M=NBR+1	MAIN0150
WRITE(MWRITE,66)	MAIN0160
WRITE(MWRITE,67) (L,BIG(L),IBIG(L),ISURF(L),ISTA(L),BTIME(L),L=1,M)	MAIN0170
IF(NTERF.EQ.0) GOTO 1272	MAIN0180
WRITE(MWRITE, 59) BIGL,IBIGL,ISURFL,ISTAL,BTIMEL	MAIN0190
59 FORMAT(' INTERFACE',4X,D15.6,1X,I4,4X,I4,4X,I4,4X,D15.6)	MAIN0200
1272 CONTINUE	MAIN0210
IF(LSPP.NE.1) GO TO 8782	MAIN0220
WRITE(MWRITE,6030)	MAIN0230
WRITE(MWRITE,6035) (L,BIGA(L),IBIGA(L),ISTAA(L),BTIMA(L),ISURA(L),	MAIN0240
@L=1,M)	MAIN0250
IF(NTERF.EQ.0) GOTO 1273	MAIN0260
WRITE(MWRITE,1271) BIGAL,IBIGAL,ISTAAL,BTIMAL,ISURAL	MAIN0270
1271 FORMAT(' INTERFACE',14X,D15.6,7X,I3,6X,I5,5X,D15.6,6X,I4)	MAIN0280
1273 CONTINUE	MAIN0290
3782 CONTINUE	MAIN0300
WRITE(MWRITE,7181)	MAIN0310
WRITE(MWRITE,7182) (L,BI(L),IBI(L),ISUR(L),BTIM(L),L=1,M)	MAIN0320
7181 FORMAT(' OSUBSTRUCTURE',5X,'LARGEST NODAL STRAIN ',5X,'NODE',7X,	MAIN0330
@'SURF',11X,'TIME')	MAIN0340
7182 FORMAT(' ',4X,I3,16X,D15.6,7X,I3,6X,I5,5X,D15.6)	MAIN0350
WRITE(MWRITE,11100)	MAIN0360
11100 FORMAT(' 0*****MAIN0370	
@*****MAIN0380	
@*****',/)	MAIN0390
131 IF(IT-MM) 120,170,150	MAIN0400
170 CONTINUE	MAIN0410
WRITE(MWRITE,6002)	MAIN0420
6002 FORMAT(' OTHE LARGEST COMPUTED STRAINS FOR EACH SUBSTRUCTURE--	MAIN0430
@MAIN AND BRANCHES -- ARE PRINTED BELOW, 1= INNER 2= OUTER SURF')	MAIN0440



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      M= NBR+1
      WRITE(MWRITE,66)
      WRITE(MWRITE,67) (L,BIG(L),IBIG(L),ISURF(L),ISTA(L),BTIME(L),L=1,M)
66  FORMAT('OSUBSTRUCTURE',8X,'MSTR',7X,'ELE',5X,'SURF',5X,'STA',
      @9X,'TIME')
67  FORMAT(' ',3X,I4,6X,D15.6,1X,I4,4X,I4,4X,I4,4X,D15.6)
      IF(NTERF.EQ.0) GOTO 1274
      WRITE(MWRITE, 59) BIGL,IBIGL,ISURFL,ISTAL,BTIMEL
1274 CONTINUE
      IF(LSPP.NE.1) GOTO 149
      WRITE(MWRITE,6030)
      WRITE(MWRITE,6035) (L,BIGA(L),IBIGA(L),ISTAA(L),BTIMA(L),ISURA(L),
      @L=1,M)
6030 FORMAT('OSUBSTRUCTURE',5X,'LARGEST ADD. PT. STRAIN',5X,'ELEM',5X,
      @'ADD. PT.',9X,'TIME',10X,'SURFACE')
6035 FORMAT(' ',4X,I3,16X,D15.6,7X,I3,6X,I5,5X,D15.6,6X,I4)
      IF(NTERF.EQ.0) GOTO 149
      WRITE(MWRITE,1271) BIGAL,IBIGAL,ISTAAL,BTIMAL,ISURAL
149  CONTINUE
      WRITE(MWRITE,7181)
      WRITE(MWRITE,7182) (L,BI(L),IBI(L),ISUR(L),BTIM(L),L=1,M)
150  IF(MPU.EQ.0) GOTO 160
      WRITE(MPUNCH,83) IT,TIME,IMCOU,TAII
      M= NBR+1
      WRITE(MPUNCH,86) (IBIGA(L),ISTAA(L),BIGA(L),BTIMA(L),ISURA(L),
      @L=1,M)
      WRITE(MPUNCH,386) (IBIG(L),ISURF(L),ISTA(L),BIG(L),BTIME(L),L=1,M)
      WRITE(MPUNCH,387) (IBI(L),ISUR(L),BI(L),BTIM(L),L=1,M)
      WRITE(MPUNCH,89) MIRP, (TNJ(I),I=1,NF)
      WRITE(MPUNCH,84) (DISP(I),I=1,NI)
      WRITE(MPUNCH,84) (DELD(I),I=1,NI)
      WRITE(MPUNCH,84) (DELDM1(I),I=1,NI)
      WRITE(MPUNCH,84) (FLVA(I),I=1,NI)
      WRITE(MPUNCH,84) (QVEL(I),I=1,NI)
      WRITE(MPUNCH,84) (QACL(I),I=1,NI)
      WRITE(MPUNCH,84) (((S NS(IR,J,K,L),L=1,MNSFL),K=1,NFL),J=1,NOGA),

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*IR=1,IK)	MAIN0810
WRITE(MPUNCH,84) ((( (SNP (IR,J,K,L),L=1,MNSFL),K=1,NFL),J=1,NOGA),	MAIN0820
*IR=1,IK)	MAIN0830
WRITE(MPUNCH,84) (FCGU(J),FCGW(J),ALFA(J),UDOT(J),WDOT(J)	MAIN0840
*,ADOT(J),J=1,NF)	MAIN0850
WRITE(MWRITE,6005)	MAIN0860
6005 FORMAT(' OCONTINUATION CARDS HAVE BEEN PUNCHED FOR THIS RUN')	MAIN0870
GO TO 161	MAIN0880
160 WRITE(MWRITE,6036)	MAIN0890
6036 FORMAT(' ONO CARDS PUNCHED DURING THIS RUN FOR CONTINUATION.')	MAIN0900
161 IF(ICON.EQ.0) GOTO 151	MAIN0910
IRRUN = IRRUN + 1	MAIN0920
GO TO 5555	MAIN0930
151 CALL EXIT	MAIN0940
END	MAIN0950
SUBROUTINE IMPACT(EFLN,IT,NBR,QACL,QVEL,BMASS,AMASS,FLN)	IMPA0010
IMPLICIT REAL*8(A-H,O-Z)	IMPA0020
DIMENSION DISM(205),DISUM(205),FLVM(205),BMASS(1),AMASS(1),FLN(1)	IMPA0030
DIMENSION PD(50,6),PALE(50,6)	IMPA0040
DIMENSION QACL(205),QVEL(205)	IMPA0050
DIMENSION AY(51),AZ(51)	IMPA0060
DIMENSION TU(205),TW(205)	IMPA0070
DIMENSION VY(51),VZ(51),TFCGU(6),TFCGW(6),TALFA(6),IFLAG(51,6),	IMPA0080
2NTSD(6),NEF(6),RL(50),EFLN(6)	IMPA0090
DIMENSION AYCD(51),AZCD(51)	IMPA0100
COMMON /HIT/ TNJ(6),MIRP	IMPA0110
COMMON /ACC/ QCD(205)	IMPA0120
COMMON/IMPT/ VEL(102),IMCO,JVEL(51)	IMPA0130
COMMON/TAPE/MREAD,MWRITE,MPUNCH	IMPA0140
COMMON/FC/ Y(51),Z(51),ANG(51),H(51,3)	IMPA0150
COMMON /VQ/ FLVA(205),DISP(205),DELD(205),BINP(50,3),BIMP(50,3)	IMPA0160
COMMON /FRAGV/ VELFU(3),VELFW(3),VELFA(3)	IMPAC170
COMMON/FRAG/ FH(3),FMASS(3),FMOI(3),UNK(3),CR(3),FCGU(3),FCGW(3),	IMPA0180
DALFA(3),DFCGU(3),DFCGW(3),DALFA(3),TREL,FKT(3),DELTAT,NF,MIMP	IMPA0190
COMMON/FG/ IK,IKK,ICP,LREF,NOGA,NFL,NI,ICOL(205),INUM(205)	IMPA0200
D,NBCOND,NBC(7),NODEB(7),KROW(8),NDEX(8),NIRREG	IMPA0210
COMMON/BR/ NVEC(51,2),LMT(51)	IMPA0220
COMMON/LEFT/RMASS(51)	IMPA0230

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COMMON/IIAT/ TAIL, IMCOU  
 COS(ZZZ)=DCOS(ZZZ)  
 SIN(ZZZ)=DSIN(ZZZ)  
 C \*\*\*\*\*  
 C  
 C \*\*\*\* MODIFIED IMPACT CONTROLLING ROUTINE \*\*\*\*\*  
 C  
 C CURRENT TIME REMAINING IN THIS TIME STEP=EXTERNAL TIME STEP  
 C AND CURRENT TIME = TB.  
 TIMEI=(IT-1)\*DELTAT  
 TIMEF = IT\*DELTAT  
 DELTR=DELTAT  
 TB=TIMEI  
 JF=1  
 8100 FORMAT(' VZ=',10D12.4)  
 8110 FORMAT(' TW=',10D12.4)  
 8120 FORMAT(' TFCGW=',D15.6,' VELFW=',D15.6)  
 8130 FORMAT(' DISM=',10D12.4)  
 8140 FORMAT(' FLVM86=',D15.6,' FLVM90=',D15.6)  
 C  
 C INITIALIZE CORRECTION 'FLAGS' TO NO-PREV.-CORR. POSITION (=0),  
 C AND NO. OF SUBDIVISIONS FOR EACH FRAG. TO ZERO  
 DO 5 I=1,IK  
 DO 5 J=1,NF  
 NTSD(J)=0  
 5 IFLAG(I,J)=0  
 C  
 C TRANSFORM NODAL VELOCITIES INTO Y AND Z COMPONENTS  
 C  
 C CALC. TRIAL POSITION OF RING NODES AND FRAGMENT TO THE END OF THIS  
 C INTERNAL TIME STEP  
 DO 7000 I=1,NI  
 7000 DISM(I)= DISP(I) + DELD(I)  
 C  
 C TRIAL POSITION OF FRAGMENT  
 C

IMPA0240  
 IMPA0250  
 IMPA0260  
 IMPA0270  
 IMPA0280  
 IMPA0290  
 IMPA0300  
 IMPA0310  
 IMPA0320  
 IMPA0330  
 IMPA0340  
 IMPA0350  
 IMPA0360  
 IMPA0370  
 IMPA0380  
 IMPA0390  
 IMPA0400  
 IMPA0410  
 IMPA0420  
 IMPA0430  
 IMPA0440  
 IMPA0450  
 IMPA0460  
 IMPA0470  
 IMPA0480  
 IMPA0490  
 IMPA0500  
 IMPA0510  
 IMPA0520  
 IMPA0530  
 IMPA0540  
 IMPA0550  
 IMPA0560  
 IMPA0570  
 IMPA0580  
 IMPA0590

C	RETURN POSITION FOR SUBSEQUENT INSPECTION AFTER INITIAL PENETRATION	IMPA0600
C	CORRECTION.	IMPA0610
	NEQ=0	IMPA0620
20	CONTINUE	IMPA0630
C		IMPA0640
	DO 7035 I=1,NF	IMPA0650
	TFCGU(I) = FCGU(I) + VELFU(I) * DELTR * TNJ(I)	IMPA0660
	TFCGW(I) = FCGW(I) + VELFW(I) * DELTR * TNJ(I)	IMPA0670
7035	TALFA(I) = ALFA(I) + VELFA(I) * DELTR * TNJ(I)	IMPA0680
6	DO 10 I=1,IKK	IMPA0690
	VY(I) = QVEL(I*4-3) * COS(ANG(I)) - QVEL(I*4-2) * SIN(ANG(I))	IMPA0700
10	VZ(I) = QVEL(I*4-3) * SIN(ANG(I)) + QVEL(I*4-2) * COS(ANG(I))	IMPA0710
	DO 7025 I=1,IKK	IMPA0720
	TU(I) = Y(I) + DISM(I*4-3) * COS(ANG(I)) - DISM(I*4-2) * SIN(ANG(I))	IMPA0730
	TW(I) = Z(I) + DISM(I*4-3) * SIN(ANG(I)) + DISM(I*4-2) * COS(ANG(I))	IMPA0740
7025	CONTINUE	IMPA0750
	IF(NTSD(JF).GT.5) GOTO 150	IMPA0760
	IF(NEQ.EQ.0) GOTO 7200	IMPA0770
	NEQ=NFQ-1	IMPA0780
	PD(IBIG,JF) = -1.0	IMPA0790
	DO 7210 IR=1,IK	IMPA0800
	DO 7210 J=1,NF	IMPA0810
	IF(PD(IR,J)-PMAX) 7210,7220,7220	IMPA0820
7210	CONTINUE	IMPA0830
	GOTO 7200	IMPA0840
7220	PAL= PALE(IR,J)/RL(IR)	IMPA0850
	IBIG=IR	IMPA0860
	JF=J	IMPA0870
	GOTO 7290	IMPA0880
7200	CONTINUE	IMPA0890
C		IMPA0900
C	CALC. PENETRATION DISTANCES FOR THIS TRIAL POSITION.	IMPA0910
	CALL PENIRN(TU,TW,TFCGU,TFCGW,NPP,PMAX,NEF,NEQ,JF,PAL,RL,IBIG,	IMPA0920
	2H,FH,IK,NF,ICP,PL,PALE)	IMPA0930
C		IMPA0940
C	CHECK PENETRATIONS.	IMPA0950

C	IF THE NUMBER OF POSITIVE PENETRATIONS, NPP, IS ZERO, AND THE	IMPA0960
C	MAX.PENETRATION IS LESS THAN ZERO, NO (MORE) PENETRATIONS OCCUR FOR	IMPA0970
C	THIS TIME STEP.	IMPA0980
	IF(NPP.EQ.0.AND.PMAX.LT.0.0)GO TO 150	IMPA0990
C		IMPA1000
C	IF MAX. PENETRATION IS ZERO, SKIP SUBDIVISION PROCESS.	IMPA1010
	7290 CONTINUE	IMPA1020
	TT=TB	IMPA1030
	TMIN=DELTA	IMPA1040
C		IMPA1050
C	RETURN FRAGMENT AND NODAL POSITIONS TO BEGINNING OF THIS INTERNAL	IMPA1060
C	TIME STEP.	IMPA1070
	DO 35 I=1,NF	IMPA1080
	TFCGU(I)=FCGU(I)	IMPA1090
	TFCGW(I)=FCGW(I)	IMPA1100
35	TALFA(I)=ALFA(I)	IMPA1110
	DO 25 I=1,IKK	IMPA1120
	TU(I)=Y(I)+DISP(I*4-3)*COS(ANG(I))-DISP(I*4-2)*SIN(ANG(I))	IMPA1130
	TW(I)=Z(I)+DISP(I*4-3)*SIN(ANG(I))+DISP(I*4-2)*COS(ANG(I))	IMPA1140
	25 CONTINUE	IMPA1150
C		IMPA1160
C	CALC. TIME OF CONTACT, ELEM. AFFECTED, AND POINT OF CONTACT.	IMPA1170
C		IMPA1180
C	UPDATE NODAL AND FRAG. POSITIONS TO THIS TIME	IMPA1190
100	CONTINUE	IMPA1200
	NTSD(JF)=NTSD(JF)+1	IMPA1210
	IMCOU = IMCOU+1	IMPA1220
C		IMPA1230
C	UPDATE NODAL VELOCITIES (VY,VZ), AND FRAGMENT VELOCITIES (VELFU,	IMPA1240
C	VELFW, VELFA) TO POST-IMPACT VALUES.	IMPA1250
	WRITE(MWPITE,8000) IMCOU,TT,IT,IBIG,JF,PAL	IMPA1260
8000	FORMAT('OIMPACT NO.',I5,5X,'TIME',D15.6,5X,'DURING CYCLE',I5,5X,	IMPA1270
	D'ELEM',I5,5X,'FRAG',I5,5X,'DISTANCE',D15.6)	IMPA1280
C		IMPA1290
C	TIME REMAINING IN THIS EXTERNAL TIME STEP	IMPA1300
	IF(IMCOU.EQ.1) TAIL = TT	IMPA1310

CALL IMPCTE(TU,TW,VY,VZ,VELFU,VELFW,VELFA,JF,IBIG,RMASS,	IMPA1320
2FMASS,FMCI,CF,UNK,PAI,EFLN,H,PH,IK,NF,ICP,RL,NBR,NRCOND,NODEB	IMPA1330
3,DELIR,AY,AZ,ANG,AYCE,AZCD)	IMPA1340
IMCO = 1	IMPA1350
DO 7050 I=1,IKK	IMPA1360
QVEL(I*4-3) = VY(I)*COS(ANG(I))+VZ(I)*SIN(ANG(I))	IMPA1370
QVEL(I*4-2) = -VY(I)*SIN(ANG(I))+VZ(I)*COS(ANG(I))	IMPA1380
7050 CONTINUE	IMPA1390
DO 7340 I=1,NI	IMPA1400
FLVM(I) = 0.0	IMPA1410
7340 DISUM(I) = 2.0*(DISP(I)+DELTAT*QVEL(I))	IMPA1420
CALL OMULT(BMASS,DISUM,ICOL,NI,FLVM,KROW,NDEX,NIRREG)	IMPA1430
DTSQ= DELTAT**2	IMPA1440
DO 7341 I=1,NI	IMPA1450
7341 FLVM(I) = -(2.0*FLVA(I)-FLN(I))*DTSQ+FLVM(I)	IMPA1460
IF(NBCOND.EQ.0) GOTO 7124	IMPA1470
DO 7125 I=1,NBCOND	IMPA1480
JT4 = NCEEB(I)*4	IMPA1490
FLVM(JT4-3) = 0.0	IMPA1500
IF(NBC(I).EQ.1.OR.NBC(I).EQ.2) FLVM(JT4-1)=0.0	IMPA1510
IF(NBC(I).EQ.2.OR. NBC(I).EQ.3) FLVM(JT4-2)= 0.0	IMPA1520
7125 CONTINUE	IMPA1530
7124 CONTINUE	IMPA1540
CALL SOLV(AMASS,FLVM,DISM,ICOL,KROW,NDEX,NI,NIRREG)	IMPA1550
C	IMPA1560
C CHECK FOR ADDITIONAL IMPACTS IN THIS EXTERNAL TIME STEP.	IMPA1570
GO TO 20	IMPA1580
C	IMPA1590
C NO ADDITIONAL IMPACTS OCCUR IN THIS TIME STEP.	IMPA1600
150 CONTINUE	IMPA1610
C	IMPA1620
C RETURN TO CONTROLLING ROUTINE WITH FINAL DISPLACEMENT INCREMENTS.	IMPA1630
C FRAGMENT LOCATION.	IMPA1640
DO 160 I=1,NF	IMPA1650
DFCGU(I) = TFCGU(I)-FCGU(I)	IMPA1660
DFCGW(I) = TFCGW(I)-FCGW(I)	IMPA1670

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160 DALFA(I) = TALFA(I) - ALFA(I)
C
C IF NO IMPACTS HAVE OCCURRED, NO FURTHER UPDATE IS REQUIRED.
  NSUM=0
  DO 165 I=1,NF
165  NSUM=NSUM+NTSD(I)
    IF(NSUM.EQ.0) RETURN
C
C IF IMPACT HAS OCCURED, UPDATE VELOCITIES
  DO 170 I=1,NI
170  DELD(I) = DISM(I) - DISP(I)
    RETURN
  END

  SUBROUTINE IMPCTE(TU,TW,VU,VW,VELFU,VELFW,VELFA,JBIG,IBIG,RMASS,
2FMASS,FMOI,CR,UNK,PAL,EFLN,H,PH,IK,NF,ICP,RL,NBR,NBCOND,NODEB
3,DELTR,AY,AZ,ANG,AYCD,AZCD)
  IMPLICIT REAL*8 (A-H,O-Z)
  DIMENSION NODEB(1), H(51,3)
  DIMENSION AY(1),AZ(1),ANG(1)
  DIMENSION AYCD(51), AZCD(51)
  DIMENSION TU(1),TW(1),VU(1),VW(1),VELFU(1),VELFW(1),VELFA(1),
2FMASS(1),RMASS(1),FMOI(1),CR(1),UNK(1),EFLN(1),RL(1),PH(1)
  DIMENSION      SSL(25),GAM(25),BET(25),SSR(25)
  DIMENSION MNO(51), MNOD(51), LT(11),PK(11)
  DIMENSION MBC(8), EF(6)
  COMMON /BOUN/ YK(51),NBCONB,NBCB(7),NODBB(7),MK(51),ROT(5,2)
2,XDIST(6),DRCT(50),NODP(6)
  COMMON/IMPT/ VEL(102),IMCO,JVEL(51)
  COMMON /TAPE/ MREAD,MWRITE,MPUNCH
  COMMON/BR/ NVEC(51,2), LMT(51)
  COMMON /TAM/ MKE(51)
  COMMON /ML/ MNEL(6),MATT(6)
  SIN(Q) = DSIN(Q)
  COS(Q) = DCOS(Q)
  MEF=1

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IMPA1680
IMPA1690
IMPA1700
IMPA1710
IMPA1720
IMPA1730
IMPA1740
IMPA1750
IMPA1760
IMPA1770
IMPA1780
IMPA1790
IMPA1800

IMPT0010
IMPT0020
IMPT0030
IMPT0040
IMPT0050
IMPT0060
IMPT0070
IMPT0080
IMPT0090
IMPT0100
IMPT0110
IMPT0120
IMPT0130
IMPT0140
IMPT0150
IMPT0160
IMPT0170
IMPT0180
IMPT0190
IMPT0200
IMPT0210
IMPT0220

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IMPT0230  
 IMPT0240  
 IMPT0250  
 IMPT0260  
 IMPT0270  
 IMPT0280  
 IMPT0290  
 IMPT0300  
 IMPT0310  
 IMPT0320  
 IMPT0330  
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 IMPT0370  
 IMPT0380  
 IMPT0390  
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 IMPT0530  
 IMPT0540  
 IMPT0550  
 IMPT0560  
 IMPT0570  
 IMPT0580

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NS=IK  
 IF(ICP.GT.0) NS = IK+1  
 IF(NBCOND.EQ.0) NODEB(1) = 0  
 DO 1000 I=1,IK  
 L1= NVEC(I,1)  
 L2= NVEC(I,2)  
 C ESTABLISH ELEMENT LENGTH, ANGLES AND DISTANCES TO NODES  
 RL(I) = DSORT((TW(L2)-TW(L1))\*\*2+(TU(L2)-TU(L1))\*\*2)  
 1000 CONTINUE  
 JNER=NBR+1  
 DO 100 I=1,JNER  
 100 EF(I)= EFLN(1)  
 L1 = NVEC(1BIG,1)  
 L2 = NVEC(1BIG,2)  
 RSIN= (TW(L2)-TW(L1))/RL(1BIG)  
 RCOS= (TU(L2)-TU(L1)) / RL(1BIG)  
 IBI= NVEC(1BIG,1)  
 C PAL = DISTANCE TO NODE1 PAX = DISTANCE TO NODE2  
 IF(PAL.EQ.0.C.OR.PAL.EQ.1.0) GOTO 937  
 GOTO 934  
 937 LZ=L1  
 IF(PAL.EQ.1.0) LZ=L2  
 DO 1007 I=1,NBCOND  
 IF(LZ.EQ.NODEB(I)) GOTO 1006  
 1007 CONTINUE  
 GOTO 934  
 1006 CONTINUE  
 KII=1  
 BET(1) = 0.0  
 MNOD(1) = NVEC(1BIG,1)  
 IF(PAL.EQ.1.0) MNOD(1) = NVEC(1BIG,2)  
 GOTO 936  
 934 CONTINUE  
 PAL= PAL\*RL(1BIG)  
 PAX= RL(1BIG)-PAL  
 5555 CONTINUE



MBC(1) = 0	IMPT0590
ZK=1.0	IMPT0600
MIML=0	IMPT0610
MIMR = 0	IMPT0620
DO 998 I= 2,JNBR	IMPT0630
998 EFLN(I) = EF(I)	IMPT0640
MMFL = 0	IMPT0650
KIL=1	IMPT0660
C ESTABLISH THE NUMBER OF NODES COUNTERCLOCKWISE FROM IMPACT WITHIN	IMPT0670
SSL(KIL)=PAL	IMPT0680
MEF=MKE(IBIG)	IMPT0690
IF(MEF.EQ.1) GO TO 1010	IMPT0700
WRITE (MWRITE,1009)	IMPT0710
1009 FORMAT(' IMPACT ON A BRANCH IS NOT PRESENTLY ALLOWED-- NO IMPACT')	IMPT0720
GO TO 350	IMPT0730
1010 CONTINUE	IMPT0740
IF(PAL.GE.EFLN(MEF)) GO TO 300	IMPT0750
MNO(KIL) = NVEC(IBIG, 1)	IMPT0760
IFF = 0	IMPT0770
IF2=0	IMPT0780
IF3 = 0	IMPT0790
MIML=1	IMPT0800
DO 301 J=1,25	IMPT0810
GAM(KIL) = ZK-SSL(KIL-IF3)/EFLN(MEF)	IMPT0820
IF(MMFL.NE.1) GO TO 931	IMPT0830
EFLN(MEF) = C.99*SSL(KIL-IF3)	IMPT0840
GO TO 5555	IMPT0850
931 DO 940 NC=1,NBCOND	IMPT0860
IF(MNO(KIL).NE.NODEB(NC)) GOTO 940	IMPT0870
MBC(1) = MBC(1) +1	IMPT0880
MBC(MBC(1)+1) = NODEB(NC)	IMPT0890
MMFL=1	IMPT0900
IF(MNO(KIL).NE.1.AND.MKE(JEL-1).EQ.1) GOTO 932	IMPT0910
EFLN(MEF) = SSL(KIL-IF3)	IMPT0920
GOTO 5555	IMPT0930
932 CONTINUE	IMPT0940

GOTO 950  
 940 CONTINUE  
 950 CONTINUE  
 JEL = IBIG - KIL - IFF  
 IF2 = 0  
 IF (ICP.LE.0.AND.JFL.LE.0) GO TO 302  
 IF (ICP.GT.0.AND.JEL.LE.0) JEL=JEL+IK

C CHECK FOR A BRANCH ATTACHMENT POINT

IF (NBR.EQ.0) GO TO 1038  
 DO 1020 I = 1, NBR  
 IF (MNO (KIL).NE.MATT (I)) GO TO 1020  
 NB = I+1  
 MTI = MATT (I)  
 EST = GAN (KIL)  
 GO TO 1030

1020 CONTINUE

GO TO 1038

C COMPUTE BRANCH NODES INVOLVED IN MOMENTUM TRANSFER,

1030 RX = 0.0

IF (MMFL.EQ.1) GOTO 1038

NUMB = 0

MBFL=0

KL = 0

DO 1035 I= 1,10

IF (MBFL.NE.1) GO TO 910

NUMB = NUMB+1

IF (NUMB.NE.2) GOTO 910

EFLN (NB) = 0.99\* RX/EST

GOTO 1030

910 CONTINUE

IF (NODP (NB-1).NE.1) GOTO 2050

IF ((MTI-1).EQ.0) GOTO 1037

RX= RX+RL (MTI-I)

P = EST-RX/EFLN (NB)

IF (P.LE.0.0) GO TO 1037

LT (KL+1) = MTI-I

IMPT0950  
 IMPT0960  
 IMPT0970  
 IMPT0980  
 IMPT0990  
 IMPT1000  
 IMPT1010  
 IMPT1020  
 IMPT1030  
 IMPT1040  
 IMPT1050  
 IMPT1060  
 IMPT1070  
 IMPT1080  
 IMPT1090  
 IMPT1100  
 IMPT1110  
 IMPT1120  
 IMPT1130  
 IMPT1140  
 IMPT1150  
 IMPT1160  
 IMPT1170  
 IMPT1180  
 IMPT1190  
 IMPT1200  
 IMPT1210  
 IMPT1220  
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 IMPT1250  
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 IMPT1280  
 IMPT1290  
 IMPT1300

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GOTO 2060  
 2050 CONTINUE  
 IF (MKE(MTI+I-1).NE.NB) GO TO 1037  
 RX= RX+RL(MTI+I-1)  
 P = EST-RX/CFLN(NB)  
 IF (P.LE.0.0) GO TO 1037  
 LT(KL+1) = MTI+I  
 2060 CONTINUE  
 PK(KL+1) = P  
 DO 900 NC= 1,NBCOND  
 IF (LT(KL+1).NE.NCDEB(NC)) GOTO 900  
 NBC(1) = NBC(1)+1  
 NBC(NBC(1)+1) = NCDEB(NC)  
 MBFL=1  
 GOTO 920  
 900 CONTINUE  
 920 CONTINUE  
 KL = KL+1  
 1035 CONTINUE  
 1037 L = KIL+1  
 IF3 = IF3 +KL  
 IFF=MNEL(NB-1) -KL +IFF  
 IF2 = MNEL(NB-1)  
 IF (KL.EQ.0) GO TO 1038  
 KIL = KIL +KL  
 DO 1036 I = 1,KIL  
 LZ= KL -I+L  
 GAM(I) = PK(LZ)  
 1036 MNG (I) = LT(LZ)  
 1038 CONTINUE  
 JEL = JEL -IF2  
 IF (JEL.EQ.0) GO TO 302  
 SSL(KIL+1-IF3) = SSL(KIL-IF3) + RL(JEL)  
 IF (EFLN(MEF).LE.SSL(KIL+1-IF3)) GOTO 302  
 KIL = KIL +1  
 MNG(KIL) = NVEC(JEL,1)

IMPT1310  
 IMPT1320  
 IMPT1330  
 IMPT1340  
 IMPT1350  
 IMPT1360  
 IMPT1370  
 IMPT1380  
 IMPT1390  
 IMPT1400  
 IMPT1410  
 IMPT1420  
 IMPT1430  
 IMPT1440  
 IMPT1450  
 IMPT1460  
 IMPT1470  
 IMPT1480  
 IMPT1490  
 IMPT1500  
 IMPT1510  
 IMPT1520  
 IMPT1530  
 IMPT1540  
 IMPT1550  
 IMPT1560  
 IMPT1570  
 IMPT1580  
 IMPT1590  
 IMPT1600  
 IMPT1610  
 IMPT1620  
 IMPT1630  
 IMPT1640  
 IMPT1650  
 IMPT1660

301	CONTINUE	IMPT1670
302	DO 303 JJ= 1,KIL	IMPT1680
	MNOD(JJ) = MNO(KIL-JJ+1)	IMPT1690
303	BET(JJ) = GAM(KIL-JJ+1)	IMPT1700
300	CONTINUE	IMPT1710
	IF2=0	IMPT1720
	IF3 =0	IMPT1730
	IFF = 0	IMPT1740
	MMFL = 0	IMPT1750
	KIR=1	IMPT1760
C	ESTABLISH THE NUMBER OF NODES	CLOCKWISE FROM IMPACT WITHINIMPT1770
	SSR(KIR)=PAX	IMPT1780
	IF(PAX .GE.EFLN(MFF)) GO TO 304	IMPT1790
	MNOD(KIR+KIL) = NVEC(IBIG,2)	IMPT1800
	MIMR=1	IMPT1810
	DO 305 J = 1,25	IMPT1820
	BET(KIL+KIR) = ZK-SSR(KIR-IF3) /EFLN(MEF)	IMPT1830
	IF(MMFL.NE.1) GO TO 941	IMPT1840
	EFLN(MEF) = 0.99*SSR(KIR-IF3)	IMPT1850
	GO TO 5555	IMPT1860
941	DO 945 NC= 1,NBCOND	IMPT1870
	IF(MNOD(KIL+KIR).NE.NODEB(NC)) GO TO 945	IMPT1880
	MBC(1) = MBC(1) +1	IMPT1890
	MBC(MBC(1)+1) = NODEB(NC)	IMPT1900
	MMFL=1	IMPT1910
	IF(MNOD(KIL+KIR).NE.NS.AND.MKE(JEL+1).EQ.1)GOTO 933	IMPT1920
	EFLN(MEF) = SSR(KIR-IF3)	IMPT1930
	GOTO 5555	IMPT1940
933	CONTINUE	IMPT1950
	GOTO 955	IMPT1960
945	CONTINUE	IMPT1970
955	CONTINUE	IMPT1980
	JER= IBIG+KIR+IFF	IMPT1990
	IF2=0	IMPT2000
	IF(ICP.LE.0.AND.JER.GT.IK) GO TO 306	IMPT2010
	IF(ICP.GT.0.AND.JPR.GT.IK) JER=JER-1K	IMPT2020

C CHECK FOR A BRANCH ATTACHMENT POINT  
 IF (NBR.EQ.0) GO TO 1080  
 DO 1050 I = 1,NBR  
 IF (MNOD (KIL+KIR) .NE.MATT(I)) GO TO 1050  
 NB= I+1  
 MTI = MATT(I)  
 EST = BET(KIL+KIR)  
 GO TO 1060  
 1050 CONTINUE  
 GO TO 1080  
 C COMPUTE BRANCH NODES INVOLVED IN MOMENTUM TRANSFER,  
 1060 RX =0  
 MBFL=0  
 NUMB = 0  
 KL =0  
 DO 1055 I = 1,10  
 IF (MMFL.EQ.1) GOTO 1080  
 IF (MBFL.NE.1) GO TO 915  
 NUMB = NUMB+1  
 IF (NUMB.NE.2) GOTO 915  
 EFLN (NB) = 0.99\* RX/EST  
 GOTO 1060  
 915 CONTINUE  
 IF (MKF(MTI+I-1).NE.NB) GO TO 1057  
 RX=RX+RL (MTI+I-1)  
 P=EST-RX/EFLN (NB)  
 IF (P.LE.0.0) GO TO 1057  
 LT (KL+1) = MTI+I  
 PK (KL+1) = P  
 DO 905 NC= 1,NBCOND  
 IF (LT (KL+1) .NE.NCDEB (NC)) GOTO 905  
 MBC (1) = MBC (1) +1  
 MBC (MBC (1) +1) = NODEB (NC)  
 MBFL=1  
 GOTO 925  
 905 CONTINUE

IMPT2030  
 IMPT2040  
 IMPT2050  
 IMPT2060  
 IMPT2070  
 IMPT2080  
 IMPT2090  
 IMPT2100  
 IMPT2110  
 IMPT2120  
 IMPT2130  
 IMPT2140  
 IMPT2150  
 IMPT2160  
 IMPT2170  
 IMPT2180  
 IMPT2190  
 IMPT2200  
 IMPT2210  
 IMPT2220  
 IMPT2230  
 IMPT2240  
 IMPT2250  
 IMPT2260  
 IMPT2270  
 IMPT2280  
 IMPT2290  
 IMPT2300  
 IMPT2310  
 IMPT2320  
 IMPT2330  
 IMPT2340  
 IMPT2350  
 IMPT2360  
 IMPT2370  
 IMPT2380

925 CONTINUE  
 KL= KL +1  
 1055 CONTINUE  
 1057 L=KIR+1  
 M = KIR  
 IF3 = IF3 +KL  
 IF2 = MNEL(NB-1)  
 IFF=MNEL(NB-1) -KL +IFF  
 IF (KL.EQ.0) GO TO 1080  
 KIR = KIR +KL  
 DO 1056 I = 1,KIR  
 BET(KIL+I) = PK(I-M)  
 1056 MNOD(KIL+I) = LT(I-M)  
 1080 CONTINUE  
 JER= JER+IF2  
 IF (JER.GT.IK) GO TO 306  
 SSR(KIR+1-IF3) = SSR(KIR-IF3) +RL(JER)  
 IF(EFLN(MEF).LE.SSR(KIR+1-IF3)) GOTO 306  
 KIR = KIR +1  
 MNOD(KIL+KIR) = NVEC(JER,2)  
 305 CONTINUE  
 306 CONTINUE  
 IF(KIL.LE.1.AND.KIR.LE.1) GOTO 308  
 IF(MIML.NE.0) GOTO 307  
 BET(1)=PAX \*BET(2)/PAL  
 MNOD(1) = NVEC(1BIG,1)  
 DO 971 J=1,NBCOND  
 IF(MNOD(1).NE.NODEB(J)) GOTO 971  
 MBC(1) = MBC(1) +1  
 MBC(MBC(1)+1) = NODEB(J)  
 971 CONTINUE  
 GO TO 307  
 304 IF(MIML.EQ.0) GO TO 308  
 IF(KIL.LE.1.AND.KIR.LE.1) GOTO 308  
 BET(KIL+1)=PAL\*BET(KIL)/PAX  
 MNOD(KIL+1) = NVEC(1BIG,2)

IMPT2390  
 IMPT2400  
 IMPT2410  
 IMPT2420  
 IMPT2430  
 IMPT2440  
 IMPT2450  
 IMPT2460  
 IMPT2470  
 IMPT2480  
 IMPT2490  
 IMPT2500  
 IMPT2510  
 IMPT2520  
 IMPT2530  
 IMPT2540  
 IMPT2550  
 IMPT2560  
 IMPT2570  
 IMPT2580  
 IMPT2590  
 IMPT2600  
 IMPT2610  
 IMPT2620  
 IMPT2630  
 IMPT2640  
 IMPT2650  
 IMPT2660  
 IMPT2670  
 IMPT2680  
 IMPT2690  
 IMPT2700  
 IMPT2710  
 IMPT2720  
 IMPT2730  
 IMPT2740

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DO 972 J=1,NBCOND
IF (MNOD(KIL+1).NE.NODEB(J)) GOTO 972
MBC(1) = MBC(1) +1
MBC(MBC(1)+1) = NODEB(J)
972 CONTINUE
GO TO 307
308 BET(1)=PAX
BET(2)=PAL
MNOD(1) = NVEC(IBIG,1)
MNOD(2) = NVEC(IBIG,2)
DO 973 J= 1,NBCOND
IF (MNOD(1).NE.NODEB(J)) GOTO 974
MBC(1) = MBC(1) +1
MBC(MBC(1)+1) = NODEB(J)
974 IF (MNOD(2) .NE.NODEB(J)) GOTO 973
MBC(1) = MBC(1) +1
MBC(MBC(1)+1) = NODEB(J)
973 CONTINUE
307 KII=KIL+KIR
SUM=0.
DO 311 J=1,KII
311 SUM=SUM+BET(J)
C BET = WEIGHTING FACTOR FOR THE EFFECTED NODES
DO 312 J=1,KII
BET(J) = BET(J)/SUM
IF (MBC(1).EQ.0) GO TO 312
L= MBC(1)+1
DO 989 I= 2,L
IF (MNOD(J).EQ.MBC(I)) BET(J)=0.0
989 CONTINUE
312 CONTINUE
936 CONTINUE
DO 101 I=1,JNBR
101 EFLN(I) = EF(I)
SUMB=0.
DO 313 J=1,KII

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IMPT2750
IMPT2760
IMPT2770
IMPT2780
IMPT2790
IMPT2800
IMPT2810
IMPT2820
IMPT2830
IMPT2840
IMPT2850
IMPT2860
IMPT2870
IMPT2880
IMPT2890
IMPT2900
IMPT2910
IMPT2920
IMPT2930
IMPT2940
IMPT2950
IMPT2960
IMPT2970
IMPT2980
IMPT2990
IMPT3000
IMPT3010
IMPT3020
IMPT3030
IMPT3040
IMPT3050
IMPT3060
IMPT3070
IMPT3080
IMPT3090
IMPT3100

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	JEE= MNOD(J)	IMPT3110
	IF(ICP.GT.0.AND.JEE.GT.IK) JEE=JEE-IK	IMPT3120
	SUMB=SUMB+BET(J)**2/RMASS(JEE)	IMPT3130
313	CONTINUE	IMPT3140
	B1=1./FMASS(JBIG)+(FH(JBIG)/2.0)**2/FMOI(JBIG)+SUMB	IMPT3150
	B2=1./FMASS(JBIG)+SUMB	IMPT3160
	SUMN=0.	IMPT3170
	SUMT=0.	IMPT3180
	DO 340 J=1,KII	IMPT3190
	JEE= MNOD(J)	IMPT3200
	IF(ICP.GT.0.AND.JEE.GT.IK) JEE=JEE-IK	IMPT3210
C	ESTABLISH THE TANGENTIAL AND NORMAL VELOCITIES OF RING AND FRAGMENT	IMPT3220
	SUMN=SUMN +BET(J)*(VW(JEE)*RCOS-VU(JEE)*RSIN)	IMPT3230
340	SUMT=SUMT + BET(J)*(VW(JEE)*RSIN+VU(JEE)*RCOS)	IMPT3240
	VFN= VELFW(JBIG)*RCOS - VELFU(JBIG)*RSIN	IMPT3250
	VFT= VELFW(JBIG) * RSIN + VELFU(JBIG)*RCOS	IMPT3260
C	SINT= RELATIVE TANGENTIAL VEL BETWEEN RING AND FRAG., AINT IS REL. N	IMPT3270
	SINT= VFT-VELFA(JBIG)*FH(JBIG) /2.0 -SUMT	IMPT3280
	AINT=VFN-SUMN	IMPT3290
C	IF AINT LE 0 THE FRAG IS NOT APPROACHING THE RING SO SKIP OUT OF THE	IMPT3300
	IF(AINT.GT.0.0) GOTO 3005	IMPT3310
	WRITE(MWRITE,3006) AINT	IMPT3320
3006	FORMAT('0AINT=',D15.6,' NO IMPACT--LEAVING IMPCTE')	IMPT3330
	GOTO 350	IMPT3340
3005	CONTINUE	IMPT3350
	IF(UNK(JBIG).EQ.0.0)GO TO 702	IMPT3360
C	CALCULATE THE EFFECT OF FRICTION ON THE RELATIVE VELOCITIES AND THE	IMPT3370
	TANX=SINT*B2/(AINT*B1)	IMPT3380
705	IF(UNK(JBIG).LE.TANX)GO TO 706	IMPT3390
	APN=(1.0+CR(JBIG))*AINT/B2	IMPT3400
	APT=SINT/B1	IMPT3410
	GO TO 760	IMPT3420
706	APN=(1.+CR(JBIG))*AINT/B2	IMPT3430
	APT=UNK(JBIG)*APN	IMPT3440
	GO TO 760	IMPT3450
702	APN=(1.0+CR(JBIG))*AINT/B2	IMPT3460

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760 APT=0.0  
 CONTINUE  
 FACTFN=-1.0\*APN/FMASS(JBIG)  
 FACTFT=-1.0\*APT/FMASS(JBIG)  
 FACTFO=APT\*FH(JBIG)/FMOI(JBIG)/2.0  
 C UPDATE THE RING AND FRAGMENT VELOCITIES  
 VELFU(JBIG) = (-FACTFN\*RSIN+FACTFT\*RCOS) +VELFU(JBIG)  
 VELFW(JBIG) = (FACTFN\*RCOS+FACTFT\*RSIN) +VELFW(JBIG)  
 VELFA(JBIG) = FACTFO +VELFA(JBIG)  
 DO 350 J=1,KII  
 JEE= MNOD(J)  
 IF(ICP.GT.0.AND.JEE.GT.IK) JEE=JEE-1K  
 FACTN=BET(J)\*APN/RMASS(JEE)  
 FACTT=BET(J)\*APT/RMASS(JEE)  
 VU(JEE)= (-FACTN\*RSIN+FACTT\*RCOS) +VU(JEE)  
 VW(JEE) = (FACTN\*RCOS+FACTT\*RSIN) +VW(JEE)  
 JVEL(JEE)= 1  
 350 CONTINUE  
 RETURN  
 END

IMPT3470  
 IMPT3480  
 IMPT3490  
 IMPT3500  
 IMPT3510  
 IMPT3520  
 IMPT3530  
 IMPT3540  
 IMPT3550  
 IMPT3560  
 IMPT3570  
 IMPT3580  
 IMPT3590  
 IMPT3600  
 IMPT3610  
 IMPT3620  
 IMPT3630  
 IMPT3640  
 IMPT3650  
 IMPT3660

SUBROUTINE PENTRN(TU,TW,TFCGU,TFCGW,NPP,PNA,NEF,NEQ,JF,PAL,RL	PENT0010
2,IBIG,H,FH,IK,NF,ICP,PD,PALE)	PENT0020
IMPLICIT REAL*8(A-H,O-Z)	PENT0030
DIMENSION PND(51,6),PD(50,6),PALE(50,6)	PENT0040
DIMENSION TU(1),TW(1),TFCGU(1),TFCGW(1),NEF(1),RL(1),H(51,3),FH(1)	PENT0050
COMMON /TAPE/ MWRITE,MREAD,MPUNCH	PENT0060
COMMON/BR/ NVEC(51,2), LMT(51)	PENT0070
C CHECK FOR NODAL IMPACT AND ELEMENT IMPACT	PENT0080
DO 110 IF = 1,NF	PENT0090
L=1	PENT0100
DO 100 IR=1,IK	PENT0110
PD(IR,IF) = -10.0	PENT0120
PND(IR,IF) = -10.0	PENT0130
L1= NVEC(IR,1)	PENT0140
L2=NVEC(IR,2)	PENT0150
IF(IR.NE.LMT(L)) GO TO 90	PENT0160
L=L+1	PENT0170
GO TO 100	PENT0180
90 CONTINUE	PENT0190
C CALCULATE DIST FROM FRAG TO NODE1 -- DFN AND LENGTH OF ELEMENT DEL	PENT0200
DFN=DSQRT((TFCGU(IF)-TU(L1))**2+(TFCGW(IF)-TW(L1))**2)	PENT0210
DEL=DSQRT((TU(L2)-TU(L1))**2+(TW(L2)-TW(L1))**2)	PENT0220
RL(IR) = DEL	PENT0230
THICK = 0.0	PENT0240
DO 400 J=1,3	PENT0250
400 THICK= THICK+ (H(L1,J)+H(L2,J))/2.0	PENT0260
C DCRN IS THE CRITICAL DISTANCE = HALF ( FRAG DIA. + AVG ELEMENT THIC	PENT0270
DCRTN= (FH(IF)+THICK)/2.0	PENT0280
DCRTE=DCRTN	PENT0290
DU= TU(L1)-TFCGU(IF)	PENT0300
DW = TW(L1) - TFCGW(IF)	PENT0310
DEU= TU(L2) -TU(L1)	PENT0320
DEW= TW(L2) - TW(L1)	PENT0330
TCOS = DEU / DEL	PENT0340
TSIN = DEW/ DEL	PENT0350
PAL = -(DU*TCOS+DW*TSIN)	PENT0360

PALE(IR,IF) = PAL	PENT0370
IF (PAL.LT.0.0) GO TO 100	PENT0380
IF (PAL.GT.DEL) GO TO 100	PENT0390
DFE= -(-DW*TCOS+ DU*TSIN)	PENT0400
PD(IR,IF) = DCRTE-DFE	PENT0410
100 CONTINUE	PENT0420
110 CONTINUE	PENT0430
C CALCULATE THE LARGEST PENETRATION DIST, AND NUMBER OF + PENETRATIONS	PENT0440
K = 0	PENT0450
IF (ICP.GT.0) K=1	PENT0460
DO 290 J=1,NF	PENT0470
290 NEF(J) = 0	PENT0480
NEQ=0	PENT0490
PMAX= -5.0	PENT0500
NPP = 0	PENT0510
PAL = -1.5	PENT0520
DO 300 IR=1,IK	PENT0530
L1= NVEC(IR,1)	PENT0540
L2= NVEC(IR,2)	PENT0550
DO 300 IF= 1,NF	PENT0560
335 IF(PD(IR,IF).GT.0.0) NPP=NPP+1	PENT0570
IF(PD(IR,IF)-PMAX) 360 ,350,340	PENT0580
340 PMAX= PD(IR,IF)	PENT0590
PAL = PALE(IR,IF)/ RL(IR)	PENT0600
IBIG = IR	PENT0610
NEQ=0	PENT0620
JF=IF	PENT0630
DO 345 J=1,NF	PENT0640
345 NEF(J) =0	PENT0650
GO TO 360	PENT0660
350 NEF(IF) =1	PENT0670
NEQ= NEQ+1	PENT0680
360 CONTINUE	PENT0690
300 CONTINUE	PENT0700
RETURN	PENT0710
END	PENT0720

SUBROUTINE PRINT(IT,TIME,HINN,HOUT,APDEN,SPRIN,BMASS,C2,NQR,	PRIN0010
*CINETO,BEP,WET,NV,ES,ASFL,SNS,NV1,NV2,NV3,SOL,QVEL)	PRIN0020
IMPLICIT REAL*8(A-H,O-Z)	PRIN0030
DIMENSION ASFL(NV1,3,NV2,NV3),SNS(NV1,3,NV2,NV3)	PRIN0040
DIMENSION AB(18),ES(3,6,6),SOL(1),QVEL(1),CINETF(3)	PRIN0050
DIMENSION CCOPY(51),COPZ(51),BEPS(3)	PRIN0060
*,BEP(50,3,3,8),WET(50,3),HINN(50,3),HOUT(50,3),FKTP(3)	PRIN0070
*,FQREF(204),BMASS(1),CINE(205),SPRIN(1),FAILI(50),FAILO(50)	PRIN0080
COMMON/VQ/ FLVA(205),DISP(205),DELD(205),BINP(50,3),BIMP(50,3)	PRIN0090
COMMON/FC/ Y(51),Z(51),ANG(51),H(51,3)	PRIN0100
COMMON /FRAGV/ UDOT(3),WDOT(3),ADOT(3)	PRIN0110
COMMON /FRAG/ FH(3),FMASS(3),FMOI(3),UNK(3),CR(3),FCGU(3),FCGW(3)	PRIN0120
*,ALFA(3),DFCGU(3),DFCGW(3),DALFA(3),TREL,FKT(3),DELTAT,NF,MIMP	PRIN0130
COMMON /EP/ EPSI(50),EPSC(50)	PRIN0140
COMMON /FG/ IK,IKK,ICP,LREF,NOGA,NFL,NI,ICOL(205),INUM(205)	PRIN0150
*,NBCOND,NBC(7),NODEB(7),KRON(8),NDEX(8),NIRREG	PRIN0160
COMMON/MAT/YOUNG(3,6),DS(3,6),SNO(3,5,6),NSFL(3,6),P(3,6),NLAY	PRIN0170
COMMON /IIAT/ TAIL, IMCOU	PRIN0180
COMMON /TAPE/ MREAD,MWRITE,MPUNCH	PRIN0190
COMMON /TAM/ MKE(51)	PRIN0200
SIN(Q)=DSIN(Q)	PRIN0210
COS(Q)=DCOS(Q)	PRIN0220
WRITE (MWRITE,1200) IT	PRIN0230
1200 FORMAT(///,' ENERGY AND WORK AT THE END OF TIME CYCLE',I5)	PRIN0240
WRITE(MWRITE,1205)	PRIN0250
1205 FORMAT('0                    FRAGMENT',10X,'KINETIC ENERGY',/)	PRIN0260
CINETT=0.0	PRIN0270
DO 1210 I=1,NF	PRIN0280
CINETF(I)=FMASS(I)/2.0*(UDOT(I)**2+WDOT(I)**2)+FMOI(I)/2.0*	PRIN0290
@(ADOT(I)**2)	PRIN0300
CINETT= CINETT+(FKT(I)-CINETF(I))	PRIN0310
WRITE(MWRITE,1215) I,CINETF(I)	PRIN0320
1215 FORMAT(' ',10X,I5,13X,D15.6)	PRIN0330
1210 CONTINUE	PRIN0340
CINET=0.0	PRIN0350
DO 701 I=1,NI	PRIN0360

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<pre> 701 CINET= CINET+(QVEL(I)**2*SOL(I))/2.0D+00     ELAST=0.0     DO 702 IR=1,IK       I=MKE(IR)       NLAP = NLAY       IF(MKE(IR).GT.1) NLAP = 1       DO 703 J=1,NOGA         SUM=0.0         DO 801 M=1,NLAP           NSFLM=NSFL(M,I)           DO 801 N=1,NFL             STRS=0.0             K=N+(M-1)*NFL             DO 802 L=1,NSFLM               LL= L+1               AB(K)= (ES(M,L,I)-ES(M,LL,I))/ ES(M,1,I) 802 STRS=STRS+SNS(IR,J,K,L)* AB(K)               STRS= STRS**2 801 SUM = SUM+STRS*ASFL(IR,J,K,NSFLM)/(AB(K)*YOUNG(M,I)) 703 ELAST= ELAST+(SUM*WET(IR,J))/2.0 702 CONTINUE           SPDEN=0.0           IF(NQR.EQ. 0) GO TO 31           DO 30 I=1,NI 30 FQREF(I)=0.0           CALL CMULT(SPRIN,DISP,ICOL,NI,FQREF,KROW,NDEX,NIRREG)           DO 32 I=1,NI 32 SPDEN=SPDEN+DISP(I)*FQREF(I)           SPDEN=SPDEN/2. 31 CONTINUE           PLAST=CINETT-CINET-ELAST-SPDEN           TAIIT= TIME - TAIL           WRITE(MWRITE,1) IT ,TIME,TAIIT,CINETT,CINET,ELAST,PLAST 1 FORMAT(' - J= ',I5, ' TIME (SEC.) =',D15.6,5X, 'TIME AFTER INIT           *IAL IMPACT =',D15.6,/,           *' WORK INPUT INTO RING (IN.-LB.) =',E15.6,/, </pre>	<pre> PRIN0370 PRIN0380 PRIN0390 PRIN0400 PRIN0410 PRIN0420 PRIN0430 PRIN0440 PRIN0450 PRIN0460 PRIN0470 PRIN0480 PRIN0490 PRIN0500 PRIN0510 PRIN0520 PRIN0530 PRIN0540 PRIN0550 PRIN0560 PRIN0570 PRIN0580 PRIN0590 PRIN0600 PRIN0610 PRIN0620 PRIN0630 PRIN0640 PRIN0650 PRIN0660 PRIN0670 PRIN0680 PRIN0690 PRIN0700 PRIN0710 PRIN0720 </pre>
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*'   RING KINETIC ENERGY   (IN.-LB.)   =' ,E15.6,/,      PRIN0730
*'   RING ELASTIC ENERGY   (IN.-LB.)   =' ,E15.6,/,      PRIN0740
*'   RING PLASTIC WORK      (IN.-LB.)   =' ,E15.6)         PRIN0750
      IF(NQR.EQ. 0) GO TO 33      PRIN0760
      WRITE(MWRITE,34) SPDEN      PRIN0770
34  FORMAT('   ENERGY STORED IN THE ELASTIC RESTRAINTS (IN.-LB.)   =' ,PRIN0780
      *E15.6)                    PRIN0790
33  DO 11 I=1,IKK                PRIN0800
      COPY(I)=Y(I)+DISP(I*4-3)*COS(ANG(I))-DISP(I*4-2)*SIN(ANG(I)) PRIN0810
11  COPZ(I)=Z(I)+DISP(I*4-3)*SIN(ANG(I))+DISP(I*4-2)*COS(ANG(I)) PRIN0820
      IKP1=IK+1                  PRIN0830
      WRITE(MWRITE,2)            PRIN0840
2   FORMAT(/,'   I ',5X,'V',11X,'W',9X,'PSI',9X,'CHI',10X,'COPY', PRIN0850
      *8X,'COPZ',9X,'L',11X,'M',7X,'STRAIN(IN)',4X,'STRAIN(OUT)') PRIN0860
50  DO 21 I=1,IK                PRIN0870
21  WRITE(MWRITE,22) I,DISP(I*4-3),DISP(I*4-2),DISP(I*4-1),DISP(I*4), PRIN0880
      *COPY(I),COPZ(I),BINP(I,2),BIMP(I,2),EPSI(I),EPSO(I) PRIN0890
22  FORMAT(I5,9E12.4,2X,E12.4) PRIN0900
      IF(ICP.GT.0) GO TO 57      PRIN0910
      WRITE(MWRITE,24) IKP1,DISP(IKP1*4-3),DISP(IKP1*4-2), PRIN0920
      *DISP(IKP1*4-1),DISP(IKP1*4),COPY(IKP1),COPZ(IKP1),EPSI(IKP1), PRIN0930
      @EPSO(IKP1)               PRIN0940
24  FORMAT(I5,6D12.4,24X,D12.4,D14.4) PRIN0950
57  CONTINUE                     PRIN0960
      WRITE(MWRITE,35)          PRIN0970
35  FORMAT(10X,'FRAG NO.=' ,5X,'FCGU =' ,9X,'FCGW =' ,9X,'ALFA =' ,9X, PRIN0980
      *'FRUV =' ,9X,'FRWV =' ,9X,'FRAV =' ,/) PRIN0990
      DO 36 I=1,NF              PRIN1000
36  WRITE(MWRITE,37) I,FCGU(I),FCGW(I),ALFA(I),UDOT(I),WDOT(I),ADOT(I) PRIN1010
37  FORMAT(10X,I5,3X,6D15.6,/) PRIN1020
      RETURN                    PRIN1030
      END                       PRIN1040

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## SECTION 7

### ILLUSTRATIVE EXAMPLES

#### 7.1 JET 5A Example: An Impulsively-Loaded Free Single-Layer Uniform-Thickness Circular Complete Ring without Branches

##### 7.1.1 Problem Description

The geometry of the free-ring structure, as shown in Fig. 11, is a free circular ring, 0.4-in thick, 2.5-in wide, with a mean radius of 7.7-in. The ring is subjected to severe impulsive loading over a peripheral sector of 126 degrees of its exterior. Taking account of the symmetry of the impulsive loading and the ring geometry, only half of the ring is analyzed with the symmetry-prescribed-displacement conditions imposed at the centerline mid-plane. Twenty uniform finite elements are used to model the half ring. To demonstrate the multilayer capability of the JET 5A program, the steel ring is modeled by two identical layers. The inner layer is designated as the reference layer.

The uniaxial stress-strain properties of the 4130 cast steel ring material are represented by a three-mechanical-sublayer model defined by  $\sigma_1, \epsilon_1 = 80,950 \text{ psi}, .00279$ ;  $\sigma_2, \epsilon_2 = 105,300 \text{ psi}, .0225$ ; and  $\sigma_3, \epsilon_3 = 121,000 \text{ psi}, .2000$ , with an elastic modulus of  $29 \times 10^6 \text{ psi}$  and a yield stress of 80,950 psi. The strain rate constants are  $D = 40.4 \text{ sec}^{-1}$  and  $p = 5$ , and the mass density is taken to be  $0.733085 \times 10^{-3} \text{ (lb-sec}^2/\text{in}^4\text{)}$ .

The impulse is modeled by an initial inward "uniform" velocity of 10,000 in/sec. In order to represent adequately the impulse at the end of the loaded region (an impulse assumed to be generated by a high explosive detonation), the last node has half the "uniform" normal velocity plus a rotational component (see Fig. 11).

The JET 5A program will predict the resulting transient structural response by using a time step of 4 microseconds. Printout will be given every 10 time steps or cycles of computation until 150 cycles have been completed.

ORIGINAL PAGE IS  
OF POOR QUALITY

7.1.2 Input Data

The values to be punched on the data cards are as follows:

Card 1	10I5
IK = 20	
ICP = 0	
NLAY = 2	
LREF = 1	
NOGA = 3	
NFL = 4	
MM = 150	
M1 = 10	
M2 = 10	
ICON = 0	
Card 2	3I5
NSFL(1,1) = 3	
NSFL(2,1) = 3	
Card 3A	3D15.6
DENS(1,1) = 0.733085D-03	
DS(1,1) = 0.404000D+02	
P(1,1) = 0.500000D+01	
Card 4AA	4D15.6
EPS(1,1,1) = 0.279000D-02	
SIG(1,1,1) = 0.809500D+05	
EPS(1,2,1) = 0.225000D-01	
SIG(1,2,1) = 0.105300D+06	
Card 4AB	4D15.6
EPS(1,3,1) = 0.200000D+00	
SIG(1,3,1) = 0.121000D+06	
Card 3B	3D15.6
DENS(2,1) = 0.733085D-03	
DS(2,1) = 0.404000D+02	
P(2,1) = 0.500000D+01	



Card 4BA 4D15.6

EPS(2,1,1) = 0.279000D-02

SIG(2,1,1) = 0.809500D+05

EPS(2,2,1) = 0.225000D-01

SIG(2,2,1) = 0.105300D+06

Card 4BB 4D15.6

EPS(2,3,1) = 0.200000D+00

SIG(2,3,1) = 0.121000D+06

Card 5 2D15.6

B(1) = 0.250000D+01

DELTAT = 0.400000D-05

Card 6A 3D15.6

Y(1) = 0.0

Z(1) = 0.770000D+01

ANG(1) = 0.0

.  
.  
.

Additional cards are punched until all the nodes are described.

.  
.  
.

Y(21) = 0.0

Z(21) = -0.770000D+01

ANG(21) = 0.0

Card 7A 5D15.6

H(1,1) = 0.200000D+00

H(1,2) = 0.200000D+00

H(2,1) = 0.200000D+00

.  
.  
.

Additional cards are punched until all the nodal thicknesses for each layer are described, five per card.

.  
.  
.

H(21,1) = 0.200000D+00	
H(21,2) = 0.200000D+00	
Card 8A	I5
NDIS = 0	
Card 9	I5
NBR = 0	
Card 10	3I5
NOP = 3	
NASP = 1	
NTERF = 1	
Card 10A	2I5,D15.6
NSBS(1) = 1	
NSEL(1) = 20	
AZET(1) = 0.570000D+00	
Card 11	3D25.16
AXG(1) = 0.1127016653792585D+00	
AXG(2) = 0.5000000000000000D+00	
AXG(3) = 0.8872983346207415D+00	
Card 12	3D25.16
AWG(1) = 0.2777777777777778D+00	
AWG(2) = 0.4444444444444444D+00	
AWG(3) = 0.2777777777777778D+00	
Card 13A	3D25.16
TXG(1) = -0.861136311594053D+00	
TXG(2) = -0.3399810435848560D+00	
TXG(3) = 0.3399810435848560D+00	
Card 13B	D25.16
TXG(4) = 0.861136311594053D+00	
Card 14A	3D25.16
TWG(1) = 0.3478548451374540D+00	

TWG(2) = 0.6521451548625460D+00

TWG(3) = 0.6521451548625460D+00

Card 14B

D25.6

TWG(4) = 0.3478548451374540D+00

Card 15

5I5

NBCOND = 2

NBC(1) = 1

NODEB(1) = 1

NBC(2) = 1

NODEB(2) = 21

Card 16

I5

NQR = 0

Card 17

4I5

NV = 1

IOTA = 1

IOTB = 0

IOTC = 0

Card 18A

2I5

IE1 = 1

IE2 = 7

Card 18AA

5D15.6

WRAD = -0.100000D+05

WRAD1 = 0.100000D+05

ANGV1 = 0.0

WARD2 = -0.500000D+04

ANGV1 = 0.200000D+05

Card 21

2D15.6

TBEGIN = 0.0

TFINAL = 0.0

Card 26

I5

ICONT = 0

THIS IS THE INPUT DECK FOR EXAMPLE 7.1

20	0	2	1	3	4	150	10	10	0
3	3								
00.7330850-03		00.4040000+02		00.5000000+01					
00.2790000-02		00.8095000 05		00.2250000-01		00.1053000 06			
00.2000000 00		00.1210000 06							
00.7330850-03		00.4040000+02		00.5000000+01					
00.2790000-02		00.8095000 05		00.2250000-01		00.1053000 06			
00.2000000 00		00.1210000 06							
00.2500000+01		00.4000000-05							
0.0000000000		0.7700000 01		0.0000000 00		0.4000000 00			
0.1204550 01		00.7605200 01		-0.9000000 01		00.4000000 00			
00.2379430 01		00.7323140 01		-0.1800000 02		00.4000000 00			
00.3495730 01		00.6860750 01		-0.2700000 02		00.4000000000			
00.4525950 01		00.6229430 01		-0.3600000 02		00.4000000 00			
00.5444720 01		00.5444720 01		-0.4500000 02		00.4000000 00			
00.5229430 01		00.4525950 01		-0.5400000 02		00.4000000 00			
00.6860750 01		00.3495730 01		-0.6300000 02		00.4000000 00			
00.7323140 01		00.2379430 01		-0.7200000 02		00.4000000 00			
00.7605200 01		00.1204550 01		-0.8100000 02		00.4000000 00			
00.7700000 01		00.0		-0.9000000 02		00.4000000 00			
00.7605200 01		-0.1204550 01		-0.9900000 02		00.4000000 00			
00.7323140 01		-0.2379430 01		-0.1080000 03		00.4000000 00			
00.6860750 01		-0.3495730 01		-0.1170000 03		00.4000000 00			
00.6229430 01		-0.4525950 01		-0.1260000 03		00.4000000 00			
00.5444720 01		-0.5444720 01		-0.1350000 03		00.4000000 00			
00.4525950 01		-0.6229430 01		-0.1440000 03		00.4000000 00			
00.3495730 01		-0.6860750 01		-0.1530000 03		00.4000000 00			
00.2379430 01		-0.7323140 01		-0.1620000 03		00.4000000 00			
00.1204550 01		-0.7605200 01		-0.1710000 03		00.4000000 00			
00.0		-0.7700000+01		00.1800000 03		00.4000000 00			
00.2000000+00		00.2000000+00		00.2000000+00		00.2000000+00		00.2000000+00	
00.2000000+00		00.2000000+00		00.2000000+00		00.2000000+00		00.2000000+00	
00.2000000+00		00.2000000+00		00.2000000+00		00.2000000+00		00.2000000+00	
00.2000000+00		00.2000000+00		00.2000000+00		00.2000000+00		00.2000000+00	
00.2000000+00		00.2000000+00		00.2000000+00		00.2000000+00		00.2000000+00	
00.2000000+00		00.2000000+00		00.2000000+00		00.2000000+00		00.2000000+00	
00.2000000+00		00.2000000+00		00.2000000+00		00.2000000+00		00.2000000+00	

00.2000000+00	00.2000000+00	00.2000000+00	00.2000000+00	00.2000000+00
00.2000000+00	00.2000000+00	00.2000000+00	00.2000000+00	00.2000000+00
00.2000000+00	00.2000000+00			

0

0

3

1

1

1

20

00.5700000+00

00.11270166537925850+00	00.5000000000000000+00	00.88729833462074150+00
00.27777777777777780+00	00.4444444444444440+00	00.27777777777777780+00
-0.86113631159405300+00	-0.33998104358485600+00	00.33998104358485600+00
00.86113631159405300+00		
00.34785484513745400+00	00.65214515486254600+00	00.65214515486254600+00
00.34785484513745400+00		

2

1

1

1

21

0

1

1

0

0

1

7

-0.1000000+05	-0.1000000+05	00.0	-0.5000000+04	00.2000000+05
00.0	00.0			
0				

### 7.1.3 Solution Output Data

The following is the output for 600 microseconds of response of the ring to the given initial velocity distribution.

The first segment of output gives a breakdown of the initial geometry of the ring and the initial loading parameters. A calculation of a guideline time step size is made and is presented to compare with the user-generated time step.

Strain information is printed at each spanwise Gaussian station, at each designated strain point (inner and outer surface and each interface), and at each node (inner and outer surface). The maximum strain is 12.39 per cent and occurs on the outer surface of element 9 at 600 microseconds after initial loading.

In the interest of conciseness, only a portion of the called-for output is given. Included are (1) all input verification information and (2) scheduled output at the end of time cycles 0, 1, 10, 20, 30, 40, 50, 140, and 150 (last). This output listing is intended for use in verification of the adaptation of the JET 5A computer code to other computing facilities.

THIS IS RUN NUMBER 1 FOR THIS JET 5A SUBMITTAL

THERE ARE NO BRANCHES CONNECTED TO THE MAIN STRUCTURE ,THEREFORE  
THE NUMBERING SYSTEM FOR NODES AND ELEMENTS REMAINS UNCHANGED

ADDITIONAL STRAIN POINT      ELEMENT      S COORDINATE  
1                                  20                                  0.570000E+00

\*\*\*\*\* A SPATIAL FINITE ELEMENT AND HOUBOLT TEMPORAL OPERATOR PROGRAM  
USED TO CALCULATE THE NONLINEAR RESPONSES OF A VARIABLE THICKNESS MULTILAYER  
ARBITRARILY CURVED PARTIAL RING WITH THE FOLLOWING PARAMETERS

PROPERTIES OF THE MAIN STRUCTURE:

WIDTH OF RING (IN)                                  = 0.250000E+01  
NUMBER OF ELEMENTS                                  = 20  
NUMBER OF SPANWISE GAUSSIAN POINTS                                  = 3  
NUMBER OF DEPTHWISE GAUSSIAN POINTS                                  = 4  
NUMBER OF LAYERS    = 2  
REFERENCE SURFACE IS THE MIDDLE SURFACE OF LAYER= 1

MATERIAL PROPERTIES OF LAYER                                  = 1  
DENSITY(LB-SEC\*\*2/IN\*\*4)                                  = 0.733085E-03  
NUMBER OF MECHANICAL SUBLAYERS                                  = 3

STRAIN                                  STRESS  
1 0.279000E-02      0.809500E+05  
2 0.225000E-01      0.105300E+06  
3 0.200000E+00      0.121000E+06

MATERIAL IS STRAIN RATE SENSITIVE WITH  
D = 0.404000E+02 P = 0.500000E+01

MATERIAL PROPERTIES OF LAYER                                  = 2  
DENSITY(LB-SEC\*\*2/IN\*\*4)                                  = 0.733095E-03  
NUMBER OF MECHANICAL SUBLAYERS                                  = 3

STRAIN                                  STRESS  
1 0.279000E-02      0.809500E+05  
2 0.225000E-01      0.105300E+06  
3 0.200000E+00      0.121000E+06

MATERIAL IS STRAIN RATE SENSITIVE WITH  
D = 0.404000E+02 P = 0.500000E+01

SYMMETRY DISPLACEMENT CONDITION AT NODE = 1  
SYMMETRY DISPLACEMENT CONDITION AT NODE = 21

THERE ARE NO ELASTIC SPRING CONSTRAINTS

NODE NO	Y COORD(IN)	Z COORD(IN)	SLOPE ( RAD)	RING THICKNESS(IN)		
				LAYER 1	LAYER 2	LAYER 3
1	0.0	0.770000E+01	0.0	0.200000E+00	0.200000E+00	
2	0.120455E+01	0.760520E+01	-0.157080E+00	0.200000E+00	0.200000E+00	
3	0.237943E+01	0.732314E+01	-0.314159E+00	0.200000E+00	0.200000E+00	
4	0.349573E+01	0.686075E+01	-0.471239E+00	0.200000E+00	0.200000E+00	
5	0.452595E+01	0.622943E+01	-0.628319E+00	0.200000E+00	0.200000E+00	
6	0.544472E+01	0.544472E+01	-0.785398E+00	0.200000E+00	0.200000E+00	
7	0.622943E+01	0.452595E+01	-0.942478E+00	0.200000E+00	0.200000E+00	
8	0.686075E+01	0.349573E+01	-0.109956E+01	0.200000E+00	0.200000E+00	
9	0.732314E+01	0.237943E+01	-0.125664E+01	0.200000E+00	0.200000E+00	
10	0.760520E+01	0.120455E+01	-0.141372E+01	0.200000E+00	0.200000E+00	
11	0.770000E+01	0.0	-0.157080E+01	0.200000E+00	0.200000E+00	
12	0.760520E+01	-0.120455E+01	-0.172788E+01	0.200000E+00	0.200000E+00	
13	0.732314E+01	-0.237943E+01	-0.188496E+01	0.200000E+00	0.200000E+00	
14	0.686075E+01	-0.349573E+01	-0.204204E+01	0.200000E+00	0.200000E+00	
15	0.622943E+01	-0.452595E+01	-0.219911E+01	0.200000E+00	0.200000E+00	
16	0.544472E+01	-0.544472E+01	-0.235619E+01	0.200000E+00	0.200000E+00	
17	0.452595E+01	-0.622943E+01	-0.251327E+01	0.200000E+00	0.200000E+00	
18	0.349573E+01	-0.686075E+01	-0.267035E+01	0.200000E+00	0.200000E+00	
19	0.237943E+01	-0.732314E+01	-0.282743E+01	0.200000E+00	0.200000E+00	
20	0.120455E+01	-0.760520E+01	-0.298451E+01	0.200000E+00	0.200000E+00	
21	0.0	-0.770000E+01	0.314159E+01	0.200000E+00	0.200000E+00	



## GAUSSIAN STATIONS AND WEIGHTS:

AXG 1 = 0.112701665379259  
 AXG 2 = 0.500000000000000  
 AXG 3 = 0.887299334620741  
 TXG 1 = -0.861136311594053  
 TXG 2 = -0.339991043584856  
 TXG 3 = 0.339981043584856  
 TXG 4 = 0.861136311594053

AWG 1 = 0.277777777777778  
 AWG 2 = 0.444444444444444  
 AWG 3 = 0.277777777777778  
 TWG 1 = 0.347854845137454  
 TWG 2 = 0.652145154862546  
 TWG 3 = 0.652145154862546  
 TWG 4 = 0.347854845137454

SIZE OF ASSEMBLED MASS OR STIFFNESS MATRIX= 530

EMASS =  
 0.100000000+01 0.0 0.34287581D-03 0.0 0.0 0.100000000+01 0.0 0.75505336D-05  
 0.0 0.12204091D-04 0.0 0.29018785D-04 0.0 0.35095693D-04 0.66918944D-03 0.0  
 0.10050242D-03 0.0 -0.78387076D-05 -0.52264855D-11 0.68574822D-03 0.0 -0.32489809D-04 0.0  
 0.18415882D-05 -0.14463178D-04 -0.14974942D-09 0.29298228D-04 0.0 -0.78387188D-05 0.0 -0.99851655D-05  
 -0.99202062D-09 0.15101190D-04 0.80307262D-09 0.24407842D-04 0.12050411D-03 0.29018948D-04 0.77852644D-05 0.35095089D-04  
 0.66919062D-03 -0.29018822D-04 0.10050120D-03 0.32488749D-04 -0.78385035D-05 -0.70286108D-11 0.68574784D-03 0.77825530D-05  
 -0.32489155D-04 -0.10417972D-04 0.18415530D-05 -0.14462681D-04 0.20231350D-08 0.29298284D-04 -0.35095128D-04 -0.78388076D-05  
 -0.18423636D-05 -0.99848921D-05 0.12236227D-08 0.15100685D-04 0.79743497D-09 0.24407891D-04 0.12050526D-03 0.29018711D-04  
 0.77855963D-05 0.35095721D-04 0.66919172D-03 -0.29018842D-04 0.10050253D-03 0.32489422D-04 -0.78388502D-05 0.40744473D-10  
 0.68575029D-03 0.77823501D-05 -0.32489891D-04 -0.10418285D-04 0.18415929D-05 -0.14463189D-04 0.43818294D-09 0.29298502D-04  
 -0.35095883D-04 -0.78385860D-05 -0.18423966D-05 -0.99851905D-05 -0.30122738D-05 0.15101195D-04 0.79341542D-09 0.24408089D-04  
 0.12050479D-03 0.29018809D-04 0.77854583D-05 0.35095463D-04 0.66918988D-03 -0.29018833D-04 0.10050198D-03 0.32489146D-04  
 -0.78387061D-05 0.7740621D-10 0.68574748D-03 0.77824352D-05 -0.32489589D-04 -0.10418156D-04 0.18415766D-05 -0.14462788D-04  
 0.53643651D-09 0.29298227D-04 -0.35095573D-04 -0.78386789D-05 -0.18423831D-05 -0.99850683D-05 -0.20064639D-09 0.15100789D-04  
 0.79030193D-09 0.24407828D-04 0.12050439D-03 0.29018756D-04 0.77856132D-05 0.35095184D-04 0.66918751D-03 -0.29018948D-04  
 0.10050153D-03 0.32488903D-04 -0.78388711D-05 0.10124117D-10 0.68574728D-03 0.77822375D-05 -0.32489388D-04 -0.10418061D-04  
 0.18415663D-05 -0.14463454D-04 0.86470085D-09 0.29298060D-04 -0.35095375D-04 -0.78384692D-05 -0.18423682D-05 -0.99849657D-05  
 0.10377000D-09 0.15101466D-04 0.79885411D-09 0.24407676D-04 0.12050439D-03 0.29018946D-04 0.77852345D-05 0.35095270D-04  
 0.66918988D-03 -0.29018776D-04 0.10050153D-03 0.32488920D-04 -0.78384709D-05 -0.31878774D-10 0.68574748D-03 0.77826141D-05  
 -0.32489315D-04 -0.10418044D-04 0.18415614D-05 -0.14462783D-04 0.12722434D-06 0.29298209D-04 -0.35095289D-04 -0.78388718D-05  
 -0.18423732D-05 -0.99849657D-05 0.40765418D-09 0.15100791D-04 0.80383476D-09 0.24407828D-04 0.12050479D-03 0.29018822D-04  
 0.77854332D-05 0.35095469D-04 0.66919172D-03 -0.29018821D-04 0.10050198D-03 0.32489147D-04 -0.78386796D-05 -0.20681772D-10  
 0.68575029D-03 0.77824602D-05 -0.32489584D-04 -0.10418155D-04 0.18415762D-05 -0.14463185D-04 0.13293194D-08 0.29298490D-04  
 -0.35095568D-04 -0.78387056D-05 -0.18423834D-05 -0.99850683D-05 0.50851487D-09 0.15101196D-04 0.80259907D-09 0.24408089D-04  
 0.12050526D-03 0.29018836D-04 0.77853475D-05 0.35095778D-04 0.66919062D-03 -0.29018729D-04 0.10050253D-03 0.32489433D-04  
 -0.78385873D-05 0.26826920D-10 0.68574784D-03 0.77825975D-05 -0.32489843D-04 -0.10418273D-04 0.18415897D-05 -0.14462682D-04  
 -0.20142189D-09 0.29298286D-04 -0.35095826D-04 -0.78388504D-05 -0.18423999D-05 -0.99851905D-05 -0.10167024D-08 0.15100685D-04  
 0.79611715D-09 0.24407891D-04 0.12050411D-03 0.29018804D-04 0.77855518D-05 0.35095023D-04 0.66918944D-03 -0.29018953D-04  
 0.10050120D-03 0.32488736D-04 -0.78388073D-05 0.25307494D-10 0.68574822D-03 0.77822672D-05 -0.32489210D-04 -0.10417985D-04  
 0.18415567D-05 -0.14463183D-04 0.19134890D-08 0.29298241D-04 -0.35095193D-04 -0.78385020D-05 -0.18423598D-05 -0.99848921D-05  
 0.11993319D-08 0.15101189D-04 0.79309534D-09 0.24407822D-04 0.12050517D-03 0.29018779D-04 0.77854721D-05 0.35095690D-04  
 0.66919274D-03 -0.29018796D-04 0.10050242D-03 0.32489370D-04 -0.78387193D-05 0.99963384D-11 0.68575089D-03 0.77824629D-05  
 -0.32489811D-04 -0.10418254D-04 0.18415883D-05 -0.14463076D-04 0.89093887D-09 0.29298594D-04 -0.35095798D-04 -0.78387070D-05  
 -0.18423951D-05 -0.99851655D-05 0.10359583D-09 0.15101083D-04 0.79768562D-09 0.24408182D-04 0.12050517D-03 0.29018785D-04  
 0.77854610D-05 0.35095693D-04 0.66918944D-03 -0.29018791D-04 0.10050242D-03 0.32489370D-04 -0.78387076D-05 -0.52264855D-11  
 0.68574822D-03 0.77824740D-05 -0.32489809D-04 -0.10418253D-04 0.18415882D-05 -0.14463178D-04 -0.14974942D-09 0.29298228D-04  
 -0.35095795D-04 -0.78387188D-05 -0.18423952D-05 -0.99851655D-05 -0.99202062D-09 0.15101190D-04 0.80307262D-09 0.24407842D-04  
 0.12050411D-03 0.29018948D-04 0.77852644D-05 0.35095089D-04 0.66919062D-03 -0.29018822D-04 0.10050120D-03 0.32488749D-04  
 -0.78385035D-05 -0.70286108D-11 0.68574784D-03 0.77825530D-05 -0.32489155D-04 -0.10417972D-04 0.18415530D-05 -0.14462681D-04  
 0.20231350D-08 0.29298284D-04 -0.35095128D-04 -0.78388076D-05 -0.18423636D-05 -0.99848921D-05 0.12236227D-08 0.15100685D-04  
 0.79743497D-09 0.24407891D-04 0.12050526D-03 0.29018711D-04 0.77855963D-05 0.35095721D-04 0.66919172D-03 -0.29018842D-04  
 0.10050253D-03 0.32489422D-04 -0.78388502D-05 0.40744473D-10 0.68575029D-03 0.77823501D-05 -0.32489891D-04 -0.10418285D-04  
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 -0.35095193D-04 -0.78385020D-05 -0.18423598D-05 -0.99848921D-05 0.11993319D-08 0.15101189D-04 0.79309534D-09 0.24407822D-04  
 0.0 0.0 0.0 0.0 0.100000000+01 -0.29018796D-04 0.10050242D-03 0.32489370D-04  
 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0  
 0.0 0.100000000+01 -0.35095798D-04 -0.78387070D-05 -0.18423951D-05 -0.99851655D-05 0.0 0.75505494D-05  
 0.0 0.12204091D-04

ORIGINAL PAGE IS  
 OF POOR QUALITY



STIPK =

0.10000000D+01	0.0	0.48024904E+07	0.0	0.48770973D+07	0.0	0.10000000D+01	0.0	0.23094894D+07
0.0	0.0	0.48024904E+07	0.0	0.48770973D+07	0.0	-0.27717367D+07	0.57646505D+08	0.0
-0.45204002D+07	0.0	0.0	-0.2772775D+07	0.66828093D+02	0.97543146D+07	0.0	0.26231086D+07	0.0
0.15877452D+07	-0.52512531D+07	0.20332430D+03	0.0	0.47369829D+07	0.0	-0.2772881D+07	0.0	-0.12006227D+07
0.11739247D+02	0.46190220D+07	0.17786280D+03	0.96049313E+07	-0.28765171D+08	0.26358911D+07	0.30738528D+07	-0.27717211D+07	0.0
0.57646445D+08	-0.26360455D+07	-0.45205273D+07	-0.26233074D+07	-0.2773074D+07	0.19142071D+02	0.97543373D+07	0.30738303D+07	0.0
0.26231731D+07	0.10826877D+07	0.15677468D+07	-0.52512348D+07	0.10417311D+03	0.47370016D+07	0.27717252D+07	-0.2773087D+07	0.0
-0.15879430D+07	-0.12006119D+07	0.19230026D+02	0.46190043D+07	0.18305862D+03	0.96049556D+07	-0.28764881D+08	0.26360041D+07	0.0
0.30738184D+07	-0.27717504D+07	0.57646305D+08	-0.26358646D+07	-0.45203884D+07	-0.26232805D+07	-0.2772724D+07	-0.82135614D+02	0.0
0.97542206D+07	0.30738102D+07	0.26230904D+07	0.10826761D+07	0.15877434D+07	-0.52512401D+07	0.20196910D+03	0.47369691D+07	0.0
0.27716992D+07	-0.27727887E+07	-0.15879485D+07	-0.12006236D+07	0.38981401D+02	0.46190036D+07	0.1935054D+03	0.96049644D+07	0.0
-0.28764999D+08	0.26359567D+07	0.30738325D+07	-0.27717382D+07	0.57646500D+08	-0.26359398E+07	-0.45204453D+07	-0.26232913D+07	0.0
-0.27727854D+07	-0.11652526D+03	0.97543523D+07	0.30738183D+07	0.26231245D+07	0.10826809D+07	0.15877448D+07	-0.52512429D+07	0.0
0.20444688D+03	0.47370006D+07	0.27717095D+07	-0.27727968D+07	-0.15879462D+07	-0.12006188D+07	0.45176062D+02	0.46190118D+07	0.0
0.19624287D+03	0.96049434E+07	-0.28765099D+08	0.26360653D+07	0.30738385D+07	-0.27717562D+07	0.57646648D+08	-0.26358545D+07	0.0
-0.45204927D+07	-0.26233283D+07	-0.27727902D+07	-0.31539103D+01	0.97543539D+07	0.30738337D+07	0.26231246D+07	0.10826846D+07	0.0
0.15877420D+07	-0.52512723D+07	0.16468836D+03	0.47369802D+07	0.27716904D+07	-0.2773094D+07	-0.15879494D+07	-0.12006148D+07	0.0
0.24242517D+02	0.46190418D+07	0.18648272D+03	0.96048994D+07	-0.28765099D+08	0.26358578D+07	0.30738467D+07	-0.27717167D+07	0.0
0.57646501D+08	-0.26360622D+07	-0.45204932D+07	-0.26232889D+07	-0.27727988D+07	0.11023260D+03	0.97543529D+07	0.30738218D+07	0.0
0.26231654D+07	0.10826849D+07	0.15877476D+07	-0.52512409D+07	0.12447864D+03	0.47370006D+07	0.27717303D+07	-0.2773014D+07	0.0
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0.30738331D+07	-0.27717356D+07	0.57646306D+08	-0.26359536D+07	-0.4520453D+07	-0.26232887D+07	-0.2772860D+07	0.75835094D+02	0.0
0.97542209D+07	0.30738175D+07	0.26231271D+07	0.10826809D+07	0.15877452D+07	-0.52512388D+07	0.12718929D+03	0.47369691D+07	0.0
0.27717121D+07	-0.27727963D+07	-0.15879457D+07	-0.12006188D+07	0.92655211D+01	0.46190038D+07	0.17788774D+03	0.96049644D+07	0.0
-0.28764881D+08	0.26358678D+07	0.30738238D+07	-0.27717244D+07	0.57646445D+08	-0.26360010D+07	-0.45203887D+07	-0.26232549D+07	0.0
0.27727800D+07	-0.25432229D+02	0.97543373D+07	0.30738024D+07	0.26231165D+07	0.10826763D+07	0.15877470D+07	-0.52512350D+07	0.0
0.22467806D+03	0.47370016D+07	0.27717244D+07	-0.27727835D+07	-0.15879433D+07	-0.12006236E+07	0.28677140D+02	0.46190043D+07	0.0
0.18609238D+03	0.96049556D+07	-0.28765170D+08	0.26360486D+07	0.30738465D+07	-0.27717512D+07	0.57646504D+08	-0.26358879D+07	0.0
-0.45205270D+07	-0.26233370D+07	-0.27727975D+07	-0.73129351D+02	0.97543142D+07	0.30738393D+07	0.26231429D+07	0.10826874D+07	0.0
0.15877426D+07	-0.52512545D+07	0.12585655D+03	0.47369828D+07	0.27716949D+07	-0.2773147D+07	-0.15879484D+07	-0.12006119D+07	0.0
0.36531157D+02	0.46190218D+07	0.19368435D+03	0.96049313D+07	-0.28764905E+08	0.26359419D+07	0.30738234D+07	-0.27717379D+07	0.0
0.57646226D+08	-0.26359326E+07	-0.45204002D+07	-0.26232728D+07	-0.2772772D+07	-0.31488846D+01	0.97541950D+07	0.30738088D+07	0.0
0.26231074D+07	0.10826772D+07	0.15877451D+07	-0.52512304D+07	0.16453814D+03	0.47369688D+07	0.27717106D+07	-0.2772884D+07	0.0
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0.30738235D+07	-0.27717367D+07	0.57646505D+08	0.26359387D+07	-0.45204002D+07	-0.26232717D+07	-0.2772775D+07	0.66828093D+02	0.0
0.97543146D+07	0.30738085D+07	0.26231086D+07	0.10826772D+07	0.15877452D+07	-0.52512531D+07	0.20332430D+03	0.47369829D+07	0.0
0.27717118D+07	-0.27727881D+07	-0.15879460D+07	-0.12006227D+07	0.11739247D+02	0.46190220D+07	0.17786280D+03	0.96049313D+07	0.0
-0.28765171D+08	0.26358911D+07	0.30738528D+07	-0.27717211D+07	0.57646445D+08	-0.26360455D+07	-0.45205273D+07	-0.26233074D+07	0.0
-0.2773041D+07	0.19142071D+02	0.97543373D+07	0.30738303D+07	0.26231371D+07	0.10826877D+07	0.15877468D+07	-0.52512348D+07	0.0
0.10417311D+03	0.47370016D+07	0.27717252D+07	-0.2773087D+07	-0.15879430D+07	-0.12006119D+07	0.19230026D+02	0.46190043D+07	0.0
0.18305862D+03	0.96049556E+07	-0.28764881D+08	0.26360041D+07	0.30738184D+07	-0.27717504D+07	0.57646305D+08	-0.26358646D+07	0.0
-0.45203884D+07	-0.26232805D+07	-0.2772724D+07	-0.82135614D+02	0.97542206D+07	0.30738102D+07	0.26230904D+07	0.10826761D+07	0.0
0.15877434D+07	-0.52512401D+07	0.20196910D+03	0.47369691D+07	0.27716992D+07	-0.27727887E+07	-0.15879485D+07	-0.12006236D+07	0.0
0.38981401D+02	0.46190036D+07	0.1935054D+03	0.96049644D+07	-0.28764999D+08	0.26359567E+07	0.30738325D+07	-0.27717382D+07	0.0
0.57646500D+08	-0.26359398D+07	-0.45204453D+07	-0.26232913D+07	-0.27727854D+07	-0.11652526D+03	0.97543523D+07	0.30738183D+07	0.0
0.26231245D+07	0.10826809D+07	0.15877448D+07	-0.52512429D+07	0.20444688D+03	0.47370006D+07	0.27717095D+07	-0.27727968D+07	0.0
-0.15879462D+07	-0.12006188D+07	0.45176062D+02	0.46190118D+07	0.19624287D+03	0.96049434D+07	-0.28765099D+08	0.26360653D+07	0.0
0.30738385D+07	-0.27717562D+07	0.57646648D+08	-0.26358545D+07	-0.45204927D+07	-0.26233283D+07	-0.2772902D+07	-0.31539103E+01	0.0
0.97543539D+07	0.30738337D+07	0.26231246D+07	0.10826846D+07	0.15877420D+07	-0.52512723D+07	0.16468836D+03	0.47369802D+07	0.0
0.27716904D+07	-0.2773094D+07	-0.15879494D+07	-0.12006148D+07	0.24242517D+02	0.46190418D+07	0.18648272D+03	0.96048994D+07	0.0
-0.28765099D+08	0.26358578D+07	0.30738467D+07	-0.27717167D+07	0.57646501D+08	-0.26360622D+07	-0.45204932D+07	-0.26232889D+07	0.0
-0.27727988D+07	0.11023260D+03	0.97543529D+07	0.30738218D+07	0.26231645D+07	0.10826849D+07	0.15877476D+07	-0.52512409D+07	0.0
0.12447864D+03	0.47370006D+07	-0.27717303D+07	-0.2773014D+07	-0.15879423D+07	-0.12006148D+07	0.28127254D+01	0.46190121D+07	0.0
0.17344647D+03	0.96049434E+07	-0.28764999D+08	0.26359430D+07	0.30738331D+07	-0.27717356D+07	0.57646306D+08	-0.26359536D+07	0.0
-0.45204453D+07	-0.26232887D+07	-0.27727860D+07	0.75835094D+02	0.97542209D+07	0.30738175D+07	0.26231271D+07	0.10826809D+07	0.0
0.15877452D+07	-0.52512388D+07	0.12718929D+03	0.47369691D+07	0.27717121D+07	-0.27727963D+07	-0.15879457D+07	-0.12006188D+07	0.0
0.92655211D+01	0.46190038E+07	0.17788774D+03	0.96049644D+07	-0.28764881D+08	0.26358678D+07	0.30738238D+07	-0.27717244D+07	0.0
0.57646445D+08	-0.26360010D+07	-0.45203887D+07	-0.26232549D+07	-0.27727800D+07	-0.25432229D+02	0.97543373D+07	0.30738024D+07	0.0
0.26231165D+07	0.10826763D+07	0.15877470D+07	-0.52512350D+07	0.22467806D+03	0.47370016D+07	0.27717244D+07	-0.27727968D+07	0.0
-0.15879438D+07	-0.12006236D+07	0.28677140D+02	0.46190043D+07	0.18609238D+03	0.96049556D+07	-0.28765170D+08	0.26360486D+07	0.0
0.30738465D+07	-0.27717512D+07	0.57646504D+08	-0.26358879D+07	-0.45205270D+07	-0.26233370D+07	-0.27727975D+07	-0.73129351E+02	0.0
0.97543142D+07	0.30738393E+07	0.26231429D+07	0.10826874D+07	0.15877426D+07	-0.52512545D+07	0.12585655D+03	0.47369828D+07	0.0
0.27716949D+07	-0.2773147D+07	-0.15879484D+07	-0.12006119D+07	0.36531157D+02	0.46190218D+07	0.19368435D+03	0.96049313D+07	0.0
0.0	0.0	0.0	0.0	0.10000000D+01	-0.26359326E+07	-0.45204002D+07	-0.26232728D+07	0.0
-0.2772772D+07	0.0	0.48770973D+07	0.0	0.2772772D+07	0.0	0.0	0.0	0.0
0.0	0.10000000D+01	0.27717106D+07	-0.2772884D+07	-0.15879462D+07	-0.12006227D+07	0.23094894D+07	0.0	0.0
0.0	0.48024904D+07	0.0	0.0	0.0	0.0	0.0	0.0	0.0

HIGHEST NATURAL FREQUENCY (RAD/SEC) = 0.12737131D+07

DELTA T SHOULD BE EQUAL TO OR LESS THAN 0.150000D-05

TIME STEP SIZE USED IN PROGRAM (SEC) = 0.400000D-05

IMPULSE LOADINGS HAVE BEEN SPECIFIED AS DESCRIBED BY INPUT

1 LOCAL INITIAL NORMAL VELOCITY FIELDS ARE DESCRIBED BELOW:

FIRST ELEM	TOTAL ELEM	WRAD	WRAD1	ANGV1	WRAD2	ANGV2
1	7	-0.100000E+05	-0.100000D+05	0.0	-0.500000D+04	0.200000D+05

THERE IS NO TIME DEPENDENT FORCE DISTRIBUTION DURING THIS RUN

THE FOLLOWING IS THE TIME SOLUTION OF AN EXTERNALLY LOADED STRUCTURE.  
 OUTPUT WILL BE PRINTED EVERY 10 CYCLES USING OUTPUT OPTION 3.  
 REACTION FORCES APPLIED TO THE STRUCTURE WILL BE PRINTED AT EACH OUTPUT CYCLE  
 FOR NODES AT WHICH BOUNDARY CONDITIONS ARE SPECIFIED. D.O.F. THAT ARE  
 NOT RESTRAINED AT THAT NODE WILL HAVE A REACTION FORCE = 0.0.

J= 0 TIME (SEC.) = 0.0  
 WORK INPUT INTO RING (IN.-LB.) = 0.306676E+06  
 RING KINETIC ENERGY (IN.-LB.) = 0.306676E+06  
 RING ELASTIC ENERGY (IN.-LB.) = 0.0  
 RING PLASTIC WORK (IN.-LB.) = 0.0

I	V	W	PSI	CHI	COPY	COPZ	L	M	STRAIN (IN)	STRAIN (OUT)
1	0.0	0.0	0.0	0.0	0.0	0.7700D+01	0.0	0.0	0.0	0.0
2	0.0	0.0	0.0	0.0	0.1205D+01	0.7605D+01	0.0	0.0	0.0	0.0
3	0.0	0.0	0.0	0.0	0.2379D+01	0.7323D+01	0.0	0.0	0.0	0.0
4	0.0	0.0	0.0	0.0	0.3496D+01	0.6861D+01	0.0	0.0	0.0	0.0
5	0.0	0.0	0.0	0.0	0.4526D+01	0.6229D+01	0.0	0.0	0.0	0.0
6	0.0	0.0	0.0	0.0	0.5445D+01	0.5445D+01	0.0	0.0	0.0	0.0
7	0.0	0.0	0.0	0.0	0.6229D+01	0.4526D+01	0.0	0.0	0.0	0.0
8	0.0	0.0	0.0	0.0	0.6861D+01	0.3496D+01	0.0	0.0	0.0	0.0
9	0.0	0.0	0.0	0.0	0.7323D+01	0.2379D+01	0.0	0.0	0.0	0.0
10	0.0	0.0	0.0	0.0	0.7605D+01	0.1205D+01	0.0	0.0	0.0	0.0
11	0.0	0.0	0.0	0.0	0.7700D+01	0.0	0.0	0.0	0.0	0.0
12	0.0	0.0	0.0	0.0	0.7605D+01	-0.1205D+01	0.0	0.0	0.0	0.0
13	0.0	0.0	0.0	0.0	0.7323D+01	-0.2379D+01	0.0	0.0	0.0	0.0
14	0.0	0.0	0.0	0.0	0.6861D+01	-0.3496D+01	0.0	0.0	0.0	0.0
15	0.0	0.0	0.0	0.0	0.6229D+01	-0.4526D+01	0.0	0.0	0.0	0.0
16	0.0	0.0	0.0	0.0	0.5445D+01	-0.5445D+01	0.0	0.0	0.0	0.0
17	0.0	0.0	0.0	0.0	0.4526D+01	-0.6229D+01	0.0	0.0	0.0	0.0
18	0.0	0.0	0.0	0.0	0.3496D+01	-0.6861D+01	0.0	0.0	0.0	0.0
19	0.0	0.0	0.0	0.0	0.2379D+01	-0.7323D+01	0.0	0.0	0.0	0.0
20	0.0	0.0	0.0	0.0	0.1205D+01	-0.7605D+01	0.0	0.0	0.0	0.0
21	0.0	0.0	0.0	0.0	0.0	-0.7700D+01	0.0	0.0	0.0	0.0

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J= 1 TIME (SEC.) = 0.400000E-05  
 WORK INPUT INTO RING (IN.-LB.) = 0.306676E+06  
 RING KINETIC ENERGY (IN.-LB.) = 0.298832E+06  
 RING ELASTIC ENERGY (IN.-LB.) = 0.181817E+04  
 RING PLASTIC WORK (IN.-LB.) = 0.602572E+04

I	V	W	PSI	CHI	COPY	COPZ	L	M	STRAIN (IN)	STRAIN (OUT)
1	0.0	-0.3993D-01	0.0	-0.4211E-02	0.0	0.7660D+01	-0.1643D+06	-0.1646D+05	-0.4209D-02	-0.4183D-02
2	-0.5368D-07	-0.3993D-01	0.3806D-06	-0.4211E-02	0.1198D+01	0.7566D+01	-0.1643D+06	-0.1646D+05	-0.4209D-02	-0.4183D-02
3	0.2838D-06	-0.3993D-01	0.5245D-05	-0.4210D-02	0.2367D+01	0.7285D+01	-0.1644D+06	-0.1647D+05	-0.4209D-02	-0.4179D-02
4	0.3751D-05	-0.3993D-01	0.2954E-04	-0.4190D-02	0.3478D+01	0.6825D+01	-0.1651D+06	-0.1654D+05	-0.4191D-02	-0.4152E-02
5	0.2048D-04	-0.3993D-01	0.5958D-04	-0.4057D-02	0.4502D+01	0.6197D+01	-0.1673D+06	-0.1658D+05	-0.4046D-02	-0.4057E-02
6	0.3605D-04	-0.4005D-01	-0.5056E-03	-0.3695D-02	0.5416D+01	0.5416D+01	-0.1639D+06	-0.1453D+05	-0.3511D-02	-0.4219D-02
7	-0.5145D-03	-0.4098D-01	-0.6398D-02	-0.5543D-02	0.6196D+01	0.4502D+01	-0.1780D+06	-0.3129D+05	-0.5832D-02	-0.4533D-02
8	0.1689D-02	-0.1996D-01	0.6158D-01	-0.2106D-02	0.6844D+01	0.3485D+01	0.6358D+05	0.2584D+05	-0.2107D-03	-0.1979E-03
9	-0.5145D-03	0.1046D-02	-0.6399E-02	-0.1333D-02	0.7324D+01	0.2380D+01	-0.3253E+03	-0.1914D+04	0.1673D-02	0.3994D-03
10	0.3606D-04	0.1193D-03	-0.5057D-03	-0.5163D-03	0.7605D+01	0.1205D+01	0.3026D+04	0.1301D+03	-0.6995D-03	0.3450D-04
11	0.2049D-04	0.8326D-06	0.5958D-04	-0.1539E-03	0.7700D+01	-0.2049D-04	0.7636D+03	0.8781D+02	-0.1631D-03	-0.1262D-03
12	0.3755D-05	-0.3416D-05	0.2955D-04	-0.2100D-04	0.7605D+01	-0.1205D+01	0.9142D+02	0.1710D+02	-0.1781D-04	-0.3056E-04
13	0.2746D-06	-0.8409D-06	0.5251D-05	-0.3482E-06	0.7323D+01	-0.2379D+01	-0.1292D+01	0.1425D+01	0.6928D-06	-0.3471D-05
14	-0.4825D-07	-0.9731E-07	0.3586D-06	0.5535D-06	0.6861D+01	-0.3496D+01	-0.3079D+01	-0.1780D+00	0.7055D-06	0.9759D-07
15	-0.1985D-07	0.2247D-08	-0.7353D-07	0.1428D-06	0.6229D+01	-0.4526D+01	-0.6964D+00	-0.8572D-01	0.1475D-06	0.1285D-06
16	-0.3279D-08	0.3487D-08	-0.2843D-07	0.1732E-07	0.5445D+01	-0.5445D+01	-0.7299D-01	-0.1508D-01	0.1385D-07	0.2774D-07
17	-0.1815D-09	0.7647D-09	-0.4563D-08	-0.1898D-09	0.4526D+01	-0.6229D+01	0.3674D-02	-0.1003D-02	-0.1163D-08	0.2731D-08
18	0.5604D-10	0.7697D-10	-0.2279D-09	-0.5705E-09	0.3496D+01	-0.6861D+01	0.3090D-02	0.2174D-03	-0.6977D-09	-0.1887D-09
19	0.1890D-10	-0.4788D-11	0.8395D-10	-0.1304D-09	0.2379D+01	-0.7323D+01	0.6237D-03	0.8210D-04	-0.1313D-09	-0.1277D-09
20	0.2874D-11	-0.3537D-11	0.2683D-10	-0.1331D-10	0.1205D+01	-0.7605D+01	0.5042D-04	0.1371D-04	-0.9559D-11	-0.2456D-10
21	0.0	-0.1371D-11	0.0	0.1281D-11	0.9564D-27	-0.7700D+01			0.3076D-11	-0.4105D-11

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CYCLE=	10	SI	STA 1	SO	SI	STA 2	SO	SI	STA 3	SO
1	-0.46634614D-01	-0.46613764D-01	-0.47142843D-01	-0.47159117D-01	-0.46585892D-01	-0.46571031D-01				
	-0.46624189D-01	0.0	-0.47150980D-01	0.0	-0.46578462D-01	0.0				
2	-0.46575659D-01	-0.46516657D-01	-0.47014564D-01	-0.46995446D-01	-0.46320722D-01	-0.46269391D-01				
	-0.46546158D-01	0.0	-0.47005005D-01	0.0	-0.46295056D-01	0.0				
3	-0.46119769D-01	-0.46284822D-01	-0.46372676D-01	-0.46313018D-01	-0.45501150D-01	-0.45145198D-01				
	-0.46202296D-01	0.0	-0.46342847D-01	0.0	-0.45323174D-01	0.0				
4	-0.45450041D-01	-0.43894255D-01	-0.44040502D-01	-0.44308822D-01	-0.40354253D-01	-0.42313584D-01				
	-0.44672148D-01	0.0	-0.44174662D-01	0.0	-0.41333919D-01	0.0				
5	-0.37503299D-01	-0.43283765D-01	-0.40204692D-01	-0.32400894D-01	-0.44979619D-01	-0.23674817D-01				
	-0.40393532D-01	0.0	-0.36302793D-01	0.0	-0.34327218D-01	0.0				
6	-0.42209898D-01	-0.13308385D-01	-0.15899850D-01	-0.33372985D-01	-0.66870863D-02	-0.57371533D-01				
	-0.27759142D-01	0.0	-0.24636418D-01	0.0	-0.25342223D-01	0.0				
7	-0.22581255D-01	-0.91441771D-01	-0.14859183D-01	-0.62925638D-01	-0.95308597E-04	-0.42393676D-01				
	-0.34430258D-01	0.0	-0.24033228D-01	0.0	-0.21244592D-01	0.0				
8	-0.39755521D-01	0.33611922D-01	-0.51132627D-01	-0.21152513D-01	-0.49288907E-01	0.22514232E-01				
	-0.30717994D-02	0.0	-0.14990057D-01	0.0	-0.13387338D-01	0.0				
9	-0.34901587E-01	0.88546734D-02	-0.17362076D-01	-0.52177394D-02	-0.49493983D-02	-0.37729692D-02				
	-0.13023437D-01	0.0	-0.60721682D-02	0.0	-0.43611837D-02	0.0				
10	-0.29612027D-02	-0.43640668D-02	-0.62842597D-02	-0.65670637D-02	-0.18877811E-02	-0.84918704D-02				
	-0.36126345D-02	0.0	-0.35977448D-02	0.0	-0.33020447D-02	0.0				
11	-0.14071050D-02	-0.70208907D-02	-0.16874755D-02	-0.36032318D-02	-0.44212693D-02	0.37686682D-03				
	-0.23003010D-02	0.0	-0.26453536D-02	0.0	-0.20223012D-02	0.0				
12	-0.40988190D-02	0.35286220D-03	-0.17141995D-02	-0.70323277D-03	-0.31252491D-03	-0.21318534D-02				
	-0.18729784D-02	0.0	-0.12087162D-02	0.0	-0.90966424D-03	0.0				
13	-0.27472065D-03	-0.12733659D-02	-0.28317293D-03	-0.52871344D-03	-0.63732977D-03	0.42959810D-03				
	-0.49932260D-03	0.0	-0.40594319D-03	0.0	-0.10386583D-03	0.0				
14	-0.28390311D-03	-0.98555975D-04	-0.32788711D-04	-0.37737806D-04	-0.14493651D-03	-0.19249817D-03				
	-0.19122954D-03	0.0	-0.24745475D-05	0.0	-0.23780831D-04	0.0				
15	-0.67823581D-05	0.78616708D-04	-0.98493671D-05	-0.45606296D-04	-0.10317334D-04	0.51537013D-04				
	-0.42699533E-04	0.0	-0.17878464D-04	0.0	-0.30927174E-04	0.0				
16	-0.38266155D-04	0.56658968D-05	-0.24039983D-04	-0.13756723D-04	-0.85630887D-05	0.20488374D-04				
	-0.21966026D-04	0.0	-0.18898353D-04	0.0	-0.14525731D-04	0.0				
17	-0.72221632D-05	0.12267237D-04	-0.78487827D-05	-0.86620228D-05	-0.64620549D-05	0.29389299D-05				
	-0.97466999E-05	0.0	-0.82554027D-05	0.0	-0.47004924D-05	0.0				
18	-0.34978086D-05	0.50564479D-05	-0.20585962D-05	-0.29008742D-05	-0.15167793D-05	0.16922162D-05				
	-0.42769282D-05	0.0	-0.24797352D-05	0.0	-0.16045077D-05	0.0				
19	-0.13418098D-05	0.11919649D-05	-0.70964630D-06	-0.73666326D-06	-0.36257670D-06	0.58143097D-06				
	-0.12668873D-05	0.0	-0.72315478E-06	0.0	-0.47200384E-06	0.0				
20	-0.34471418D-06	0.33325813D-06	-0.23418164D-06	-0.24091080D-06	-0.17328668D-06	0.20079319D-06				
	-0.33898615D-06	0.0	-0.23754622D-06	0.0	-0.18703993D-06	0.0				

CYCLE=	10	SI	SO	SI	SO
STRAIN AT ADDITIONAL POINTS	1	0.21954989D-06	0.22984242D-06	0.21954986D-06	0.22984239D-06
		0.22469615D-06	0.0		

J= 10 TIME (SEC.) = 0.400000D-04  
 WORK INPUT INTO RING (IN.-LB.) = 0.306676D+06  
 RING KINETIC ENERGY (IN.-LB.) = 0.222548D+06  
 RING ELASTIC ENERGY (IN.-LB.) = 0.579372E+04  
 RING PLASTIC WORK (IN.-LB.) = 0.783343E+05

I	V	W	PSI	CHI	COPY	COP2	L	H	STRAIN (IN)	STRAIN (OUT)
1	0.0	-0.3701D+00	0.0	-0.4740D-01	0.0	0.7330D+01	-0.2841D+06	-0.2841D+05	-0.4628D-01	-0.4626D-01
2	0.8171D-04	-0.3701D+00	-0.8125D-05	-0.4733D-01	0.1147D+01	0.7240D+01	-0.2835D+06	-0.2835D+05	-0.4622D-01	-0.4619E-01
3	0.3655D-03	-0.3702D+00	-0.1265D-03	-0.4699D-01	0.2265D+01	0.6971D+01	-0.2811D+06	-0.2808D+05	-0.4588D-01	-0.4591D-01
4	0.1475D-02	-0.3701D+00	-0.3670D-03	-0.4598D-01	0.3329D+01	0.6530D+01	-0.2732D+06	-0.2742D+05	-0.4508E-01	-0.4444D-01
5	0.5936D-02	-0.3710D+00	-0.3325D-03	-0.4025D-01	0.4313D+01	0.5926D+01	-0.2479D+06	-0.2479D+05	-0.3868D-01	-0.4172D-01
6	0.1601D-01	-0.3725D+00	-0.2319D-01	-0.4162D-01	0.5193D+01	0.5170D+01	-0.1873E+06	-0.2655D+05	-0.4471D-01	-0.2782D-01
7	0.5080D-01	-0.4004D+00	0.2982E-01	-0.5958E-02	0.5935D+01	0.4249D+01	-0.1541D+06	-0.3039D+05	0.7152D-02	-0.4384D-01
8	0.7131D-01	-0.1827D+00	0.2657D+00	-0.5213D-01	0.6730D+01	0.3349D+01	-0.1428D+06	0.4116D+02	-0.1809D-01	-0.7670D-02
9	0.2729D-01	0.1327D-01	0.4657D-01	-0.2985E-01	0.7348D+01	0.2358D+01	-0.1135D+06	0.1776D+04	-0.3592D-01	-0.5509D-02
10	0.7713D-02	-0.1401D-01	-0.2151D-01	-0.3807D-02	0.7620D+01	0.1199D+01	-0.1019D+06	-0.1547D+05	-0.3237D-02	-0.4564D-02
11	0.4562D-02	-0.3772D-02	-0.3550D-02	-0.1859E-03	0.7696D+01	-0.4562D-02	-0.7675D+05	-0.9528D+04	0.1210D-02	-0.4349D-02
12	0.2329D-02	-0.1313D-02	0.2231D-02	-0.3538D-02	0.7606D+01	-0.1207D+01	-0.3507D+05	-0.2529D+04	-0.4292D-02	-0.1240D-02
13	0.3102D-03	-0.3947D-03	-0.8133D-03	0.7696D-05	0.7323D+01	-0.2380D+01	-0.1178D+05	-0.1415D+04	-0.3441D-03	-0.1000E-02
14	-0.5350D-05	0.1253D-03	-0.7915D-04	-0.3528D-03	0.6967D+01	-0.3496D+01	-0.7180D+02	-0.7539D+02	-0.4596D-03	-0.3244E-04
15	-0.5894D-04	-0.5319D-04	0.1434E-03	0.3762D-04	0.6229D+01	-0.4526D+01	0.5187D+03	0.1055D+03	0.5889D-04	-0.2616D-04
16	-0.3986D-04	-0.1891D-05	-0.2611D-04	0.3263D-04	0.5445D+01	-0.5445D+01	0.5483D+03	0.4489D+02	0.3273D-04	0.3232D-04
17	-0.1356D-04	-0.8980D-06	0.5077D-05	0.8183D-05	0.4526D+01	-0.6229D+01	0.2395D+03	0.2474D+02	0.6644D-05	0.1280E-04
18	-0.4382D-05	-0.9140D-06	0.2706D-05	0.4522D-05	0.3496D+01	-0.6861D+01	0.7195D+02	0.8009D+01	0.4712D-05	0.3955E-05
19	-0.1283D-05	-0.1475D-06	0.1168D-06	0.1532D-05	0.2379D+01	-0.7323D+01	0.2098D+02	0.2124D+01	0.1545D-05	0.1493D-05
20	-0.3957D-06	-0.2456D-07	0.2252D-07	0.3824E-06	0.1205D+01	-0.7605D+01	0.6892D+01	0.6957D+00	0.3661D-06	0.4314D-06
21	0.0	-0.1628D-07	0.0	0.1732D-06	0.1136D-22	-0.7700D+01			0.1689D-06	0.1859D-06

REACTIONS AT NODE	RV (LBS)	RW (LBS)	RN (IN.-LBS)
1	0.270320D+06	0.0	-0.284250D+05
21	0.541103D+01	0.0	-0.594910D+00

SUBSTRUCTURE	MSR	EL	SURF	STA	TIME
1	0.406287D-01	8	2	1	0.120000D-04
INTERFACE	0.981461D-02	8	1	1	0.800000D-05
SUBSTRUCTURE	LARGST	ADD. PT.	STRAIN	ELN	ADD. PT.
1	0.229842D-06			20	1
INTERFACE	0.224696D-06			20	1
SUBSTRUCTURE	LARGST	MODAL	STRAIN	MODE	SURF
1	0.715155D-02			7	1
					0.400000D-04

ORIGINAL PAGE IS  
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CYCLE= 20		SI STA 1		SI STA 2		SI STA 3	
ELEMENT		SO		SO		SO	
1	-0.81080454D-01	-0.80895465E-01	-0.81187515D-01	-0.81005996D-01	-0.80334731D-01	-0.80084296D-01	
2	-0.8098796CD-01	0.0	-0.81096756D-01	0.0	-0.80209514D-01	0.0	
3	-0.79813157D-01	-0.79715948D-01	-0.78996366D-01	-0.78663052D-01	-0.77091188D-01	-0.76442452D-01	
4	-0.79764652D-01	0.0	-0.78829694D-01	0.0	-0.76766820E-01	0.0	
5	-0.76301527D-01	-0.74114293D-01	-0.73243837D-01	-0.72168329D-01	-0.67897544D-01	-0.67787632E-01	
6	-0.75208910E-01	0.0	-0.72706083D-01	0.0	-0.67842588D-01	0.0	
7	-0.62612557D-01	-0.69530308D-01	-0.60643927D-01	-0.58418114D-01	-0.61011188D-01	-0.49758695D-01	
8	-0.66071433E-01	0.0	-0.59531021D-01	0.0	-0.55383041D-01	0.0	
9	-0.61931917D-01	-0.40870132D-01	-0.58736583D-01	-0.31391833D-01	-0.55978837D-01	-0.22390256E-01	
10	-0.51376025D-01	0.0	-0.45064208D-01	0.0	-0.39184546D-01	0.0	
11	-0.41269730D-01	-0.23946742D-01	-0.21283657D-02	-0.74503881D-01	0.29433635D-01	-0.13345526D+00	
12	-0.32608236D-01	0.0	-0.38316124D-01	0.0	-0.52010812D-01	0.0	
13	-0.33675275D-01	-0.12893628D+00	0.20067750D-01	-0.80856344D-01	-0.96911016D-03	-0.40548297D-01	
14	-0.47620501D-01	0.0	-0.30394297D-01	0.0	-0.20758704D-01	0.0	
15	-0.44718751D-01	0.35183113D-01	-0.70473313D-01	0.29917600D-01	-0.84231940E-01	0.37323927D-01	
16	-0.47578187D-02	0.0	-0.20277857D-01	0.0	-0.23454006D-01	0.0	
17	-0.71779001D-01	0.24695457D-01	-0.40882846D-01	0.15008264D-01	-0.12514042D-01	0.25731123D-02	
18	-0.23541772D-01	0.0	-0.12937291D-01	0.0	-0.49694647D-02	0.0	
19	-0.54619320D-02	-0.63957111D-03	-0.27823113D-02	-0.42224333D-02	0.85429322D-04	-0.75949071D-02	
20	-0.30507515D-02	0.0	-0.35023723D-02	0.0	-0.37547389D-02	0.0	
21	-0.14364349D-02	-0.97396986D-02	0.13487222D-02	-0.90351700D-02	0.14642824D-02	-0.81640327D-02	
22	-0.41516119D-02	0.0	-0.38432239D-02	0.0	-0.33498751E-02	0.0	
23	0.60067351D-03	-0.67252753D-02	-0.17672499D-02	-0.45446274D-02	-0.42196659D-02	-0.24631581D-02	
24	-0.306230C9E-02	0.0	-0.31559612D-02	0.0	-0.33414120E-02	0.0	
25	-0.52800685D-02	-0.12641106D-02	-0.51357179D-02	-0.15853762D-02	-0.46970837D-02	-0.15835271D-02	
26	-0.32720995D-02	0.0	-0.33605471D-02	0.0	-0.31403054E-02	0.0	
27	-0.35734482D-02	-0.31406366D-02	-0.22882336D-02	-0.41320302D-02	-0.13357963D-02	-0.54793196D-02	
28	-0.33570424D-02	0.0	-0.32101319D-02	0.0	-0.34075579D-02	0.0	
29	-0.19832852D-02	-0.48870937D-02	-0.32978024D-02	-0.35473561D-02	-0.42576939D-02	-0.22347263D-02	
30	-0.32351895D-02	0.0	-0.34225793D-02	0.0	-0.32462101D-02	0.0	
31	-0.38295540D-02	-0.28756242D-02	-0.28775022D-02	-0.31985274D-02	-0.20972479D-02	-0.37027118D-02	
32	-0.33525891D-02	0.0	-0.30380148D-02	0.0	-0.28999798E-02	0.0	
33	-0.22050490D-02	-0.30016456D-02	-0.22843195D-02	-0.24859155D-02	-0.21774574D-02	-0.17754695D-02	
34	-0.26037771D-02	0.0	-0.23851175D-02	0.0	-0.19764635D-02	0.0	
35	-0.18009630D-02	-0.19066662D-02	-0.13537000D-02	-0.15810460D-02	-0.10239293D-02	-0.13803848D-02	
36	-0.19539146D-02	0.0	-0.14672060D-02	0.0	-0.12021570D-02	0.0	
37	-0.96794184D-03	-0.10445055D-02	-0.18084653D-03	-0.82023571D-03	-0.60381419D-03	-0.60810834D-03	
38	-0.10069599D-02	0.0	-0.60054097D-03	0.0	-0.60596127E-03	0.0	
39	-0.49164729D-03	-0.58345161D-03	-0.40551769D-03	-0.46548608D-03	-0.38019815D-03	-0.41167543D-03	
40	-0.53754945D-03	0.0	-0.43550188D-03	0.0	-0.39593679E-03	0.0	

CYCLE= 20		SI		SI		SI	
STRAIN AT ADDITIONAL POINTS		SO		SO		SO	
1	-0.39638247E-03	-0.45095377D-03	-0.39646106D-03	-0.45105549D-03			
2	-0.42366812D-03	0.0					

J= 20 TIME (SEC.) = 0.800000D-04  
WCRK INPUT INTO RING (IN.-LB.) = 0.306676D+06  
RING KINETIC ENERGY (IN.-LB.) = 0.170015D+06  
RING ELASTIC ENERGY (IN.-LB.) = 0.608105D+04  
RING PLASTIC WCRK (IN.-LB.) = 0.130581E+06

I	V	W	PSI	CHI	COPY	COPY2	L	M	STRAIN (IN)	STRAIN (OUT)
1	0.0	-0.6654D+00	0.0	-0.8438E-01	0.0	0.7035D+01	-0.2923D+06	-0.2922D+05	-0.8084D-01	-0.8074D-01
2	0.2410D-02	-0.6656D+00	-0.6097D-03	-0.8330E-01	0.1103D+01	0.6947D+01	-0.2869D+06	-0.2863D+05	-0.7986D-01	-0.7977E-01
3	0.7854D-02	-0.6660D+00	-0.1684D-02	-0.7929D-01	0.2181D+01	0.6687D+01	-0.2718D+06	-0.2723D+05	-0.7635D-01	-0.7553D-01
4	0.2175D-01	-0.6688D+00	-0.5061D-02	-0.6827D-01	0.3211D+01	0.6255D+01	-0.2314D+06	-0.2049D+05	-0.6532D-01	-0.6776E-01
5	0.5069D-01	-0.6662D+00	-0.1170D-01	-0.60C2D-01	0.4175D+01	0.5661D+01	-0.2098D+06	-0.1621D+05	-0.6022D-01	-0.5193D-01
6	0.9136D-01	-0.7345D+00	-0.9439D-01	-0.5217E-01	0.5004D+01	0.4875D+01	-0.1690D+06	-0.3297D+05	-0.5128D-01	-0.3161E-01
7	0.1782D+00	-0.7464D+00	0.1251E+00	-0.1177D-01	0.5730D+01	0.3943D+01	-0.1358D+06	-0.2999D+05	-0.1926D-01	-0.7325D-01
8	0.1898D+00	-0.3304D+00	0.4306D+00	-0.1170D+00	0.6653D+01	0.3177D+01	-0.1092D+06	0.7474D+04	-0.2070D-01	-0.7629D-02
9	0.9476D-01	0.4515D-01	0.1265E+00	-0.6282D-01	0.7395D+01	0.2303D+01	-0.1010D+06	0.7377D+04	-0.6760D-01	-0.8583E-02
10	0.4683D-01	0.7430D-01	-0.4233D-01	-0.5518D-02	0.7686D+01	0.1170D+01	-0.9310D+05	-0.9434D+04	-0.5221D-02	-0.2765D-02
11	0.3399D-01	0.2700D-01	-0.3799D-01	-0.2064E-02	0.7727D+01	-0.3399D-01	-0.8861D+05	-0.1556D+05	-0.3340D-04	-0.5260D-02
12	0.3013D-01	0.5634D-02	-0.6563D-02	-0.8525D-03	0.7606D+01	-0.1235D+01	-0.9132D+05	-0.1185D+05	0.2987D+03	-0.4218D-02
13	0.2595D-01	0.1083D-01	0.1848E-02	-0.4242D-02	0.7325D+01	-0.2407D+01	-0.9540D+05	-0.6498D+04	-0.2873D-03	-0.2876E-02
14	0.1909D-01	0.9726D-02	-0.8912D-02	-0.3809D-02	0.6861D+01	-0.3517D+01	-0.9314E+05	-0.1107D+05	-0.4017D-02	-0.2997D-02
15	0.1467D-01	0.3143D-02	-0.3317E-02	-0.2307D-02	0.6223D+01	-0.4540D+01	-0.9930D+05	-0.9125D+04	-0.1800D-02	-0.3793D-02
16	0.1022D-01	0.3338D-02	-0.2578D-02	-0.3832E-02	0.5440D+01	-0.5454D+01	-0.8815D+05	-0.9125D+04	-0.4072D-02	-0.3069D-02
17	0.6231D-02	0.1069E-02	-0.9979D-03	-0.2388D-02	0.4522D+01	-0.6234D+01	-0.6920D+05	-0.7115D+04	-0.2200D-02	-0.2937D-02
18	0.3330D-02	0.7130D-03	-0.9979D-03	-0.1975E-02	0.3493E+01	-0.6863D+01	-0.4257D+05	-0.4477D+04	-0.2004D-02	-0.1877E-02
19	0.1518D-02	0.1921E-03	-0.3038D-03	-0.1048D-02	0.2378D+01	-0.7324D+01	-0.2323D+05	-0.2361D+04	-0.1018D-02	-0.1138E-02
20	0.5161D-03	0.7818D-04	-0.1841D-03	-0.5534D-03	0.1204D+01	-0.7605D+01	-0.1264D+05	-0.1322D+04	-0.5473D-03	-0.5713D-03
21	0.0	0.2999D-04	0.0	-0.3906D-03	-0.2092D-19	-0.7700D+01			-0.3875D-03	-0.3994D-03

REACTIONS AT NODE		RV (LBS)		RW (LBS)		RM (IN.-LBS)	
1	0.268202D+06	0.0	-0.293358D+05				
21	-0.114003D+05	0.0	0.115324D+04				

SUBSTRUCTURE		MSTR		ELE		STA		TIME	
1	0.406287D-01	8	2	1	0.120000D-04				
INTFACE	0.981461D-02	8	1	1	0.800000D-05				
SUBSTRUCTURE		LARGST AED. PT. STRAIN		ELEN		ADD. PT.		TIME	
1	0.104085D-04	20	1	0.600000D-04					
INTFACE	0.100070D-04	20	1	0.600000D-04					
SUBSTRUCTURE		LARGST MODAL STRAIN		MODK		SURF		TIME	
1	0.192603D-01	7	1	0.800000D-04					

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CYCLE=		30													
ELEMENT		SI STA 1				SI STA 2				SI STA 3				SO	
1	2	-0.97555892D-01	-0.96552079D-01			-0.97073742D-01	-0.95689131D-01			-0.95514855D-01	-0.93661353D-01			-0.94588104D-01	
		-0.97053886D-01	0.0			-0.96381437D-01	0.0			-0.94588104D-01	0.0			-0.94588104D-01	
		-0.94133282D-01	-0.92340899D-01			-0.9073287D-01	-0.88369775D-01			-0.85456571D-01	-0.82388530D-01			-0.82388530D-01	
3	4	-0.93237091E-01	0.0			-0.89551311D-01	0.0			-0.83922551E-01	0.0			-0.83922551E-01	
		-0.89809512D-01	-0.83951327D-01			-0.76250112E-01	-0.76940728D-01			-0.69900004D-01	-0.68028140D-01			-0.68028140D-01	
		-0.82380420E-01	0.0			-0.76595420D-01	0.0			-0.69964072E-01	0.0			-0.69964072E-01	
4	5	-0.66636468D-01	-0.64999551D-01			-0.69967367D-01	-0.50054490D-01			-0.75961044D-01	-0.37898474D-01			-0.37898474D-01	
		-0.65819009D-01	0.0			-0.60010928D-01	0.0			-0.56929759D-01	0.0			-0.56929759D-01	
		-0.73405475D-01	-0.32313698D-01			-0.60982291D-01	-0.25036768D-01			-0.53706724D-01	-0.23106931D-01			-0.23106931D-01	
5	6	-0.528959587E-01	0.0			-0.43009530D-01	0.0			-0.38406827E-01	0.0			-0.38406827E-01	
		-0.24791293D-01	-0.32373654D-01			-0.24171667D-01	-0.10760661D+00			-0.67884410D-01	-0.19384841D+00			-0.19384841D+00	
		-0.30582472D-01	0.0			-0.41717474D-01	0.0			-0.62981998E-01	0.0			-0.62981998E-01	
7	8	0.59321800D-01	-0.14753360E+00			-0.31264575D-01	-0.91063594D-01			-0.96377634D-03	-0.36251783D-01			-0.36251783D-01	
		-0.44105900D-01	0.0			-0.29899509D-01	0.0			-0.17644003D-01	0.0			-0.17644003D-01	
		-0.45256824D-01	0.38798837D-01			-0.81476834D-01	0.44819295D-01			-0.10800423D+00	0.61468115D-01			0.61468115D-01	
8	9	-0.32289937E-02	0.0			-0.18328769D-01	0.0			-0.17644003D-01	0.0			-0.17644003D-01	
		-0.99715917D-01	0.53473210D-01			-0.56523830D-01	0.32707493D-01			-0.23268059D-01	0.0			-0.23268059D-01	
		-0.22621354D-01	0.0			-0.11908168D-01	0.0			-0.16310429D-01	0.94164082D-02			0.94164082D-02	
10	11	-0.72647136D-02	0.42747826D-02			-0.26144610D-02	0.17120284D-03			-0.13104064D-02	-0.46471618D-02			-0.46471618D-02	
		-0.14949555D-02	0.0			-0.12216291D-02	0.0			-0.16683777D-02	0.0			-0.16683777D-02	
		-0.30519987D-02	-0.70593215D-02			-0.43467443D-02	-0.80156171D-02			-0.57045721D-02	-0.89556736D-02			-0.89556736D-02	
12	13	-0.20037064D-02	0.0			-0.18344364D-02	0.0			-0.16255507D-02	0.0			-0.16255507D-02	
		0.51439265D-02	-0.72473501D-02			-0.34055408D-02	-0.53706666D-02			-0.15294741D-02	-0.36905482E-02			-0.36905482E-02	
		-0.10517118D-02	0.0			-0.98256291D-03	0.0			-0.10850371D-02	0.0			-0.10850371D-02	
14	15	0.44240285D-03	-0.26683475D-02			-0.76258876D-03	-0.14258231D-02			-0.20709706D-02	-0.29484403E-03			-0.29484403E-03	
		-0.11129724E-02	0.0			-0.10942059D-02	0.0			-0.11829073E-02	0.0			-0.11829073E-02	
		-0.27116152E-02	0.37066407D-03			-0.30002787D-02	0.37176259D-03			-0.32889902D-02	0.38486891D-03			0.38486891D-03	
16	17	-0.11704756D-02	0.0			-0.13142581D-02	0.0			-0.14520607D-02	0.0			-0.14520607D-02	
		-0.28747464D-02	-0.14559113D-03			-0.13483725D-02	0.18672807D-02			-0.16987415D-03	-0.35962625D-02			-0.35962625D-02	
		-0.15101688D-02	0.0			-0.16078266D-02	0.0			-0.17131942D-02	0.0			-0.17131942D-02	
18	19	0.52151004D-03	-0.43518235D-02			-0.65651349D-03	-0.34703982D-02			-0.21088716D-02	-0.28894181D-02			-0.28894181D-02	
		-0.19151567D-02	0.0			-0.20634559D-02	0.0			-0.24991448E-02	0.0			-0.24991448E-02	
		-0.32450642D-02	-0.16706979D-02			-0.36368033D-02	-0.22525167D-02			-0.36633261D-02	-0.24440985D-02			-0.24440985D-02	
20	21	-0.24578810D-02	0.0			-0.29446603D-02	0.0			-0.30537123D-02	0.0			-0.30537123D-02	
		-0.30467136D-02	-0.38816992D-02			-0.28380060D-02	-0.43534353D-02			-0.27999830D-02	-0.50098371D-02			-0.50098371D-02	
		-0.34620664D-02	0.0			-0.35957207D-02	0.0			-0.39049101D-02	0.0			-0.39049101D-02	
22	23	-0.35983277D-02	-0.44446873D-02			-0.45573574D-02	-0.48952437D-02			-0.48043412D-02	-0.46265402D-02			-0.46265402D-02	
		-0.40065075D-02	0.0			-0.47263006D-02	0.0			-0.47154407D-02	0.0			-0.47154407D-02	
		-0.47144183D-02	-0.45324474D-02			-0.45593546D-02	-0.52175168D-02			-0.44172933D-02	-0.59177751D-02			-0.59177751D-02	
24	25	-0.46234329D-02	0.0			-0.48884357D-02	0.0			-0.51675342D-02	0.0			-0.51675342D-02	

CYCLE=		30							
STRAIN AT ADDITIONAL PCINTS		SI		SO		SI		SO	
1	2	-0.45345178D-02		-0.53447584D-02		-0.45448857D-02		-0.53591185D-02	
		-0.49396381D-02		0.0					

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J= 30 TIME (SEC.) = 0.120000D-03  
WORK INPUT INTO PING (IN.-LB.) = 0.306676D+06  
RING KINETIC ENERGY (IN.-LB.) = 0.150824E+06  
RING ELASTIC ENERGY (IN.-LB.) = 0.439917D+04  
RING PLASTIC WORK (IN.-LB.) = 0.151453D+06

I	V	W	PSI	CHI	COPY	COPE	L	N	STRAIN (IN)	STRAIN (OUT)
1	0.0	-0.8863D+00	0.0	-0.1025D+00	0.0	0.6814D+01	-0.2012D+06	-0.1978D+05	-0.9738D-01	-0.9692D-01
2	0.1640D-01	-0.8873D+00	-0.4261D-02	-0.9930D-01	0.1082D+01	0.6726D+01	-0.2256D+06	-0.2126D+05	-0.9459D-01	-0.9367D-01
3	0.4230D-01	-0.8920D+00	-0.1152D-01	-0.8655D-01	0.2144D+01	0.6462D+01	-0.1718D+06	-0.1462D+05	-0.8271D-01	-0.8284D-01
4	0.8694D-01	-0.8928E+00	-0.9524D-02	-0.6953D-01	0.3168D+01	0.6026D+01	-0.1410D+06	-0.4119D+04	-0.6700D-01	-0.6727D-01
5	0.1445D+00	-0.9082D+00	-0.6963D-01	-0.7231E-01	0.4109D+01	0.5410D+01	-0.9916D+05	-0.2811D+04	-0.7264D-01	-0.5117D-01
6	0.2190D+00	-0.1034D+01	-0.1782D+00	-0.6324D-01	0.4868D+01	0.4559D+01	-0.8793D+05	-0.3078D+05	-0.4927D-01	-0.3367D-01
7	0.3639D+00	-0.1065D+01	0.2218E+00	-0.6238D-02	0.5582D+01	0.3606D+01	-0.8459D+05	-0.2742D+05	-0.5158D-01	-0.8123D-01
8	0.3412D+00	-0.4462D+00	0.5912E+00	-0.2155D+00	0.6618D+01	0.2989D+01	-0.4230D+05	-0.1603D+05	-0.2123D-01	-0.6332D-02
9	0.1702D+00	0.1104D+00	0.2085D+00	-0.9090E-01	0.7481D+01	0.2252D+01	-0.4068D+05	0.1695D+05	-0.8707D-01	0.1086D-02
10	0.9589D-01	0.1696D+00	-0.6084D-01	-0.7170D-02	0.7788D+01	0.1136D+01	-0.2693D+05	0.1271D+04	-0.6620D-02	-0.1312D-02
11	0.6916D-01	0.9680D-01	-0.6927D-01	-0.2119D-02	0.7797D+01	-0.6916D+01	-0.2371D+05	-0.1028D+05	0.1405D-02	-0.3086E-02
12	0.5852D-01	0.4371D-01	-0.3185D-01	-0.1809E-02	0.7639D+01	-0.1269D+01	-0.2554D+05	-0.1057D+05	0.3454D-03	-0.3086E-02
13	0.5613D-01	0.3294D-01	-0.5274D-02	-0.1689D+03	0.7338D+01	-0.2441D+01	-0.2964D+05	-0.3997D+04	0.4149D-02	-0.8460D-03
14	0.4744D-01	0.3772D-01	-0.3262D-02	-0.1882E-02	0.6873D+01	-0.3555D+01	-0.3813D+05	-0.5520D+03	-0.2218D-02	-0.1640D-02
15	0.3892D-01	0.3462D-01	-0.1347D-01	-0.2528D-02	0.6235D+01	-0.4578D+01	-0.4665D+05	-0.5167D+04	-0.2899D-02	-0.2414D-02
16	0.3254D-01	0.2228D-01	-0.0000D-01	-0.6019D+03	0.5437D+01	-0.5483D+01	-0.5987D+05	-0.8708D+04	0.1058D+03	-0.2385D-02
17	0.2762D-01	0.1940E-01	-0.3370D-02	-0.2665D-02	0.4515D+01	-0.6261D-01	-0.8544D+05	-0.7205D+04	-0.2745D-02	-0.3206E-02
18	0.2084D-01	0.1645D-01	-0.7577D-02	-0.3341E-02	0.3485D+01	-0.6685E+01	-0.1093D+06	-0.1190D+05	-0.3340D-02	-0.3206E-02
19	0.1467D-01	0.1231D-01	-0.2982D-02	-0.3427D-02	0.2369D+01	-0.7339D+01	-0.1284D+06	-0.1265D+05	-0.3207D-02	-0.4582D-02
20	0.7140D-02	0.1144D-01	-0.1992E-02	-0.4677D-02	0.1199D+01	-0.7618D+01	-0.1381D+06	-0.1441D+05	-0.4712D-02	-0.5822D-02
21	0.0	0.1016D-01	0.0	-0.4818D-02	-0.7087D-17	-0.7710D+01			-0.4588D-02	-0.5861D-02

ORIGINAL PAGE IS  
OF POOR QUALITY

CYCLE=		40		SI		STA 1		SC		SI		STA 2		SO		SI		STA 3		SO	
ELEMENT																					
1		-0.92135959D-01		-0.86002837D-01		-0.90742796D-01		-0.86670923D-01		-0.86145249D-01		-0.83915597D-01		0.0		-0.85030423D-01		0.0		-0.73718428D-01	
2		-0.89069398D-01		0.0		-0.84307207D-01		-0.81320719D-01		-0.79598871D-01		-0.78606514D-01		0.0		-0.76162471D-01		0.0		-0.56018659D-01	
3		-0.83626075D-01		0.0		-0.72635480D-01		-0.70238118D-01		-0.65436819D-01		-0.71285235D-01		0.0		-0.63651947D-01		0.0		-0.26251601D-01	
4		-0.76723273D-01		0.0		-0.50037764D-01		-0.72608463D-01		-0.37534311D-01		-0.76453535D-01		0.0		-0.51352568D-01		0.0		-0.25855703D-01	
5		-0.69879207D-01		0.0		-0.28003478D-01		-0.54873814D-01		-0.24775576D-01		-0.43825832D-01		0.0		-0.34840767D-01		0.0		-0.22677722D+00	
6		-0.59358485D-01		0.0		-0.44910292D-01		-0.39824695D-01		-0.12734017D+00		-0.97020874D-01		0.0		-0.68478173D-01		0.0		-0.37632539D-01	
7		-0.70208085D-01		0.0		-0.25921358D-01		0.52351595D-01		0.0		-0.37494288D-01		0.0		-0.49950315D-02		0.0		0.78905838D-01	
8		-0.49105782D-01		0.0		-0.15606459D+00		-0.37494288D-01		0.0		-0.42436099D-01		0.0		-0.16318754D-01		0.0		0.17802851D-01	
9		-0.43814654D-01		0.0		0.39275414D-01		-0.85939980D-01		0.55190700D-01		-0.12153312D+00		0.0		-0.21313642D-01		0.0		0.0	
10		-0.22696221D-02		0.0		0.81866893D-01		-0.15074640D-01		0.0		-0.10170035D-01		0.0		-0.20988325D-01		0.0		0.0	
11		-0.19826630D-01		0.0		0.83882525D-02		-0.51232186D-02		0.33642794D-02		-0.48784744D-03		0.0		-0.15927368D-02		0.0		-0.24861029D-02	
12		-0.10624013D-01		0.0		-0.11789050D-02		-0.87946964D-03		0.0		-0.87946964D-03		0.0		-0.14869750D-02		0.0		0.0	
13		-0.13644457D-02		0.0		-0.47552971D-02		-0.35227617D-02		-0.69054735D-02		-0.60216021D-02		0.0		-0.87224664D-02		0.0		0.0	
14		-0.16954757D-02		0.0		-0.80172335D-02		-0.16913559D-02		0.0		-0.13504322D-02		0.0		-0.66521619D-02		0.0		0.0	
15		-0.63734217D-02		0.0		-0.82190588D-03		-0.56267948D-02		-0.72474432D-02		-0.93840260D-03		0.0		0.0		0.0		0.0	
16		-0.40064167D-02		0.0		-0.59798426D-02		-0.81032422D-03		0.0		-0.43588703D-02		0.0		-0.29590920D-02		0.0		0.0	
17		-0.93683779D-03		0.0		-0.16943486D-02		-0.27347561D-02		-0.10173652D-02		-0.79022287D-03		0.0		0.0		0.0		0.0	
18		-0.33180559D-03		0.0		-0.68127149D-03		-0.10173652D-02		0.0		-0.23762029D-02		0.0		0.11498801D-02		0.0		0.0	
19		-0.27674019D-02		0.0		0.18651042D-02		-0.64295718D-03		0.15023690D-02		-0.61316138D-03		0.0		0.0		0.0		0.0	
20		-0.45114885D-03		0.0		-0.45114885D-03		-0.31515626D-03		0.0		-0.14284045D-02		0.0		0.12263039D-02		0.0		0.0	
21		-0.69397473D-03		0.0		0.59161510D-03		0.57855443D-03		-0.26234930D-03		-0.10105029D-03		0.0		-0.11066741D-02		0.0		0.0	
22		-0.51179818D-04		0.0		-0.17292289D-02		0.15810257D-03		0.0		0.18614999D-02		0.0		0.0		0.0		0.0	
23		0.24906635D-02		0.0		0.38071731D-03		0.24741447D-02		0.12625100D-02		0.2212861D-02		0.0		-0.10694722D-02		0.0		0.0	
24		0.12911447D-02		0.0		0.33887113D-03		0.60581735D-03		0.0		0.57140595D-03		0.0		0.24381238D-02		0.0		0.0	
25		0.81500793D-03		0.0		0.16299250D-02		0.19000184D-03		0.12543619D-02		-0.65976675D-03		0.0		0.0		0.0		0.0	
26		-0.26276981D-03		0.0		0.68357759D-03		0.72218188D-03		0.0		0.88917854D-03		0.0		-0.60683385D-03		0.0		0.0	
27		0.19969076D-02		0.0		-0.11111368D-04		0.85029702D-03		0.64689126D-03		0.20456646D-02		0.0		0.50128701D-03		0.0		0.0	
28		0.99289811D-03		0.0		0.0		0.65949414D-03		0.32568862D-03		0.45018311D-03		0.0		0.0		0.0		0.0	
29		0.0		0.0		0.0		0.12982187D-02		0.0		0.47571506D-03		0.0		0.0		0.0		0.0	
30		0.0		0.0		0.0		0.81195363D-03		0.0		0.0		0.0		0.0		0.0		0.0	

CYCLE=		40		SI		SO		SI		SO	
STRAIN AT ADDITIONAL POINTS											
1		0.11583164D-02		0.37167917D-03		0.11576464D-02		0.37161013D-03		0.0	
2		0.76499781D-03		0.0		0.0		0.0		0.0	

J= 40 TIME (SEC.) = 0.160000E-03  
WORK INPUT INTO RING (IN.-LB.) = 0.306676D+06  
RING KINETIC ENERGY (IN.-LB.) = 0.145875D+06  
RING ELASTIC ENERGY (IN.-LB.) = 0.205421D+04  
RING PLASTIC WORK (IN.-LB.) = 0.158747D+06

I	V	W	PSI	CHI	COPY	COPZ	L	H	STRAIN (IN)	STRAIN (OUT)
1	0.0	-0.1053D+01	0.0	-0.9475E-01	0.0	0.6647D+01	0.5386D+05	0.8853D+00	-0.9111D-01	-0.8772D-01
2	0.5292D-01	-0.1058D+01	-0.1250D-01	-0.8767D-01	0.1091D+01	0.6552D+01	0.3816D+05	0.4486D+04	-0.8372D-01	-0.8384D-01
3	0.7740D+00	-0.1060D+01	-0.1777D-01	-0.7949D-01	0.2163D+01	0.2729D+01	0.1084D+05	0.1290D+05	-0.7570D-01	-0.7661D-01
4	0.1934D+00	-0.1071D+01	-0.4693D-01	-0.6906D-01	0.3182D+01	0.5819D+01	-0.7622D+04	0.1454D+05	-0.6760D-01	-0.5951D-01
5	0.2795D+00	-0.1143D+01	-0.1529D+00	-0.7870D-01	0.4081D+01	0.5141D+01	-0.6752D+04	0.7745D+03	-0.7018D-01	-0.5511D-01
6	0.3852D+00	-0.1340D+01	-0.2039D+00	-0.7008E-01	0.4769D+01	0.4225D+01	-0.1267E+05	-0.2491D+05	-0.3895D-01	-0.3467D-01
7	0.5902D+00	-0.1342D+01	0.3021D+00	-0.8433E-02	0.5490D+01	0.3259D+01	-0.6211D+05	-0.2595D+05	0.7668D-01	-0.8107D-01
8	0.5178D+00	-0.5519D+00	0.7239D+00	-0.3365D+00	0.6604D+01	0.2784D+01	-0.1368D+05	0.2053D+05	-0.2116D-01	-0.8100D-02
9	0.2542D+00	-0.1698D+00	0.2960E+00	-0.1219D+00	0.7563D+01	0.2190D+01	-0.2641D+05	0.2049D+05	-0.9833D-01	0.1233D-01
10	0.1553D+00	-0.2743D+00	-0.6777D-01	-0.9241D-02	0.7900D+01	0.1096E+01	-0.1708D+05	0.7755D+04	-0.9206D-02	0.1231D-04
11	0.1078D+00	-0.1888D+00	-0.9347D-01	-0.8465D-02	0.7089D+01	-0.1078D+00	-0.1956D+05	-0.7999D+04	0.1347D-03	-0.2343D-02
12	0.8231D-01	-0.1061D+00	-0.6193D-01	0.9697E-03	0.7697D+01	-0.1302D+01	-0.2166D+05	-0.1391D+05	0.4816D-02	-0.2869D-02
13	0.7100D-01	-0.6786D-01	-0.2294D-01	0.1462E-02	0.7366D+01	-0.2468D+01	-0.2146D+05	-0.9398D+04	0.3084D-02	-0.2347E-02
14	0.6197D-01	-0.6574D-01	-0.1463D-02	0.4221D-04	0.6891D+01	-0.3581D+01	-0.1865D+05	-0.1141D+04	0.4448D-03	-0.1152E-02
15	0.6985D-01	-0.7360D-01	-0.3729D-02	0.1724D-02	0.6260D+01	-0.4610D+01	-0.9145D+04	0.2601D+04	-0.2295D-02	0.2061D-04
16	0.3697D-01	-0.6845D-01	-0.1474E-01	0.1717D-03	0.5467D+01	-0.5519D+01	0.4587D+04	-0.3566D+03	-0.8759D-03	0.1933D-03
17	0.2757D-01	-0.5550D-01	-0.1219D-01	0.1289D-02	0.4536D+01	-0.6291D+01	0.1758D+05	-0.1856D+04	0.1861D-02	-0.1272D-03
18	0.2106D-01	-0.5179D-01	-0.8691D-03	0.1294E-02	0.3500D+01	-0.6916D+01	0.2095D+05	0.3125D+04	0.1589D-02	0.4158D-03
19	0.1339D-01	-0.5310D-01	-0.4102D-02	0.3604D-04	0.2383D+01	-0.7178D+01	0.2784D+05	0.2934D+04	-0.3460D-03	0.1216E-02
20	0.6336D-02	-0.4855D-01	-0.2951E-02	0.1600D-02	0.1206D+01	-0.7654D+01	0.2731D+05	0.2222D+04	0.1957D-02	0.5511D-03
21	0.0	-0.4811D+01	0.0	0.2507D-03	-0.3356D-16	-0.7748D+01			0.2074D-03	0.3080E-03

CYCLE- ELEMENT	50	SI	STA 1	SO	SI	STA 2	SO	SI	STA 3	SO
1	-0.83291991D-01	-0.87970637D-01	-0.85830577D-01	-0.85734344D-01	-0.84590237D-01	-0.79461692D-01				
	-0.85631374D-01	0.0	-0.85782461D-01	0.0	-0.82035965D-01	0.0				
2	-0.93041785D-01	-0.77435964D-01	-0.82810621D-01	-0.70550330D-01	-0.81179949D-01	-0.62141374D-01				
	-0.80238875D-01	0.0	-0.76680475D-01	0.0	-0.71660661E-01	0.0				
3	-0.78506223D-01	-0.60196326D-01	-0.74335340D-01	-0.51566032D-01	-0.68595544D-01	-0.41240623D-01				
	-0.69351275D-01	0.0	-0.62950686D-01	0.0	-0.54918083D-01	0.0				
4	-0.66490656D-01	-0.35517774D-01	-0.66169285D-01	-0.31487768D-01	-0.67264975D-01	-0.28945797D-01				
	-0.51004215D-01	0.0	-0.48828527D-01	0.0	-0.48105386D-01	0.0				
5	-0.61576713D-01	-0.30904427D-01	-0.44924192D-01	-0.28737530D-01	-0.29799028D-01	-0.27898915D-01				
	-0.46240570E-01	0.0	-0.36830861D-01	0.0	-0.28848971D-01	0.0				
6	-0.13157225D-01	-0.50799825E-01	-0.71670883D-01	-0.13198430D+00	-0.11460213D+00	-0.23294953D+00				
	-0.14821300D-01	0.0	-0.30156707D-01	0.0	-0.59173699D-01	0.0				
7	-0.91399411D-01	-0.15532835D+00	-0.49453791D-01	-0.10169252D+00	-0.12489607D-01	-0.42208741D-01				
	-0.31964470E-01	0.0	-0.26119412D-01	0.0	-0.14859567E-01	0.0				
8	-0.34268034D-01	-0.38452217D-01	-0.84709582D-01	-0.53078028D-01	-0.12293320D+00	-0.77845219D-01				
	-0.92091459E-04	0.0	-0.15815777D-01	0.0	-0.22543993D-01	0.0				
9	-0.13512464D+00	-0.10689984D+00	-0.85014653D-01	-0.65636741D-01	-0.27903432D-01	-0.29758178D-01				
	-0.14112400D-01	0.0	-0.96889563D-02	0.0	-0.92737285D-03	0.0				
10	-0.15066162D-01	-0.15897973D-01	-0.72195090D-02	-0.95255401D-02	-0.81787331D-03	-0.17562495D-02				
	-0.41590572E-03	0.0	-0.11530155D-02	0.0	-0.46918807E-03	0.0				
11	-0.10966425D-02	-0.31841272D-04	-0.36149878D-02	-0.20972504D-02	-0.65016874D-02	-0.38430143D-02				
	-0.55924188D-03	0.0	-0.75886868D-03	0.0	-0.13293366E-02	0.0				
12	-0.76610386D-02	-0.36791994D-02	-0.91580847D-02	-0.46807603D-02	-0.10824265D-01	-0.55596067D-02				
	-0.19909196D-02	0.0	-0.22386622D-02	0.0	-0.26323290D-02	0.0				
13	-0.10440051D-01	-0.46116666D-02	-0.85924139D-02	-0.35117802D-02	-0.70293909E-02	-0.21742353E-02				
	-0.23141924D-02	0.0	-0.25403169D-02	0.0	-0.24275778D-02	0.0				
14	-0.61723653D-02	-0.12587251D-02	-0.45800285D-02	-0.21317010D-03	-0.30241787D-02	-0.15991953D-02				
	-0.24068201D-02	0.0	-0.23965993D-02	0.0	-0.23116870D-02	0.0				
15	-0.20911799D-02	-0.26879195D-02	-0.11924132D-02	-0.36488676D-02	-0.26817962D-03	-0.45912532E-02				
	-0.23895497D-02	0.0	-0.24206404D-02	0.0	-0.24297164D-02	0.0				
16	-0.17407338D-04	-0.49917262D-02	-0.62129765D-03	-0.43900728D-02	-0.13911927D-02	-0.39768760D-02				
	-0.25045666D-02	0.0	-0.25056852D-02	0.0	-0.26840354D-02	0.0				
17	-0.2380177D-02	-0.28341187D-02	-0.37790999D-02	-0.16358643D-02	-0.52896639D-02	-0.50439560E-03				
	-0.25860682D-02	0.0	-0.27074821D-02	0.0	-0.28970298D-02	0.0				
18	-0.54547409D-02	-0.45920320D-03	-0.44939716D-02	-0.13306900D-02	-0.35915129D-02	-0.22496791D-02				
	-0.29569720D-02	0.0	-0.29123308D-02	0.0	-0.29205960D-02	0.0				
19	-0.30552990D-02	-0.27087131D-02	-0.26440216D-02	-0.28442711D-02	-0.25485475D-02	-0.33123785D-02				
	-0.28820060D-02	0.0	-0.27441463D-02	0.0	-0.29304630E-02	0.0				
20	-0.27838262D-02	-0.33719203D-02	-0.33991082D-02	-0.26007021D-02	-0.38531400D-02	-0.16562929D-02				
	-0.30778733D-02	0.0	-0.29999051D-02	0.0	-0.27547164D-02	0.0				

CYCLE=	50				
STRAIN AT ADDITIONAL POINTS	SI	SO	SI	SO	
1	0.34900492D-02	0.24397740D-02	0.34839801D-02	0.24368050D-02	
	0.29649116D-02	0.0			

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J= 50 TIME (SEC.) = 0.200000D-03  
 WORK INPUT INTO RING (IN.-LB.) = 0.306676D+06  
 RING KINETIC ENERGY (IN.-LB.) = 0.138058D+06  
 RING ELASTIC ENERGY (IN.-LB.) = 0.306025E+04  
 RING PLASTIC WORK (IN.-LB.) = 0.165558D+06

I	V	U	PSI	CHI	COPY	COPZ	L	N	STRAIN (IN)	STRAIN (OUT)
1	0.0	-0.1234D+01	0.0	-0.8709D-01	0.0	0.6466D+01	0.9157D+05	0.9461D+04	-0.8255D-01	-0.8556D-01
2	0.8586D-01	-0.1223D+01	-0.4904D-03	-0.8556D-01	0.1098D+01	0.6384D+01	0.8969D+05	0.1384D+05	-0.8255D-01	-0.7997D-01
3	0.1770D+00	-0.1220D+01	-0.3767D-01	-0.7902D-01	0.2171D+01	0.6108D+01	0.8549D+05	0.1766D+05	-0.7757D-01	-0.6805E-01
4	0.2827D+00	-0.1268D+01	-0.1066D+00	-0.6738D-01	0.3172D+01	0.5602D+01	0.7951D+05	0.1237D+05	-0.6309D-01	-0.4844D-01
5	0.4025D+00	-0.1404D+01	-0.2114E+00	-0.8382D-01	0.4026D+01	0.4857D+01	0.5847D+05	-0.2744D+04	-0.6260D-01	-0.4403E-01
6	0.5502D+00	-0.1627D+01	-0.2605D+00	-0.6204D-01	0.4684D+01	0.3905D+01	0.5863D+05	-0.1356D+05	-0.2453D-01	-0.3111D-01
7	0.8097D+00	-0.1573D+01	-0.3588D+00	-0.1513D-01	0.5833D+01	0.2946D+01	-0.3939D+05	-0.2757D+05	0.9089D-01	-0.7526E-01
8	0.6966D+00	-0.6602D+00	0.8151D+00	-0.4440D+00	0.6585D+01	0.2575D+01	-0.2592D+05	0.1461D+05	-0.1531D-01	-0.7096D-02
9	0.3407D+00	-0.2603D+00	0.3968D+00	-0.1632D+00	0.7619D+01	0.2117D+01	-0.8935D+04	0.2298D+05	-0.1016D+00	-0.2031E-01
10	0.2113D+00	-0.3744D+00	-0.5734D-01	-0.1051D-01	0.8008D+01	0.1054D+01	0.2868D+05	0.1705D+05	-0.1290D-01	-0.3454D-02
11	0.1486D+00	-0.2912D+00	-0.1080D+00	-0.5414D-02	0.7991D+01	-0.1486D+00	0.5153D+05	0.3671D+04	0.5108D-03	-0.2019D-03
12	0.1076D+00	-0.1872D+00	-0.9076D-01	0.4377D-03	0.7773D+01	-0.1340D+01	0.6448D+05	-0.3588D+04	0.5951D-02	-0.3735D-03
13	0.8823D-01	0.1159D+00	-0.4088D-01	0.5894D-02	0.7406D+01	-0.2499D+01	0.6775D+05	-0.3904D+04	0.9171D-02	0.9084D-03
14	0.7852D-01	0.9430D-01	-0.1224E-01	0.4401E-02	0.6909D+01	-0.3609D+01	0.6954D+05	0.2730D+04	0.5521D-02	0.1379D-02
15	0.6752D-01	0.1013D+00	0.9865D-03	0.2376D-02	0.6272D+01	-0.4640D+01	0.7023D+05	0.9399D+04	0.2412D-02	0.2283D-02
16	0.5302D-01	0.1090D+00	-0.6447D-02	0.1174D-02	0.5484D+01	-0.5559D+01	0.7270D+05	0.1092D+05	0.5582D-03	0.3107D-02
17	0.3820D-01	0.1005D+00	-0.1786D-01	0.2056E-02	0.4554D+01	-0.6333D+01	0.7856D+05	0.5783D+04	0.1999D-02	0.2876D-02
18	0.2742D-01	0.8582D-01	-0.1138D-01	0.4312D-02	0.3510D+01	-0.6950D+01	0.8450D+05	0.5391D+04	0.5079D-02	0.2307D-02
19	0.1877D-01	0.8292D-01	-0.1805D-02	0.3108D-02	0.2387D+01	-0.7408D+01	0.8833D+05	0.9545D+04	0.3197D-02	0.2868D-02
20	0.9065D-02	0.8299D-01	-0.2424E-02	0.2800D-02	0.1209D+01	-0.7689D+01	0.9079D+05	0.8739D+04	0.2687D-02	0.3167E-02
21	0.0	0.8113D-01	0.0	0.3313D-02	-0.5660D-16	-0.7781D+01			0.3645D-02	0.2342D-02

REACTIONS AT NODE	RV (LBS)	RW (LBS)	RN (IN.-LBS)
1	-0.797149D+05	0.0	0.587083D+04
21	0.916714E+05	0.0	-0.870350D+04

SUBSTRUCTURE	RSTR	ELN	SURF	STA	TIME
1	0.114602D+00	6	1	3	0.200000D-03
INTERFACE	0.981461D-02	8	1	1	0.800000D-05
SUBSTRUCTURE	LARGEST ADD. PT. STRAIN	ELN	ADD. PT.	TIME	SURFACE
1	0.417591D-02	20	1	0.180000D-03	1
INTERFACE	0.296491D-02	20	1	0.200000D-03	1
SUBSTRUCTURE	LARGEST NODAL STRAIN	NODE	SURF	TIME	
1	0.908899D-01	7	1	0.200000D-03	

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CYCLE= 140		SI STA 1 SO		SI STA 2 SO		SI STA 3 SO	
ELEMENT							
1	-0.12810922D+00	-0.40886195D-01	-0.11921994D+00	-0.50313177D-01	-0.10548300D+00	-0.54564315D-01	
	-0.84497705D-01	0.0	-0.84766559D-01	0.0	-0.80023657D-01	0.0	
2	-0.95530795D-01	-0.69543325D-01	-0.92407727D-01	-0.66199999D-01	-0.87588612D-01	-0.60999248D-01	
	-0.92537060D-01	0.0	-0.79303863D-01	0.0	-0.74293930D-01	0.0	
3	-0.83327493D-01	-0.60415455D-01	-0.73549910D-01	-0.58993405D-01	-0.60254610D-01	-0.53599282D-01	
	-0.71871474D-01	0.0	-0.66271658D-01	0.0	-0.56926946D-01	0.0	
4	-0.43418638D-01	-0.56927603D-01	-0.34314784D-01	-0.62789168D-01	-0.18494308D-01	-0.67602022D-01	
	-0.53173121D-01	0.0	-0.48561976D-01	0.0	-0.43048163D-01	0.0	
5	-0.10707260D-01	-0.68535550D-01	-0.47198656D-02	-0.62951683D-01	0.17895469D-02	-0.57293454D-01	
	-0.39621405D-01	0.0	-0.33835774D-01	0.0	-0.27751953D-01	0.0	
6	0.34511952D-01	-0.69502215D-01	0.73218961D-01	-0.13526797D+00	0.86537485D-01	-0.22254188D+00	
	-0.17495131D-01	0.0	-0.31024506D-01	0.0	-0.63002195D-01	0.0	
7	0.10027262D+00	-0.18912806D+00	0.45770085D-01	-0.89859198D-01	-0.10837998D-01	0.18466533D-02	
	-0.44550219D-01	0.0	-0.22044557D-01	0.0	-0.46956726D-02	0.0	
8	-0.45396489D-03	-0.92184587D-02	-0.60304522D-01	0.93965761D-02	-0.10222075D+00	0.52675970D-01	
	-0.48362118D-02	0.0	-0.25453973D-01	0.0	-0.24772388D-01	0.0	
9	-0.12140667D+00	0.12058654D+00	-0.92534251D-01	0.73840707D-01	-0.42740408D-01	0.43529141D-01	
	-0.41006134D-03	0.0	-0.93467721D-02	0.0	0.39436676D-03	0.0	
10	-0.39117256D-01	0.40143279D-01	-0.38098152D-01	0.36072446D-01	-0.36846733D-01	0.32060454D-01	
	0.51301153D-03	0.0	-0.10128531D-02	0.0	-0.23931399D-02	0.0	
11	-0.41347296D-01	0.43614099D-01	-0.31804880D-01	0.28617404D-01	-0.19339262D-01	0.16765285D-01	
	0.11334018D-02	0.0	-0.15937379D-02	0.0	-0.12869883D-02	0.0	
12	-0.14950109D-01	0.13780718D-01	-0.96915753D-02	0.89298830D-02	-0.37466583D-02	0.49621693D-02	
	-0.58479572D-03	0.0	-0.38084615D-03	0.0	0.60775553D-03	0.0	
13	-0.11085383D-02	0.30501530D-02	0.46724469D-03	0.41068368D-03	0.12639242D-02	-0.29926296D-02	
	0.97080736D-03	0.0	0.43896818D-03	0.0	-0.86435274D-03	0.0	
14	0.20658992D-02	-0.37086407D-02	0.51868641D-02	-0.48292825D-02	0.86903433D-02	-0.55405985D-02	
	-0.82137072D-03	0.0	0.17879080D-03	0.0	0.15748724D-02	0.0	
15	0.10161123D-01	-0.68550918D-02	0.10042931D-01	-0.77766497D-02	0.99999110D-02	-0.87008306D-02	
	0.16530156D-02	0.0	0.11331406D-02	0.0	0.64954021D-03	0.0	
16	0.97354994D-02	-0.94250429D-02	0.96584395D-02	-0.11276920D-01	0.10751532D-01	-0.11998136D-01	
	0.15522828D-03	0.0	-0.80924027D-03	0.0	-0.62330159D-03	0.0	
17	0.11774580D-01	-0.12999888D-01	0.92785103D-02	-0.10803034D-01	0.75511482D-02	-0.85349755D-02	
	-0.71121476D-03	0.0	-0.76226197D-03	0.0	-0.49191364D-03	0.0	
18	0.58787671D-02	-0.64332090D-02	0.35592468D-02	-0.41599223D-02	0.14720277D-02	-0.16687344D-02	
	-0.27721997D-03	0.0	-0.30033775D-03	0.0	-0.98353319D-04	0.0	
19	0.19496624D-03	-0.98115850D-03	-0.16598408D-02	0.99790258D-03	-0.37373222D-03	0.29702744D-02	
	-0.29309613D-03	0.0	-0.33096811D-03	0.0	-0.38372899D-03	0.0	
20	-0.45844876D-02	0.36372301D-02	-0.50300274D-02	0.31713611D-02	-0.55267752D-02	0.26779461D-02	
	-0.47362874D-03	0.0	-0.92933313D-03	0.0	-0.14244146D-02	0.0	

CYCLE= 140		SI		SO		EI		EO	
STRAIN AT ADDITIONAL POINTS									
1		-0.51160675D-02	0.30841715D-02	-0.51292220D-02	0.30794301D-02				
		-0.10159480D-02	0.0						

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J= 140 TIME (SEC.) = 0.560000D-03  
WORK INPUT INTO RING (IN.-LB.) = 0.306676D+06  
RING KINETIC ENERGY (IN.-LB.) = 0.119210E+06  
RING ELASTIC ENERGY (IN.-LB.) = 0.390173D+04  
RING PLASTIC WORK (IN.-LB.) = 0.183565D+06

I	V	W	PSI	CHI	COPY	COPZ	L	N	STRAIN (IN)	STRAIN (OUT)
1	0.0	-0.2848D+01	0.0	-0.1123E+00	0.0	0.4852D+01	-0.1780D+05	0.1262D+05	-0.1176D+00	-0.7127D-01
2	0.3136D+00	-0.2964D+01	-0.2086D+00	-0.1184D+00	0.1051D+01	0.4629D+01	-0.9509D+04	0.8504D+04	-0.9412D-01	-0.7619D-01
3	0.6461D+00	-0.3189D+01	-0.2880D+00	-0.1290D+00	0.2009D+01	0.4091D+01	-0.1364D+05	-0.6997D+04	-0.8244D-01	-0.6940D-01
4	0.1013D+01	-0.3441D+01	-0.3324D+00	-0.1166D+00	0.2837D+01	0.3335D+01	-0.5376D+04	-0.1609D+05	-0.5474D-01	-0.5397D-01
5	0.1495D+01	-0.3614D+01	-0.2466E+00	-0.5892D-01	0.3582D+01	0.2448D+01	-0.5336D+04	-0.1802D+05	-0.1972D-01	-0.4794D-01
6	0.1984D+01	-0.3537D+01	-0.7016D-01	-0.1363D-01	0.4346D+01	0.1541D+01	-0.5954D+05	-0.4990D+04	-0.2689D-02	-0.3623D-01
7	0.2484D+01	-0.2968D+01	0.5654D+00	-0.1362D+00	0.5288D+01	0.7719D+00	0.7480D+05	0.6308D+04	0.7590D-01	-0.9593D-01
8	0.2110D+01	-0.1534D+01	0.9802E+00	-0.1189D+01	0.6452D+01	0.9195E+00	-0.3158D+06	-0.3014D+05	-0.3257D-02	0.2727D-02
9	0.1178D+01	-0.1659D+00	0.7638D+00	-0.4284D+00	0.7529D+01	0.1207D+01	-0.7785D+05	0.1309D+05	-0.7270D-01	0.3833D-01
10	0.9131D+00	0.5545D+00	0.2645D+00	-0.5549E-01	0.8296D+01	0.3894D+00	-0.1264D+05	0.1869D+05	-0.2790D-01	0.7811D-02
11	0.7574D+00	0.8661E+00	0.4037D-01	-0.2083E-01	0.8566D+01	-0.7574D+00	-0.8017D+04	0.1658D+05	-0.2977D-01	0.1010D-01
12	0.5923D+00	0.8911D+00	-0.1425D+00	-0.1873D-01	0.8393D+01	-0.1929D+01	-0.1430D+04	0.1323D+05	-0.1220D-01	0.2997D-02
13	0.4363D+00	0.7572D+00	-0.1990D+00	-0.2041D-01	0.7908D+01	-0.3028D+01	0.4979D+03	0.8959D+04	-0.1109D-02	0.1703D-02
14	0.3072D+00	0.5713D+00	-0.1988D+00	-0.1994D-01	0.7230D+01	-0.4029D+01	0.1312D+04	0.2232D+04	0.6525D-03	-0.1850D-02
15	0.2144D+00	0.3862D+00	-0.1686D+00	-0.8248D-02	0.6416D+01	-0.4926D+01	0.1342D+04	-0.6890D+04	0.8011D-02	-0.5169D-04
16	0.1601D+00	0.2433D+00	-0.1146E+00	-0.1296D-02	0.5504D+01	-0.5730D+01	-0.4708D+03	-0.1382D+05	0.7626D-02	-0.1779E-02
17	0.1103D+00	0.1641D+00	-0.5129D-01	0.4186D-02	0.4517D+01	-0.6439D+01	0.1382D+04	-0.1352D+05	0.8552D-02	-0.3616E-02
18	0.1105D+00	0.1610D+00	-0.9516D-02	0.3207D-02	0.3470D+01	-0.7054D+01	-0.7761D+03	-0.8170D+04	0.5045D-02	-0.2103D-02
19	0.8371D-01	0.2056D+00	0.3287D-01	-0.1497D-03	0.2363D+01	-0.7505D+01	-0.8954D+03	0.2999D+04	0.6629D-03	-0.4266D-03
20	0.4559D-03	0.2540D+00	0.2482E-01	-0.2718D-02	0.1199D+01	-0.7863D+01	-0.4075D+04	0.9026D+04	-0.3414D-02	0.6162D-03
21	0.0	0.2726D+00	0.0	-0.3635D-02	-0.1902D-15	-0.7973D+01			-0.4654D-02	-0.5493D-03

REACTIONS AT NODE		RV (LBS)		RW (LBS)		RH (IN.-LBS)	
1		0.166511E+05	0.0	0.141255D+05			
21		-0.389145E+04	0.0	-0.101930D+05			
SUBSTRUCTURE		MSR	ELR	SURF	STA	TIME	
1		0.120587D+00	9	2	1	0.560000D-03	
INTERFACE		0.981461D-02	8	1	1	0.800000D-05	
SUBSTRUCTURE		LARGEST	ADD. PT.	STRAIN	ELEM	ADD. PT.	TIME
1		0.489302D-02		20	1	0.384000D-03	
INTERFACE		0.296491D-02		20	1	0.200000D-03	
SUBSTRUCTURE		LARGEST	NODAL	STRAIN	MODE	SURF	TIME
1		0.980506D-01		7	1	0.556000D-03	



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CYCL= 150
ELEMENT  SI STA 1 SC SI STA 2 SO SI STA 3 SO
1 -0.13102706D+00 -0.38707042D-01 -0.12075693D+00 -0.48598696D-01 -0.10610727D+00 -0.53811807D-01
2 -0.84867054E-01 0.0 -0.84677815D-01 0.0 -0.79959580D-01 0.0
3 -0.8279089E-01 0.0 -0.91602712D-01 -0.66943883D-01 -0.66393428D-01 -0.62316200D-01
4 -0.82361202D-01 -0.61254137D-01 -0.79273302D-01 0.0 -0.74354818E-01 0.0
5 -0.71807670E-01 0.0 -0.72444246D-01 -0.59993480D-01 -0.58730005E-01 -0.54460354D-01
6 -0.48473417D-01 -0.56825030D-01 -0.66218863D-01 0.0 -0.56595180D-01 0.0
7 -0.52649224E-01 0.0 -0.34264972D-01 -0.63075427D-01 -0.18516572D-01 -0.67464132D-01
8 -0.10394109D-01 -0.69563802D-01 -0.48670199D-01 0.0 -0.42990352D-01 0.0
9 -0.39978956D-01 0.0 -0.46836786D-02 -0.64196775D-01 -0.21775549D-02 -0.58109173D-01
10 -0.34911294D-01 -0.69841287D-01 -0.34440227D-01 0.0 -0.27965809D-01 0.0
11 -0.17444966E-01 0.0 -0.73277954D-01 -0.13589424D+00 -0.56996954D-01 -0.22276553D+00
12 -0.10184363D+00 -0.19716494D+00 -0.31308144D-01 0.0 -0.62884288D-01 0.0
13 -0.47660693D-01 0.0 -0.42015706D-01 -0.86095048D-01 -0.18009495D-01 -0.19149860E-01
14 -0.10126008D-01 -0.17403924D-01 -0.22039671D-01 0.0 -0.57018264D-03 0.0
15 -0.36389580D-02 0.0 -0.49084704D-01 -0.56453848D-02 -0.98389528D-01 -0.46704163D-01
16 -0.12191013D+00 -0.12390818E+00 -0.21719660D-01 0.0 -0.25842682D-01 0.0
17 -0.97902672D-03 0.0 -0.93376377D-01 -0.74271867D-01 -0.41768435D-01 -0.42743934D-01
18 -0.39722794D-01 -0.37898308D-01 -0.95522550D-02 0.0 -0.48774964E-03 0.0
19 -0.58775494D-03 0.0 -0.37606678D-01 -0.35852999D-01 -0.36300274D-01 -0.31812443D-01
20 -0.41216966D-01 -0.44537314D-01 -0.87639588D-03 0.0 -0.22439154E-02 0.0
21 -0.16602238D-02 0.0 -0.32818617D-01 -0.30810298D-01 -0.22039434D-01 -0.19594035D-01
22 -0.18559027D-01 -0.18500237D-01 -0.10041594D-02 0.0 -0.12226995D-02 0.0
23 -0.79350240D-04 0.0 -0.12787947D-01 -0.13490163D-01 -0.66541102D-02 -0.89243258D-02
24 -0.34936586D-02 -0.57170727D-02 -0.35110805D-03 0.0 -0.11351078E-02 0.0
25 -0.11117021D-02 0.0 -0.88667622D-03 -0.26416110D-02 -0.90870833D-03 -0.11965625D-02
26 -0.21954404D-02 0.0 -0.87746740D-03 0.0 -0.14392707D-03 0.0
27 -0.14913010D-03 0.0 -0.55898889D-02 -0.38733925D-02 -0.94582236D-02 -0.47334575D-02
28 -0.11069724D-01 -0.60246852D-02 0.85824821D-03 0.0 -0.23623630D-02 0.0
29 -0.25216692D-02 0.0 -0.10897531D-01 -0.66839348D-02 -0.10734334D-01 -0.74177704E-02
30 -0.11184040D-01 -0.83589869E-02 0.21067981D-02 0.0 -0.16582818D-02 0.0
31 -0.14125263D-02 0.0 -0.13120137D-01 -0.10738437D-01 -0.15965772D-01 -0.12265604D-01
32 -0.16546494D-01 -0.13398063D-01 0.11908496E-02 0.0 -0.18500841D-02 0.0
33 -0.15743927D-02 0.0 -0.13134676D-01 -0.10103874D-01 -0.95497951D-02 -0.71267550E-02
34 -0.59029728D-02 -0.43851167D-02 0.15154012D-02 0.0 -0.12115201D-02 0.0
35 -0.12589280E-02 0.0 -0.42684777D-02 -0.20560788D-02 -0.19635659D-02 -0.59986537D-03
36 -0.11630419D-02 0.0 -0.11061995D-02 0.0 -0.12817156D-02 0.0
37 -0.10315535D-02 0.0 -0.20405386D-03 -0.23054187D-02 -0.16182621E-02 -0.36686571E-02
38 -0.23721132D-02 0.0 -0.10506824D-02 0.0 -0.10251975D-02 0.0
39 -0.99282462D-03 0.0 -0.29383928D-02 -0.42673224D-02 -0.34126239D-02 -0.42975344D-02
40 -0.99282462D-03 0.0 -0.66446480D-03 0.0 -0.44285526D-03 0.0

```

```

CYCLE= 150
STRAIN AT ADDITIONAL POINTS
1 SI SO EI FO
-0.30303549D-02 0.42644153D-02 -0.30349604D-02 0.42553613D-02
0.61703023D-03 0.0

```

```

J= 150 TIME (SEC.) = 0.600000D-03
WORK INPUT INTO RING (IN.-LB.) = 0.306676D+06
RING KINETIC ENERGY (IN.-LB.) = 0.117574D+06
RING ELASTIC ENERGY (IN.-LB.) = 0.407289E+04
RING PLASTIC WORK (IN.-LB.) = 0.185030D+06

```

```

892 I V W PSI CHI COPY COPZ L M STRAIN (IN) STRAIN (OUT)
1 0.0 -0.30640D+01 0.0 -0.11440D+00 0.0 0.46360D+01 -0.1285D+05 0.14060D+05 -0.1202D+00 -0.7105D-01
2 0.34540D+00 -0.3185D+01 -0.21840D+00 -0.12120D+00 0.10470D+01 0.4405D+01 -0.8125D+04 -0.7112D+04 -0.9448D-01 -0.7642D-01
3 0.71070D+00 -0.34120D+01 -0.29310D+00 -0.13010D+00 0.20010D+01 0.38580D+01 -0.1211D+05 -0.8880D+04 -0.8162D-01 -0.6971E-01
4 0.11130D+01 -0.36540D+01 -0.33120D+00 -0.11490D+00 0.28280D+01 0.31000D+01 -0.6428D+04 -0.1587D+05 -0.5342D-01 -0.5351E-01
5 0.15910D+01 -0.38070D+01 -0.24430D+00 -0.5815D-01 0.35750D+01 0.22140D+01 -0.7967D+04 -0.1749D+05 -0.1949D-01 -0.4796D-01
6 0.21440D+01 -0.37010D+01 -0.64020D-01 -0.1289E-01 0.43840D+01 0.1311D+01 -0.5131D+05 -0.6476D+04 -0.2253D-02 -0.3628D-01
7 0.26660D+01 -0.3096D+00 0.57360D+00 -0.1408D+00 0.5292D+01 0.5490D+00 0.9168D+05 0.9169D+04 0.7760D-01 -0.9813E-01
8 0.22640D+01 -0.1625D+01 0.9658E+00 -0.1259D+01 0.6441D+01 0.7405D+00 -0.3132D+06 -0.3054D+05 -0.2326D-02 0.6236E-02
9 0.12630D+01 -0.2259D+00 0.79350D+00 -0.4650D+00 0.7488D+01 0.1109D+01 -0.8049D+05 0.1358D+05 -0.6965D-01 0.4049E-01
10 0.9830D+00 0.5379D+00 0.2907D+00 -0.6299E-01 0.8290D+01 0.3178D+00 -0.8690D+04 0.1339D+05 -0.2747D-01 0.7396D-02
11 0.82130D+00 0.8929D+00 0.6872D-01 -0.2206D-01 0.8593D+01 -0.8213D+00 -0.1605D+04 0.1608D+05 -0.2938D-01 0.1030D-01
12 0.6498D+00 0.9578D+00 0.1238D+00 -0.1797D-01 0.8450D+01 -0.1996D+01 0.2568D+04 0.1597D+05 -0.1488D-01 0.4029E-02
13 0.4813D+00 0.8401D+00 -0.2034D+00 -0.2267D-01 0.7973D+01 -0.3097D+01 0.5599D+04 0.1013D+05 -0.3188D-02 0.2655E-02
14 0.3362D+00 0.6470D+00 -0.2181D+00 -0.2278D-01 0.7285D+01 -0.4089D+01 0.2103D+05 0.4738D+04 0.8365D-03 -0.9156D-03
15 0.2295D+00 0.4454D+00 -0.1855D+00 -0.1040D-01 0.6455D+01 -0.4973D+01 0.2959D+05 -0.3835D+04 0.8902D-02 -0.7707D-03
16 0.1653D+00 0.2833D+00 -0.1323D+00 -0.2641E-02 0.5528D+01 -0.5762D+01 0.3397D+05 -0.9585D+04 0.8404D-02 -0.7542E-03
17 0.1323D+00 0.1866D+00 -0.6011D-01 0.7860D-02 0.4529D+01 -0.6458D+01 0.4090D+05 -0.8542D+04 0.1354D-01 -0.1822E-02
18 0.1127D+00 0.1810D+00 0.1028D-01 0.4561D-02 0.3477D+01 -0.7073D+01 0.3762D+05 -0.2570D+04 0.6344D-02 -0.5375E-03
19 0.8415D-01 0.2245D+00 0.2941E-01 0.8758D-03 0.2369D+01 -0.7563D+01 0.3919D+05 0.6865D+04 0.1370D-02 0.1125D-02
20 0.4531D-01 0.2679D+00 0.2181D-01 -0.7761D-03 0.1202D+01 -0.7877D+01 0.3718D+05 0.1126D+05 -0.1331D-02 0.1842E-02
21 0.0 0.2851D+00 0.0 -0.1572D-02 -0.1989D-15 -0.7995D+01 -0.2553D-02 -0.2553D-02 0.1378E-02

```

```

REACTIONS AT NODE RV (LBS) RW (LBS) RM (IN.-LBS)
1 0.150261D+05 0.0 0.152230D+05
0.369255D+05 0.0 -0.123557D+05

SUBSTRUCTURE NSTR ELE SURF STA TIME
1 0.123908D+00 9 2 1 0.600000D-03
INTERFACE 0.981461D-02 8 1 1 0.800000D-05

SUBSTRUCTURE LARGEST ADD. PT. STRAIN ELN ADD. PT. TIME SURFACE
1 0.488302D-02 20 1 0.384000D-03 1
INTERFACE 0.296491D-02 20 1 0.200000D-03 1

SUBSTRUCTURE LARGEST MODAL STRAIN NODE SURF TIME
1 0.100950E+00 7 1 0.596000D-03

```

THE LARGEST COMPUTED STRAINS FOR EACH SUBSTRUCTURE--

MAIN AND BRANCHES -- ARE PRINTED BELOW, 1= INNER 2= OUTER SURF

```

SUBSTRUCTURE NSTR ELE SURF STA TIME
1 0.123908D+00 9 2 1 0.600000D-03
INTERFACE 0.981461D-02 8 1 1 0.800000D-05

SUBSTRUCTURE LARGEST ADD. PT. STRAIN ELN ADD. PT. TIME SURFACE
1 0.488302D-02 20 1 0.384000D-03 1
INTERFACE 0.296491E-02 20 1 0.200000D-03 1

SUBSTRUCTURE LARGEST MODAL STRAIN NODE SURF TIME
1 0.100950D+00 7 1 0.596000D-03

```

THERE ARE NO CARDS PUNCHED FOR CONTINUATION

## 7.2 CIVM-JET 5B Example: A Fragment-Impacted, Elastic-Foundation-Supported, Variable-Thickness, Two-Layer, Partial Ring with One Support Branch

### 7.2.1 Problem Description

The geometry of the main structure, as shown in Fig. 12, is a partial ring composed of an initially-straight portion and a circular portion. The straight section is 10.0-in long, 1.5-in wide, and varies linearly in thickness from 0.3-in at its pinned end to 0.1-in where it joins the circular portion. The circular section has a 5.0-in mean radius, a 1.5-in width, a 0.1-in uniform thickness, and consists of a  $60^\circ$  arc. The partial ring is supported by a pinned joint at its left-hand end, a branch connected at the straight-circular junction, and an elastic foundation located as depicted in Fig. 12. This foundation consists of arbitrarily chosen normal  $k_N$  and tangential  $k_T$  stiffness equal to 1500 psi and 3000 psi, respectively.

The "main structure" of the partial ring is called substructure one (1) and is assumed to consist of two layers of material firmly attached to each other at the interface. The inner layer and the outer layer of the structure are equal thicknesses of aluminum and steel, respectively.

The main structure has a steel branch attached to its steel outer layer. The branch is 1.0-in wide, 2.23607-in long, and has a constant thickness of 0.4 in. The branch has a slope discontinuity between its two equal-length elements. The branch attaches to the steel outer surface of the main structure at the eleventh node of the ring and is clamped at its other end.

The aluminum material of the main structure's inner layer has a yield stress of 46,000 psi, an elastic modulus of  $10^7$  psi, and is represented by a two mechanical-sublayer model defined by the following stress-strain ( $\sigma$ ,  $\epsilon$ ) pairs:  $\sigma_1$ ,  $\epsilon_1$  = 46,000 psi, .0046 and  $\sigma_2$ ,  $\epsilon_2$  = 58,000 psi, 0.18000. The strain-rate constants were chosen to be  $D = 6500 \text{ sec}^{-1}$  and  $p = 4$ . The mass density is  $0.250 \times 10^{-3} \text{ (lb-sec}^2\text{)/in}^4$ . The steel material used in the main structure's outer layer and in the branch has an elastic modulus of  $29 \times 10^6$  psi, a yield stress of 80,950 psi, and is represented by a three-mechanical-sublayer model defined by  $\sigma_1$ ,  $\epsilon_1$  = 80,950 psi, .00279;  $\sigma_2$ ,  $\epsilon_2$  = 105,300 psi, .02250, and  $\sigma_3$ ,  $\epsilon_3$  = 121,000 psi, .20000. The strain rate constants for the steel are assumed to be  $D = 40.4 \text{ sec}^{-1}$  and  $p = 5$ , with a mass density of  $.733085 \times 10^{-3} \text{ (lb-sec}^2\text{)/in}^4$ .

The variable-thickness straight portion of the structure is modeled by 10 equal-length finite elements; 6 equal-arc finite elements represent the constant thickness curved section; and 2 equal-length elements represent the constant thickness branch. This makes a total of 18 finite elements used for the entire structure.

The elements of the main structure are initially numbered consecutively from 1 to 16, and the branch elements are initially numbered from 1 to 2; this is depicted in Fig. 12b. The program will then renumber the elements from left to right to include the branch elements in the global system; the resulting renumbering is shown in Fig. 12c.

The attacking fragment has the following parameters (see Fig. 12a): radius  $r_f = 0.5$  in, mass  $m_f = .385610 \times 10^{-3}$  (lb-sec<sup>2</sup>/in); mass moment of inertia  $I_f = 0.482014 \times 10^{-4}$  (lb-sec<sup>2</sup>-in); initial translational velocity components:  $\dot{Y}_f = 2607.96$  in/sec,  $\dot{Z}_f = 1482.75$  in/sec; initial rotational velocity  $\dot{\theta}_f = 0.0$ ; initial C.G. position  $Y_{CG} = 6.0$  in,  $Z_{CG} = -2.0$  in. The value of the coefficient of restitution,  $e$ , is set at 1.0 to represent a perfectly-elastic impact reaction, and the coefficient of friction is set to 0.0.

The strain is to be calculated at each of the three spanwise Gaussian stations and each node of the main structure and the branch. Also, 3 additional points at which strain predictions are desired are requested. Two of these are on main structural elements 9 and 11; the point on element 9 is located near the point of first impact and the point on element 11 is located near the branch connection ( $\bar{s}$  coordinates 0.53 and 0.05, respectively). The additional strain point on the branch is located at  $\bar{s} = 0.50$  of the first element; this corresponds to the same location as the second Gaussian station on this element. The strains should be exactly the same at this point since both the Gaussian station and the additional point are at the same physical location.

The CIVM-JET 5B program will be used to calculate the structural response of the ring and the motion of the fragment, using a time step of 2 microseconds. Printout of structural responses and fragment position data are desired at intervals of every 20 time steps (or cycles) until 300 cycles have been completed.

### 7.2.2 Input Data

The values to be punched on the data cards are as follows:

Card 1	10I5
IK = 16	
ICP = 0	
NLAY = 2	
LREF = 1	
NOGA = 3	
NFL = 4	
MM = 790	
M1 = 490	
M2 = 20	
ICON = 0	
Card 2	2I5
NSFL(1,1) = 2	
NSFL(2,1) = 3	
Card 3A	3D15.6
DENS(1,1) = 0.250000D-03	
DS(1,1) = 0.650000D+04	
P(1,1) = 0.400000D+01	
Card 4AA	4D15.6
EPS(1,1,1) = 0.460000D-02	
SIG(1,1,1) = 0.460000D+05	
EPS(1,2,1) = 0.180000D+00	
SIG(1,2,1) = 0.580000D+05	
Card 3B	3D15.6
DENS(2,1) = 0.733085D-03	
DS(2,1) = 0.404000D+02	
P(2,1) = 0.500000D+01	
Card 4BA	4D15.6
EPS(2,1,1) = 0.279000D-02	

SIG(2,1,1) = 0.809500D+05

EPS(2,2,1) = 0.225000D-01

SIG(2,2,1) = 0.105300D+06

Card 4BB

2D15.6

EPS(2,3,1) = 0.200000D+00

SIG(2,3,1) = 0.121000D+06

Card 5

2D15.6

B(1) = 0.150000D+01

DELTAT = 0.200000D-05

Card 6A

3D15.6

Y(1) = 0.0

Z(1) = 0.0

ANG(1) = 0.0

.

.

.

Additional cards are punched in the same format until all 17 nodes of the main structure are described.

Y(17) = 0.143301D+02

Z(17) = 0.250000D+01

ANG(17) = 0.600000D+02

Card 7A

5D15.6

H(1,1) = 0.150000D+00

H(1,2) = 0.150000D+00

H(2,1) = 0.140000D+00

H(2,2) = 0.140000D+00

H(3,1) = 0.130000D+00

.

.

.

Additional cards are punched until all the nodal thicknesses for each layer are described, with five data entries per card.

.

.

.

H(16,1) = 0.050000D+00

H(16,2) = 0.050000D+00

H(17,1) = 0.050000D+00

H(17,2) = 0.050000D+00

Card 8A

I5

NDIS = 0

Card 9

NBR = 1

Card 9A

I5,4D15.6

NSFL(1,2) = 3

B(2) = 0.100000D+01

DENS(1,2) = 0.733085D-03

DS(1,2) = 0.404000D+02

P(1,2) = 0.500000D+01

Card 9AA

4D15.6

EPS(1,1,2) = 0.279000D-02

SIG(1,1,2) = 0.809500D+05

EPS(1,2,2) = 0.225000D-01

SIG(1,2,2) = 0.105300D+06

Card 9AB

2D15.6

EPS(1,3,2) = 0.200000D+00

SIG(1,3,2) = 0.121000D+06

Card 9B

4I5

NELT(1) = 2

NODP(1) = 11

LHIT(1) = 0

LATT(1) = 0

Card 9BA

4D15.6

YB(1,1) = 0.105000D+02

ZB(1,1) = 0.100000D+01

ANB(1,1) = 0.634349D+02

HB(1,1) = 0.400000D+00

Card 9BB

4D15.6

YB(1,2) = 0.115000D+02  
ZB(1,2) = 0.150000D+01  
ANB(1,2) = 0.265651D+02  
HB(1,2) = 0.400000D+00

Card 9BC

4D15.6

YB(1,2) = 0.100000D+02  
ZB(1,3) = 0.0  
ANB(1,3) = 0.634349D+02  
HB(1,3) = 0.400000D+00

NOTE: This is the attachment  
point information.

Card 9C

I5

NDISB = 1

Card 9CA

2I5,D15.6

NEDIB = 2  
NBDI = 1  
ANGB = 0.265651D+02

Card 9D

I5

NBCONB = 1

Card 9DA

3I5

NBCB(1) = 2  
NODBB(1) = 2  
LBR(1) = 1

Card 10

3I5

NOP = 3  
NASP = 3  
NTERF = 1

Card 10A

2I5,D15.6

NSBS(1) = 1  
NSEL(1) = 9  
AZET(1) = 0.530000D+00

Card 10B	2I5,D15.6
NSBS(2) = 2	
NSEL(2) = 1	
AZET(2) = 0.500000D+00	
Card 10C	2I5,D15.6
NSBS(3) = 1	
NSEL(3) = 1	
AZET(3) = 0.500000D-01	
Card 11	3D25.16
AXG(1) = 0.1127016653792585D+00	
AXG(2) = 0.5000000000000000D+00	
AXG(3) = 0.8872983346207415D+00	
Card 12	3D25.16
AWG(1) = 0.2777777777777778D+00	
AWG(2) = 0.4444444444444444D+00	
AWG(3) = 0.2777777777777778D+00	
Card 13A	3D25.16
TXG(1) = -0.861136311594053D+00	
TXG(2) = -0.3399810435848560D+00	
TXG(3) = 0.3399810435848560D+00	
Card 13B	D25.16
TXG(4) = 0.861136311594053D+00	
Card 14A	3D25.16
TWG(1) = 0.3478548451374540D+00	
TWG(2) = 0.6521451548625460D+00	
TWG(3) = 0.6521451548625460D+00	
Card 14B	D25.16
TWG(4) = 0.3478548451374540D+00	
Card 15	3I5
NBCOND = 1	



NBC(1) = 3  
NODEB(1) = 1

Card 16 3I5  
NQR = 2  
NORP = 0  
NORU = 2

Card 16B 3D15.6  
SCTU = 0.300000D+04  
SCTW = 0.0  
SCRU = 0.150000D+04

Card 16BB 4I5  
NRST(1) = 9  
NREU(1) = 2  
NRST(2) = 13  
NREU(2) = 3

Card 17 I5,D15.6  
NF = 1  
EFLN(1) = 0.0

Card 18AA 5D15.6  
FH(1) = 0.100000D+01  
FCG(1) = -0.200000D+01  
FCGX(1) = 0.600000D+01  
FMASS(1) = 0.385610D-03  
FMOI(1) = 0.482014D-04

Card 18AB D15.6  
UNK(1) = 0.0

Card 18AC 5D15.6  
UDOT(1) = 0.260796D+04  
WDOT(1) = 0.148275D+04  
ADOT(1) = 0.0  
TPRIM(1) = 0.960000D-03  
CR(1) = 0.100000D+01

Card 19

I5

ICONT = 0

This is the last data card for this CIVM-JET 5B run.

THIS IS THE INPUT DECK FOR EXAMPLE 7.2

16	0	2	1	3	4	790	490	20	0
2	3								
00.250000D-03	00.650000D+04	00.400000D+01							
00.460000D-02	00.460000D+05	00.180000D+00	00.580000D+05						
00.733085D-03	00.404000D+02	00.500000D+01							
00.279000D-02	00.809500D 05	00.225000D-01	00.105300D 05						
00.200000D 00	00.121000D 06								
00.150000D+01	00.200000D-05								
00.0	00.0	00.0	00.300000D+00						
00.100000D+01	00.0	00.0	00.280000D+00						
00.200000D+01	00.0	00.0	00.260000D+00						
00.300000D+01	00.0	00.0	00.240000D+00						
00.400000D+01	00.0	00.0	00.220000D+00						
00.500000D+01	00.0	00.0	00.200000D+00						
00.600000D+01	00.0	00.0	00.180000D+00						
00.700000D+01	00.0	00.0	00.160000D+00						
00.800000D+01	00.0	00.0	00.140000D+00						
00.900000D+01	00.0	00.0	00.120000D+00						
00.100000D+02	00.0	00.0	00.100000D+00						
00.108682D+02	-0.759612D-01	-0.100000D+02	00.100000D+00						
00.117101D+02	-0.301537D+00	-0.200000D+02	00.100000D+00						
00.125000D+02	-0.669873D+00	-0.300000D+02	00.100000D+00						
00.132139D+02	-0.116978D+01	-0.400000D+02	00.100000D+00						
00.138302D+02	-0.178606D+01	-0.500000D+02	00.100000D+00						
00.143301D+02	-0.250000D+01	-0.600000D+02	00.100000D+00						
00.150000D+00	00.150000D+00	00.140000D+00	00.140000D+00	00.130000D+00					
00.130000D+00	00.120000D+00	00.120000D+00	00.110000D+00	00.110000D+00					
00.100000D+00	00.100000D+00	00.090000D+00	00.090000D+00	00.080000D+00					
00.080000D+00	00.070000D+00	00.070000D+00	00.060000D+00	00.060000D+00					
00.050000D+00	00.050000D+00	00.050000D+00	00.050000D+00	00.050000D+00					
00.050000D+00	00.050000D+00	00.050000D+00	00.050000D+00	00.050000D+00					
00.050000D+00	00.050000D+00	00.050000D+00	00.050000D+00	00.050000D+00					
0									
1									
3	00.100000D+01	00.733085D-03	00.404000D+02	00.500000D+01					
	00.279000D-02	00.809500D 05	00.225000D-01	00.105300D 05					

00.2000000-00	00.1210000 06			
2 11 0	0			
00.1050000+02	00.1000000+01	00.6343490+02	00.4000000+00	
00.1150000+02	00.1500000+01	00.2656510+02	00.4000000+00	
00.1000000+02	00.0	00.6343490+02	00.4000000+00	
1				
2	1	00.2656510+02		
1				
2	2	1		
3	3	1		
1	9	00.5300000+00		
2	1	00.5000000+00		
1	11	00.5000000-01		
00.11270166537925850+00	00.5000000000000000+00	00.88729833462074150+00		
00.27777777777777780+00	00.44444444444444440+00	00.27777777777777780+00		
-0.86113631159405300+00	-0.33998104358485600+00	00.33998104358485600+00		
00.86113631159405300+00				
00.34785484513745400+00	00.65214515486254600+00	00.65214515486254600+00		
00.34785484513745400+00				
1 3 1				
2 0 2				
00.3000000+04	00.0	00.1500000+04		
9 2 13	3			
1 00.0				
00.1000000+01	-0.2000000+01	00.6000000+01	00.3856100-03	00.4820140-04
00.0				
00.2607960+04	00.1482750+04	00.0	00.9600000-03	00.1000000+01
0				

### 7.2.3 Solution Output Data for Example 2

The following is the output obtained as a result of a 600 microsecond CIVM-JET 5B analysis of this two layer partial ring example.

The numbering system for the nodes and elements is listed as well as an identification of the branch attachment point and the slopes at the branch connection and at the slope discontinuity. The partial ring initial geometry (for both layers), boundary conditions, and elastic foundations are defined as well as all the necessary data pertaining to the impacting fragment. A reference time step is computed and printed for a comparison against the user-designated time step of 2 microseconds in this case.

Each impact is recorded (there are 2 impacts during this run) and the essential data concerning element number, fragment number, time, location and post-impact fragment energies are output. For each printout cycle, an update of each nodal position, the fragment position, the strains at each Gaussian point and each addition strain point (inner and outer surfaces and interface) and at each node, and the reaction forces are given.

Initial impact occurs on element 9 at 967.796 microseconds after fragment release; this is computational time cycle 484. During this computer run the maximum strain reaches 3.36% on the main structure and only 2.73% on the branch.

Note that for conciseness only a portion of the requested output is presented here. Included are: all initial problem data, printout at time cycles 490, 510, 530, 550, 570, 590, ... skip to 770, 790 (last); a record of all impacts occurring up to time cycle 790 is retained.

THIS IS RUN NUMBER 1 FOR THIS CIVM-JET 5B SUBMITTAL

THERE ARE 18 ELEMENTS AND 19 NODES

THERE ARE 1 BRANCHES AND THEY ARE AT NODES 11

THE GLOBAL SLOPE(RAD) AT EACH BRANCH CONNECTION: 0.110715D+01

THE ATTACHMENT POINT CODE FOR THE 1 BRANCHES IS AS FOLLOWS:

0  
WHERE -1= INNER AND 0 = OUTER SURFACES. 1,2,3 INDICATE MIDSURFACE OF CORRESPONDING LAYER.

PRESENT ELEM. NO.	NODE1	NODE2	SUBSTRUCTURE	SUBST. ELEM. NO.
1	1	2	1	1
2	2	3	1	2
3	3	4	1	3
4	4	5	1	4
5	5	6	1	5
6	6	7	1	6
7	7	8	1	7
8	8	9	1	8
9	9	10	1	9
10	10	11	1	10
11	11	12	2	1
12	12	13	2	2
13	11	14	1	11
14	14	15	1	12
15	15	16	1	13
16	16	17	1	14
17	17	18	1	15
18	18	19	1	16

THE UPDATED NODE NUMBERS FOR THE MAIN STRUCTURE, GIVEN IN THEIR ORIGINAL NUMBERING ORDER:

1 2 3 4 5 6 7 8 9 10 11 14 15 16 17 18 19

NOTE: THE ELEMENT NUMBERS REFERRED TO BELOW ARE PRESENT ELEMENT NUMBERS

ELEMENTS THAT CAN NOT BE IMPACTED:

11	12	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0

ADDITIONAL STRAIN POINT	ELEMENT	S COORDINATE
1	9	0.530000D+00
2	11	0.500000D+00
3	13	0.500000D-01

EACH OF THE FOLLOWING ELEMENTS HAS A SLOPE DISCONTINUITY AT ITS FIRST NODE  
12

THE GLOBAL SLOPE (RAD.) AT EACH DISCONTINUITY EQUALS:  
0.463648D+00

\*\*\*\*\* A SPATIAL FINITE ELEMENT AND HOUBOLT TEMPORAL OPERATOR PROGRAM  
USED TO CALCULATE THE NONLINEAR RESPONSES OF A VARIABLE THICKNESS MULTILAYER  
ARBITRARILY CURVED PARTIAL RING WITH THE FOLLOWING PARAMETERS

ORIGINAL PAGE IS  
OF POOR QUALITY

PROPERTIES OF THE MAIN STRUCTURE:

WIDTH OF RING (IN) = 0.150000D+01  
 NUMBER OF ELEMENTS = 16  
 NUMBER OF SPANWISE GAUSSIAN POINTS = 3  
 NUMBER OF DEPTHWISE GAUSSIAN POINTS = 4  
 NUMBER OF LAYERS = 2  
 REFERENCE SURFACE IS THE MIDDLE SURFACE OF LAYER= 1

MATERIAL PROPERTIES OF LAYER = 1  
 DENSITY(LB-SEC\*\*2/IN\*\*4) = 0.250000D-03  
 NUMBER OF MECHANICAL SUBLAYERS = 2

	STRAIN	STRESS
1	0.460000D-02	0.460000D+05
2	0.180000D+00	0.580000D+05

MATERIAL IS STRAIN RATE SENSITIVE WITH  
 D = 0.650000D+04 P = 0.400000D+01

MATERIAL PROPERTIES OF LAYER = 2  
 DENSITY(LB-SEC\*\*2/IN\*\*4) = 0.733085D-03  
 NUMBER OF MECHANICAL SUBLAYERS = 3

	STRAIN	STRESS
1	0.279000D-02	0.809500D+05
2	0.225000D-01	0.105300D+06
3	0.200000D+00	0.121000D+06

MATERIAL IS STRAIN RATE SENSITIVE WITH  
 D = 0.404000D+02 P = 0.500000D+01

PROPERTIES OF BRANCH NUMBER 1 :

WIDTH OF RING (IN) = 0.100000D+01  
 NUMBER OF ELEMENTS = 2  
 NUMBER OF SPANWISE GAUSSIAN POINTS = 3  
 NUMBER OF DEPTHWISE GAUSSIAN POINTS = 4  
 NUMBER OF LAYERS = 1  
 REFERENCE SURFACE IS THE MIDDLE SURFACE OF LAYER= 1

MATERIAL PROPERTIES OF LAYER = 1  
 DENSITY(LB-SEC\*\*2/IN\*\*4) = 0.733085D-03  
 NUMBER OF MECHANICAL SUBLAYERS = 3

	STRAIN	STRESS
1	0.279000D-02	0.809500D+05
2	0.225000D-01	0.105300D+06
3	0.200000D+00	0.121000D+06

MATERIAL IS STRAIN RATE SENSITIVE WITH  
 D = 0.404000D+02 P = 0.500000D+01

HINGED DISPLACEMENT CONDITION AT NODE = 1  
 CLAMPED DISPLACEMENT CONDITION AT NODE = 13

CONSTRAINTS (ELASTIC FOUNDATION/SPRING) AS DESCRIBED BY INPUT

NODE NO	Y COORD(IN)	Z COORD(IN)	SLOPE ( RAD)	RING THICKNESS(IN)		
				LAYER 1	LAYER 2	LAYER 3
1	0.0	0.0	0.0	0.150000D+00	0.150000D+00	
2	0.100000D+01	0.0	0.0	0.140000D+00	0.140000D+00	
3	0.200000D+01	0.0	0.0	0.130000D+00	0.130000D+00	
4	0.300000D+01	0.0	0.0	0.120000D+00	0.120000D+00	
5	0.400000D+01	0.0	0.0	0.110000D+00	0.110000D+00	
6	0.500000D+01	0.0	0.0	0.100000D+00	0.100000D+00	
7	0.600000D+01	0.0	0.0	0.900000D-01	0.900000D-01	
8	0.700000D+01	0.0	0.0	0.800000D-01	0.800000D-01	
9	0.800000D+01	0.0	0.0	0.700000D-01	0.700000D-01	
10	0.900000D+01	0.0	0.0	0.600000D-01	0.600000D-01	
11	0.100000D+02	0.0	0.0	0.500000D-01	0.500000D-01	
12	0.105000D+02	0.100000D+01	0.110715D+01	0.400000D+00	0.0	
13	0.115000D+02	0.150000D+01	0.463648D+00	0.400000D+00	0.0	
14	0.108692D+02	-0.759612D-01	-0.174533D+00	0.500000D-01	0.500000D-01	
15	0.117101D+02	-0.301537D+00	-0.349066D+00	0.500000D-01	0.500000D-01	
16	0.125000D+02	-0.669873D+00	-0.523599D+00	0.500000D-01	0.500000D-01	
17	0.132139D+02	-0.116978D+01	-0.698132D+00	0.500000D-01	0.500000D-01	
18	0.138302D+02	-0.178606D+01	-0.872665D+00	0.500000D-01	0.500000D-01	
19	0.143301D+02	-0.250000D+01	-0.104720D+01	0.500000D-01	0.500000D-01	

## GAUSSIAN STATIONS AND HEIGHTS:

AKG 1 =	0.112701665379259	AWG 1 =	0.277777777777778
AKG 2 =	0.500000000000000	AWG 2 =	0.444444444444444
AKG 3 =	0.887298334620741	AWG 3 =	0.277777777777778
TXG 1 =	-0.861136311594053	TWG 1 =	0.347854845137454
TXG 2 =	-0.339981043584456	TWG 2 =	0.652145154862546
TXG 3 =	0.339981043584456	TWG 3 =	0.652145154862546
TXG 4 =	0.861136311594053	TWG 4 =	0.347854845137454

SIZE OF ASSEMBLED MASS OR STIFFNESS MATRIX= 510

## LUMPED MASS MATRIX FOR EACH ELEMENT:

283

0.1083850-03	0.0	0.0	0.0	0.0	0.0	0.0	0.0
0.0	0.1083850-03	0.0	0.0	0.0	0.0	0.0	0.0
0.0	0.0	0.2495800-05	0.0	0.0	0.0	0.0	0.0
0.0	0.0	0.0	0.1972310-05	0.0	0.0	0.0	0.0
0.0	0.0	0.0	0.0	0.1054360-03	0.0	0.0	0.0
0.0	0.0	0.0	0.0	0.0	0.1754360-03	0.0	0.0
0.0	0.0	0.0	0.0	0.0	0.0	0.2419800-05	0.0
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.1947740-05
0.1010120-03	0.0	0.0	0.0	0.0	0.0	0.0	0.0
0.0	0.1010120-03	0.0	0.0	0.0	0.0	0.0	0.0
0.0	0.0	0.2261260-05	0.0	0.0	0.0	0.0	0.0
0.0	0.0	0.0	0.1837140-05	0.0	0.0	0.0	0.0
0.0	0.0	0.0	0.0	0.9806270-04	0.0	0.0	0.0
0.0	0.0	0.0	0.0	0.0	0.9806270-04	0.0	0.0
0.0	0.0	0.0	0.0	0.0	0.0	0.2192110-05	0.0
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.1812560-05
0.9363880-04	0.0	0.0	0.0	0.0	0.0	0.0	0.0
0.0	0.9363880-04	0.0	0.0	0.0	0.0	0.0	0.0
0.0	0.0	0.2040160-05	0.0	0.0	0.0	0.0	0.0
0.0	0.0	0.0	0.1701970-05	0.0	0.0	0.0	0.0
0.0	0.0	0.0	0.0	0.9068960-04	0.0	0.0	0.0
0.0	0.0	0.0	0.0	0.0	0.9068960-04	0.0	0.0
0.0	0.0	0.0	0.0	0.0	0.0	0.1977370-05	0.0
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.1677390-05
0.8626570-04	0.0	0.0	0.0	0.0	0.0	0.0	0.0
0.0	0.8626570-04	0.0	0.0	0.0	0.0	0.0	0.0
0.0	0.0	0.1831540-05	0.0	0.0	0.0	0.0	0.0
0.0	0.0	0.0	0.1566790-05	0.0	0.0	0.0	0.0
0.0	0.0	0.0	0.0	0.8331650-04	0.0	0.0	0.0
0.0	0.0	0.0	0.0	0.0	0.8331650-04	0.0	0.0
0.0	0.0	0.0	0.0	0.0	0.0	0.1774610-05	0.0
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.1542210-05
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
0.7889260-04	0.0	0.0	0.0	0.0	0.0	0.0	0.0
0.0	0.7889260-04	0.0	0.0	0.0	0.0	0.0	0.0
0.0	0.0	0.1634410-05	0.0	0.0	0.0	0.0	0.0
0.0	0.0	0.0	0.1431620-05	0.0	0.0	0.0	0.0
0.0	0.0	0.0	0.0	0.7594330-04	0.0	0.0	0.0
0.0	0.0	0.0	0.0	0.0	0.7594330-04	0.0	0.0
0.0	0.0	0.0	0.0	0.0	0.0	0.1582860-05	0.0
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.1407340-05
0.7151940-04	0.0	0.0	0.0	0.0	0.0	0.0	0.0
0.0	0.7151940-04	0.0	0.0	0.0	0.0	0.0	0.0
0.0	0.0	0.1447790-05	0.0	0.0	0.0	0.0	0.0
0.0	0.0	0.0	0.1296440-05	0.0	0.0	0.0	0.0
0.0	0.0	0.0	0.0	0.6857620-04	0.0	0.0	0.0
0.0	0.0	0.0	0.0	0.0	0.6857620-04	0.0	0.0
0.0	0.0	0.0	0.0	0.0	0.0	0.1401130-05	0.0
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.1271870-05
0.6414630-04	0.0	0.0	0.0	0.0	0.0	0.0	0.0
0.0	0.6414630-04	0.0	0.0	0.0	0.0	0.0	0.0
0.0	0.0	0.1270700-05	0.0	0.0	0.0	0.0	0.0
0.0	0.0	0.0	0.1161270-05	0.0	0.0	0.0	0.0
0.0	0.0	0.0	0.0	0.6119700-04	0.0	0.0	0.0
0.0	0.0	0.0	0.0	0.0	0.6119700-04	0.0	0.0
0.0	0.0	0.0	0.0	0.0	0.0	0.1228450-05	0.0
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.1136690-05
0.5677320-04	0.0	0.0	0.0	0.0	0.0	0.0	0.0
0.0	0.5677320-04	0.0	0.0	0.0	0.0	0.0	0.0
0.0	0.0	0.1102180-05	0.0	0.0	0.0	0.0	0.0
0.0	0.0	0.0	0.1026090-05	0.0	0.0	0.0	0.0
0.0	0.0	0.0	0.0	0.5382390-04	0.0	0.0	0.0
0.0	0.0	0.0	0.0	0.0	0.5382390-04	0.0	0.0
0.0	0.0	0.0	0.0	0.0	0.0	0.1063840-05	0.0
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.1001520-05

ORIGINAL PAGE IS  
OF POOR QUALITY



0.4940000-04	0.0	0.0	0.0	0.0	0.0	0.0	0.0
0.0	0.4940000-04	0.0	0.0	0.0	0.0	0.0	0.0
0.0	0.0	0.9412340-06	0.0	0.0	0.0	0.0	0.0
0.0	0.0	0.0	0.4909210-06	0.0	0.0	0.0	0.0
0.0	0.0	0.0	0.0	0.4645080-04	0.0	0.0	0.0
0.0	0.0	0.0	0.0	0.0	0.4645080-04	0.0	0.0
0.0	0.0	0.0	0.0	0.0	0.0	0.9063140-06	0.0
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.8663440-06
0.4202690-04	0.0	0.0	0.0	0.0	0.0	0.0	0.0
0.0	0.4202690-04	0.0	0.0	0.0	0.0	0.0	0.0
0.0	0.0	0.7868900-06	0.0	0.0	0.0	0.0	0.0
0.0	0.0	0.0	0.7557670-06	0.0	0.0	0.0	0.0
0.0	0.0	0.0	0.0	0.3907760-04	0.0	0.0	0.0
0.0	0.0	0.0	0.0	0.0	0.3907760-04	0.0	0.0
0.0	0.0	0.0	0.0	0.0	0.0	0.7547040-06	0.0
0.1437200-03	0.0	0.0	0.0	0.0	0.0	0.0	0.7111690-06
0.0	0.1437200-03	0.0	0.0	0.0	0.0	0.0	0.0
0.0	0.0	0.7633870-05	0.0	0.0	0.0	0.0	0.0
0.0	0.0	0.0	0.3756560-05	0.0	0.0	0.0	0.0
0.0	0.0	0.0	0.0	0.1403610-03	0.0	0.0	0.0
0.0	0.0	0.0	0.0	0.0	0.1426830-03	0.0	0.0
0.0	0.0	0.0	0.0	0.0	0.0	0.4339400-05	0.0
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.3756560-05
0.1569100-03	0.0	0.0	0.0	0.0	0.0	0.0	0.0
0.0	0.1569100-03	0.0	0.0	0.0	0.0	0.0	0.0
0.0	0.0	0.4339400-05	0.0	0.0	0.0	0.0	0.0
0.0	0.0	0.0	0.3756560-05	0.0	0.0	0.0	0.0
0.0	0.0	0.0	0.0	0.1553490-03	0.0	0.0	0.0
0.0	0.0	0.0	0.0	0.0	0.1562380-03	0.0	0.0
0.0	0.0	0.0	0.0	0.0	0.0	0.4339400-05	0.0
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.3756560-05
0.3265630-04	0.0	0.0	0.0	0.0	0.0	0.0	0.0
0.0	0.3265630-04	0.0	0.0	0.0	0.0	0.0	0.0
0.0	0.0	0.4668950-06	0.0	0.0	0.0	0.0	0.0
0.0	0.0	0.0	0.4558380-06	0.0	0.0	0.0	0.0
0.0	0.0	0.0	0.0	0.3265620-04	0.0	0.0	0.0
0.0	0.0	0.0	0.0	0.0	0.3217320-04	0.0	0.0
0.0	0.0	0.0	0.0	0.0	0.0	0.4668820-06	0.0
0.3265920-04	0.0	0.0	0.0	0.0	0.0	0.0	0.4558370-06
0.0	0.3265920-04	0.0	0.0	0.0	0.0	0.0	0.0
0.0	0.0	0.4670170-06	0.0	0.0	0.0	0.0	0.0
0.0	0.0	0.0	0.4559610-06	0.0	0.0	0.0	0.0
0.0	0.0	0.0	0.0	0.3265920-04	0.0	0.0	0.0
0.0	0.0	0.0	0.0	0.0	0.3217610-04	0.0	0.0
0.0	0.0	0.0	0.0	0.0	0.0	0.4670070-06	0.0
0.3265780-04	0.0	0.0	0.0	0.0	0.0	0.0	0.4559620-06
0.0	0.3265780-04	0.0	0.0	0.0	0.0	0.0	0.0
0.0	0.0	0.4669590-06	0.0	0.0	0.0	0.0	0.0
0.0	0.0	0.0	0.4559020-06	0.0	0.0	0.0	0.0
0.0	0.0	0.0	0.0	0.3265770-04	0.0	0.0	0.0
0.0	0.0	0.0	0.0	0.0	0.3217480-04	0.0	0.0
0.0	0.0	0.0	0.0	0.0	0.0	0.4669470-06	0.0
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.4559020-06
0.3265680-04	0.0	0.0	0.0	0.0	0.0	0.0	0.0
0.0	0.3265680-04	0.0	0.0	0.0	0.0	0.0	0.0
0.0	0.0	0.4669160-06	0.0	0.0	0.0	0.0	0.0
0.0	0.0	0.0	0.4558550-06	0.0	0.0	0.0	0.0
0.0	0.0	0.0	0.0	0.3265650-04	0.0	0.0	0.0
0.0	0.0	0.0	0.0	0.0	0.3217370-04	0.0	0.0
0.0	0.0	0.0	0.0	0.0	0.0	0.4668990-06	0.0
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.4558530-06
0.3265800-04	0.0	0.0	0.0	0.0	0.0	0.0	0.0
0.0	0.3265800-04	0.0	0.0	0.0	0.0	0.0	0.0
0.0	0.0	0.4669690-06	0.0	0.0	0.0	0.0	0.0
0.0	0.0	0.0	0.4559130-06	0.0	0.0	0.0	0.0
0.0	0.0	0.0	0.0	0.3265810-04	0.0	0.0	0.0
0.0	0.0	0.0	0.0	0.0	0.3217500-04	0.0	0.0
0.0	0.0	0.0	0.0	0.0	0.0	0.4669590-06	0.0
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.4559150-06
0.3265780-04	0.0	0.0	0.0	0.0	0.0	0.0	0.0
0.0	0.3265780-04	0.0	0.0	0.0	0.0	0.0	0.0
0.0	0.0	0.4669570-06	0.0	0.0	0.0	0.0	0.0
0.0	0.0	0.0	0.4558990-06	0.0	0.0	0.0	0.0
0.0	0.0	0.0	0.0	0.3265760-04	0.0	0.0	0.0
0.0	0.0	0.0	0.0	0.0	0.3217470-04	0.0	0.0
0.0	0.0	0.0	0.0	0.0	0.0	0.4669440-06	0.0
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.4558990-06

THE TRANSLATIONAL AND ROTATIONAL MASSES AT EACH NODE ARE:

THE CONSTANTS FOR 2 ELASTIC FOUNDATIONS ARE:

FIRST ELEMENT	NUMBER OF ELEMENTS
9	2
11	1

### THE ASSEMBLED MASS MATRIX:

285

# THE ASSEMBLED STIFFNESS MATRIX:

0.1000000+01	0.0	0.1000000+01	0.0	0.0	0.6218500+06	0.0	0.0
0.4810580+06	0.1150920+07	0.0	0.0	0.9531210+06	-0.8193010+06	0.1966320+08	0.0
0.0	-0.4177190+06	-0.9407350+06	-0.1462320+06	0.3206830+07	0.0	0.0	0.2958680+06
0.4598770+06	-0.1706040+07	-0.1139490+06	0.1064610+07	0.0	0.0	-0.4556700+06	-0.2827540+06
-0.1170430+06	0.1707780+07	-0.1624800+05	0.2184800+07	-0.9480480+07	0.7050480+05	0.8286490+06	-0.7607800+06
0.1825870+08	0.7050480+05	-0.1432460+07	-0.7427010+06	-0.8173340+06	-0.1357870+06	0.2570070+07	0.7581450+06
0.6897630+06	0.2388750+06	0.3988020+06	-0.1471030+07	-0.9826790+05	0.8526620+06	0.8193010+06	-0.7703310+06
-0.3948950+06	-0.2634470+06	-0.1170430+06	0.1477770+07	-0.1508750+05	0.2028750+07	-0.8778230+07	0.6528230+05
0.7128820+06	-0.7022580+06	0.1685420+08	0.6524230+06	-0.1137600+07	-0.5914950+06	-0.7024170+06	-0.1253420+05
0.2023700+07	0.6476000+06	0.5461070+06	0.1897210+06	0.3420790+06	-0.1253420+07	-0.4374840+05	0.6709170+06
0.7607800+06	-0.6589160+06	-0.3384520+06	-0.2438400+06	-0.1170430+06	0.1255160+07	-0.1392690+05	0.1872690+07
-0.8035770+07	0.6005970+05	0.6058190+06	-0.6437370+06	0.1544970+08	0.6005970+05	-0.8862790+06	-0.4623590+06
-0.5962450+05	-0.1148970+06	0.1561370+07	0.5457600+06	0.4239400+06	0.1478280+06	0.2897080+06	-0.1053220+07
-0.7039050+05	0.5170490+06	0.7022580+06	-0.5562050+06	-0.2863720+06	-0.2243320+06	-0.1170430+06	0.1054960+07
-0.1276630+05	0.1716630+07	-0.7377170+07	0.5483710+05	0.5074610+06	-0.5852150+06	0.1404520+08	0.5483710+05
0.6750690+06	-0.3535500+06	-0.4987560+06	-0.1044520+06	0.1175500+07	0.4526240+06	0.3215200+06	0.1126130+06
0.2416890+06	-0.8704300+06	-0.5817410+05	0.3887350+06	0.6437370+06	-0.4621980+06	-0.2386430+06	-0.2048250+06
-0.1170430+06	0.8721710+06	-0.1160570+05	0.1560570+07	-0.6671450+07	0.4761450+05	0.4178060+06	-0.5266940+06
0.1264060+08	0.4961450+05	-0.5004290+06	-0.2633250+06	-0.4099730+06	-0.9400650+05	0.8593210+06	0.3681920+06
0.2371030+06	0.8349670+05	0.1980230+06	-0.7050480+06	-0.4715930+05	0.2936530+06	0.5852150+06	-0.1768960+06
-0.1952680+06	-0.1853180+06	-0.1173430+06	0.7067890+06	-0.1044520+05	0.1404520+07	-0.5969190+07	0.4439180+05
0.3368560+06	-0.4681720+06	0.1123610+08	0.4439190+05	-0.3588030+06	-0.1899440+06	-0.3298930+06	-0.8356130+05
0.6058190+06	0.2974650+06	0.1807490+06	0.5989770+05	0.1587080+06	-0.5570750+06	-0.3728600+05	0.1994780+06
0.5266940+06	-0.3002980+06	-0.1562420+06	-0.1658110+06	-0.1170430+06	0.5588160+06	-0.9284590+04	0.1248460+07
-0.5266940+07	0.3916940+05	0.2646110+06	-0.4096510+06	0.7831610+07	0.3916940+05	-0.2469770+06	-0.1316630+06
-0.2595180+05	-0.7311610+05	0.4081720+06	0.2254410+06	0.1153140+06	0.4123530+05	0.1237460+06	-0.4265110+06
-0.2957440+05	0.1338890+06	0.4681720+06	-0.2324050+06	-0.1215700+06	-0.1463040+06	-0.1170430+06	0.4782520+06
-0.8124710+04	0.1092400+07	-0.4564680+07	0.3394680+05	0.2010690+06	-0.3511290+06	0.8427100+07	0.3394680+05
-0.1611950+06	-0.8573940+05	-0.1959470+06	-0.6267100+05	0.2592600+06	0.1671230+06	0.7445590+05	0.2692880+05
0.9313600+05	-0.3133550+06	-0.2102420+05	0.8456150+05	0.4096510+06	-0.1732160+06	-0.9125010+05	0.1267970+06
-0.1170430+06	0.3150960+06	-0.6963440+04	0.9363440+06	-0.3862420+07	0.2872420+05	0.1462320+06	-0.2726880+06
0.1143100+08	0.2872420+05	-0.9804600+05	-0.5343170+05	-0.1418800+06	0.4081690+07	0.1047880+08	0.1175080+06
0.4463290+05	0.1639770+05	0.6687800+05	-0.1219250+07	0.2110640+05	0.7350260+06	0.3511290+06	-0.1227310+06
-0.6528230+05	-0.1072890+06	0.4758860+06	0.1269190+07	-0.4134990+05	0.2485270+07	-0.5570750+07	-0.1114150+08
0.4178070+05	-0.1160570+07	0.2070710+08	0.1188420+07	-0.5942240+06	-0.8318990+06	-0.4667840+00	-0.5341770+07
0.6663430+07	-0.6643510+06	0.3321760+06	0.3266390+06	0.2609400+00	0.4456600+06	-0.1485530+06	0.1107250+07
0.5190250+06	0.1078050+07	-0.3892660+05	-0.4325200+06	-0.2321140+06	-0.4763430+06	-0.4357210+09	0.3460160+07
0.0	0.0	0.0	0.0	0.1000000+01	0.0	0.0	0.0
0.0	0.0	0.1000000+01	0.0	0.0	0.0	0.0	0.0
0.0	0.1000000+01	0.9284600+06	-0.6961430+06	-0.2609400+00	-0.4325200+06	0.0	0.0
0.0	0.1730080+07	-0.4012520+07	0.3615580+06	0.1799280+06	-0.2844870+06	0.0	0.0
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
-0.8827110+05	-0.3671330+05	-0.1602430+06	0.0	0.0	0.0	0.0	0.0
0.0	0.0	-0.1602430+06	0.0	0.0	0.0	0.0	0.0
0.6248930+05	0.0	0.0	0.0	0.0	0.0	0.0	0.0
0.0	-0.3416270+06	-0.3898890+00	0.6702330+05	0.2844800+06	-0.1602450+06	-0.6250940+05	-0.4638510+05
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
0.3026400+00	0.2168110+06	0.1728780+02	0.6911110+06	-0.4012150+07	0.3614550+06	0.1799140+06	-0.2944830+06
0.8028120+07	-0.3615560+06	-0.8824240+05	-0.3670090+05	-0.1602340+06	0.3700130+02	0.2993780+06	0.1799160+06
0.3669550+05	0.1202030+05	0.6249100+05	-0.3416240+06	0.1314950+02	0.6702460+05	0.2844860+06	-0.1602310+06
-0.6250880+05	-0.8539290+05	0.1182460+01	0.2168000+06	0.1638870+02	0.6911290+06	-0.4012330+07	0.3615210+06
0.1799210+06	-0.2844860+06	0.8024430+07	-0.3615240+08	-0.8825610+05	-0.3670780+05	-0.1602180+06	-0.1252600+01
0.2994200+06	0.1799200+06	0.3669620+05	0.1202090+09	0.6248990+05	-0.3416350+04	0.2364180+02	0.6702830+05
0.2944420+06	-0.1602350+06	-0.6250940+05	-0.8638920+05	0.1120760+02	0.2168060+06	0.2313460+02	0.6911040+06
-0.4012470+07	0.3616530+06	0.1799300+06	-0.2844940+06	0.8028440+07	-0.3614180+06	-0.8826700+05	-0.3671840+05
-0.1602380+05	-0.3268830+02	0.2993160+06	0.1799210+06	0.3669160+05	0.1202130+05	0.6248770+05	-0.3416270+06
0.1036830+02	0.6702130+05	0.2844740+06	-0.1602470+06	-0.6251130+05	-0.8638620+05	0.5958090+01	0.2168200+06
0.2079110+02	0.6911010+06	-0.4012300+07	0.3614490+06	0.1799180+06	-0.2844810+06	0.8028260+07	-0.3615880+06
-0.8925350+05	-0.3670280+05	-0.1602390+06	0.4006700+02	0.2994000+06	0.1799210+06	0.3669980+05	0.1202080+05
0.6249110+05	-0.3416290+06	0.1003610+02	0.6702660+05	0.2844870+06	-0.1602350+06	-0.6250820+05	-0.8638990+05
0.1119640+01	0.2168020+06	0.1660960+02	0.6911180+06	-0.4012340+07	0.3615480+06	0.1799230+06	-0.2844880+06
0.4014170+07	-0.3614970+06	-0.8825680+02	-0.3670970+05	-0.1602370+06	0.3406800+06	0.1496890+06	0.1799280+06
0.3669680+05	0.1202090+05	0.6248990+05	-0.1708140+06	-0.6737990+05	0.3350660+05	0.2844800+06	-0.1602400+06
-0.6250980+05	-0.8638900+05	-0.3079840+06	0.1084060+06	-0.5500580+05	0.3455550+06		

HIGHEST NATURAL FREQUENCY (RAD/SEC) = 0.981252170+06

DELTA SHOULD BE EQUAL TO OR LESS THAN 0.2000000-05

TIME STEP SIZE USED IN PROGRAM (SEC) = 0.2000000-05

## FRAGMENT PROPERTIES

NO. OF FRAGMENTS	=	1
EFFECTIVE LENGTH OF IMPACT (IN) ON MAIN STRUCTURE	=	0.4000000+00
FRAG. NO.	=	1
DIAMETER (IN)	=	0.1000000+01
WEIGHT(LBS-SEC**2/IN.)	=	0.3856100-03
MOMENT OF INERTIA(IN-LB-SEC**2)	=	0.4820140-04
CG Y COORDINATE (IN)	=	0.6000000+01
CG Z COORDINATE (IN)	=	-0.2000000+01
ANGULAR ROTATION (DEG)	=	0.0
VEL IN Y DIR (IN/SEC)	=	0.2607960+04
VEL IN Z DIR (IN/SEC)	=	0.1482750+04
ANGULAR VEL (DEG/SEC)	=	0.0
COEFF OF RESTITUTION	=	0.1000000+01
COEFF OF FRICTION	=	0.0
INITIAL KINETIC ENERGY (IN-LB)	=	0.1735250+04

THE TPRIN FOR EACH FRAGMENT IS: 0.9600000-03

THE FOLLOWING IS THE TIME SOLUTION OF THE FRAGMENT- RING IMPACT  
 OUTPUT WILL BE PRINTED EVERY 20 CYCLES USING OUTPUT OPTION 3.  
 REACTION FORCES APPLIED TO THE STRUCTURE WILL BE PRINTED AT EACH OUTPUT CYCLE  
 FOR NODES AT WHICH BOUNDARY CONDITIONS ARE SPECIFIED. D.O.F. THAT ARE  
 NOT RESTRAINED AT THAT NODE WILL HAVE A REACTION FORCE = 0.0.  
 ALL IMPACTS WILL BE DESIGNATED AND ALL THE FRAGMENT ENERGIES WILL BE  
 LISTED AFTER EACH IMPACT.

ORIGINAL PAGE IS  
OF POOR QUALITY

IMPACT NO. 1 TIME 0.966000D-03 DURING CYCLE 404 ELEM 9 FRAG 1 DISTANCE 0.524505D+00  
FRAG 1 TC= 0.1361D+04 RT= 0.0 TOE= 0.1361D+04 FRAG

CYCLE= 490  
ELEMENT SI STA 1 SO SI STA 2 SO SI STA 3 SO  
1 0.74534499D-07 -0.35510519D-07 0.18297507D-07 0.63840875D-07 -0.21954007D-06 -0.26566986D-07  
2 0.19511990D-07 0.0 0.41069191D-07 0.0 -0.12305333D-06 0.0  
3 0.10219743D-06 -0.32601344D-06 -0.20753801D-06 0.31699906D-07 -0.21103042D-05 -0.12412288D-05  
4 -0.11190800D-06 0.0 -0.87919052D-07 0.0 -0.16757665D-05 0.0  
5 -0.18334090D-05 -0.25653355D-05 -0.33417826D-05 -0.32443108D-05 -0.10497115D-04 -0.96182171D-05  
6 -0.22003382D-05 0.0 -0.24989156D-04 -0.24403137D-04 -0.10037666D-04 0.0  
7 -0.16131788D-04 -0.15521684D-04 -0.24696147D-04 0.0 -0.13659480D-04 -0.33097262D-04  
8 -0.15826736D-04 0.0 -0.10062018D-03 -0.56647952D-04 -0.33378371D-04 0.0  
9 -0.36978186D-04 -0.85708697D-04 -0.10062018D-03 -0.56647952D-04 -0.15524489D-03 -0.25280812D-04  
10 -0.61343441D-04 0.0 -0.78634068D-04 0.0 -0.70262849D-04 0.0  
11 0.89578394D-04 -0.31985044D-03 -0.50205709D-04 0.92464174D-04 -0.81119103D-03 -0.16013095D-03  
12 -0.11513602D-03 0.0 0.21129232D-04 0.0 -0.48566099D-03 0.0  
13 -0.10897450D-02 0.10803838D-02 -0.15510782D-02 -0.0159575D-02 -0.42513842D-02 -0.26297411D-02  
14 -0.46805814D-05 0.0 0.26756034D-03 0.0 -0.81082154D-03 0.0  
15 0.36723105D-02 -0.17684892D-02 0.53510987D-03 -0.15908405D-03 -0.15912327D-02 -0.19885445D-02  
16 0.95191063D-03 0.0 0.18801291D-03 0.0 0.20365589D-03 0.0  
17 -0.85649772D-03 0.74257972D-03 -0.18044902D-02 0.25833928D-02 -0.48025834D-02 -0.20316363D-02  
18 -0.57158986D-04 0.0 0.38920129D-03 0.0 -0.13854736D-02 0.0  
19 -0.49718296D-02 0.53355814D-02 0.18747160D-02 0.42063151D-03 0.44640963D-02 -0.71905422D-02  
20 0.18187930D-01 0.0 0.11476738D-02 0.0 -0.13632229D-02 0.0  
21 0.13969542D-02 -0.44870764D-04 0.12787932D-03 -0.56976147D-03 -0.10915314D-03 -0.62611332D-04  
22 -0.79228070D-04 0.17933620D-03 -0.16051046D-03 -0.97554651D-04 -0.28120653D-05 -0.13546190D-03  
23 0.10249830D-02 0.33108227D-03 0.30145404D-03 0.15651048D-03 0.54921508D-04 0.46784351D-03  
24 0.67933578D-01 0.0 0.22889226D-03 0.0 0.26138351D-03 0.0  
25 0.23156850D-03 0.45199967D-04 0.15103077D-03 0.87832320D-04 0.44204607D-04 0.10334494D-03  
26 0.13818431D-03 0.0 0.11941550D-03 0.0 0.73774774D-04 0.0  
27 0.21720252D-04 0.31887313D-04 0.13036570D-04 0.15327861D-04 0.76049830D-05 0.20949883D-05  
28 0.26803782D-04 0.0 0.14182216D-04 0.0 0.48498957D-05 0.0  
29 0.12677964D-05 0.29449982D-05 -0.48257495D-05 -0.44755272D-05 -0.34786871D-05 -0.42831651D-05  
30 0.21163969D-05 0.0 -0.46506383D-05 0.0 -0.38810261D-05 0.0  
31 -0.20985397D-05 -0.21425209D-05 -0.22261834D-05 -0.23150227D-05 -0.15808859D-05 -0.16492422D-05  
32 -0.21205304D-05 0.0 -0.22706030D-05 0.0 -0.16400640D-05 0.0  
33 -0.95149317D-06 -0.93969521D-06 -0.31331858D-06 -0.30491162D-06 -0.43277866D-06 -0.44292738D-06  
34 -0.94559419D-06 0.0 -0.30911510D-06 0.0 -0.43785302D-06 0.0

CYCLE= 490  
STRAIN AT ADDITIONAL POINTS  
1 SI SO EI EO  
2 -0.19584300D-02 0.26216555D-02 -0.19703802D-02 0.26182280D-02  
3 0.26323759D-03 0.0 0.12787115D-03 -0.56992337D-03  
4 0.12787115D-03 0.0 0.11954370D-02 0.41412169D-03  
5 0.11761516D-02 0.0 0.41420744D-03 0.0

ENERGY AND WORK AT THE END OF TIME CYCLE 490

FRAGMENT KINETIC ENRGY

1 0.136119D+04

J= 490 TIME (SEC.) = 0.966000D-03 TIME AFTER INITIAL IMPACT = 0.140000D-04  
WORK INPUT INTO RING (IN.-LB.) = 0.374054D+03  
RING KINETIC ENERGY (IN.-LB.) = 0.346430D+03  
RING ELASTIC ENERGY (IN.-LB.) = 0.229818D+02  
RING PLASTIC WORK (IN.-LB.) = 0.177300D+01  
ENERGY STORED IN THE ELASTIC RESTRAINTS (IN.-LB.) = 0.862960D+00

I	V	W	PSI	CHI	COPY	CPZ	L	M	STRAIN(IN)	STRAIN(OUT)
1	0.0	0.0	-0.5197D-07	0.1757D-07	0.0	0.0	0.3756D+00	0.5033D-01	0.3718D-07	-0.4125D-07
2	-0.2133D-07	-0.1718D-07	-0.2090D-06	-0.2643D-06	0.1000D+01	-0.1718D-07	-0.4643D+00	-0.1166D-01	-0.2396D-06	-0.3384D-06
3	-0.6142D-06	-0.1468D-06	-0.1075D-05	-0.2702D-05	0.2000D+01	-0.1468D-06	-0.2401D+02	-0.2219D+01	-0.2706D-05	-0.2690D-05
4	-0.5505D-05	-0.7459D-06	-0.1493D-05	-0.1337D-04	0.3000D+01	-0.7459D-06	-0.1657D+03	-0.1411D+02	-0.1347D-04	-0.1304D-04
5	-0.3030D-04	-0.3517D-05	-0.4041D-05	-0.3601D-04	0.4000D+01	-0.3517D-05	-0.4503D+03	-0.3127D+02	-0.3123D-04	-0.5034D-04
6	-0.1179D-03	-0.1905D-04	-0.2134D-03	-0.1310D-03	0.5000D+01	-0.1905D-04	-0.2141D+03	-0.2545D+02	-0.1045D-03	-0.2106D-03
7	-0.3381D-01	-0.8631D-06	-0.9643D-03	-0.9521D-03	0.6000D+01	-0.8631D-06	-0.2249D+03	-0.1629D+03	-0.1227D-02	-0.1226D-03
8	0.6128D-03	0.7089D-03	0.1414D-01	0.2972D-02	0.7000D+01	0.7089D-03	0.4540D+03	-0.5981D+01	0.4012D-02	0.2702D-02
9	0.9756D-03	0.2358D-01	0.1876D-01	0.1000D-02	0.8000D+01	0.2358D-01	0.3514D+04	0.3185D+03	-0.1166D-07	0.2025D-03
10	-0.3988D-03	0.3023D-01	-0.1499D-01	-0.4250D-02	0.9000D+01	0.3023D-01	0.3124D+04	0.9251D+02	-0.5473D-02	-0.9695D-04
11	-0.4646D-03	0.1713D-03	-0.1774D-02	0.1129D-02	0.1000D+02	0.1713D-03	-0.2564D+04	-0.2699D+03	0.1736D-02	-0.4752D-03
12	0.7594D-04	-0.1551D-04	0.1760D-03	0.1471D-03	0.1050D+02	0.1000D+01	-0.1498D+04	0.2435D+02	0.7476D-04	0.2194D-03
13	0.0	0.0	0.0	-0.6817D-05	0.1500D+02	0.1500D+01	0.6183D+03	0.2009D+02	0.4058D-04	-0.5421D-04
14	-0.1232D-03	0.3217D-04	-0.5308D-03	0.1985D-03	0.1087D-02	-0.7591D-01	0.3269D+03	0.1089D+02	0.1765D-03	0.2651D-03
15	-0.7278D-05	0.2392D-05	0.2279D-04	0.2772D-04	0.1171D-02	-0.3015D+00	0.4232D+02	0.1619D+01	0.2103D-04	0.4780D-04
16	0.4896D-05	0.7092D-06	0.2614D-05	0.4944D-05	0.1250D+02	-0.6649D+00	-0.1348D+02	-0.4943D+00	0.5102D-05	0.1877D-05
17	0.2449D-05	0.2059D-06	-0.8109D-06	-0.1925D-05	0.1321D+02	-0.1170D+01	-0.6676D+01	-0.2500D+00	-0.1853D-07	-0.2118D-05
18	0.6601D-06	0.2202D-07	-0.7281D-07	-0.1278D-05	0.1383D+02	-0.1786D+01	-0.9015D+00	-0.3335D-01	-0.1270D-05	-0.1249D-05
19	0.2012D-06	-0.8806D-08	-0.1094D-06	-0.6119D-06	0.1433D+02	-0.2500D+01	0.0	0.0	-0.6116D-06	-0.6208D-06

FRAG NO. = FCG = FCG = ALFA = FRUV = FRW = FRV =

1 0.855540D+01 -0.560546D+00 0.0 0.260796D+04 0.508411D+03 0.0

REACTIONS AT NODE  
1 RV(LRS) RW(LRS) RW(LRS)  
13 -0.135568D+00 -0.174652D+03 0.733247D+02

SUBSTRUCTURE MSTR ELE SURF STA TIME  
1 0.533558D-02 10 1 1 0.980000D-03  
2 0.139695D-02 11 1 1 0.980000D-03  
INTERFACE 0.114767D-02 10 1 2 0.980000D-03

SUBSTRUCTURE LARGEST ADD. PT. STRAIN ELEM ADD. PT. TIME SURFACE  
1 0.262166D-02 9 1 0.980000D-03 2  
2 0.127879D-03 11 2 0.980000D-03 1  
INTERFACE 0.950723D-03 9 1 0.974000D-03 1

SUBSTRUCTURE LARGEST NODAL STRAIN NODE SURF TIME  
1 0.401169D-02 8 1 0.980000D-03  
2 0.219403D-03 12 2 0.980000D-03

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CYCLE= 510
ELEMENT 1 0.497787000-01 -0.920910970-04 0.448355740-03 0.196870180-03 0.561810350-04 0.505020030-03
2 0.402447950-03 0.0 0.322613060-03 0.0 0.280601530-03 0.0
3 0.104556100-01 0.494133710-03 0.472420250-01 0.362216260-03 0.742118640-03 0.160186270-03
4 0.297345110-03 0.0 0.417118250-03 0.0 0.451152450-03 0.0
5 0.500674800-03 0.418208600-03 0.640971450-04 0.522025440-03 -0.653463480-04 0.899642990-03
6 0.459441700-03 0.0 0.293061290-01 0.0 0.417118320-03 0.0
7 0.607067730-03 0.103354280-03 0.112492080-02 0.250075430-03 0.992234620-03 -0.23131850-03
8 0.353209010-03 0.0 0.687498000-03 0.0 0.380426380-03 0.0
9 0.862667280-04 0.750335260-03 -0.625281070-03 0.701093240-03 -0.839700090-03 0.109837830-02
10 0.418301000-03 0.0 0.379060810-04 0.0 0.129339070-03 0.0
11 0.345831260-03 0.713624750-03 0.634813210-03 0.226694140-03 0.147389420-02 -0.285561200-03
12 0.183896750-03 0.0 0.430763670-03 0.0 0.594166480-03 0.0
13 0.272142780-02 -0.825156510-03 0.616528680-02 -0.289497190-02 0.957738610-02 -0.448030640-02
14 0.948135670-03 0.0 0.163515740-02 0.0 0.254868990-02 0.0
15 0.845347050-02 -0.395308590-02 0.195195620-02 -0.455521970-03 -0.334991750-02 0.327200140-02
16 0.225019230-02 0.0 0.748217130-03 0.0 -0.189080400-04 0.0
17 -0.505126660-02 0.334192390-02 -0.123311190-01 0.790295050-02 -0.188328960-01 0.117747460-01
18 -0.854671340-03 0.0 -0.221408440-02 0.0 -0.352907500-02 0.0
19 -0.427486970-02 0.548140490-02 0.693278960-02 -0.168951000-02 0.983667490-02 -0.190088100-01
20 -0.189682400-02 0.0 0.262163980-02 0.0 -0.458867400-02 0.0
21 0.245992120-02 -0.618205350-03 0.910827260-03 -0.159910100-02 0.872202980-03 -0.11192710-02
22 0.843517100-03 -0.616271740-03 0.381305250-03 -0.566623900-03 0.179203050-01 -0.232031520-03
23 0.144089100-02 0.100085730-02 0.115627380-02 0.318202830-03 0.142085560-02 0.191853450-01
24 0.122387820-02 0.0 0.737238290-03 0.0 0.806369550-03 0.0
25 0.148407690-02 0.247593860-03 0.102161790-02 0.363800010-03 0.519883080-03 0.412719400-03
26 0.865835360-03 0.0 0.693708980-03 0.0 0.476301240-03 0.0
27 0.212724630-03 0.788298490-03 0.794557850-03 0.478878440-03 0.457215020-03 0.252656660-03
28 0.500511560-03 0.0 0.186718150-03 0.0 0.354935840-03 0.0
29 0.355352890-03 0.364553340-03 0.147896790-03 0.239474500-03 0.143410300-03 0.321879170-03
30 0.359953110-03 0.0 0.193595690-03 0.0 0.232654740-03 0.0
31 0.264804140-03 0.155354430-04 0.117721630-03 0.118460010-03 -0.655499080-04 0.184484970-03
32 0.140169790-03 0.0 0.118090820-03 0.0 0.594675310-04 0.0
33 -0.423154040-04 0.992154970-04 0.180794170-03 -0.587355820-04 0.423739760-03 -0.197611950-03
34 0.284500470-04 0.0 0.610292960-04 0.0 0.113063910-03 0.0

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CYCLE= 510
STRAIN AT ADDITIONAL POINTS
1 -0.129491260-01 0.814090360-02 -0.130340700-01 0.810803350-02
2 -0.269527940-02 0.0 0.910412830-03 -0.160038160-02
3 0.910827260-03 -0.159910100-02 0.153078700-02 0.115635770-02
0.153195860-02 0.115702630-02 0.134449250-02 0.0

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# ENERGY AND WORK AT THE END OF TIME CYCLE 510

## FRAGMENT KINETIC ENERGY

1 0.1361190+04

J= 510 TIME (SEC.) = 0.1020000-02 TIME AFTER INITIAL IMPACT = 0.5400000-04  
WORK INPUT INTO RING (IN.-LB.) = 0.3740540+03  
RING KINETIC ENERGY (IN.-LB.) = 0.2198160+03  
RING ELASTIC ENERGY (IN.-LB.) = 0.8758490+02  
RING PLASTIC WORK (IN.-LB.) = 0.5763740+02  
ENERGY STORED IN THE ELASTIC RESTRAINTS (IN.-LB.) = 0.9010860+01

I	V	M	PSI	CHI	COPY	COP2	L	M	STRAIN(IN)	STRAIN(OUT)
1	0.0	0.0	-0.82770-03	0.73600-03	0.0	0.0	0.24780+04	0.22480+03	0.88810-01	0.28220-03
2	0.39860-03	0.13460-03	0.39490-04	0.11420-03	0.10000+01	0.13460-03	0.31910+04	0.30430+03	0.40060-04	0.33650-03
3	0.81800-03	-0.11410-04	-0.44770-03	0.62350-03	0.20010+01	-0.11410-04	0.25520+04	0.29460+03	0.48180-03	0.44380-03
4	0.17970-02	-0.16650-04	-0.17860-02	0.23060-03	0.30010+01	-0.16650-04	0.39090+04	0.24160+03	0.18650-01	0.36670-03
5	0.18050-02	0.13500-03	0.24200-02	0.49810-03	0.40020+01	0.13500-03	0.12260+04	0.21300+03	0.55480-03	0.34020-03
6	0.16440-02	0.99340-04	-0.38960-02	-0.28820-03	0.50020+01	0.99340-04	0.21180+04	0.12010+03	-0.50650-03	0.39730-03
7	0.21350-02	-0.43180-02	-0.17480-02	0.11590-02	0.60020+01	-0.43180-02	0.26430+04	-0.35770+03	0.14090-02	0.41540-03
8	0.57740-02	0.13390-01	0.51550-01	0.55040-02	0.70060+01	0.13390-01	0.19970+04	0.28060+01	0.87800-02	0.10520-02
9	0.46890-02	0.86430-01	0.67600-01	-0.46830-02	0.80050+01	0.86430-01	0.22710+04	0.62340+03	-0.32460-02	0.18880-03
10	-0.36110-02	0.96580-01	-0.88050-01	-0.15090-01	0.89960+01	0.96580-01	0.47210+04	0.41410+01	-0.14570-01	-0.68960-03
11	-0.70730-02	0.38930-02	-0.76650-02	0.14840-02	0.99930+01	0.38930-02	-0.39940+04	-0.97100+03	0.28180-02	-0.19280-02
12	0.68990-03	0.88290-03	-0.26500-02	0.21040-03	0.10500+02	0.10010+01	-0.10750+04	0.36670+03	0.64920-03	-0.22130-03
13	0.0	0.0	0.0	0.42420-04	0.11500+02	0.15000+01	0.18580+04	0.52310+02	0.10620-03	0.21340-04
14	-0.61040-02	-0.31690-02	-0.23690-02	0.12770-02	0.10860+02	-0.78020-01	0.17950+04	0.53510+02	0.14520-02	0.76540-03
15	-0.47780-02	-0.27150-02	0.33990-02	0.35840-03	0.11700+02	-0.30250+00	0.11970+04	0.48710+02	0.31620-03	0.50840-03
16	-0.40810-02	-0.18650-02	0.17850-02	0.45150-03	0.12500+02	-0.66940+00	0.59940+03	0.24120+02	0.47190-03	0.39110-03
17	-0.36270-02	-0.11900-02	0.97460-03	0.22810-03	0.13210+02	-0.11680+01	0.34580+03	0.12870+02	0.23600-01	0.20660-03
18	-0.31820-02	-0.53910-03	0.96990-03	-0.53720-04	0.13830+02	-0.17840+01	0.93180+02	-0.13350+01	-0.89160-04	0.54520-04
19	-0.32000-02	0.17390-04	0.30620-02	0.32350-03	0.14330+02	-0.24970+01	.	.	0.41980-01	0.53550-04

FRAG NO. = FCGU = FCGW = ALFA = FRUV = FRWV = FRAV =  
1 0.8660120+01 -0.5402090+00 0.0 0.2607960+04 0.5084110+03 0.0

REACTIONS AT NODE  
1 RV(LBS) -0.2524030+04  
13 -0.5628110+03  
RW(LBS) -0.3439000+03  
4.796560+03  
RM(IN-LBS) 0.0  
0.9871970+02

SUBSTRUCTURE	MSTR	ELE	SURF	STA	TIME
1	0.1177470-01	9	2	3	0.1020000-02
2	0.2574200-02	11	1	1	0.1014000-02
INTERFACE	0.3092560-02	10	1	2	0.1006000-02

SUBSTRUCTURE	LARGEST ADD. PT. STRAIN	ELEM	ADD. PT.	TIME	SURFACE
1	0.8140900-02	9	1	0.1020000-02	2
2	0.9298350-03	11	3	0.1018000-02	1
INTERFACE	0.1344490-02	13	2	0.1020000-02	1

SUBSTRUCTURE	LARGEST NODAL STRAIN	NODE	SURF	TIME
1	0.8780260-02	8	1	0.1020000-02
2	0.6492130-03	12	1	0.1020000-02

CYCLE=	530	SI	STA 1	SO	SI	STA 2	SO	SI	STA 3	SO
ELEMENT										
1	0.14474656D-02	-0.19846690D-03	0.12594775D-02	-0.10942719D-03	0.12061690D-02	0.10167656D-03				
	0.62549917D-03	0.0	0.57502515D-03	0.0	0.65492277D-03	0.0				
2	0.13936140D-02	-0.19686511D-03	0.10225971D-02	0.32749766D-03	0.23655728D-03	0.38800784D-03				
	0.59874440D-03	0.0	0.67504741D-03	0.0	0.31228256D-03	0.0				
3	-0.47249727D-03	0.11381322D-02	-0.22920836D-03	0.50565404D-03	0.54905416D-03	0.45941932D-03				
	0.33281745D-03	0.0	0.13822284D-03	0.0	0.50423674D-03	0.0				
4	0.11953943D-02	-0.41177405D-03	0.46771581D-03	0.44190640D-03	-0.74229141D-03	0.71024130D-03				
	0.39180512D-03	0.0	0.45481112D-03	0.0	-0.16015059D-04	0.0				
5	-0.15974426D-02	0.16578126D-02	-0.14109660D-02	0.11484402D-02	-0.87937497D-03	0.10269733D-02				
	0.30185003D-04	0.0	-0.13126289D-03	0.0	0.73799145D-04	0.0				
6	0.67840590D-03	-0.12171313D-03	0.40677524D-02	-0.20519227D-02	0.69854046D-02	-0.40179169D-02				
	0.27834639D-03	0.0	0.10040149D-02	0.0	0.14837438D-02	0.0				
7	0.75110712D-02	-0.43687724D-02	0.68572766D-02	-0.40341807D-02	0.64294238D-02	-0.34982827D-02				
	0.15811494D-02	0.0	0.14115480D-02	0.0	0.14655706D-02	0.0				
8	0.47376981D-07	-0.29588300D-02	-0.12022769D-02	0.29900932D-03	-0.68345701D-02	0.29536168D-02				
	0.88943435D-03	0.0	-0.45163378D-03	0.0	-0.19404767D-02	0.0				
9	-0.10207965D-01	0.58080404D-02	-0.17427290D-01	0.85156143D-02	-0.21883023D-01	0.12696477D-01				
	-0.21999622D-02	0.0	-0.44558379D-02	0.0	-0.45932728D-02	0.0				
10	-0.87823212D-02	0.29949217D-02	0.81174464D-02	-0.39779552D-02	0.10052994D-01	-0.22662045D-01				
	-0.28936998D-02	0.0	0.20697456D-02	0.0	-0.63045253D-02	0.0				
11	0.13100209D-02	-0.54835853D-03	0.82278118D-03	-0.11904063D-02	0.10092492D-02	-0.11587472D-02				
	0.13307427D-02	-0.12483152D-02	0.17678882D-02	-0.18487843D-02	0.23139123D-02	-0.23403548D-02				
12	-0.29879310D-03	0.13803653D-02	-0.65625648D-03	-0.66711021D-03	0.96819461D-03	-0.67060438D-03				
	0.54278580D-03	0.0	-0.66168336D-03	0.0	0.13876711D-03	0.0				
14	0.22297470D-02	-0.20177964D-02	0.13952115D-02	-0.12728158D-02	-0.79631616D-03	-0.70953346D-03				
	0.10597513D-03	0.0	0.61178297D-04	0.0	-0.15660865D-03	0.0				
15	-0.13701968D-03	-0.39621056D-03	-0.33395657D-03	-0.23770932D-03	-0.52719359D-03	-0.74767027D-04				
	0.26661512D-03	0.0	-0.28543295D-03	0.0	-0.30098131D-03	0.0				
16	-0.52282029D-03	-0.86005457D-04	-0.15857811D-03	-0.12324820D-03	-0.20436647D-03	-0.16971897D-03				
	0.30441288D-03	0.0	-0.24091315D-03	0.0	-0.18704271D-03	0.0				
17	-0.10144204D-03	-0.21311149D-03	-0.36625414D-04	-0.16779981D-03	-0.41685869D-04	-0.19437490D-03				
	-0.15727677D-03	0.0	-0.10221261D-03	0.0	-0.11803039D-03	0.0				
18	-0.12995744D-03	0.56611958D-05	-0.12838142D-03	0.32801007D-05	-0.12196241D-03	0.64456563D-05				
	-0.62148121D-04	0.0	-0.62550859D-04	0.0	-0.57758370D-04	0.0				

CYCLE=	530	SI	SN	EI	EO
STRAIN AT ADDITIONAL POINTS					
1	-0.17468640D-01	0.86493541D-02	-0.18133044D-01	0.86519262D-02	
	-0.50076824D-02	0.0			
2	0.82278118D-03	-0.11904063D-02	0.82244297D-03	-0.11911157D-02	
3	-0.78645508D-04	0.18780701D-02	-0.78648601D-04	0.18763098D-02	
	0.89971228D-03	0.0			

# ENERGY AND WORK AT THE END OF TIME CYCLE 530

FRAGMENT		KINETIC ENERGY								
1		0.136119D+04								
J= 530 TIME (SEC.) = 0.106000D-02 TIME AFTER INITIAL IMPACT = 0.940000D-04										
WORK INPUT INTO RING (IN.-LB.)		= 0.374054D+03								
RING KINETIC ENERGY (IN.-LB.)		= 0.161234D+03								
RING ELASTIC ENERGY (IN.-LB.)		= 0.918047D+02								
RING PLASTIC WORK (IN.-LB.)		= 0.105552D+03								
ENERGY STORED IN THE ELASTIC RESTRAINTS (IN.-LB.) = 0.154641D+02										
I	V	W	PSI	CHI	COPY	CUPZ	L	M	STRAIN(IN)	STRAIN(OUT)
1	0.0	0.0	-0.4682D-02	0.1086D-02	0.0	0.0	0.3664D+04	0.1428D+03	0.1314D-02	0.4485D-03
2	0.9507D-03	-0.2147D-02	0.3842D-04	0.9588D-03	0.1001D+01	-0.2147D-02	0.4664D+04	0.3667D+03	0.1140D-02	0.4178D-03
3	0.1678D-02	-0.1427D-03	0.2613D-02	0.2338D-04	0.2002D+01	-0.1427D-03	0.1666D+04	0.2469D+03	-0.1147D-03	0.4512D-01
4	0.1784D-02	0.2883D-03	0.3266D-03	0.7954D-03	0.3002D+01	0.2883D-03	0.3040D+04	0.2572D+03	0.9462D-03	0.3445D-03
5	0.2103D-02	0.1448D-02	-0.2144D-03	0.7184D-03	0.4002D+01	0.1448D-02	0.1110D+04	0.3128D+03	-0.1051D-02	0.2811D-03
6	0.1401D-02	-0.5454D-02	-0.1240D-01	0.3077D-03	0.5001D+01	-0.5454D-02	0.1459D+04	-0.3397D+03	-0.3904D-03	0.2482D-03
7	0.3784D-02	-0.7811D-02	0.1981D-01	0.4528D-02	0.6004D+01	-0.7811D-02	-0.1564D+03	-0.5856D+03	0.6269D-02	0.1328D-03
8	0.6433D-02	0.4465D-01	0.8388D-01	0.4081D-03	0.7006D+01	0.4465D-01	-0.1179D+04	0.1910D+01	0.5188D-02	0.1382D-03
9	0.1404D-02	0.1362D+00	0.7387D-01	-0.8062D-02	0.8001D+01	0.1362D+00	-0.2784D+04	0.3180D+03	-0.6858D-02	-0.6297D-03
10	-0.1066D-01	0.1282D+00	-0.1257D+00	-0.2033D-01	0.8989D+01	0.1282D+00	0.1450D+04	-0.2058D+03	-0.1573D-01	-0.1686D-02
11	-0.1696D-01	0.1228D-01	-0.1574D+00	0.5477D-03	0.9983D+01	0.1228D-01	-0.2133D+04	-0.7788D+03	0.1840D-03	-0.2605D-02
12	0.3937D-02	0.5058D-02	-0.1011D-01	0.3261D-04	0.1050D+02	0.1006D+01	-0.4694D+03	-0.1399D+04	0.6450D-03	-0.4775D-03
13	0.0	0.0	0.0	0.1722D-04	0.1150D+02	0.1500D+01	-0.1940D+04	-0.7236D+02	0.1256D-02	-0.1222D-02
14	-0.1765D-01	-0.7264D-02	-0.1574D-01	0.1217D-02	0.1085D+02	-0.8005D-01	-0.7721D+03	-0.8218D+02	0.1769D-02	0.5851D-04
15	-0.1517D-01	-0.1111D-01	0.7583D-02	-0.1866D-03	0.1169D+02	-0.3068D+00	-0.8021D+03	-0.2789D+02	-0.9430D-04	-0.3485D-03
16	-0.1391D-01	-0.6797D-02	0.6741D-02	0.4779D-03	0.1248D+02	-0.6688D+00	-0.6210D+03	-0.1898D+02	-0.5208D-03	-0.2578D-01
17	-0.1323D-01	-0.4508D-02	0.4686D-02	-0.1717D-03	0.1320D+02	-0.1165D+01	-0.3458D+03	-0.1549D+02	-0.1526D-03	-0.1851D-03
18	-0.1275D-01	-0.2210D-02	0.5835D-02	-0.1125D-03	0.1382D+02	-0.1778D+01	-0.1361D+03	-0.2422D+01	-0.9402D-04	-0.9963D-04
19	-0.1265D-01	0.1673D-03	0.4685D-02	-0.9812D-04	0.1432D+02	-0.2489D+01			-0.1031D-01	-0.3929D-04
FRAG NO.		FCGU	FCGW	ALFA	FRUV	FRW	FRV	FRV	FRV	
1	0.876444D+01	-0.519873D+00	0.0	0.260796D+04	0.508411D+03	0.0				

REACTIONS AT NODE	RV(LBS)	RH(LBS)	RH(IN-LBS)
1	-0.364613D+04	-0.19689D+03	0.0
13	-0.258809D+03	-0.25828D+03	0.191730D+04
SUBSTRUCTURE	MSTR	ELE	STA
1	0.127241D-01	9	3
2	0.257420D-02	11	1
INTERFACE	0.309256D-02	10	2
SUBSTRUCTURE	LARGEST ADD. PT. STRAIN	ELEM	TIME
1	0.907227D-02	9	0.104600D-02
2	0.103464D-02	11	0.104200D-02
INTERFACE	0.134700D-02	13	0.102200D-02
SUBSTRUCTURE	LARGEST NODAL STRAIN	NODE	TIME
1	0.881166D-02	8	0.102200D-02
2	0.175627D-02	13	0.106000D-02

CYCLE=	550	SI	STA 1	SO	SI	STA 2	SO	SI	STA 3	SO
ELEMENT										
1	-0.29198869D-02	0.72151655D-03	-0.14976653D-02	-0.19845969D-03	-0.45976793D-05	-0.92757927D-03	-0.10991852D-02	0.0	-0.46606347D-03	0.0
2	0.68256662D-03	-0.13997157D-02	-0.14926570D-02	-0.15408522D-02	0.15346708D-02	-0.17250746D-02	0.0	0.13997157D-02	0.0	0.0
3	0.10873885D-02	-0.14649597D-02	-0.89025304D-03	-0.16167086D-03	-0.28631511D-02	0.94780290D-03	0.0	0.10873885D-02	0.0	0.0
4	-0.18878557D-03	0.0	-0.52596195D-03	0.0	-0.95767409D-03	0.0	0.0	-0.18878557D-03	0.0	0.0
5	0.32935599D-02	0.12527335D-02	-0.78418423D-02	0.10025884D-02	-0.25559976D-02	0.62771369D-03	0.0	0.32935599D-02	0.0	0.0
6	-0.10204132D-02	0.0	-0.92062695D-03	0.0	-0.96413194D-03	0.0	0.0	-0.10204132D-02	0.0	0.0
7	-0.20790167D-02	0.52740580D-03	-0.23878667D-03	-0.11990094D-02	-0.27668201D-02	-0.24236881D-02	0.0	-0.20790167D-02	0.0	0.0
8	-0.77580547D-03	0.0	-0.44011138D-03	0.0	-0.17156601D-03	0.0	0.0	-0.77580547D-03	0.0	0.0
9	0.44766422D-02	-0.37069807D-02	-0.63371620D-02	-0.45848995D-02	0.79567068D-02	-0.54543732D-02	0.0	0.44766422D-02	0.0	0.0
10	0.38483075D-03	0.0	0.87613125D-03	0.0	0.12511668D-02	0.0	0.0	0.38483075D-03	0.0	0.0
11	0.74853338D-02	-0.51852548D-02	-0.49131482D-02	-0.35108433D-02	0.28905176D-02	-0.16230699D-02	0.0	0.74853338D-02	0.0	0.0
12	0.11502895D-02	0.0	0.70115248D-03	0.0	0.63373387D-03	0.0	0.0	0.11502895D-02	0.0	0.0
13	0.11818402D-02	-0.10073454D-02	-0.44619397D-02	0.24472804D-02	-0.10024222D-01	0.50548266D-02	0.0	0.11818402D-02	0.0	0.0
14	0.87247408D-04	0.0	-0.10073296D-02	0.0	-0.24846978D-02	0.0	0.0	0.87247408D-04	0.0	0.0
15	-0.12314783D-01	0.67620151D-02	-0.16503925D-01	0.84546619D-02	-0.18841125D-01	0.11170487D-01	0.0	-0.12314783D-01	0.0	0.0
16	-0.27763838D-02	0.0	-0.40246315D-02	0.0	-0.38353190D-02	0.0	0.0	-0.27763838D-02	0.0	0.0
17	-0.67998272D-02	0.23342492D-02	-0.86783808D-02	-0.40420202D-02	-0.98863261D-01	-0.21695287D-01	0.0	-0.67998272D-02	0.0	0.0
18	-0.22327890D-02	0.0	-0.23181803D-02	0.0	-0.57044806D-02	0.0	0.0	-0.22327890D-02	0.0	0.0
19	0.11219134D-02	-0.43984617D-03	-0.83374125D-03	-0.12837102D-02	-0.12308539D-02	-0.14422902D-02	0.0	0.11219134D-02	0.0	0.0
20	0.18086386D-02	-0.17597630D-02	-0.28851906D-02	-0.29819872D-02	0.40611546D-02	-0.41047995D-02	0.0	0.18086386D-02	0.0	0.0
21	0.70700446D-03	-0.13070912D-03	-0.27734103D-03	-0.28066107D-04	0.13440257D-04	0.24154065D-03	0.0	0.70700446D-03	0.0	0.0
22	0.28814767D-03	0.0	0.12463746D-03	0.0	0.12749045D-03	0.0	0.0	0.28814767D-03	0.0	0.0
23	0.47642360D-03	-0.46601087D-04	-0.16694560D-02	-0.69456511D-03	0.28119343D-02	-0.14046997D-02	0.0	0.47642360D-03	0.0	0.0
24	0.321491125D-03	0.0	-0.48745444D-03	0.0	0.70361733D-03	0.0	0.0	0.321491125D-03	0.0	0.0
25	0.26511899D-02	-0.12390595D-02	-0.12162116D-02	-0.37738380D-03	-0.22281741D-03	0.47622387D-03	0.0	0.26511899D-02	0.0	0.0
26	0.70706520D-03	0.0	-0.41941390D-03	0.0	-0.12670323D-03	0.0	0.0	0.70706520D-03	0.0	0.0
27	-0.36797993D-03	0.75524059D-03	-0.35779647D-03	-0.54021538D-03	-0.14602420D-04	-0.35034030D-03	0.0	-0.36797993D-03	0.0	0.0
28	0.37720597D-04	0.0	-0.91209457D-04	0.0	-0.16786894D-03	0.0	0.0	0.37720597D-04	0.0	0.0
29	0.17572195D-03	0.13413387D-03	-0.18443315D-03	0.13430561D-03	0.16565597D-03	0.10618791D-03	0.0	0.17572195D-03	0.0	0.0
30	0.15492791D-03	0.0	-0.15936938D-03	0.0	-0.13592194D-03	0.0	0.0	0.15492791D-03	0.0	0.0
31	0.14161304D-03	0.27133785D-04	-0.57505351D-04	0.34020312D-04	0.42351551D-05	0.72305181D-04	0.0	0.14161304D-03	0.0	0.0
32	0.84373411D-04	0.0	-0.45762831D-04	0.0	0.38270168D-04	0.0	0.0	0.84373411D-04	0.0	0.0

CYCLE=	550	SI	SO	EI	EQ
STRAIN AT ADDITIONAL POINTS	1	-0.16811542D-01	0.85680215D-02	-0.16955324D-01	0.85316272D-02
	2	-0.44721704D-02	0.0	0.83339397D-03	-0.12845352D-02
	3	0.83174125D-03	-0.12837102D-02	0.80077341D-03	-0.12269184D-03
		0.80109403D-03	-0.12268431D-03		
		0.33920446D-03	0.0		

# ENERGY AND WORK AT THE END OF TIME CYCLE 550

FRAGMENT	KINETIC ENERGY
1	0.136119D+04

J= 550 TIME (SEC.) = 0.110000D-02 TIME AFTER INITIAL IMPACT = 0.134000D-03  
 WORK INPUT INTO RING (IN.-LB.) = 0.374054D+03  
 RING KINETIC ENERGY (IN.-LB.) = 0.121609D+03  
 RING ELASTIC ENERGY (IN.-LB.) = 0.116116D+03  
 RING PLASTIC WORK (IN.-LB.) = 0.116917D+03  
 ENERGY STORED IN THE ELASTIC RESTRAINTS (IN.-LB.) = 0.194124D+02

I	V	W	PSI	CHI	COPY	COPY2	L	M	STRAIN(IN)	STRAIN(OUT)
1	0.0	0.0	0.3634D-03	-0.2233D-02	0.0	0.0	-0.5853D+04	-0.4122D+03	-0.2774D-02	-0.6010D-03
2	-0.1153D-02	-0.3544D-02	-0.4117D-02	0.4701D-04	0.9988D+00	-0.3544D-02	-0.4133D+04	-0.8083D+03	0.2708D-03	-0.5905D-03
3	-0.7007D-03	-0.3210D-02	0.5847D-02	0.7613D-03	0.1999D+01	-0.3210D-02	-0.3198D+04	-0.2060D+03	0.1214D-02	-0.5268D-03
4	-0.1449D-02	0.3938D-02	0.2932D-02	-0.2270D-02	0.2999D+01	0.3938D-02	-0.3042D+04	0.1476D+03	-0.2852D-02	-0.4952D-03
5	-0.3404D-02	-0.2008D-02	-0.1379D-01	-0.1852D-02	0.3997D+01	-0.2008D-02	-0.2591D+04	-0.4415D+03	-0.2183D-02	-0.4739D-03
6	-0.3555D-02	-0.1642D-01	-0.6945D-02	0.1975D-02	0.4899D+01	-0.1642D-01	-0.2591D+04	-0.9661D+03	0.2849D-02	-0.5430D-03
7	-0.3999D-03	0.1909D-02	0.5054D-01	0.3642D-02	0.6000D+01	0.1909D-02	-0.2235D+04	-0.5715D+03	0.6679D-02	-0.3354D-03
8	-0.6795D-03	0.8190D-01	0.1001D+00	-0.3530D-02	0.6999D+01	0.8190D-01	-0.7264D+03	0.2710D+03	0.2013D-02	-0.9935D-04
9	-0.7533D-02	0.1719D+00	0.5403D-01	-0.8551D-02	0.7992D+01	0.1719D+00	-0.1295D+04	0.3133D+03	-0.9211D-02	-0.5878D-03
10	-0.1953D-01	0.1474D+00	-0.1180D+00	-0.2033D-01	0.8980D+01	0.1474D+00	-0.1847D+04	-0.1959D+03	-0.1357D-01	-0.1723D-02
11	-0.2596D-01	0.1970D-01	-0.2232D-01	0.3849D-03	0.9974D+01	0.1970D-01	-0.2611D+04	-0.8192D+03	0.1924D-02	-0.3062D-02
12	0.6498D-02	0.8518D-02	-0.1640D-01	-0.7610D-04	0.1050D+02	0.1010D+01	-0.5617D+03	-0.2270D+04	0.7752D-03	-0.6584D-03
13	0.0	0.0	0.0	0.1224D-04	0.1150D+02	0.1500D+01	0.2558D+03	0.3392D+01	0.2221D-02	-0.2196D-02
14	-0.2740D-01	-0.2449D-02	-0.1966D-01	-0.1476D-03	0.1084D+02	0.7362D-01	0.5835D+03	-0.2568D+02	0.2100D-04	0.1195D-03
15	-0.2449D-01	-0.1821D-01	0.1003D-02	0.2031D-02	0.1168D+02	-0.3103D+00	0.6591D+03	-0.7428D+01	0.2416D-02	0.2858D-03
16	-0.2108D-01	-0.1142D-01	0.1492D-01	-0.4981D-03	0.1248D+02	-0.6692D+00	0.5870D+03	0.3982D+02	-0.5715D-01	0.1674D-03
17	-0.1979D-01	-0.6262D-02	0.7079D-02	0.1329D-03	0.1319D+02	-0.1162D+01	0.4485D+03	0.1567D+02	0.1472D-01	0.1900D-03
18	-0.1883D-01	-0.3269D-02	0.7518D-02	0.1115D-03	0.1382D+02	-0.1774D+01	0.1255D+03	0.4197D+01	0.1524D-01	0.1016D-03
19	-0.1854D-01	0.2803D-03	0.7722D-02	-0.1462D-04	0.1472D+02	-0.2484D+01	0.0	0.0	0.3343D-05	0.5075D-04

FRAG NO.	FCGU	FCGW	ALFA	FRUV	FRWV	FRAY
1	0.886876D+01	-0.499536D+00	0.0	0.260796D+04	0.508411D+03	0.0

REACTIONS AT NODE	RV(LBS)	RW(LBS)	RM(IN-LBS)
1	0.564348D+04	0.834679D+03	0.0
13	-0.369374D+03	-0.205052D+04	0.341751D+04

SUBSTRUCTURE	MSTR	ELE	SURF	STA	TIME
1	0.127241D-01	9	2	3	0.105800D-02
2	0.406115D-02	12	1	3	0.110000D-02
INTERFACE	0.309256D-02	10	1	2	0.100600D-02
SUBSTRUCTURE	LARGEST ADD. PT. STRAIN	ELEM	ADD. PT.	TIME	SURFACE
1	0.907227D-02	9	1	0.104600D-02	2
2	0.103464D-02	11	2	0.104200D-02	1
INTERFACE	0.134700D-02	13	3	0.102200D-02	1
SUBSTRUCTURE	LARGEST NODAL STRAIN	NODE	SURF	TIME	
1	0.881660D-02	8	1	0.102200D-02	
2	0.222096D-02	13	1	0.110000D-02	

CYCLE=	570	SI	STA 1	SO	SI	STA 2	SO	SI	STA 1	SO
ELEMENT										
1	-0.175194520-02	0.179219320-03	-0.087474670-03	-0.119822440-03	-0.214071590-03	-0.544568840-03				
	-0.685712940-03	0.0	-0.553548550-03	0.0	-0.179333210-03	0.0				
2	0.551624230-04	-0.780689100-03	-0.448136770-04	-0.666386730-03	-0.217720110-03	-0.635971940-03				
	-0.362763340-03	0.0	-0.355600200-03	0.0	-0.426846030-03	0.0				
3	-0.572756320-03	-0.416518990-03	-0.155304220-02	0.163615630-03	-0.255263900-02	0.627452730-03				
	-0.494617660-03	0.0	-0.694713300-03	0.0	-0.962593120-03	0.0				
4	-0.285966550-02	0.934647460-03	-0.234791830-02	0.410443530-03	-0.166705380-02	0.116807990-03				
	-0.962509020-03	0.0	-0.968737400-03	0.0	-0.775122930-03	0.0				
5	-0.319522270-03	-0.862357810-03	-0.284700460-02	-0.273471550-02	0.579322780-02	-0.445329930-02				
	-0.590440340-03	0.0	-0.561445280-04	0.0	0.669964260-03	0.0				
6	0.719550970-02	-0.596892740-02	0.728774270-02	-0.554712040-02	0.700462490-02	-0.548549070-02				
	0.613291130-03	0.0	0.870311130-03	0.0	0.759567110-03	0.0				
7	0.541951990-02	-0.448627240-02	0.18555960-02	-0.243598890-02	-0.968358140-03	-0.117945370-03				
	0.466522240-03	0.0	-0.790214650-03	0.0	-0.543151770-03	0.0				
8	-0.265830620-02	0.541155730-03	-0.762991160-02	0.318213500-02	-0.122326360-01	0.538954480-02				
	-0.105847520-02	0.0	-0.222188810-02	0.0	-0.342154570-02	0.0				
9	-0.132714480-01	0.577222680-02	-0.152570110-01	0.714489550-02	-0.163726800-01	0.864261200-02				
	-0.365061060-02	0.0	-0.405605750-02	0.0	-0.385503380-02	0.0				
10	-0.610049920-02	0.154228330-02	0.796496610-02	-0.480048360-02	0.925409920-02	-0.211161040-01				
	-0.227910790-02	0.0	0.158224120-02	0.0	-0.593134220-02	0.0				
11	0.942704040-03	-0.354261210-03	0.122851120-02	-0.147706380-02	0.203282370-02	-0.208202490-02				
	0.261233310-02	-0.243452910-02	0.339261470-02	-0.329922200-02	0.422367240-02	-0.411513900-02				
12	0.980530260-04	-0.210008920-02	-0.278295390-03	-0.121247080-02	-0.152277400-02	-0.317112340-03				
	-0.559729450-03	0.0	-0.745383300-03	0.0	-0.919943150-03	0.0				
13	-0.136990840-02	-0.559738130-03	-0.360627290-04	-0.118259400-02	0.121269000-02	-0.189552640-02				
	-0.964822450-03	0.0	-0.609128340-03	0.0	-0.341418200-03	0.0				
14	0.149807050-02	-0.201917100-02	0.110682330-02	-0.170927730-02	0.753422100-03	-0.137522430-02				
	-0.260540270-03	0.0	-0.301227480-03	0.0	-0.310901080-03	0.0				
15	0.325367730-01	-0.111750630-02	-0.547205690-03	-0.418377860-03	-0.150811980-02	0.193376970-03				
	-0.396269460-03	0.0	-0.482791770-01	0.0	-0.657371420-03	0.0				
16	-0.166185680-02	0.460378250-03	-0.823195750-03	0.173830870-04	0.418160920-04	-0.395446500-03				
	-0.600739270-03	0.0	-0.402988330-03	0.0	-0.176815200-03	0.0				
17	0.298528580-03	-0.444761420-03	0.849206270-04	-0.178246490-03	-0.236819400-03	-0.229131730-04				
	-0.731164200-04	0.0	-0.466629300-04	0.0	-0.129866290-03	0.0				

CYCLE=	570	SI	SO	EI	EO
STRAIN AT ADDITIONAL POINTS					
1	-0.154068950-01	0.721695860-02	-0.155274460-01	0.719110260-02	
	-0.440731240-02	0.0			
2	0.122851120-02	-0.147706380-02	0.122775750-02	-0.147815630-02	
	0.122716200-02	-0.220170320-02	0.122641000-02	-0.220413230-02	
3	-0.487270570-03	0.0			

## ENERGY AND WORK AT THE END OF TIME CYCLE 570

## FRAGMENT KINETIC ENERGY

1 0.136119D+04

J= 570 TIME (SEC.) = 0.114000D-02 TIME AFTER INITIAL IMPACT = 0.174000D-03  
WORK INPUT INTO RING (IN.-LB.) = 0.374054D+03  
RING KINETIC ENERGY (IN.-LB.) = 0.977968D+02  
RING ELASTIC ENERGY (IN.-LB.) = 0.127748D+03  
RING PLASTIC WORK (IN.-LB.) = 0.126400D+03  
ENERGY STORED IN THE ELASTIC RESTRAINTS (IN.-LB.) = 0.221101D+02

I	V	W	PSI	CHI	COPY	COPZ	L	M	STRAIN(IN)	STRAIN(OUT)
1	0.0	0.0	0.22600-02	-0.13460-02	0.0	0.0	-0.3801D+04	-0.2636D+03	-0.1657D-02	-0.4016D-03
2	-0.7642D-03	-0.1317D-03	-0.7320D-03	-0.1547D-03	0.9992D+00	-0.1317D-03	-0.3408D+04	-0.4329D+03	-0.5644D-04	-0.4483D-03
3	-0.9458D-03	0.4395D-03	0.1570D-02	-0.3734D-03	0.1999D+01	0.4395D-03	-0.3552D+04	-0.1152D+03	-0.3298D-03	-0.4991D-03
4	-0.2125D-02	-0.7660D-04	-0.5296D-02	-0.1963D-02	0.2998D+01	-0.7660D-04	-0.4258D+04	-0.7172D+02	-0.2428D-02	-0.5038D-03
5	-0.3813D-02	-0.1222D-01	-0.1729D-01	-0.1212D-02	0.3996D+01	-0.1222D-01	-0.3834D+04	-0.7927D+03	-0.1218D-02	-0.5924D-03
6	-0.2473D-02	-0.2140D-01	0.9290D-02	0.3729D-02	0.4998D+01	-0.2140D-01	-0.3774D+04	-0.1109D+04	0.5325D-02	-0.8642D-03
7	0.3901D-03	0.2145D-01	0.7684D-01	0.8073D-03	0.6000D+01	0.2145D-01	-0.4661D+04	-0.4856D+03	0.5261D-02	-0.7429D-03
8	-0.3305D-02	0.1175D+00	0.1021D+00	-0.6350D-02	0.6997D+01	0.1175D+00	-0.3621D+04	0.2552D+03	-0.1312D-02	-0.5399D-03
9	-0.1143D-01	0.1947D+00	0.3001D-01	-0.8832D-02	0.7989D+01	0.1947D+00	-0.2600D+04	0.1637D+03	-0.1070D-01	-0.1272D-02
10	-0.2341D-01	0.1455D+00	-0.1423D+00	-0.2005D-01	0.8977D+01	0.1455D+00	-0.6696D+03	-0.2928D+03	-0.1221D-01	-0.2252D-02
11	-0.3034D-01	0.2227D-01	-0.2627D-01	0.1663D-03	0.9970D+01	0.2227D-01	-0.1442D+04	-0.1047D+04	0.1891D-02	-0.3517D-02
12	0.6945D-02	0.9245D-02	-0.1870D-01	-0.7099D-04	0.1049D+02	0.1010D+01	0.5419D+03	-0.2589D+04	0.1240D-02	-0.1032D-02
13	0.0	0.0	0.0	0.7162D-04	0.1150D+02	0.1500D+01	-0.2514D+04	-0.1122D+03	0.2276D-02	-0.2133D-02
14	-0.3285D-01	0.8771D-03	-0.1810D-01	-0.1664D-02	0.1084D+02	-0.6939D-01	-0.2192D+04	-0.1045D+03	-0.1699D-02	-0.8979D-03
15	-0.3153D-01	-0.1946D-01	-0.8081D-02	0.6892D-03	0.1167D+02	-0.3090D+00	-0.1885D+04	-0.1265D+03	0.1185D-02	-0.6652D-03
16	-0.2746D-01	-0.1977D-01	0.1653D-01	0.6052D-05	0.1247D+02	-0.6733D+00	-0.1367D+04	-0.4824D+02	0.3821D-01	-0.5757D-03
17	-0.2569D-01	-0.7856D-02	0.1540D-01	-0.1431D-02	0.1319D+02	-0.1159D+01	-0.8794D+03	-0.1585D+02	-0.1652D-02	-0.4386D-03
18	-0.2530D-01	-0.4177D-02	0.8056D-02	0.1039D-03	0.1391D+02	-0.1769D+01	-0.2304D+03	-0.1384D+02	0.2421D-03	-0.1809D-03
19	-0.2498D-01	0.2715D-03	0.1016D-01	-0.3325D-03	0.1432D+02	-0.2478D+01			-0.3229D-03	-0.1468D-03
FRAG NO. = FCGU = FCGW = ALFA = FRUV = FRWV = FRAY =										
1	0.897307D+01	-0.479200D+00	0.0	0.260796D+04	0.508411D+03	0.0				

REACTIONS AT NODE		RV(LBS)		RM(LBS)		RM(ITN-LBS)	
1		0.372777D+04		0.494185D+03		0.0	
13		0.647512D+03		-0.146518D+04		0.340203D+04	
SUBSTRUCTURE	NSTR	ELE	SURF	STA	TIME		
1	0.127241D-01	9	2	3	0.105800D-02		
2	0.422367D-02	12	1	3	0.114000D-02		
INTERFACE	0.309256D-02	10	1	2	0.100600D-02		
SUBSTRUCTURE	LARGEST	ADD. PT.	TIME	ELEM	ADD. PT.	TIME	SURF
1	0.907227D-02	9	1	9	1	0.104600D-02	
2	0.122851D-02	11	2	11	2	0.114000D-02	
INTERFACE	0.134700D-02	13	3	13	3	0.102200D-02	
SUBSTRUCTURE	LARGEST	MODAL STRAIN	MODE	SURF	TIME		
1	0.881166D-02		8	1	0.102200D-02		
2	0.227614D-02		13	1	0.114700D-02		



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CYCLE= 590				SI STA 1 SD				SI STA 2 SD				SI STA 3 SD			
ELEMENT	SI	STA 1	SD	SI	STA 2	SD	SI	STA 3	SD	SI	STA 3	SD			
1	-0.464119480-03	0.15425107D-04	-0.59671976D-03	0.39369569D-03	-0.11623871D-02	0.68795616D-03									
	-0.54933205D-05	0.0	-0.10151204D-03	0.0	-0.23721546D-03	0.0									
2	-0.16453460D-02	0.10380165D-02	-0.25306419D-02	0.15197996D-02	-0.33165030D-02	0.20182821D-02									
	-0.30366474D-03	0.0	-0.50542117D-03	0.0	-0.64911148D-03	0.0									
3	-0.31265010D-02	0.19201119D-02	-0.18436784D-02	0.11612890D-02	-0.66979615D-03	0.41064366D-03									
	-0.60319455D-03	0.0	-0.34119473D-03	0.0	-0.12957625D-03	0.0									
4	0.21440206D-01	-0.10470314D-03	0.21407755D-02	-0.13126952D-02	0.19577261D-02	-0.24186647D-02									
	0.55049462D-04	0.0	0.41404017D-03	0.0	0.76953070D-03	0.0									
5	0.46955851D-02	-0.29024280D-02	0.53450025D-02	-0.31498063D-02	0.60536038D-02	-0.36371494D-02									
	0.89657855D-01	0.0	0.79759810D-03	0.0	0.12087272D-02	0.0									
6	0.64041718D-02	-0.42137401D-02	0.61221422D-02	-0.38831882D-02	0.58817234D-02	-0.35261393D-02									
	0.10957159D-02	0.0	0.11194770D-02	0.0	0.11777921D-02	0.0									
7	0.47760918D-02	-0.30721137D-02	0.11839211D-02	-0.67882800D-03	0.20930657D-02	0.15153623D-02									
	0.85199002D-01	0.0	0.25214652D-03	0.0	0.28885169D-03	0.0									
8	-0.40805429D-02	0.26385513D-02	-0.83215237D-02	0.44687363D-02	-0.11907802D-01	0.62925208D-02									
	0.72099580D-03	0.0	-0.19263937D-02	0.0	-0.28076408D-02	0.0									
9	-0.12235943D-01	0.62041077D-02	-0.13845309D-01	0.75247941D-02	-0.15126268D-01	0.86991239D-02									
	-0.30159177D-02	0.0	-0.31602573D-02	0.0	-0.32145821D-02	0.0									
10	-0.48569776D-02	0.20871750D-02	0.94764165D-02	-0.46186213D-02	0.10208259D-01	-0.22026451D-01									
	-0.13844493D-02	0.0	0.24288976D-02	0.0	-0.59090959D-02	0.0									
11	0.12210450D-02	-0.23024403D-03	0.78367649D-03	-0.13061040D-02	0.12497906D-02	-0.14784829D-02									
	0.18196420D-02	-0.17515230D-02	0.30318902D-02	-0.31747923D-02	0.44086878D-02	-0.44211901D-02									
12	0.18426137D-02	-0.18767723D-02	0.12056370D-02	-0.55282051D-03	-0.26806726D-03	-0.92733967D-04									
	-0.17077263D-04	0.0	0.32640823D-03	0.0	-0.18040062D-03	0.0									
13	-0.10785076D-02	0.56571591D-03	-0.67711747D-03	0.21372769D-03	-0.25514243D-03	-0.11264385D-03									
	-0.25639583D-03	0.0	-0.23169489D-03	0.0	-0.18389314D-03	0.0									
14	0.31981339D-03	-0.39755948D-03	0.14807476D-02	-0.12030637D-02	0.27212063D-02	-0.19404351D-02									
	-0.38863042D-04	0.0	0.13884196D-03	0.0	0.39038559D-03	0.0									
15	0.24391513D-02	-0.18157405D-02	0.68857261D-03	-0.77564357D-03	-0.10007060D-02	0.37921375D-03									
	0.34086530D-03	0.0	-0.43535478D-04	0.0	-0.31074613D-03	0.0									
16	-0.14407966D-02	0.53006939D-03	-0.11089650D-02	0.41872369D-03	-0.76436652D-03	0.32655680D-03									
	-0.45516361D-03	0.0	-0.34512064D-03	0.0	-0.21890486D-03	0.0									
17	-0.42853892D-03	0.42042916D-04	-0.14706560D-03	0.46665880D-04	-0.89660796D-05	-0.94198514D-04									
	-0.19324800D-03	0.0	-0.50199860D-04	0.0	-0.51582297D-04	0.0									

CYCLE= 590  
 STRAIN AT ADDITIONAL POINTS

	SI	SD	EI	EO
1	-0.13986332D-01	0.75910048D-02	-0.14085533D-01	0.75624097D-02
	-0.34955930D-02	0.0		
2	0.78167674D-03	-0.13061040D-02	0.78336991D-03	-0.13069580D-02
3	0.19082549D-02	-0.21311487D-02	0.19064377D-02	-0.21334245D-02
	-0.11144690D-03	0.0		

# ENERGY AND WORK AT THE END OF TIME CYCLE 590

FRAGMENT	KINETIC ENERGY
1	0.136119D+04

J= 590 TIME (SEC.) = 0.118000D-02 TIME AFTER INITIAL IMPACT = 0.214000D-03  
 WORK INPUT INTO RING (IN.-LB.) = 0.374054D+03  
 RING KINETIC ENERGY (IN.-LB.) = 0.103389D+03  
 RING ELASTIC ENERGY (IN.-LB.) = 0.115838D+03  
 RING PLASTIC WORK (IN.-LB.) = 0.131968D+03  
 ENERGY STORED IN THE ELASTIC RESTRAINTS (IN.-LB.) = 0.228596D+02

I	V	W	PSI	CHI	COPY	COPZ	L	M	STRAIN(IN)	STRAIN(OUT)
1	0.0	0.0	0.8729D-02	0.2433D-04	0.0	0.0	0.1626D+03	0.1845D+03	0.8639D-04	-0.9458D-05
2	-0.3870D-03	0.7697D-02	0.5313D-02	-0.8206D-03	0.9996D+00	0.7697D-02	-0.9407D+02	0.5823D+03	-0.1079D-02	0.1165D-04
3	-0.1894D-02	0.6658D-02	-0.9688D-02	-0.2147D-02	0.1998D+01	0.6658D-02	0.1824D+03	0.3933D+03	-0.2807D-02	0.3169D-04
4	-0.3166D-02	-0.1067D-01	-0.2171D-01	-0.4535D-03	0.2997D+01	-0.1067D-01	-0.4534D+02	-0.3700D+03	-0.2912D-03	0.2692D-05
5	-0.2063D-02	-0.2781D-01	-0.6693D-02	0.2660D-02	0.3998D+01	-0.2781D-01	-0.3797D+03	-0.7981D+03	0.3589D-02	-0.2257D-04
6	0.9767D-03	-0.1520D-01	0.3471D-01	0.3191D-02	0.5001D+01	-0.1520D-01	-0.4725D+03	-0.6712D+03	0.5096D-02	-0.9411D-04
7	0.2614D-02	0.4606D-01	0.8737D-01	-0.3096D-03	0.6003D+01	0.4606D-01	-0.4695D+03	-0.8118D+02	0.4690D-02	-0.4095D-04
8	-0.1836D-02	0.1461D+00	0.9833D-01	-0.6569D-02	0.6998D+01	0.1461D+00	-0.6310D+03	0.4638D+03	-0.2334D-02	0.1491D-03
9	-0.9068D-02	0.2109D+00	0.1306D-01	-0.7758D-02	0.7991D+01	0.2109D+00	0.3296D+03	0.2703D+03	-0.9965D-02	-0.6776D-03
10	-0.2368D-01	0.1484D+00	-0.1513D+00	-0.2063D-01	0.8979D+01	0.1484D+00	0.1908D+04	-0.2055D+03	-0.1135D-01	-0.1834D-02
11	-0.2732D-01	0.2085D-01	-0.2319D-01	0.6158D-03	0.9973D+01	0.2085D-01	-0.3032D+04	-0.9094D+03	0.2388D-02	-0.3465D-02
12	0.6355D-02	0.9111D-02	-0.1735D-01	-0.5163D-04	0.1049D+02	0.1010D+01	-0.8292D+03	-0.2401D+04	0.8156D-03	-0.2343D-02
13	0.0	0.0	0.0	0.5527D-04	0.1150D+02	0.1500D+01	0.3282D+03	-0.2304D+02	0.2454D-02	-0.2591D-03
14	-0.2304D-01	0.5587D-02	-0.7779D-02	-0.7767D-03	0.1084D+02	-0.6542D-01	-0.3604D+03	0.4453D+01	-0.9084D-03	-0.1660D-03
15	-0.2714D-01	-0.1096D-01	-0.1557D-01	-0.2456D-03	0.1168D+02	-0.3019D+00	-0.5506D+03	-0.7426D+02	-0.1106D-03	-0.6114D-04
16	-0.2525D-01	-0.2234D-01	0.7983D-02	-0.1852D-02	0.1247D+02	-0.6766D+00	-0.6494D+03	-0.5349D+02	0.2533D-02	-0.2131D-03
17	-0.2218D-01	-0.9293D-02	0.2066D-01	-0.1235D-02	0.1319D+02	-0.1163D+01	-0.4652D+03	0.1332D+02	-0.1290D-02	-0.1244D-03
18	-0.2211D-01	-0.1662D-02	0.7315D-02	-0.4354D-03	0.1381D+02	-0.1770D+01	-0.7782D+02	0.9887D+00	-0.5033D-03	-0.9084D-04
19	-0.2209D-01	-0.3287D-03	0.5630D-02	-0.4413D-04	0.1473D+02	-0.2481D+01			-0.7435D-05	

FRAG NO. = FCGU = FCCW = ALFA = FRUV = FRWV = FRAV =

1	0.907739D+01	-0.458863D+00	0.0	0.260796D+04	0.508411D+03	0.0
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REACTIONS AT NODE	RVI(LBS)	RWI(LBS)	RM(IN-LBS)
1	-0.986779D+02	-0.344694D+03	0.0
13	-0.539901D+03	-0.224871D+04	0.363887D+04

SUBSTRUCTURE	MSTR	ELE	SURF	STA	TIME
1	0.127241D-01	9	2	3	0.105800D-02
2	0.440869D-02	12	1	3	0.118000D-02
INTERFACE	0.309256D-02	10	1	2	0.100600D-02

SUBSTRUCTURE	LARGEST ADD. PT. STRAIN	ELEM	ADD. PT.	TIME	SURFACE
1	0.907227D-02	9	1	0.104600D-02	2
2	0.129943D-02	11	2	0.115000D-02	1
INTERFACE	0.134700D-02	13	3	0.102200D-02	1

SUBSTRUCTURE	LARGEST NODAL STRAIN	NODE	SURF	TIME
1	0.881166D-02	8	1	0.102200D-02
2	0.245358D-02	13	1	0.116000D-02

IMPACT NO. 2 TIME 0.121800D-02 DURING CYCLE 610 ELEM 10 FRAG 1 DISTANCE 0.271727D+00  
 F+AG 1 TC= 0.1239D+04 RE= 0.0 TOE= 0.1239D+04 FRAG

IMPACT NO. 1 TIME 0.129600D-02 DURING CYCLE 649 ELEM 10 FRAG 1 DISTANCE 0.492054D+00  
FRAG 1 TR= 0.1219D+04 RC= 0.0 TRE= 0.1219D+04 FRAG

CYCLE= 770  
ELEMENT SI STA 1 SO SI STA 2 SO SI STA 3 SO  
1 -0.46197173D-03 0.28005973D-03 -0.45569344D-03 0.23514265D-03 -0.19627964D-03 0.44506472D-03  
2 -0.90956000D-04 0.0 -0.11027540D-01 0.0 0.12437254D-03 0.0  
3 0.89721309D-03 -0.36493890D-03 0.31327935D-02 -0.12998239D-02 0.49562585D-02 -0.24629910D-02  
4 0.26613709D-03 0.0 0.91648481D-03 0.0 0.12466838D-02 0.0  
5 0.54532147D-02 -0.28920737D-02 0.54056084D-02 -0.29476083D-02 0.52597097D-02 -0.30853917D-02  
6 0.12805730D-02 0.0 0.12290001D-02 0.0 0.10871560D-02 0.0  
7 0.54554887D-02 -0.32016506D-02 0.63618311D-02 -0.36680970D-02 0.72829987D-02 -0.40082541D-02  
8 0.11269190D-02 0.0 0.13468671D-02 0.0 0.16373723D-02 0.0  
9 0.67157447D-02 -0.37718134D-02 0.35956102D-02 -0.17600065D-02 0.50270087D-03 -0.72041035D-04  
10 0.14719656D-02 0.0 0.91780187D-03 0.0 0.21532992D-03 0.0  
11 -0.11710932D-02 0.75627521D-03 -0.35045750D-02 0.21127534D-02 -0.53556039D-02 0.36446622D-02  
12 -0.20740899D-01 0.0 -0.69591081D-03 0.0 -0.85547088D-03 0.0  
13 -0.59475807D-02 0.37255048D-02 -0.78805921D-02 0.50654446D-02 -0.95906874D-02 0.62716247D-02  
14 -0.11110380D-02 0.0 -0.14075737D-02 0.0 -0.16495313D-02 0.0  
15 -0.88116097D-02 0.55310191D-02 -0.51523550D-02 0.35202827D-02 -0.17871754D-02 0.17337911D-02  
16 -0.16402953D-02 0.0 -0.81747642D-03 0.0 -0.26692146D-04 0.0  
17 -0.13225767D-02 0.57324737D-03 -0.47615426D-02 0.35150089D-02 -0.78177177D-02 0.60664737D-02  
18 -0.37466465D-03 0.0 -0.62326687D-03 0.0 -0.87562200D-03 0.0  
19 -0.65893590D-03 0.15735201D-02 0.92950038D-02 -0.33632785D-02 0.79664984D-02 -0.17504234D-01  
20 -0.45842120D-03 0.0 0.29658626D-02 0.0 -0.47688677D-02 0.0  
21 -0.63475093D-03 0.26397642D-03 0.32828320D-03 0.12683762D-03 0.89919747D-03 -0.40262010D-03  
22 0.79710561D-03 -0.34574510D-03 0.26700445D-02 -0.19233042D-02 0.45659070D-02 -0.34777912D-02  
23 -0.15244712D-03 -0.49586736D-03 0.69654610D-01 0.46149630D-03 0.20491982D-03 0.38126267D-03  
24 -0.17171012D-03 0.0 0.57825450D-03 0.0 0.28307124D-03 0.0  
25 0.68970861D-04 0.51077605D-03 0.92457893D-03 0.12931563D-03 0.14811440D-02 -0.56026104D-03  
26 0.28981866D-03 0.0 0.52687280D-03 0.0 0.46044150D-03 0.0  
27 0.12160680D-02 0.10700397D-03 0.12569492D-02 -0.35232168D-03 0.17778288D-02 0.31009070D-03  
28 0.66153539D-03 0.0 0.45230877D-03 0.0 0.72386905D-03 0.0  
29 0.16557471D-02 -0.63366168D-03 -0.21970393D-03 0.68729993D-03 -0.22421432D-02 0.18649936D-02  
30 0.51104271D-03 0.0 0.23379800D-03 0.0 -0.18857476D-03 0.0  
31 -0.20680442D-02 0.16128619D-02 0.14663770D-03 0.37855155D-03 -0.21442174D-02 -0.10748022D-02  
32 -0.22759116D-03 0.0 0.26259463D-03 0.0 0.53470761D-03 0.0  
33 0.23960959D-02 -0.11060100D-02 0.16211067D-02 -0.86395217D-03 0.10495250D-02 -0.42617608D-03  
34 0.64504297D-03 0.0 0.37857729D-03 0.0 0.31157446D-03 0.0

CYCLE= 770  
STRAIN AT ADDITIONAL POINTS  
1 -0.50309014D-02 0.37076383D-02 -0.50436204D-02 0.3777904D-02  
2 -0.78227550D-03 0.0 0.32822933D-03 0.12682958D-03  
3 0.32828320D-03 0.12683762D-03 -0.26262628D-04 -0.74388372D-03  
4 -0.26762283D-04 -0.74360704D-03 0.0

ENERGY AND WORK AT THE END OF TIME CYCLE 770

FRAGMENT KINETIC ENERGY

1 0.121866D+04

J= 770 TIME (SEC.) = 0.154000D-02 TIME AFTER INITIAL IMPACT = 0.574000D-03  
WORK INPUT INTO RING (IN.-LB.) = 0.516582D+03  
RING KINETIC ENERGY (IN.-LB.) = 0.831107D+02  
RING ELASTIC ENERGY (IN.-LB.) = 0.119100D+03  
RING PLASTIC WORK (IN.-LB.) = 0.297698D+03  
ENERGY STORED IN THE ELASTIC RESTRAINTS (IN.-LB.) = 0.166737D+02

1 V M PSI CHI COPY COPZ L M STRAIN(IN) STRAIN(OUT)  
1 0.0 0.0 -0.1782D-01 -0.3857D-03 0.0 0.0 -0.3210D+03 0.9876D+02 -0.3216D-01 0.5704D-04  
2 -0.3439D-03 -0.1903D-01 -0.2020D-01 -0.1204D-03 0.9996D+00 -0.1903D-01 0.6599D+03 0.1957D+03 0.6343D-04 0.1440D-03  
3 0.1409D-02 -0.3357D-01 -0.3781D-02 0.3349D-02 0.2001D+01 -0.3357D-01 0.3490D+03 0.8537D+03 0.4398D-02 0.2501D-03  
4 0.4568D-02 -0.2087D-01 0.2963D-01 0.2674D-02 0.3005D+01 -0.2087D-01 0.2388D+03 0.9568D+03 0.4152D-02 0.8065D-05  
5 0.7107D-02 0.2902D-01 0.7324D-01 0.1987D-02 0.4007D+01 0.2902D-01 0.2734D+03 -0.3012D+03 0.6146D-02 0.2251D-03  
6 0.1850D-02 0.1890D+00 0.9874D-01 -0.5120D-02 0.5005D+01 0.1890D+00 0.1735D+02 0.4936D+03 -0.3285D-03 0.5809D-04  
7 0.7501D-03 0.2081D+00 0.6918D-01 -0.5685D-02 0.5990D+01 0.2081D+00 0.7437D+03 0.7260D+03 -0.4437D-02 0.2088D-03  
8 -0.6255D-02 0.2439D+00 -0.6975D-02 -0.5803D-02 0.6994D+01 0.2439D+00 0.1786D+04 0.4003D+03 -0.7090D-02 0.3814D-03  
9 -0.1336D-01 0.2009D+00 -0.6481D-01 -0.2536D-02 0.7970D+01 0.2009D+00 0.3256D+04 -0.5614D+02 -0.5584D-03 -0.5560D-04  
10 -0.1690D-01 0.1150D+00 -0.1285D+00 -0.1287D-01 0.8983D+01 0.1150D+00 0.9820D+03 -0.3179D+02 -0.5326D-02 -0.3456D-03  
11 -0.1938D-01 0.1519D-01 -0.1340D-01 -0.4691D-03 0.9981D+01 0.1519D-01 0.2641D+04 0.7793D+02 0.4932D-03 -0.1149D-02  
12 0.5398D-02 0.7823D-02 -0.1284D-01 0.9850D-04 0.1050D+02 0.1008D+01 0.4133D+04 -0.1777D+04 0.4010D-03 -0.3919D-04  
13 0.0 0.0 0.0 0.6077D-03 0.1150D+02 0.1500D+01 0.1610D+04 0.5517D+02 0.2870D-02 -0.1654D-02  
14 -0.2057D-01 0.1540D-02 -0.1110D-01 -0.1433D-03 0.1085D+02 -0.7086D-01 0.1758D+04 0.3085D+02 -0.1461D-03 0.1204D-03  
15 -0.1916D-01 -0.1082D-01 -0.4316D-02 0.1024D-02 0.1169D+02 -0.3052D+00 0.7498D+03 -0.4717D+01 0.1244D-02 0.4021D-03  
16 -0.1610D-01 -0.1238D-01 0.9703D-02 0.1429D-02 0.1248D+02 -0.6725D+00 0.1007D+04 0.5564D+02 0.1819D-02 0.4511D-03  
17 -0.1479D-01 -0.4769D-02 0.1780D-02 -0.1676D-02 0.1320D+02 -0.1164D+01 0.8511D+03 0.3629D+02 -0.2281D-02 0.1498D-03  
18 -0.1322D-01 -0.1226D-01 -0.2396D-03 0.1757D-02 0.1381D+02 -0.1784D+01 0.2218D+03 -0.4155D+02 0.2260D-02 0.2539D-03  
19 -0.1074D-01 -0.3387D-02 0.2147D-01 0.3501D-03 0.1432D+02 -0.2492D+01 0.2218D+03 -0.4155D+02 0.7286D-03 0.1367D-03  
FRAG NO.= FCGU = FCGW = ALFA = FRUV = FRWV = FRAV =  
1 0.997591D+01 -0.563367D+00 0.0 0.246631D+04 -0.487898D+03 0.0

REACTIONS AT NODE  
1 RV(LBS) RM(LBS) RM(IN-LBS)  
13 0.106878D+03 -0.257016D+03 0.0  
0.397745D+04 -0.127764D+04 0.203428D+04

SUBSTRUCTURE MSTR ELE SURF STA TIME  
1 0.179342D-01 9 2 3 0.126400D-02  
2 0.790080D-02 12 1 3 0.133400D-02  
INTERFACE 0.529821D-02 10 1 2 0.122600D-02  
SUBSTRUCTURE LARGEST ADD. PT. STRAIN ELEM ADD. PT. TIME SURFACE  
1 0.107466D-01 9 1 0.125400D-02 2  
2 0.185545D-02 11 2 0.127400D-02 1  
INTERFACE 0.161777D-02 13 1 0.125200D-02 1  
SUBSTRUCTURE LARGEST NODAL STRAIN NODE SURF TIME  
1 0.881166D-02 8 1 0.102200D-02  
2 0.494756D-02 13 1 0.131400D-02

CYCL=	790	SI	STA 1	SN	SI	STA 2	SO	SI	STA 1	SN
ELEMENT										
1	0.14507210D-03	0.74626170D-04	-0.16691297D-04	0.17585144D-03	-0.12665095D-04	0.44784667D-03	0.0	0.20759080D-03	0.0	0.0
2	0.49314867D-03	0.8979053D-05	0.12947659D-02	-0.15109452D-03	0.17930761D-02	-0.5165891D-03	0.0	0.61070861D-03	0.0	0.0
3	0.24214440D-03	-0.10280170D-02	0.43577594D-02	-0.23981302D-02	0.62580451D-02	-0.35911841D-02	0.0	0.13134105D-02	0.0	0.0
4	0.69790603D-03	-0.42371385D-02	0.72241760D-02	-0.42422611D-02	0.71448660D-02	-0.42802614D-02	0.0	0.13477291D-02	0.0	0.0
5	0.13477291D-02	0.0	0.14705575D-02	0.0	0.15323176D-02	0.0	0.0	0.71437012D-03	0.0	0.0
6	0.64105340D-02	-0.37435617D-02	0.14740983D-02	-0.20386235D-02	0.15313260D-03	0.0	0.0	0.15313260D-03	0.0	0.0
7	-0.13194440D-02	0.0	0.17737400D-02	0.0	-0.04236324D-02	0.41827294D-02	0.0	0.0	0.0	0.0
8	-0.76926531D-03	-0.18494533D-04	-0.45162806D-02	0.24054946D-02	-0.21208060D-02	0.0	0.0	0.0	0.0	0.0
9	-0.46387920D-03	0.51661090D-02	-0.10553930D-02	0.0	-0.49695643D-02	0.46194356D-02	0.0	0.0	0.0	0.0
10	-0.97184129D-02	0.0	-0.49695643D-02	0.0	-0.78138599D-02	0.43555906D-02	0.0	0.0	0.0	0.0
11	-0.21754015D-02	0.14013529D-02	-0.52845964D-02	0.24232991D-02	-0.17291393D-02	0.0	0.0	0.0	0.0	0.0
12	-0.68788407D-02	0.0	-0.14308437D-02	0.0	-0.74232446D-02	0.14951590D-02	0.0	0.0	0.0	0.0
13	-0.17007440D-02	0.89357543D-03	-0.42221104D-02	0.15277759D-02	-0.12145428D-02	0.0	0.0	0.0	0.0	0.0
14	-0.36730236D-02	0.0	-0.13471671D-02	0.0	-0.42606071D-02	0.25007514D-02	0.0	0.0	0.0	0.0
15	-0.13897240D-02	0.0	-0.74313679D-03	0.0	-0.87982692D-03	0.0	0.0	0.0	0.0	0.0
16	0.79114171D-03	-0.74313679D-03	0.61751800D-02	-0.40646609D-02	0.72431100D-02	-0.13577170D-01	0.0	0.0	0.0	0.0
17	0.24074540D-04	0.0	0.11552596D-02	0.0	-0.41670012D-02	0.0	0.0	0.0	0.0	0.0
18	-0.71111760D-02	-0.17262110D-03	0.19667859D-01	0.20945718D-03	0.85978168D-03	-0.45541541D-03	0.0	0.0	0.0	0.0
19	0.70673174D-03	0.54904485D-03	0.28290014D-02	-0.22707106D-02	0.48733583D-02	-0.40107910D-02	0.0	0.0	0.0	0.0
20	-0.18409472D-02	0.59450086D-03	-0.14115219D-02	-0.44498190D-03	-0.22045139D-03	-0.71077892D-03	0.0	0.0	0.0	0.0
21	-0.62127317D-03	0.0	-0.93067692D-03	0.0	-0.46559016D-03	0.0	0.0	0.0	0.0	0.0
22	0.81175297D-03	-0.11137778D-02	-0.11401081D-02	-0.16422218D-02	0.14726302D-02	-0.17832449D-02	0.0	0.0	0.0	0.0
23	-0.40390046D-01	0.0	-0.72595676D-03	0.0	-0.19530734D-03	0.0	0.0	0.0	0.0	0.0
24	0.15152911D-02	-0.18128942D-02	0.12691293D-02	-0.15120024D-02	0.86402494D-03	-0.13577461D-02	0.0	0.0	0.0	0.0
25	-0.14840153D-03	0.0	-0.12143653D-03	0.0	-0.26161059D-03	0.0	0.0	0.0	0.0	0.0
26	-0.47016970D-03	-0.28092061D-03	-0.30202122D-02	0.10975248D-02	-0.52675044D-02	0.28041525D-02	0.0	0.0	0.0	0.0
27	-0.37554516D-03	0.0	-0.96118231D-03	0.0	-0.12316754D-02	0.0	0.0	0.0	0.0	0.0
28	-0.40528517D-02	0.18404457D-02	0.29318155D-03	-0.45465039D-03	0.43870539D-02	-0.30016317D-02	0.0	0.0	0.0	0.0
29	-0.11062056D-02	0.0	-0.80734421D-04	0.0	0.69271110D-03	0.0	0.0	0.0	0.0	0.0
30	0.50342114D-02	-0.31643610D-02	0.30959301D-02	-0.19563911D-02	0.11498813D-02	-0.78464991D-03	0.0	0.0	0.0	0.0
31	0.93613764D-03	0.0	0.57026850D-03	0.0	0.18261669D-03	0.0	0.0	0.0	0.0	0.0

CYCLE=	790	SI	SN	EI	EO
STRAIN AT ADDITIONAL POINTS					
1	-0.42461914D-02	0.15881904D-02	-0.42552450D-02	0.15869313D-02	
2	-0.14095497D-02	0.0	0.39659994D-03	0.20943545D-03	
3	-0.39667859D-03	0.20945718D-03	-0.18588460D-02	0.81863878D-03	
	-0.18571183D-02	0.81897387D-03			
	-0.51907224D-03	0.0			

ENERGY AND WORK AT THE END OF TIME CYCLE 790

FRAGMENT KINETIC ENERGY

1 0.121866D+04

J= 790 TIME (SEC.) = 0.158000D-02 TIME AFTER INITIAL IMPACT = 0.614000D-03  
 WORK INPUT INTO RING (IN.-LB.) = 0.516582D+03  
 RING KINETIC ENERGY (IN.-LB.) = 0.502939D+02  
 RING ELASTIC ENERGY (IN.-LB.) = 0.126456D+03  
 RING PLASTIC WORK (IN.-LB.) = 0.324631D+03  
 ENERGY STORED IN THE ELASTIC RESTRAINTS (IN.-LB.) = 0.152012D+02

I	V	W	PSI	CHI	COPY	COPZ	L	M	STRAIN(IN)	STRAIN(OUT)
1	0.0	0.0	-0.9104D-02	0.1525D-03	0.0	0.0	0.7106D+03	0.1294D+03	0.2134D-03	0.1356D-03
2	0.2439D-04	-0.9262D-02	-0.9817D-02	0.9400D-04	0.1000D+01	-0.9262D-02	0.8023D+03	0.2547D+03	0.1189D-03	0.2127D-03
3	0.8407D-03	-0.1720D-01	-0.4475D-02	0.1215D-02	0.2001D-01	-0.1720D-01	-0.4411D+02	-0.6994D+03	0.1543D-02	0.2739D-03
4	0.3463D-02	-0.1109D-01	0.2256D-01	0.3892D-02	0.3003D+01	-0.1109D-01	-0.1508D+03	-0.1127D+04	0.5524D-02	0.4534D-04
5	0.6572D-02	0.3586D-01	0.7241D-01	0.1815D-02	0.4007D+01	0.3586D-01	-0.1074D+04	-0.4203D+03	0.5715D-02	0.8444D-04
6	0.4636D-02	0.1259D+00	0.9866D-01	-0.4934D-02	0.5005D+01	0.1259D+00	-0.1059D+04	0.5077D+03	0.1210D-04	-0.2556D-03
7	-0.2140D-02	0.2133D+00	0.6273D-01	-0.7918D-02	0.5998D+01	0.2133D+00	-0.1750D+04	0.5247D+03	-0.7907D-02	-0.1921D-03
8	-0.8104D-02	0.2345D+00	-0.1770D-01	-0.4651D-02	0.6992D+01	0.2345D+00	-0.1423D+04	0.1776D+03	-0.5905D-02	-0.2207D-03
9	-0.1268D-01	0.1893D+00	-0.6909D-01	-0.4797D-02	0.7987D+01	0.1893D+00	-0.8942D+03	-0.3271D+03	-0.2960D-02	-0.7151D-03
10	-0.1419D-01	0.3947D-01	-0.1133D+00	-0.8846D-02	0.8991D+01	0.1702D-01	-0.3517D+04	-0.7243D+02	-0.2943D-02	-0.2486D-03
11	-0.2116D-01	0.1702D-01	-0.1478D-01	-0.1254D-02	0.9979D+01	0.1702D-01	-0.6924D+02	0.2087D-03	-0.2087D-03	-0.2564D-03
12	0.6133D-02	0.8558D-02	-0.1425D-01	-0.1289D-03	0.1050D+02	0.1009D+01	0.3240D+04	-0.1973D+04	0.2987D-03	-0.5161D-03
13	0.0	0.0	0.0	0.4604D-03	0.1150D+02	0.1500D+01	-0.2180D+04	-0.6924D+02	0.2987D-03	-0.2564D-03
14	-0.2329D-01	-0.5908D-02	-0.2322D-01	-0.1822D-03	0.1084D+02	-0.7774D-01	-0.1671D+04	-0.1189D+03	0.3567D-03	-0.4057D-03
15	-0.2040D-01	-0.1991D-01	0.1537D-02	0.7092D-03	0.1168D+02	-0.3133D+00	-0.1347D+04	-0.1058D+03	0.1140D-02	-0.5780D-03
16	-0.1710D-01	-0.1031D-01	0.2585D-01	-0.1680D-03	0.1248D+02	-0.6703D+00	-0.1345D+04	0.3251D+02	0.3567D-03	-0.4057D-03
17	-0.1847D-01	-0.3955D-04	-0.1015D-01	-0.3640D-02	0.1320D+02	-0.1158D+01	-0.5029D+03	-0.3368D+02	-0.4668D-02	-0.3846D-03
18	-0.1577D-01	-0.2015D-01	-0.1620D-02	0.3503D-02	0.1100D+02	-0.1786D+01	-0.1130D+03	-0.1062D+03	0.4668D-02	-0.5977D-04
19	-0.1106D-01	-0.1410D-02	0.4054D-01	-0.6649D-03	0.1432D+02	-0.2449D+01	-0.1130D+03	-0.1062D+03	0.2859D-03	-0.2249D-03
FKAG NO.	FCGU	FCGM	ALFA	FKUV	FRW	FRV				
1	0.100746D+02	-0.592879D+00	0.0	0.246631D+04	-0.487898D+03	0.0				

REACTIONS AT NODE	RV(LBS)	RW(LBS)	KM(IN-LBS)
1	-0.816222D+03	-0.345116D+03	0.0
13	0.268815D+04	-0.158427D+04	0.240503D+04

SUBSTRUCTURE	MSTR	ELE	SURF	STA	TIME
1	0.179342D-01	9	2	3	0.126400D-02
2	0.790080D-02	12	1	3	0.133400D-02
INTERFACE	0.529821D-02	10	1	2	0.122600D-02

SUBSTRUCTURE	LARGST	ADD. PT.	STRAIN	ELEM	ADD. PT.	TIME	SURFACE
1	0.107466D-01	9	1	1	0.125400D-02	2	
2	0.185450D-02	11	2	2	0.127400D-02	1	
INTERFACE	0.161777D-02	13	3	1	0.125200D-02	1	

SUBSTRUCTURE	LARGST	NODAL STRAIN	NODE	SURF	TIME
1	0.881166D-02	8	1	1	0.102200D-02
2	0.494756D-02	13	1	1	0.131400D-02

THE LARGEST COMPUTED STRAINS FOR EACH SUBSTRUCTURE--

MAIN AND BRANCHES -- ARE PRINTED BELOW, 1= INNER 2= OUTER SURF

SUBSTRUCTURE	MSTR	ELE	SURF	STA	TIME
1	0.179342D-01	9	2	3	0.126400D-02
2	0.790080D-02	12	1	3	0.133400D-02
INTERFACE	0.529821D-02	10	1	2	0.122600D-02

SUBSTRUCTURE	LARGST	ADD. PT.	STRAIN	ELEM	ADD. PT.	TIME	SURFACE
1	0.107466D-01	9	1	1	0.125400D-02	2	
2	0.185450D-02	11	2	2	0.127400D-02	1	
INTERFACE	0.161777D-02	13	3	1	0.125200D-02	1	

SUBSTRUCTURE	LARGST	NODAL STRAIN	NODE	SURF	TIME
1	0.881166D-02	8	1	1	0.102200D-02
2	0.494756D-02	13	1	1	0.131400D-02

NO CARDS PUNCHED DURING THIS RUN FOR CONTINUATION.

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TABLE

EXAMPLE PROBLEM RESULTS OBTAINED FROM SEVERAL SYSTEMS, COMPILERS, AND PROGRAM MODIFICATIONS FOR JET 5A AND CIVM-JET 5B (SEE SUBSECTIONS 7.1 AND 7.2)

PROGRAM	SYSTEM	COMPILER	J	TIME (SEC)	REACTIONS AT NODE 1			REACTIONS AT NODE 21			LARGEST STRAINS FOR EACH SUBSTRUCTURE					
					RV (LBS)	RW (LBS)	RM (IN-LBS)	RV (LBS)	RW (LBS)	RM (IN-LBS)	SUBS.	MSTR	ELE	SURF	STA	TIME (SEC)
JET 5A	IBM 370	G EXTEN AT MIT	150	0.000600	15026.1	0.0	15223.0	36925.5	0.0	-12355.7	1	0.123908	9	2	1	0.000600
	IBM 360	{ H EXTEN <sup>b</sup> H EXTEN <sup>a,b</sup> TSS <sup>a,b</sup>	150	0.000600	15026.1	0.0	15223.0	36925.5	0.0	-12355.7	1	0.123908	9	2	1	0.000600
			150	0.000600	15026.1	0.0	15223.0	36925.5	0.0	-12355.7	1	0.123908	9	2	1	0.000600
			150	0.000600	9304.59	0.0	15939.1	38072.8	0.0	-11465.6	1	0.124536	9	2	1	0.000600
	UNIVAC 1100/42	{ FOR.V <sup>a,b,c</sup> ASCII <sup>a,b</sup>	150	0.000600	5044.37	0.0	16854.9	33979.1	0.0	-12119.5	1	0.124189	9	2	1	0.000600
			150	0.000600	12396.0	0.0	15788.8	29090.4	0.0	-11940.2	1	0.123941	9	2	1	0.000600
CIVM-JET 5B	IBM 370	G EXTEN AT MIT	790	0.001580	REACTIONS AT NODE 1			REACTIONS AT NODE 13			1	0.0179342	9	2	3	0.001264
					-816.222	-345.116	0.0	2688.15	-1584.27	2405.03						
	IBM 360	{ H EXTEN <sup>b</sup> H EXTEN <sup>a,b</sup> TSS <sup>a,b</sup>	790	0.001580	-816.222	-345.116	0.0	2688.15	-1584.27	2405.03	1	0.0179342	9	2	3	0.001264
			790	0.001580	-816.222	-345.116	0.0	2688.15	-1584.27	2405.03	1	0.0179342	9	2	3	0.001264
			790	0.001580	-585.535	-321.497	0.0	2767.64	-1642.0	2477.13	1	0.0177578	9	2	3	0.001262
	UNIVAC 1100/42	ASCII <sup>a,b</sup>	790	0.001580	-237.605	-344.243	0.0	3269.89	-1635.11	2522.31	1	0.0178627	9	2	3	0.001262

a: NASA-Lewis elimination of nested indices.

b: NASA-Lewis addition of special symbol for index retention in subprogram PRINT.

c: NASA-Lewis segmentation (overlay).

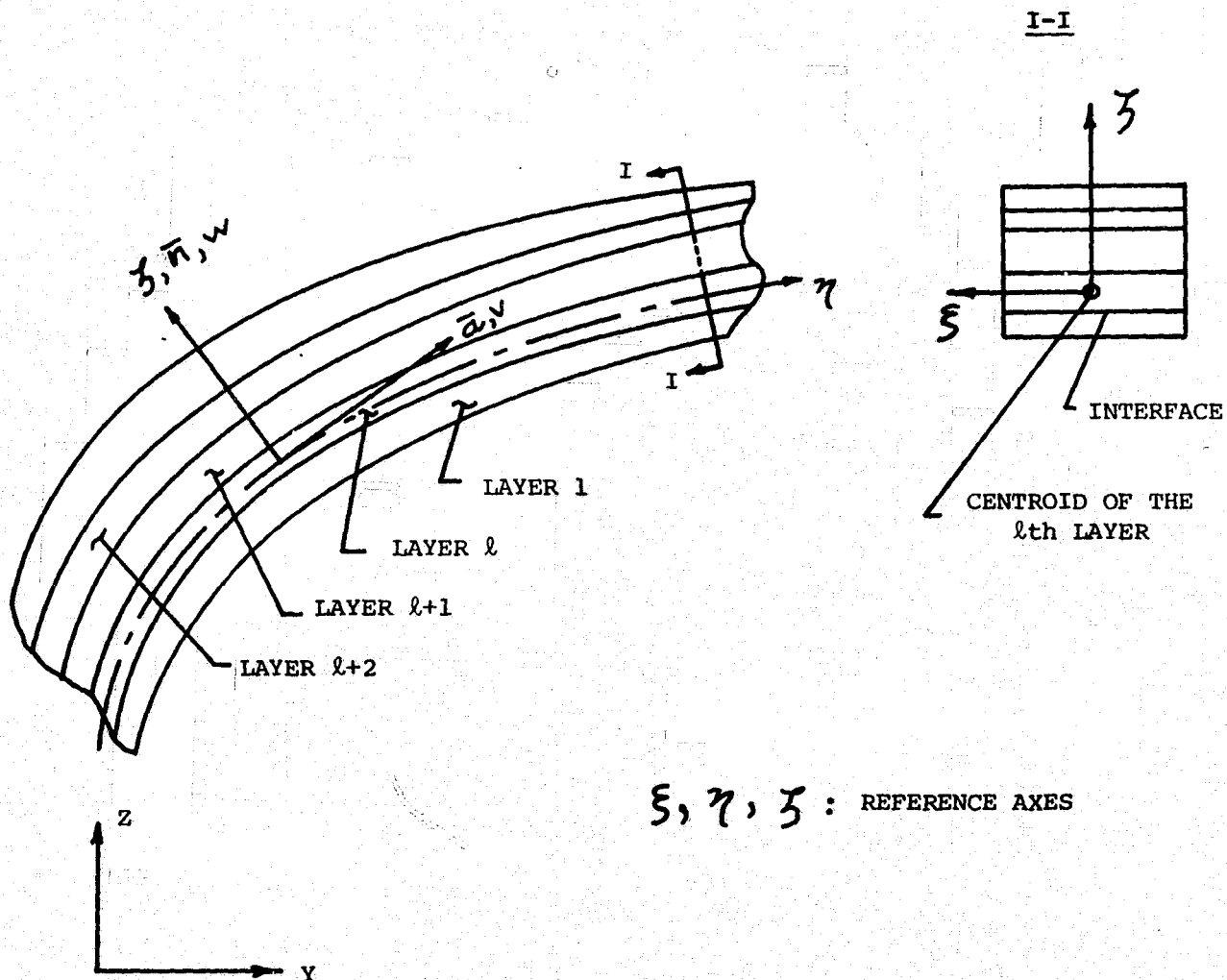
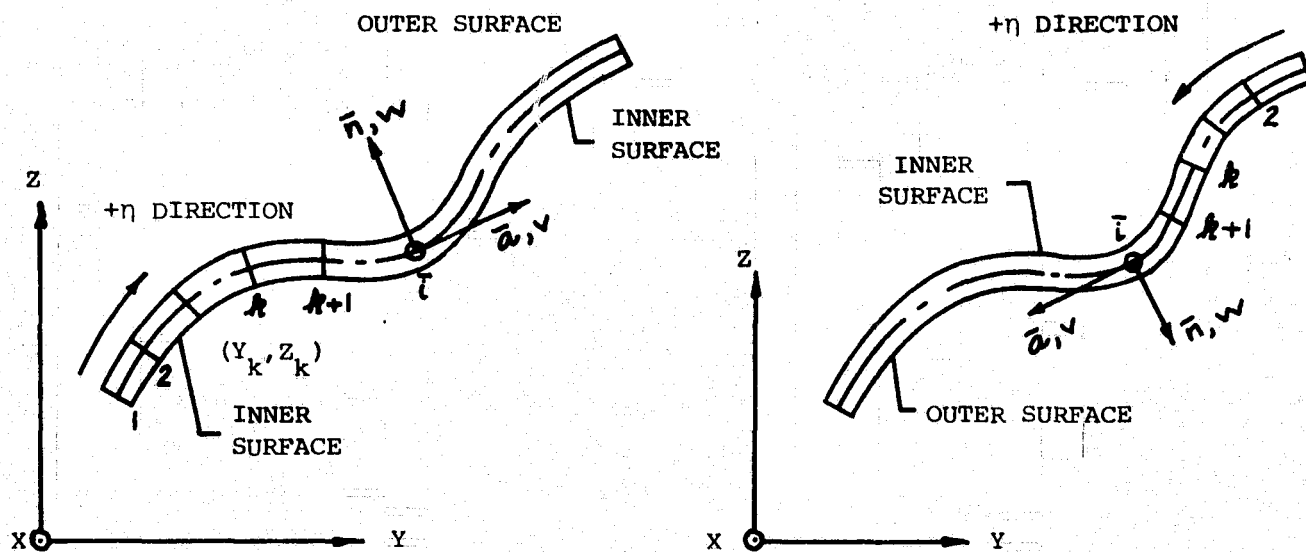


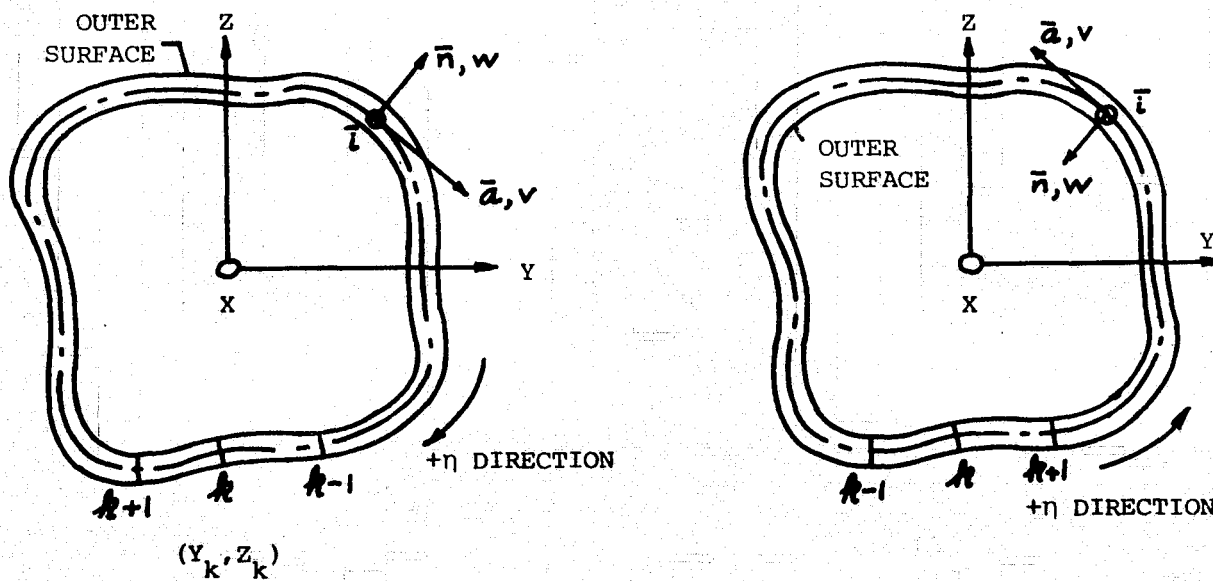
FIG. 1 ILLUSTRATION OF A MULTILAYER VARIABLE-THICKNESS, ARBITRARILY-CURVED BEAM

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OF POOR QUALITY

— RING CONTOUR  
- - - REFERENCE AXIS



(a) Variable-Thickness Arbitrarily-Curved Partial Ring

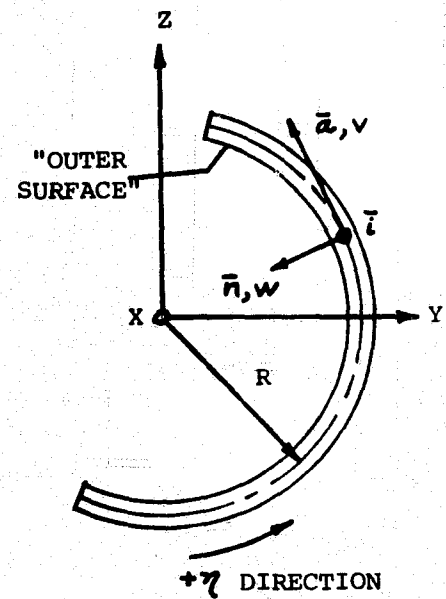
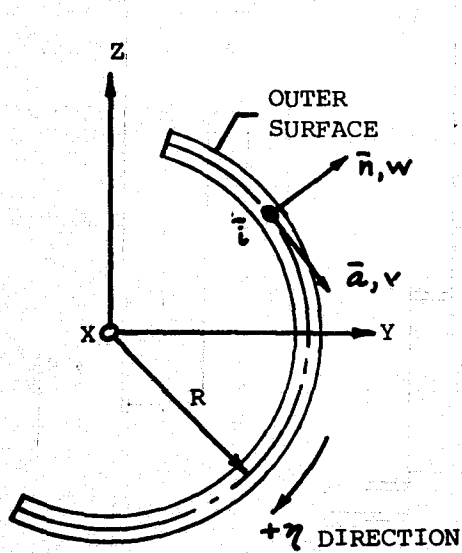


(b) Variable-Thickness Arbitrarily-Curved Complete Ring

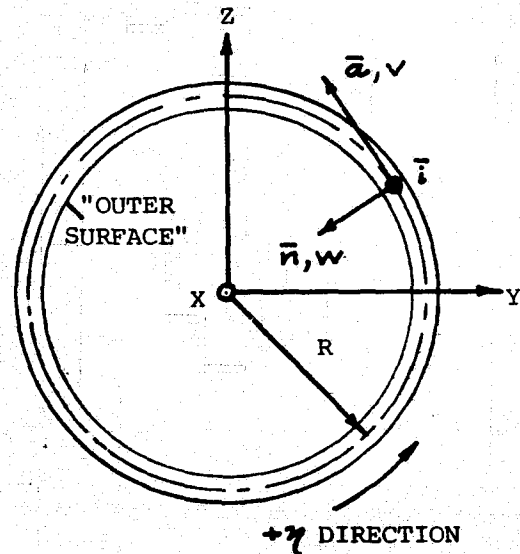
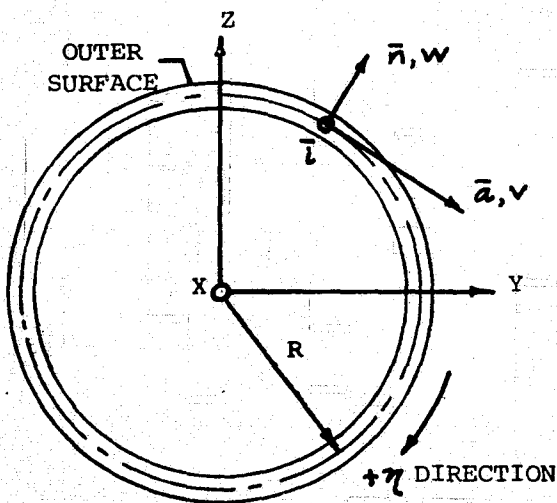
FIG. 2 EXAMPLE GEOMETRICAL SHAPES OF STRUCTURAL RINGS  
ANALYZED BY THE JET 5 PROGRAM



— RING CONTOUR  
 - - - REFERENCE AXIS



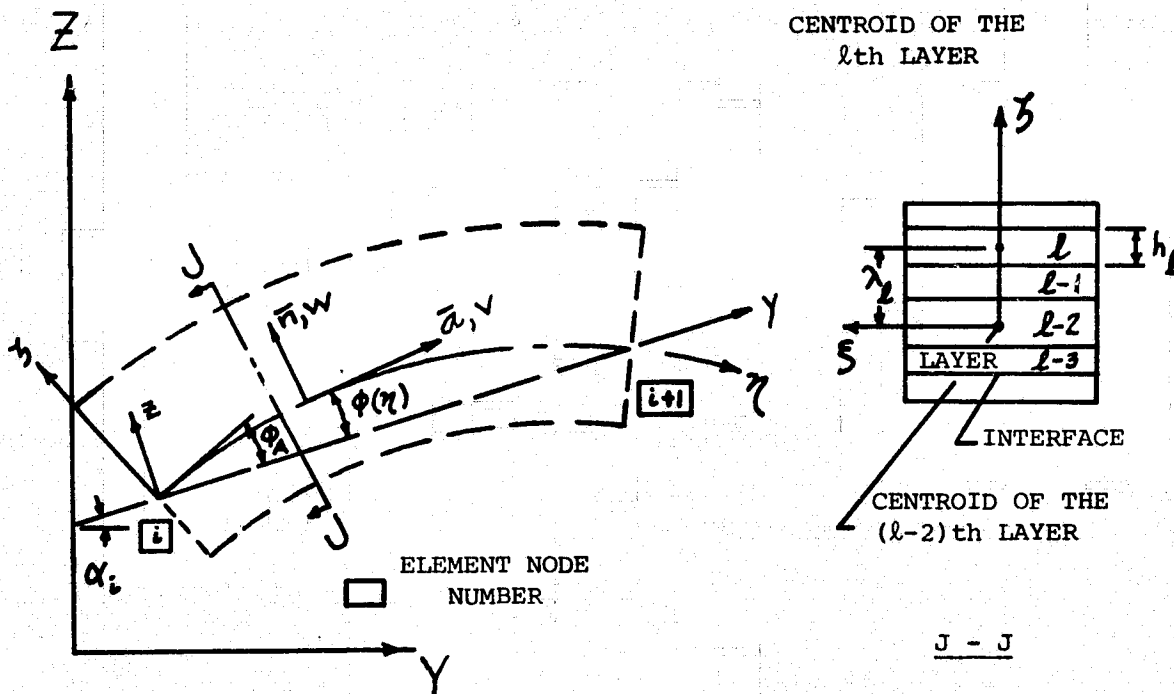
(C) Variable-Thickness Partial Circular Ring



(d) Variable-Thickness Complete Circular Ring

FIG. 2 CONCLUDED

ORIGINAL PAGE IS  
OF POOR QUALITY



$$-15^\circ \leq \phi_{i+1} - \phi_i \leq 0$$

$$-180^\circ < \phi_i \leq 180^\circ$$

$$\phi(\eta) = b_0 + b_1 \eta + b_2 \eta^2$$

$$h_l = h_{i,l} \left(1 - \frac{\eta}{\eta_i}\right) + h_{i+1,l} \frac{\eta}{\eta_i}$$

#### LOCAL SYSTEM

$\xi, \eta, \zeta$ : COORDINATES

$v, w, \psi, \chi$ : DISPLACEMENTS

$q_1, q_2, \dots, q_8$ : ELEMENT GENERALIZED DISPLACEMENTS

#### CARTESIAN REFERENCE

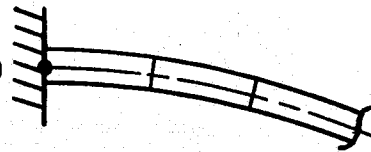
$Y, Z$ : GLOBAL COORDINATES

$y, z$ : LOCAL COORDINATES

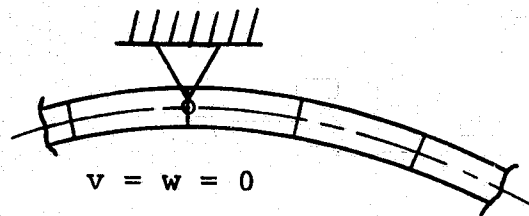
FIG. 3 NOMENCLATURE FOR GEOMETRY, COORDINATES, AND DISPLACEMENTS OF A MULTILAYER CURVED-BEAM FINITE ELEMENT

IDEALLY-CLAMPED

$$v = w = \psi = 0$$

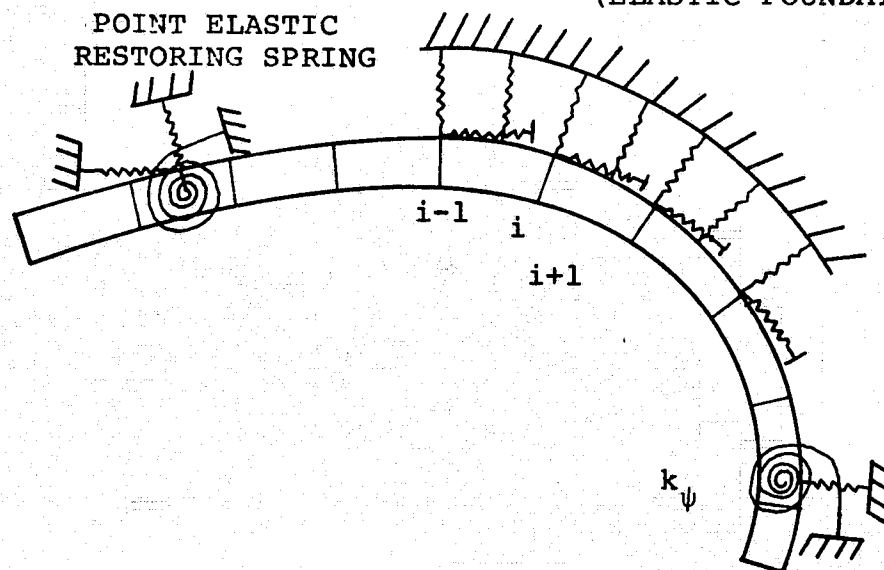


SMOOTHLY-HINGED



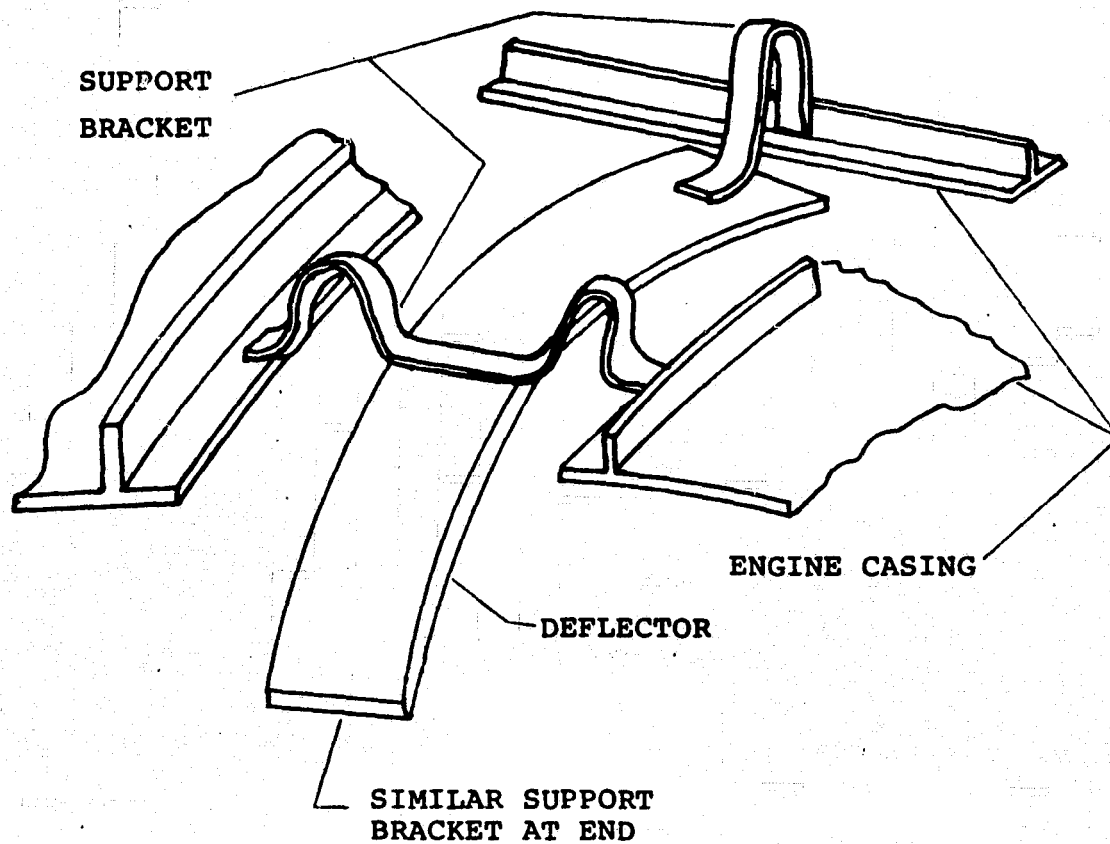
(a) Prescribed Displacement Conditions

DISTRIBUTED ELASTIC  
RESTORING SPRING  
(ELASTIC FOUNDATION)



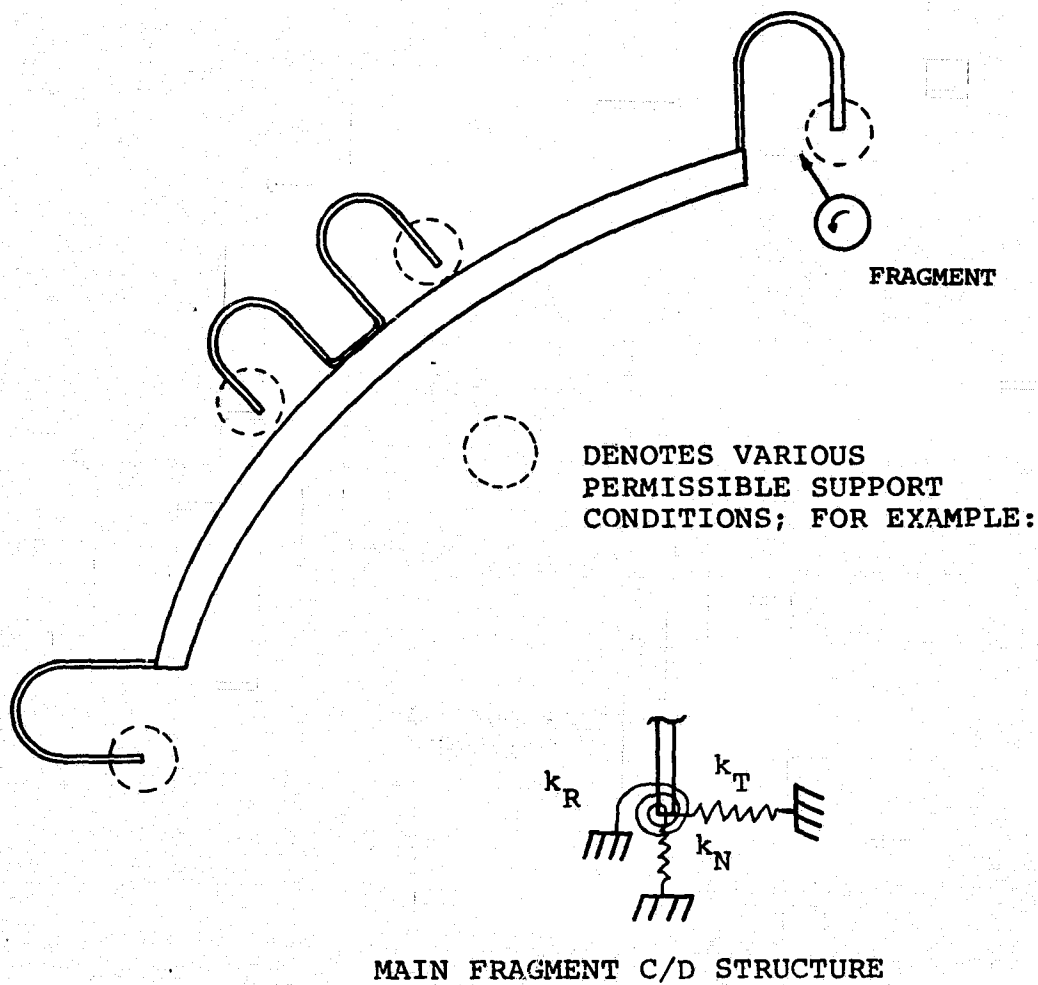
(b) Elastic Restraints

FIG. 4 SCHEMATICS FOR THE SUPPORT CONDITIONS OF THE STRUCTURE



(c) Schematic of a Bracket-Supported Fragment Containment/  
Deflector Structure

FIG. 4 CONTINUED



(d) Idealized Two-Dimensional Model of the Configuration Depicted in (c)

FIG. 4 CONCLUDED

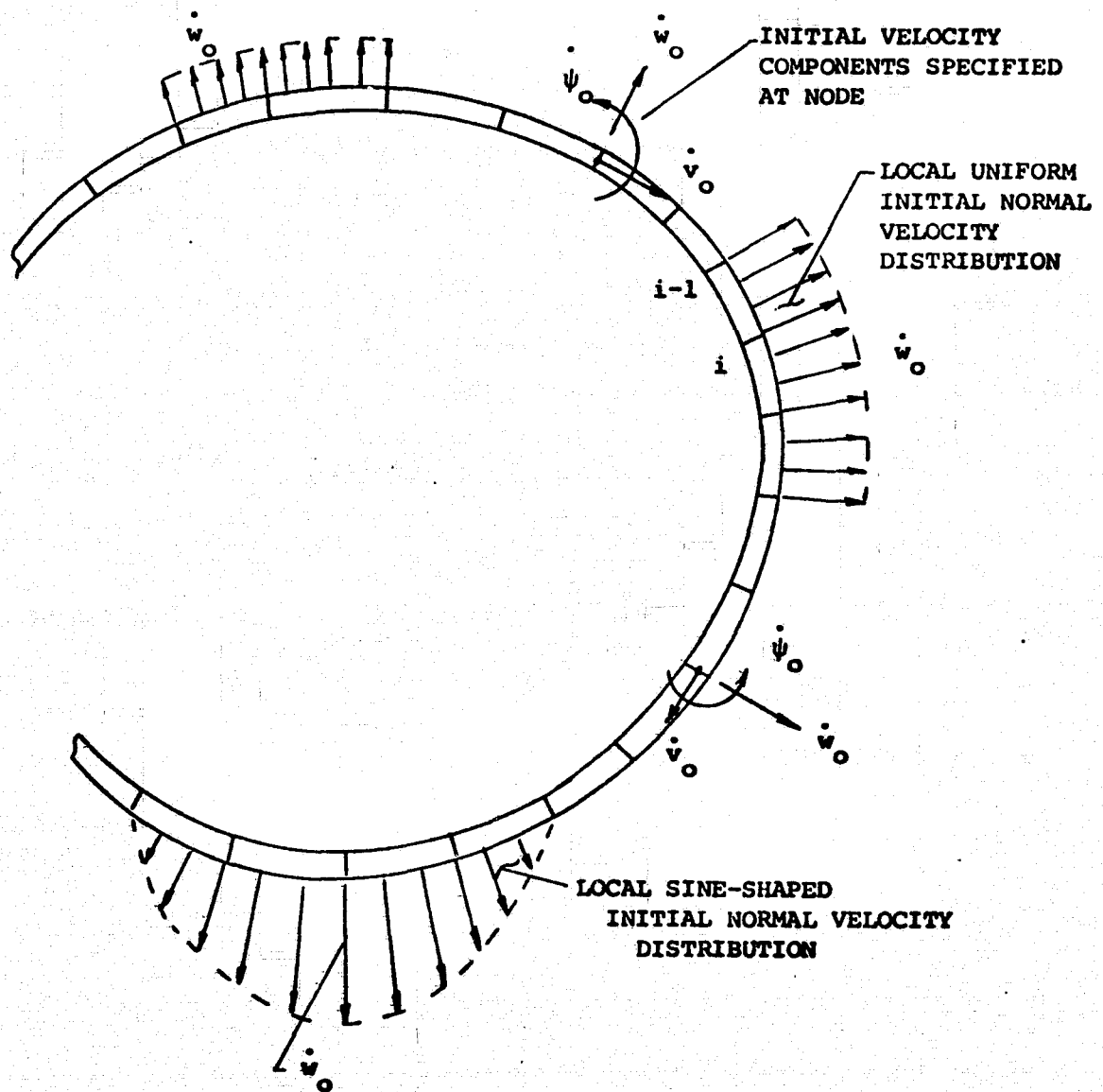
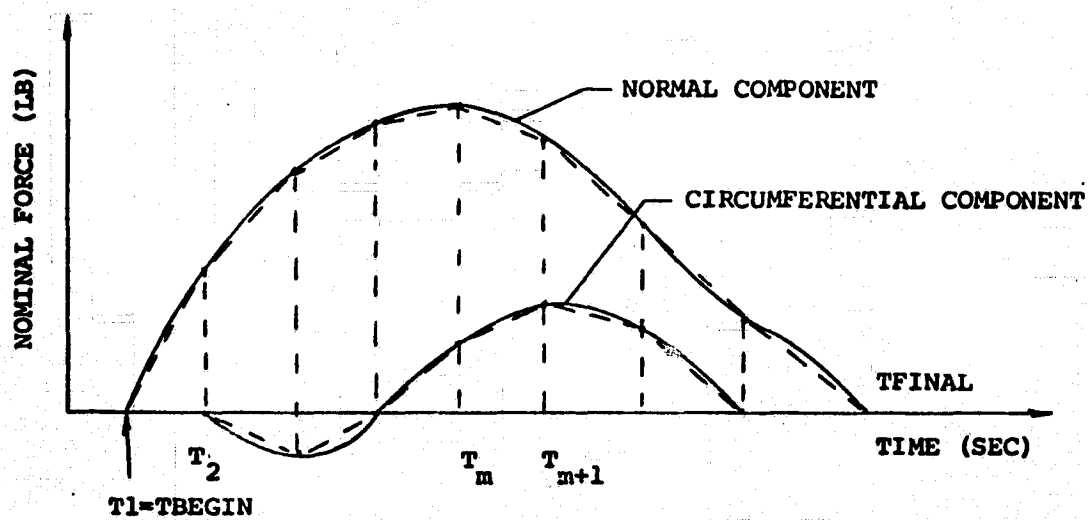
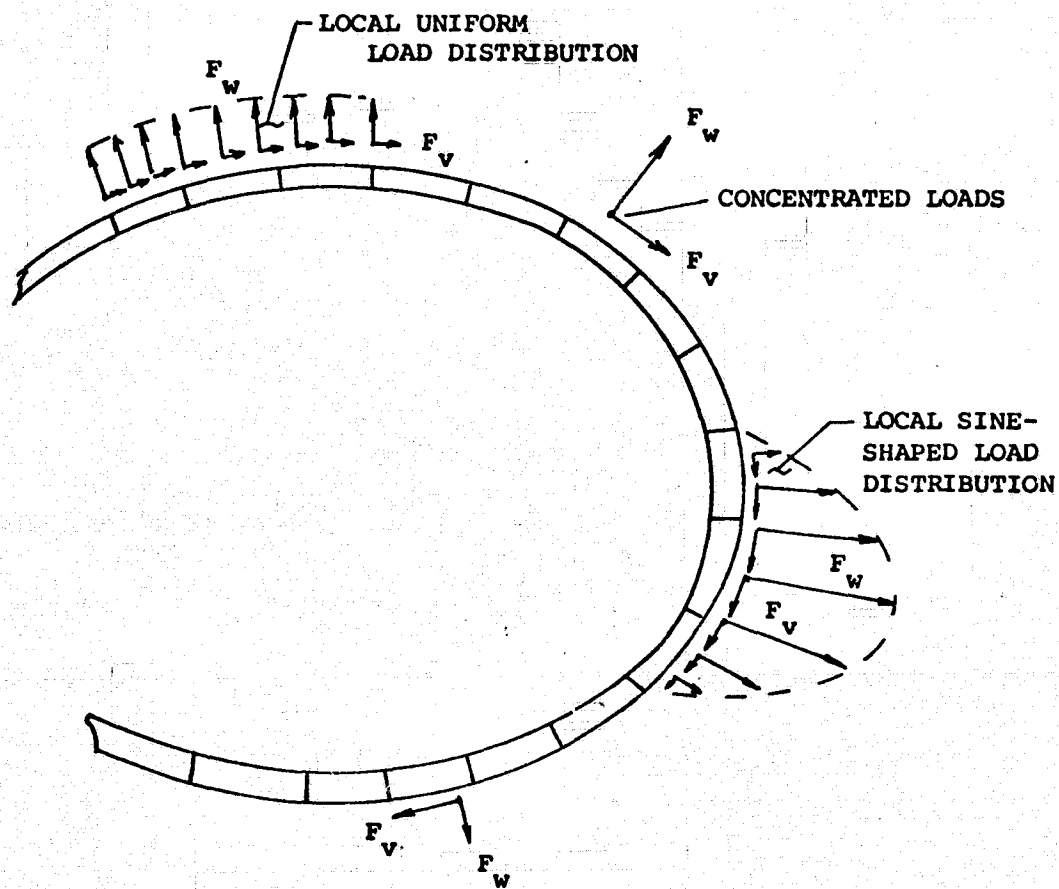


FIG. 5 SCHEMATIC OF INITIAL-VELOCITY PROVISIONS



(a) "Nominal Force" Component Time History

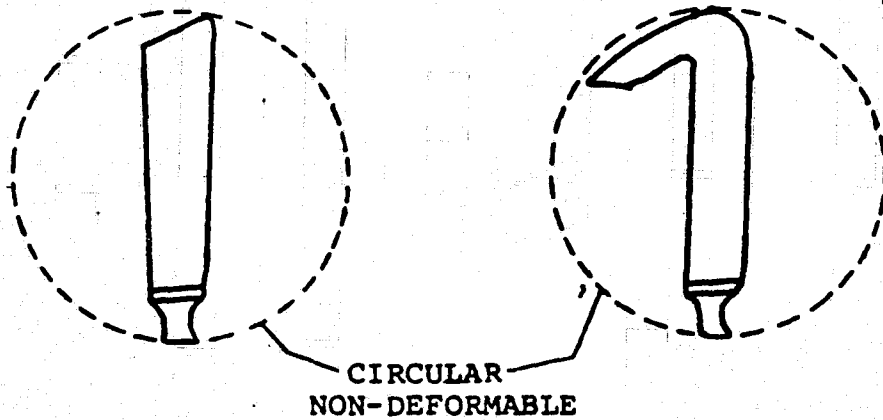


(b) Spatial Force Distribution

FIG. 6 TIME HISTORY AND SPATIAL DISTRIBUTIONS OF THE EXTERNALLY-APPLIED LOADINGS

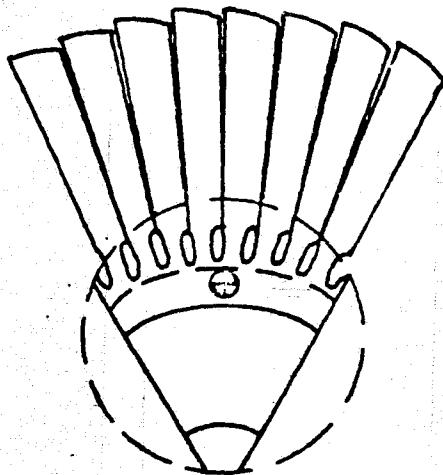
PRE-TEST

FINAL

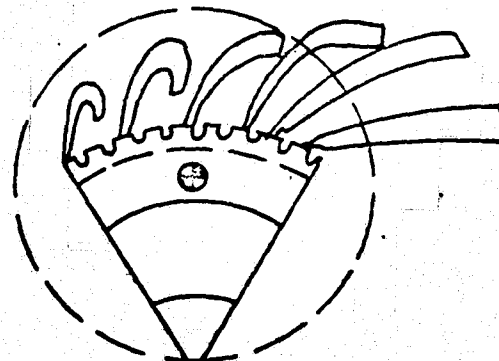


(a) Single Blade Fragment

—— ACTUAL  
---- IDEALIZED



BEFORE IMPACT



POST-TEST

(b) Bladed-Disk Type Fragment

FIG. 7 SCHEMATICS OF ACTUAL AND IDEALIZED FRAGMENTS



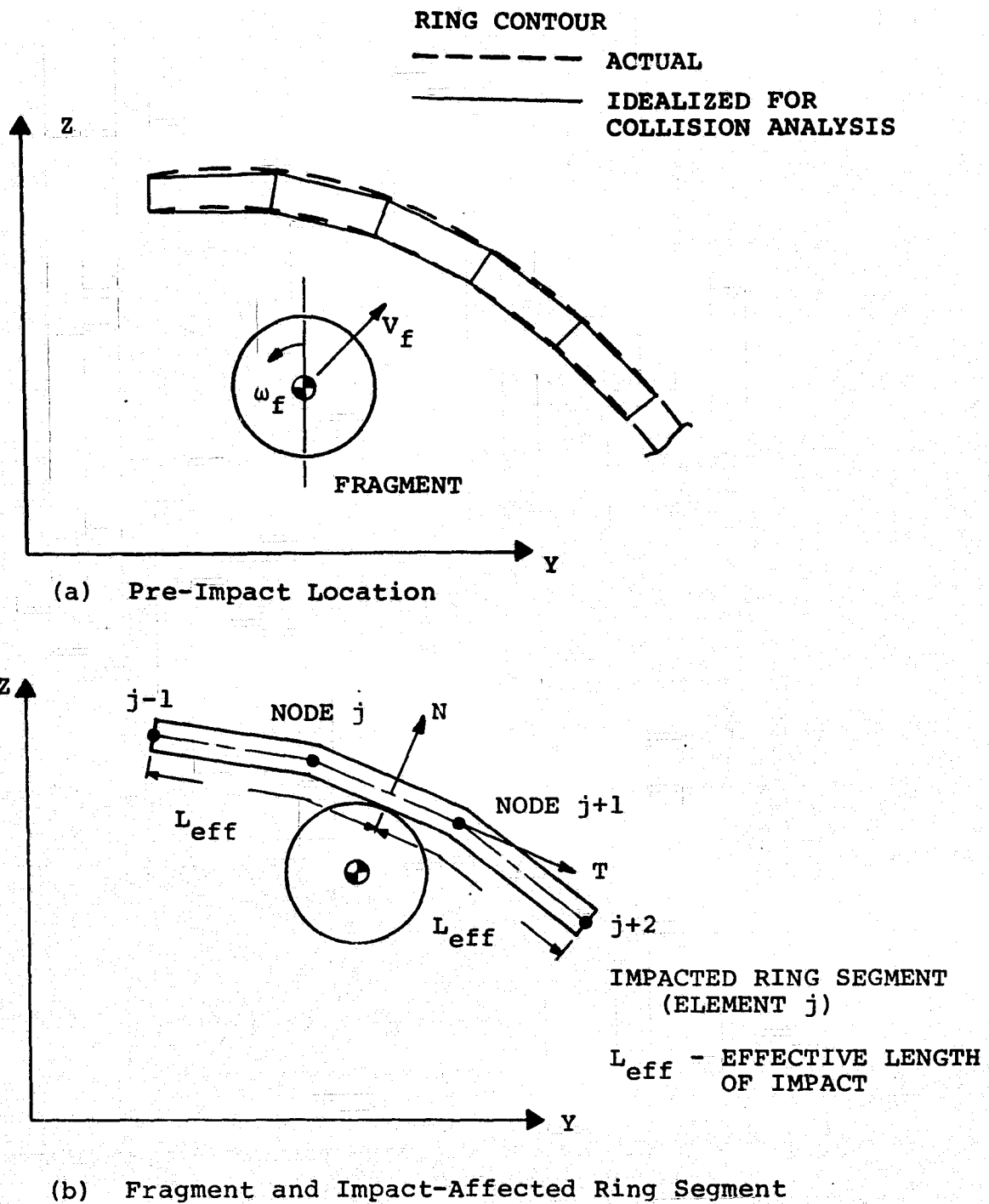


FIG. 8 IDEALIZATION OF RING CONTOUR FOR COLLISION ANALYSIS

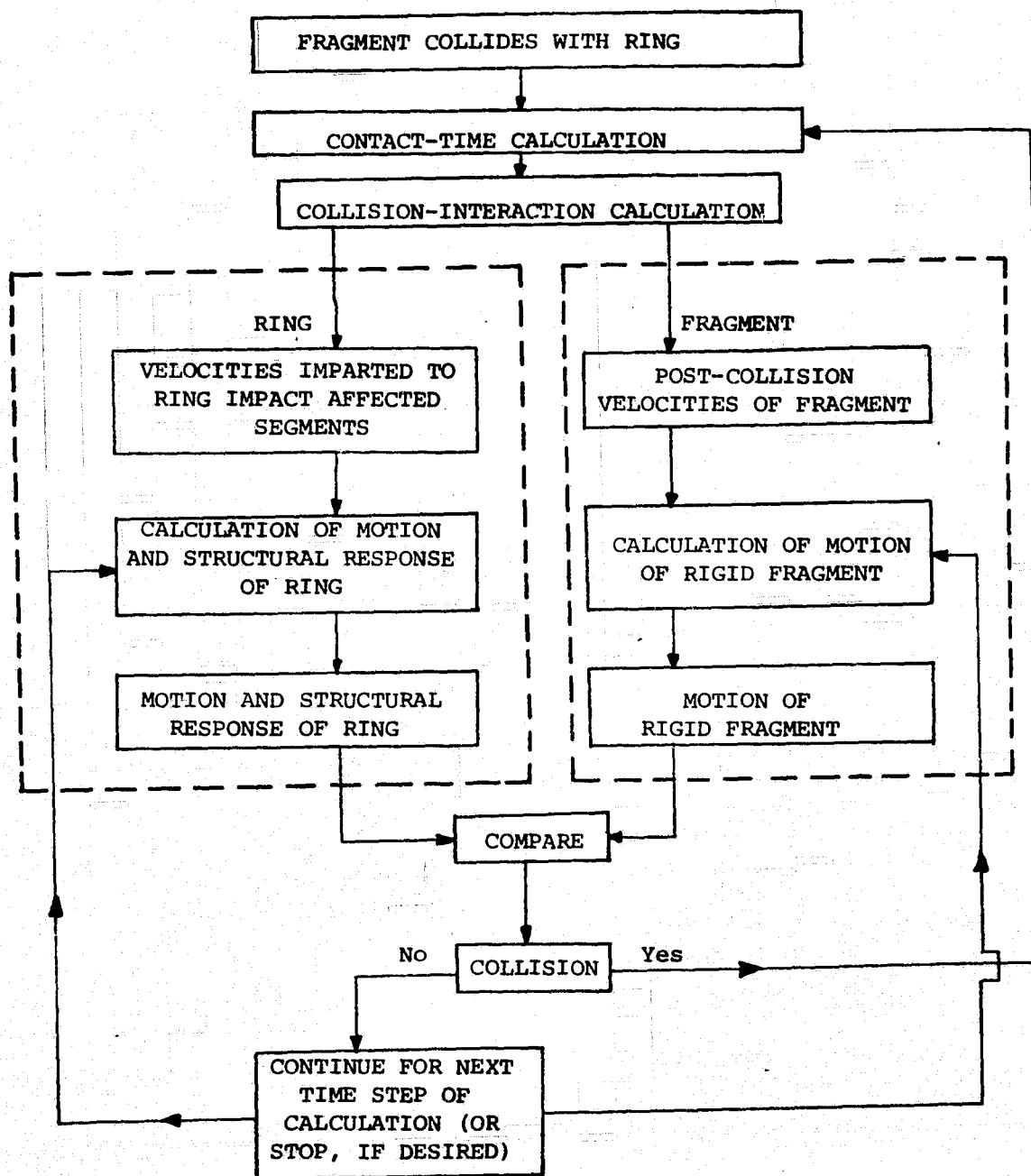
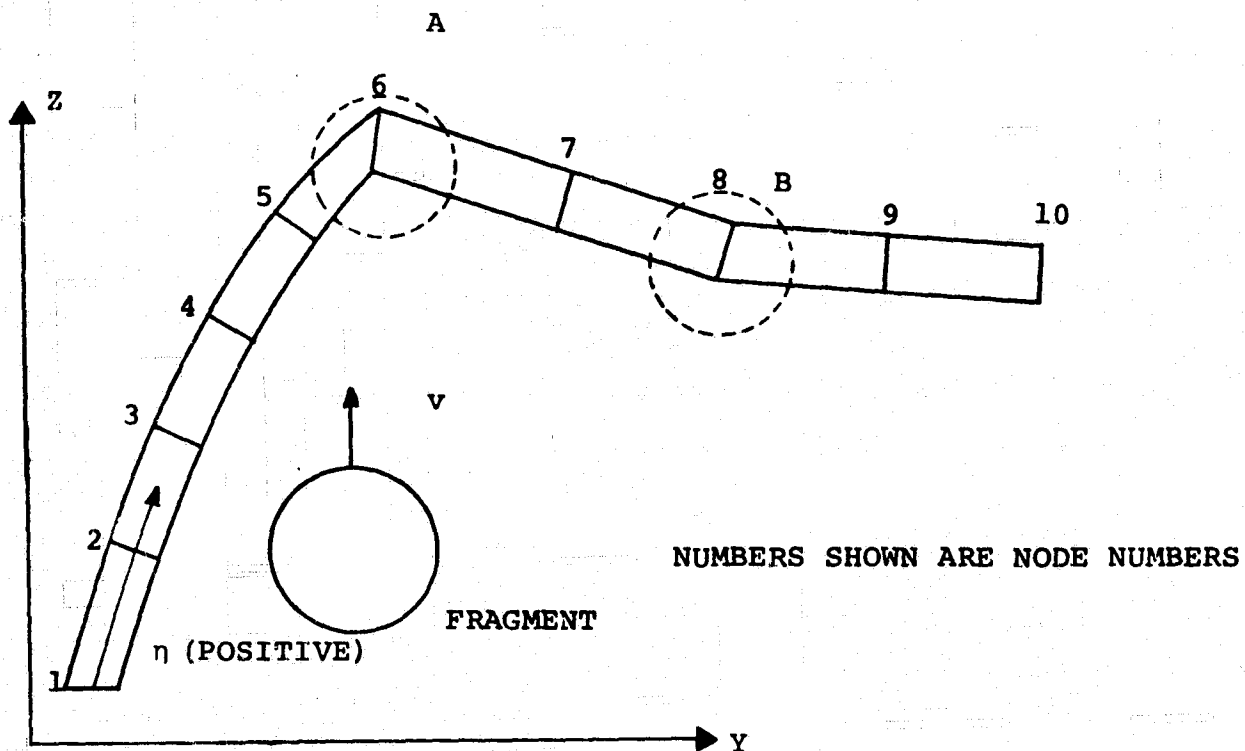
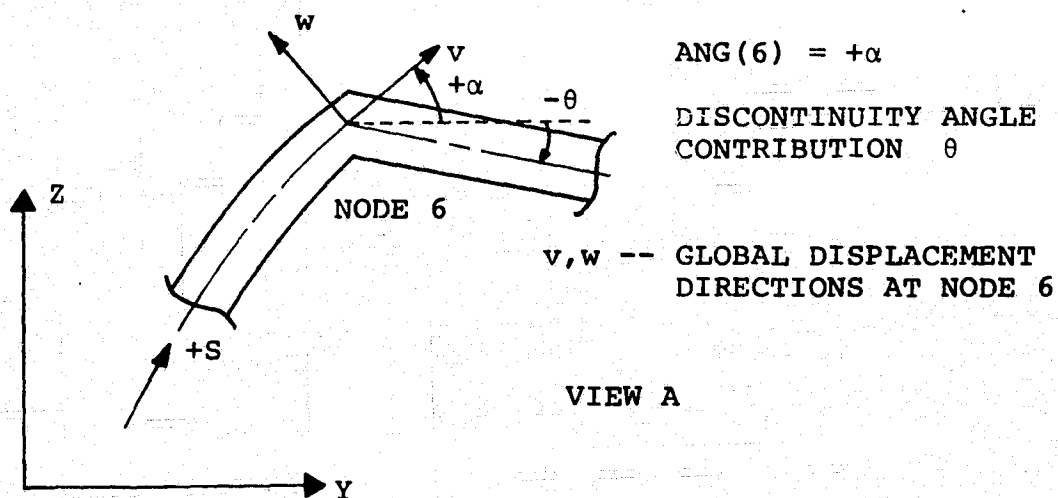


FIG. 9 INFORMATION FLOW SCHEMATIC FOR PREDICTING RING AND FRAGMENT MOTIONS IN THE COLLISION-IMPARTED VELOCITY METHOD

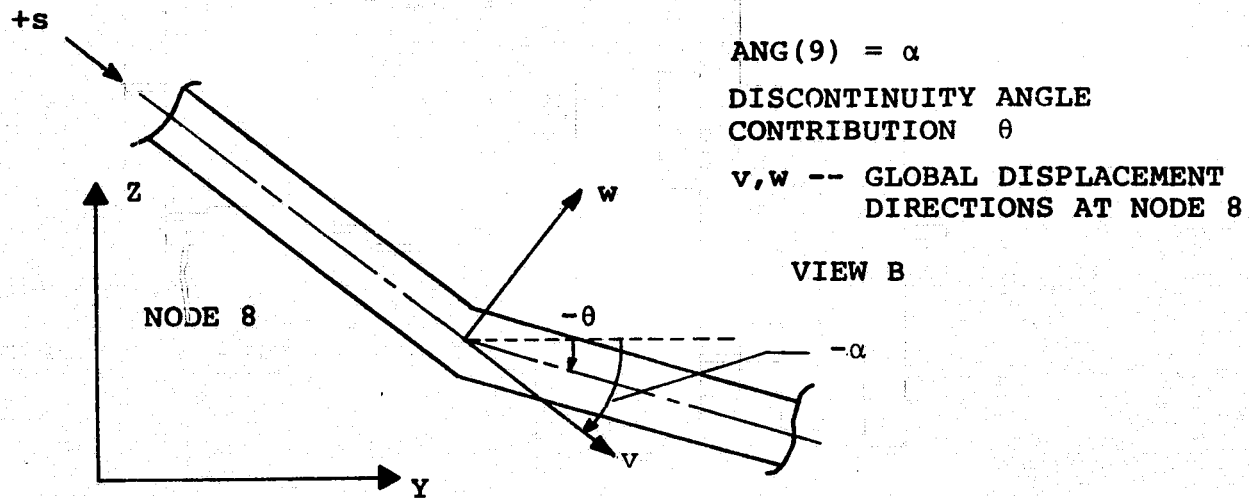


(a) Illustrative Fragment C/D Structure with Slope Discontinuities



(b) Exploded View of Node 6 -- Angle Definitions

FIG. 10 DEFINITION OF SLOPE-DISCONTINUITY ANGLES FOR AN ILLUSTRATIVE FRAGMENT AND C/D STRUCTURE



(c) Exploded View of Node 8 -- Angle Definitions

FIG. 10 CONCLUDED

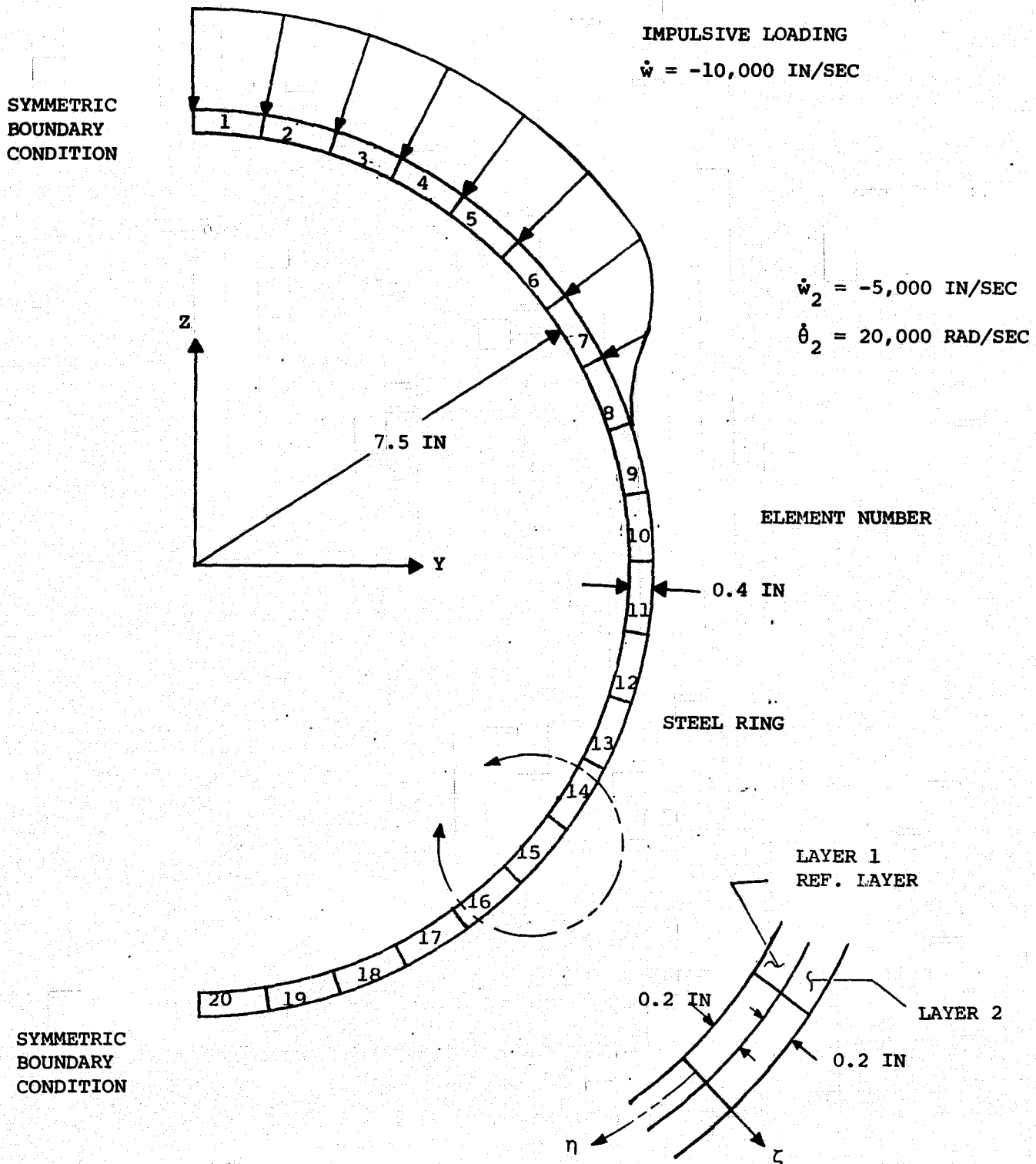
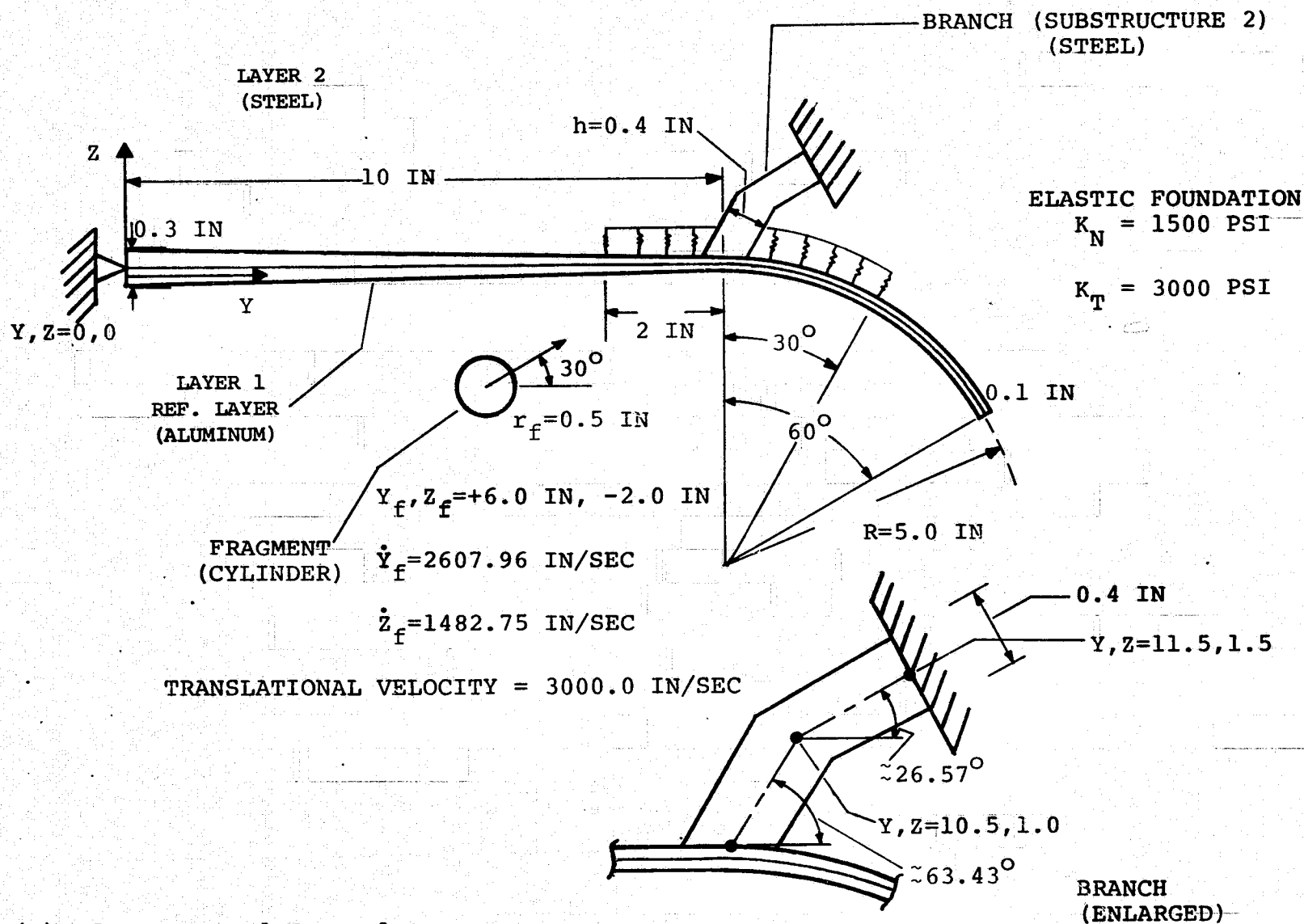
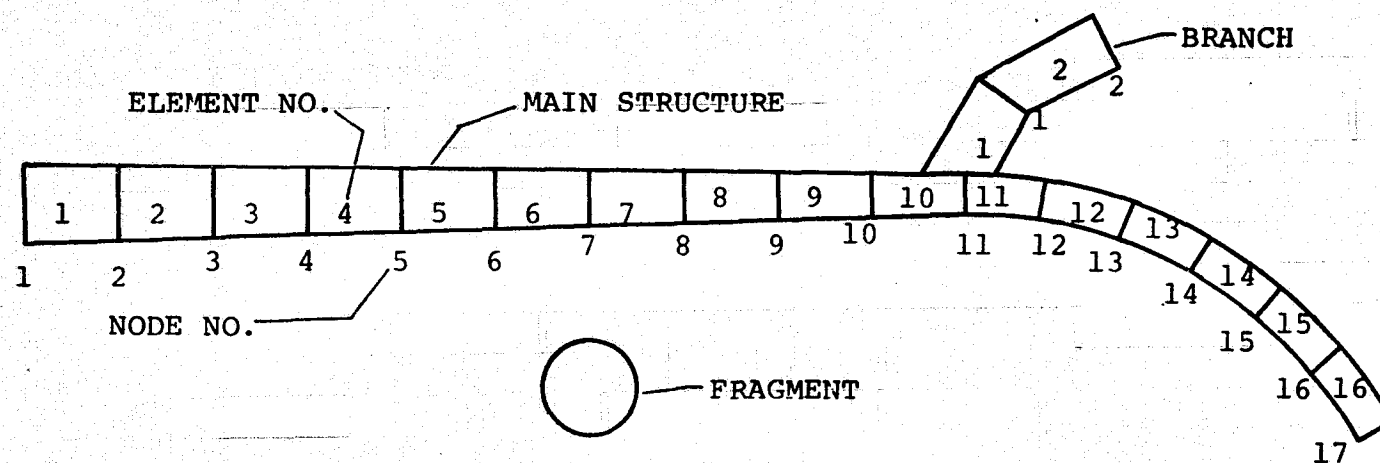


FIG. 11 PROBLEM DATA, GEOMETRY, NOMENCLATURE, AND FINITE-ELEMENT MODELING FOR THE JET 5A EXAMPLE



(a) Geometry and Nomenclature

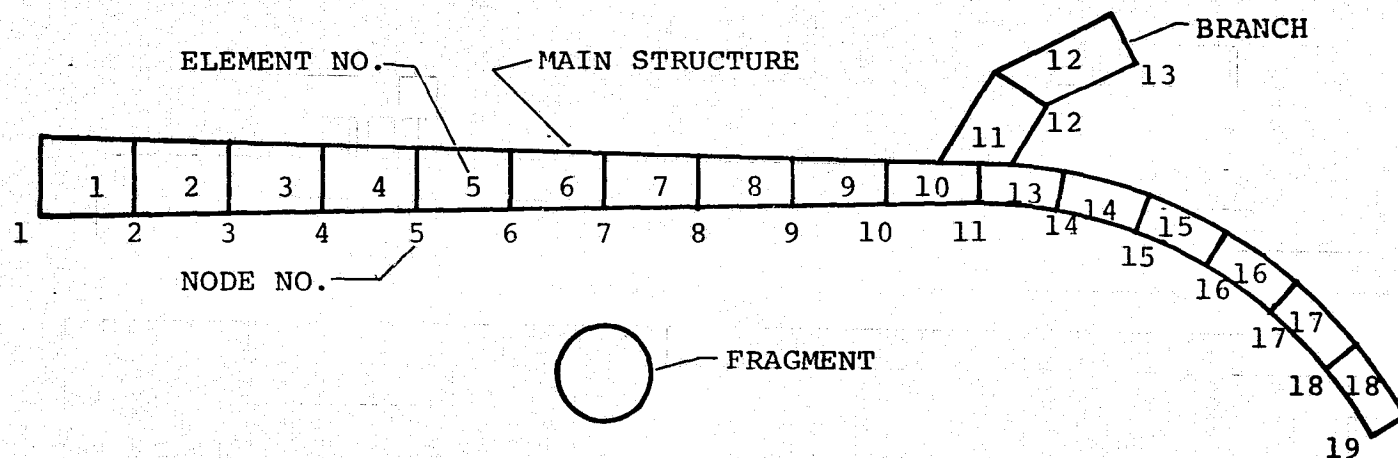
FIG. 12 PROBLEM DATA, GEOMETRY, NOMENCLATURE, AND FINITE-ELEMENT MODELING FOR THE CIVM-JET 5B EXAMPLE



NOTE: NODAL NUMBERS USED FOR B.C.'S ARE FOUND ON THIS FIGURE.

(b) User-Generated Numbering System

FIG. 12 CONTINUED



NOTE: USER MUST GENERATE ELASTIC FOUNDATION NUMBERS FROM THIS NUMBERING SCHEME. ELASTIC FOUNDATION #1 COVERS ELEMENTS 9 AND 10. ELASTIC FOUNDATION #2 COVERS ELEMENTS 13, 14, AND 15. SEE PAGE 52 AND CARD 16BB FOR EXPLANATION.

(c) Computer Generated Global Numbering System

FIG. 12 CONCLUDED



## APPENDIX A

### GOVERNING EQUATIONS ON WHICH JET 5A IS BASED

#### A.1 Formulation for Variable-Thickness Arbitrarily-Curved Multilayer Beam Elements and Structures

The geometry and nomenclature of a typical curved multilayer beam discrete element are shown in Fig. 3, where the deformation plane is  $\eta, \zeta$  and the coordinates  $\eta$  along and  $\zeta$  normal to the centroidal axis of a conveniently-chosen layer are employed as the reference coordinates of the multilayer-beam element. The slope,  $\phi$ , of the reference circumferential axis, which is the angle between the tangent vector and the y-axis of the local-reference Cartesian coordinate may be approximated by a second degree polynomial in  $\eta$  as follows:

$$\phi(\eta) = b_0 + b_1 \eta + b_2 \eta^2 \quad (\text{A.1})$$

where the constants  $b_0$ ,  $b_1$ , and  $b_2$  can be determined from the known initial geometry of the curved beam element. Assume that the change in element slope between nodes  $i$  and  $i+1$  is small so that

$$\cos(\phi_{i+1} - \phi_i) \doteq 1 \quad (\text{A.2a})$$

and

$$\sin(\phi_{i+1} - \phi_i) \doteq \phi_{i+1} - \phi_i \quad (\text{A.2b})$$

This restricts the slope change within an element to  $\lesssim 15$  degrees. The arc length,  $\eta_i$ , of the element is approximated to be the same as the length of a circular arc passing through the nodal points at the slopes  $\phi_i$  and  $\phi_{i+1}$ ;  $\eta_i$  is given by

$$\eta_i = \frac{L_i (\phi_{i+1} - \phi_i)}{2 \sin\left(\frac{\phi_{i+1} - \phi_i}{2}\right)} \quad (\text{A.3})$$

where  $L_i$  is the length of the chord joining nodes  $i$  and  $i+1$  and is given by

$$L_i = \left[ (Z_{i+1} - Z_i)^2 + (Y_{i+1} - Y_i)^2 \right]^{\frac{1}{2}} \quad (\text{A.3a})$$

and  $Y_i$  and  $Z_i$  are the initial Y and Z coordinates, respectively, of the  $i$ th node. The three constants in Eq. A.1 are then determined from the relations

$$\begin{aligned} \phi(\eta=0) &= \phi_i \\ \phi(\eta=\eta_i) &= \phi_{i+1} \\ \int_0^{\eta_i} \sin \phi d\eta &\doteq \int_0^{\eta_i} \phi d\eta = 0 \end{aligned} \quad (\text{A.4})$$

From Eq. A.4, the constants in Eq. A.1 are found to be

$$\begin{aligned} b_0 &= \phi_i \\ b_1 &= -2(\phi_{i+1} + 2\phi_i)/\eta_i \\ b_2 &= 3(\phi_{i+1} + \phi_i)/(\eta_i)^2 \end{aligned} \quad (\text{A.5})$$

Accordingly, the radius of curvature,  $R$ , of the centroidal axis may be expressed as  $R = - (d\phi/d\eta)^{-1} = - (b_1 + 2b_2\eta)^{-1}$ , and the coordinates  $Y(\eta)$  and  $Z(\eta)$  of the centroidal axis are given by

$$Y(\eta) = Y_i + \int_0^{\eta} \cos[\phi(\eta) + \alpha] d\eta \quad (\text{A.6a})$$

and

$$Z(\eta) = Z_i + \int_0^{\eta} \sin[\phi(\eta) + \alpha] d\eta \quad (\text{A.6b})$$

where

$$\alpha = \tan^{-1} \left( \frac{Z_{i+1} - Z_i}{Y_{i+1} - Y_i} \right)$$

The thickness variation of each layer is approximated as being linear between nodes; thus

$$h_l = h_{i,l} \left( 1 - \frac{\eta}{\eta_i} \right) + h_{i+1,l} \frac{\eta}{\eta_i} \quad (\text{A.7})$$

where subscript  $l$  is used to denote quantities pertaining to the  $l$ th layer.

Employing the Bernoulli-Euler hypothesis, the displacement field  $\tilde{v}, \tilde{w}$  of the beam may be specified by the reference plane displacements  $v$  and  $w$ ,

and the rotation,  $\psi$ , as follows:

$$\begin{aligned}\tilde{v}(\eta, \zeta) &= v(\eta) - \zeta \psi(\eta) \\ \tilde{w}(\eta, \zeta) &= w(\eta)\end{aligned}\tag{A.8}$$

where

$$\psi(\eta) = \frac{\partial w}{\partial \eta} - \frac{v}{R}\tag{A.8a}$$

To account for the strain-inducing modes and the rigid-body modes, the assumed displacement field takes the form:

$$\begin{Bmatrix} v \\ w \end{Bmatrix} = \begin{bmatrix} \cos \phi & \sin \phi & -(Z-Z_i) \cos(\phi+\alpha) + (Y-Y_i) \sin(\phi+\alpha) \\ -\sin \phi & \cos \phi & (Z-Z_i) \sin(\phi+\alpha) + (Y-Y_i) \cos(\phi+\alpha) \\ \eta & 0 & 0 & \eta^2 & \eta^3 \\ 0 & \eta^2 & \eta^3 & 0 & 0 \end{bmatrix} \begin{Bmatrix} \beta_1 \\ \beta_2 \\ \beta_3 \\ \beta_4 \\ \beta_5 \end{Bmatrix}\tag{A.9}$$

or in more compact matrix form, Eq. A.9 becomes

$$\{u\} \equiv \begin{Bmatrix} v \\ w \end{Bmatrix} = \begin{bmatrix} G_v(\eta) \\ G_w(\eta) \end{bmatrix} \{\beta\} \equiv [U(\eta)] \{\beta\}\tag{A.9a}$$

The generalized displacements  $\{q\}$  are selected so that there are four degrees of freedom  $v, w, \psi, \chi = (\partial v / \partial \eta) + w/R$  at each node of the element:

$$\{q\} = [v_i \ w_i \ \psi_i \ \chi_i \ v_{i+1} \ w_{i+1} \ \psi_{i+1} \ \chi_{i+1}]^T = [A] \{\beta\}\tag{A.10}$$

where

$$[A] = \begin{bmatrix} \cos \phi_i & \sin \phi_i & 0 & 0 & 0 & 0 & 0 & 0 \\ -\sin \phi_i & \cos \phi_i & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ \cos \phi_{i+1} & \sin \phi_{i+1} & A_{53} & \eta_i & 0 & 0 & \eta_i^2 & \eta_i^3 \\ -\sin \phi_{i+1} & \cos \phi_{i+1} & A_{63} & 0 & \eta_i^2 & \eta_i^3 & 0 & 0 \\ 0 & 0 & 1 & \eta_i(\phi')_{\eta_i} & 2\eta_i & 3\eta_i^2 & \eta_i^2(\phi')_{\eta_i} & \eta_i^3(\phi')_{\eta_i} \\ 0 & 0 & 0 & 1 & -\eta_i^2(\phi')_{\eta_i} & -\eta_i^3(\phi')_{\eta_i} & 2\eta_i & 3\eta_i^2 \end{bmatrix}\tag{A.10a}$$

and

$$A_{53} = (Y_{i+1} - Y_i) \sin(\phi_{i+1} + \alpha) - (Z_{i+1} - Z_i) \cos(\phi_{i+1} + \alpha) \quad (\text{A.10b})$$

$$A_{63} = (Y_{i+1} - Y_i) \cos(\phi_{i+1} + \alpha) + (Z_{i+1} - Z_i) \sin(\phi_{i+1} + \alpha)$$

Corresponding to the assumed displacement field Eq. A.9, one finds

$$\psi = \begin{bmatrix} 0 & 0 & 1 & -\frac{\eta}{R} & 2\eta & 3\eta^2 & -\frac{\eta^2}{R} & -\frac{\eta^3}{R} \end{bmatrix} \{\beta\} \equiv [G_\psi] \{\beta\} \quad (\text{A.11a})$$

and

$$\chi = \begin{bmatrix} 0 & 0 & 0 & 1 & \frac{\eta^2}{R} & \frac{\eta^3}{R} & 2\eta & 3\eta^2 \end{bmatrix} \{\beta\} \equiv [G_\chi] \{\beta\} \quad (\text{A.11b})$$

Under the Bernoulli-Euler hypothesis, the only nonvanishing strain component and corresponding stress component are the axial strain,  $\tilde{\epsilon}$ , and axial stress,  $\sigma$ . For this case, the nonlinear strain-displacement relation may be expressed as:

$$\tilde{\epsilon}(\eta, \zeta) = \epsilon(\eta) + \zeta \mathcal{K}(\eta) \quad (\text{A.12})$$

where

$$\begin{aligned} \epsilon(\eta) &= \left( \frac{\partial v}{\partial \eta} + \frac{w}{R} \right) + \frac{1}{2} \left( \frac{\partial v}{\partial \eta} + \frac{w}{R} \right)^2 + \frac{1}{2} \left( \frac{\partial w}{\partial \eta} - \frac{v}{R} \right)^2 \\ &\equiv [B_1] \{u\} + \frac{1}{2} [u] \{B_1\} [B_1] \{u\} + \frac{1}{2} [u] \{B_2\} [B_2] \{u\} \end{aligned} \quad (\text{A.12a})$$

$$\mathcal{K}(\eta) = -\frac{\partial}{\partial \eta} \left( \frac{\partial w}{\partial \eta} - \frac{v}{R} \right) \equiv [B_3] \{u\}$$

Combining Eqs. A.9 through A.12, one obtains

$$\{u\} = [U(\eta)] [A^{-1}] \{\gamma\} \quad (\text{A.13})$$

and

$$\begin{aligned} \epsilon &= [D_1] \{\gamma\} + \frac{1}{2} [\gamma] \{D_1\} [D_1] \{\gamma\} + \frac{1}{2} [\gamma] \{D_2\} [D_2] \{\gamma\} \\ \mathcal{K} &= [D_3] \{\gamma\} \end{aligned} \quad (\text{A.14})$$

where

$$[D_i] = [B_i][U][A^{-1}] \quad \text{for } i = 1, 2, 3 \quad (\text{A.14a})$$

and

$$\begin{aligned} [B_1][U] &= \begin{bmatrix} 0 & 0 & 0 & 1 & -\gamma^2 \phi' & -\gamma^3 \phi' & 2\gamma & 3\gamma^2 \end{bmatrix} \\ [B_2][U] &= \begin{bmatrix} 0 & 0 & 1 & \gamma \phi' & 2\gamma & 3\gamma^2 & \gamma^2 \phi' & \gamma^3 \phi' \end{bmatrix} \\ [B_3][U] &= \begin{bmatrix} 0 & 0 & 0 & -\phi' - \gamma \phi'' & -2 & -6\gamma & -2\gamma \phi' - \gamma^2 \phi'' & -3\gamma^2 \phi' - \gamma^3 \phi'' \end{bmatrix} \end{aligned} \quad (\text{A.14b})$$

In the process of solution, it is necessary to evaluate the strain increment  $\Delta \tilde{\epsilon}_m$  from time  $t_{m-1}$  to time  $t_m$ . Using Eqs. A.12 and A.14, one has

$$\Delta \tilde{\epsilon}_m = \Delta \epsilon_m + \zeta \Delta \mathcal{K}_m \quad (\text{A.15})$$

where

$$\begin{aligned} \Delta \epsilon_m &= [D_1] \{\Delta \mathcal{F}\}_m + [g]_m \{D_1\} [D_1] \{\Delta \mathcal{F}\}_m + [g]_m \{D_2\} [D_2] \{\Delta \mathcal{F}\}_m \\ &\quad - \frac{1}{2} [ \Delta \mathcal{F} ]_m \{D_1\} [D_1] \{\Delta \mathcal{F}\}_m - \frac{1}{2} [ \Delta \mathcal{F} ]_m \{D_2\} [D_2] \{\Delta \mathcal{F}\}_m \end{aligned} \quad (\text{A.15a})$$

$$\Delta \mathcal{K}_m = [D_3] \{\Delta \mathcal{F}\}_m$$

The consistent mass matrix of the  $i$ th discrete element may be obtained from the expression for the kinetic energy,  $T_i$ , as follows:

$$T_i = \frac{1}{2} \int_{V_i} \rho (\dot{\tilde{v}}^2 + \dot{\tilde{w}}^2) dV = \frac{1}{2} \int_{V_i} \rho [(\dot{v} - \zeta \dot{\psi})^2 + \dot{w}^2] dV \quad (\text{A.16})$$

where  $V_i$  is the volume of the  $i$ th discrete element. The integration extending over the whole multilayer beam element is now performed by a summation of the integrals extending over each individual layer. Thus, one has

$$T_i = \frac{1}{2} \int_0^{\gamma_i} \begin{bmatrix} \dot{v} & \dot{w} & \dot{\psi} \end{bmatrix} [B] \begin{Bmatrix} \dot{v} \\ \dot{w} \\ \dot{\psi} \end{Bmatrix} d\gamma \quad (\text{A.16a})$$

where

$$[B] = \sum_{l=1}^L b \begin{bmatrix} \rho_l h_l(\eta) & 0 & -\rho_l h_l(\eta) \lambda_l(\eta) \\ 0 & \rho_l h_l(\eta) & 0 \\ -\rho_l h_l(\eta) \lambda_l(\eta) & 0 & \rho_l \left( \frac{h_l^3(\eta)}{12} + h_l(\eta) \lambda_l^2(\eta) \right) \end{bmatrix} \quad (A.16b)$$

and  $b$  is the width of the ring,  $h_l(\eta)$  is the thickness of the  $l$ th layer,  $\lambda_l(\eta)$  is the  $\eta$ -dependent  $\zeta$ -location of the centroidal axis of the  $l$ th layer, and  $\rho_l$  is the mass per unit volume of the  $l$ th layer. All quantities pertaining to the  $l$ th layer are denoted with subscript  $l$ , and the summation extends over the  $L$  number of layers. Equation A.16b applies for  $\zeta/R$  negligible compared with unity.

With the assumption that the velocity field is of a form which is consistent with the displacement function, Eqs. A.9 and A.11, one has

$$\begin{Bmatrix} \dot{v} \\ \dot{w} \\ \dot{\psi} \end{Bmatrix} = \begin{bmatrix} U(\eta) \\ \dots \\ G_\psi(\eta) \end{bmatrix} \{\dot{\beta}\} \equiv [N(\eta)] \{\dot{\beta}\} = [N(\eta)] [A^{-1}] \{\dot{\xi}\} \quad (A.17)$$

Substituting Eq. A.17 into Eq. A.16a, one has

$$T_i = \frac{1}{2} [\dot{\xi}] [A^{-1}]^T \int_0^{\eta_i} [N]^T [B] [N] d\eta [A^{-1}] \{\dot{\xi}\} \quad (A.18)$$

or

$$T_i = \frac{1}{2} [\dot{\xi}] [m] \{\dot{\xi}\} \quad (A.18a)$$

where the consistent mass matrix  $[m]$  of the element is

$$[m] = [A^{-1}]^T \int_0^{\eta_i} [N]^T [B] [N] d\eta [A^{-1}] \quad (A.18b)$$

The equivalent generalized nodal forces which correspond to the externally-applied loading can be obtained from the variational statement of the work of the externally-applied loading,  $\delta W_i$ :

$$\delta W_i = \int_0^{\eta_i} [F_v(\eta, t) \delta v + F_w(\eta, t) \delta w] d\eta \quad (A.19)$$

where the components  $F_v$  and  $F_w$  of the force vector  $\bar{F}$  are given by

$$\begin{aligned}\bar{F}(\eta, t) &= F_v(\eta, t) \bar{a} + F_w(\eta, t) \bar{n} \\ &= g_v(\eta) f_v(t) \bar{a} + g_w(\eta) f_w(t) \bar{n}\end{aligned}\quad (\text{A.19a})$$

The quantity  $\bar{F}(\eta, t)$  is the externally-applied time-varying forcing function.

Substituting the assumed displacement function, Eqs. A.9 and A.10 into Eq. A.19, one has

$$\begin{aligned}\delta W_i &= [\delta q] [A^{-1}]^T \left\langle \int_0^{\eta_i} \{G_v(\eta)\} g_v(\eta) d\eta f_v(t) \right. \\ &\quad \left. + \int_0^{\eta_i} \{G_w(\eta)\} g_w(\eta) d\eta f_w(t) \right\rangle \\ &\equiv [\delta q] \{f\}\end{aligned}\quad (\text{A.20})$$

where

$$\begin{aligned}\{f\} &= [A^{-1}]^T \left\langle \int_0^{\eta_i} \{G_v\} g_v d\eta f_v + \int_0^{\eta_i} \{G_w\} g_w d\eta f_w \right\rangle \\ &= \text{element generalized nodal load vector}\end{aligned}\quad (\text{A.20a})$$

The effective stiffness matrix supplied by the elastic restraints may be obtained from the variation of the work done by the elastic restoring spring forces,  $\delta W_s$ :

$$-\delta W_s = \int_0^{\eta_i} (k_v v \delta v + k_w w \delta w + k_\psi \psi \delta \psi) d\eta \quad (\text{A.21})$$

or

$$-\delta W_s = \int_0^{\eta_i} [\delta v \quad \delta w \quad \delta \psi] [C] \begin{Bmatrix} v \\ w \\ \psi \end{Bmatrix} d\eta \quad (\text{A.21a})$$

where

$$[C] = \begin{bmatrix} k_v & 0 & 0 \\ 0 & k_w & 0 \\ 0 & 0 & k_\psi \end{bmatrix} \quad (\text{A.21b})$$

and  $k_v$  and  $k_w$ , respectively, are the linear elastic spring constants and  $k_\psi$  is the torsional elastic spring constant.

Substituting the assumed displacement function into Eq. A.21, one has

$$\begin{aligned} -\delta W_s &= [\delta q] [A^{-1}]^T \int_0^{\eta_i} [N]^T [C] [N] d\eta [A^{-1}] \{q\} \\ &\equiv [\delta q] [k_s] \{q\} \end{aligned} \quad (A.22)$$

where

$$[k_s] = [A^{-1}]^T \int_0^{\eta_i} [N]^T [C] [N] d\eta [A^{-1}] \quad (A.22a)$$

= effective element stiffness matrix supplied by the elastic restraint

The variation of the internal work  $\delta U_i$  of the axial stress,  $\sigma$ , may be expressed in terms of displacements and plastic strains, wherein the large deflection and plasticity effects are taken into account through the use of "effective generalized loadings"; thus

$$\delta U_i = \int_{V_i} \sigma \delta \tilde{\epsilon} dV = \int_{V_i} E(\epsilon + \gamma \kappa - \tilde{\epsilon}^p)(\delta \epsilon + \gamma \delta \kappa) dV \quad (A.23)$$

Employing the strain-displacement relations given by Eqs. A.12 and A.14, Eq. A.23 becomes

$$\delta U_i = [\delta q] \left( [k] \{q\} - \{f_q^{NL}\} - \{f_p^L\} - \{f_p^{NL}\} \right) \quad (A.24)$$

where, assuming that  $\zeta/R$  is negligible compared with unity:\*

$$[k] = \int_0^{\eta_i} [D_1 \mid D_3] \sum_{l=1}^L \begin{bmatrix} b E_l h_l(\eta) & + b E_l h_l(\eta) \lambda_l(\eta) \\ + b E_l h_l(\eta) \lambda_l(\eta) & b E_l \left( \frac{h_l^3(\eta)}{12} + h_l(\eta) \lambda_l^2(\eta) \right) \end{bmatrix} \begin{bmatrix} D_1 \\ \vdots \\ D_3 \end{bmatrix} d\eta \quad (A.24a)$$

\* Otherwise, additional terms would be present.



$$\{f_p^{NL}\} = - \int_0^{\eta_i} \{D_1\} \left( \frac{1}{2}(\chi^2 + \psi^2) \left\langle \sum_{l=1}^L b E_l h_l(\eta) \right\rangle + \chi \varepsilon \left\langle \sum_{l=1}^L b E_l h_l(\eta) \right\rangle + \chi \kappa \left\langle \sum_{l=1}^L b E_l h_l(\eta) \lambda_l(\eta) \right\rangle \right) d\eta \\ - \int_0^{\eta_i} \{D_2\} \left( \psi \varepsilon \left\langle \sum_{l=1}^L b E_l h_l(\eta) \right\rangle + \psi \kappa \left\langle \sum_{l=1}^L b E_l h_l(\eta) \lambda_l(\eta) \right\rangle \right) d\eta \\ - \int_0^{\eta_i} \{D_3\} \left( \frac{1}{2}(\chi^2 + \psi^2) \left\langle \sum_{l=1}^L b E_l h_l(\eta) \lambda_l(\eta) \right\rangle \right) d\eta$$

(A.24b)

$$\{f_p^L\} = \int_0^{\eta_i} \{D_1\} \left( \sum_{l=1}^L b E_l \int_{h_l} \tilde{\varepsilon}^p(\eta, \zeta) d\zeta \right) d\eta$$

$$+ \int_0^{\eta_i} \{D_3\} \left( \sum_{l=1}^L b E_l \int_{h_l} \zeta \tilde{\varepsilon}^p(\eta, \zeta) d\zeta \right) d\eta$$

(A.24c)

$$\{f_p^{NL}\} = \int_0^{\eta_i} \{D_1\} \left( \chi \sum_{l=1}^L b E_l \int_{h_l} \tilde{\varepsilon}^p(\eta, \zeta) d\zeta \right) d\eta$$

$$+ \int_0^{\eta_i} \{D_2\} \left( \psi \sum_{l=1}^L b E_l \int_{h_l} \tilde{\varepsilon}^p(\eta, \zeta) d\zeta \right) d\eta$$

(A.24d)

and in the above,  $E_l$  is the modulus of elasticity of the  $l$ th layer, and  $\tilde{\varepsilon}^p$  is the plastic strain.

Note that in the present analysis the integrations along the beam span are performed numerically by employing Gaussian quadrature which requires the integrand to be evaluated only at each selected spanwise Gaussian station. At

each spanwise station, the integration of the plastic strain,  $\tilde{\epsilon}^p$ , through the thickness of each individual layer, also requires evaluating  $\tilde{\epsilon}^p$  at selected Gaussian points across the thickness of each layer and the corresponding weighting factors are used in evaluating the pertinent integrals by Gaussian quadrature; hence

$$\begin{aligned}\int_{h_2} \tilde{\epsilon}^p d\zeta &= \frac{h_2}{2} \sum_{j=1}^J \tilde{\epsilon}_j^p W_j \\ \int_{h_2} \zeta \tilde{\epsilon}^p d\zeta &= \frac{h_2}{2} \sum_{j=1}^J \zeta_{j,L} \tilde{\epsilon}_j^p W_j\end{aligned}\quad (\text{A.25})$$

where

$$\begin{aligned}\zeta_{j,L} &= \frac{h_2}{2} \zeta_j' + \lambda_2 \quad \text{and} \quad \int_{h_2} \equiv \int_{\lambda_2(\tau) - \frac{h_2(\tau)}{2}}^{\lambda_2 + \frac{h_2}{2}} \\ \tilde{\epsilon}_j^p &= \tilde{\epsilon}^p(\zeta_{j,L})\end{aligned}\quad (\text{A.25a})$$

and J denotes the number of Gaussian points that have been used for the thick-wise integration through the cross section of each beam layer;  $\zeta_j'$  and  $W_j$  are the numerical values of the jth Gaussian station and weight, respectively.

Since the strain-hardening behavior of the material is accounted for by using the mechanical sublayer model in which the material at each Gaussian station is treated as consisting of equally-strained sublayers of elastic, perfectly-plastic material with each sublayer having the same elastic modulus but an appropriately different yield stress, the plastic strain at any station is calculated from the plastic strain of each mechanical-sublayer at that station. Let K mechanical-sublayers be used to approximate the strain-hardening material behavior.

Thus, one has:

$$\begin{aligned}\int_{h_2} \tilde{\epsilon}^p d\zeta &= \frac{h_2}{2} \sum_{j=1}^J W_j \left( \sum_{k=1}^K \tilde{\epsilon}_{jk}^p C_k \right) \\ \int_{h_2} \zeta \tilde{\epsilon}^p d\zeta &= \frac{h_2}{2} \sum_{j=1}^J \zeta_{j,L} W_j \left( \sum_{k=1}^K \tilde{\epsilon}_{jk}^p C_k \right)\end{aligned}\quad (\text{A.26})$$

where  $C_k$ , the mechanical sublayer weighting factor, is defined by

$$C_k = \frac{1}{E} (E_k - E_{k+1}) \quad (\text{A.26a})$$

$$E_k = \frac{\sigma_k - \sigma_{k-1}}{\epsilon_k - \epsilon_{k-1}} \quad (\text{A.26b})$$

is the  $k$ th slope of the polygonal approximate stress-strain diagram. The quantities  $\sigma_k$ ,  $\epsilon_k$  represent the coordinate defining the piecewise-linear approximation of the uniaxial stress-strain curve.

An illustration of the method of computing the axial stress and plastic-strain increment of any mechanical sublayer of the material model at any spanwise or depthwise Gaussian station, is presented as follows. One begins by knowing the sublayer stress  $(\sigma_{jk})_{m-1}$  at time  $t_{m-1}$  for the  $k$ th sublayer of the  $j$ th depthwise Gaussian station, and the strain increment  $(\Delta \tilde{\epsilon}_j)_m$  at station  $j$  at time  $t_m$  (that is, the strain increment from time  $t_{m-1}$  to time  $t_m$ ). One then takes a trial value (superscript T) of  $(\sigma_{jk})_m$  which is computed by assuming an elastic path:

$$(\sigma_{jk})_m^T = (\sigma_{jk})_{m-1} + E(\Delta \tilde{\epsilon}_j)_m \quad (\text{A.27})$$

A check is then performed to see what the correct value of  $(\sigma_{jk})_m$  must be:

$$\begin{aligned} \text{If } -\sigma_{ok} \leq (\sigma_{jk})_m^T \leq \sigma_{ok} \text{ then } (\sigma_{jk})_m &= (\sigma_{jk})_m^T \text{ and } (\Delta \epsilon_{jk}^p)_m = 0 \\ \text{If } (\sigma_{jk})_m^T > \sigma_{ok} \text{ then } (\sigma_{jk})_m &= \sigma_{ok} \text{ and } (\Delta \epsilon_{jk}^p)_m = \frac{(\sigma_{jk})_m^T - \sigma_{ok}}{E} \quad (\text{A.28}) \\ \text{If } (\sigma_{jk})_m^T < -\sigma_{ok} \text{ then } (\sigma_{jk})_m &= -\sigma_{ok} \text{ and } (\Delta \epsilon_{jk}^p)_m = \frac{(\sigma_{jk})_m^T + \sigma_{ok}}{E} \end{aligned}$$

If desired, the sublayer yield stresses may be treated as strain-rate dependent. Since the strain increment at the  $j$ th Gaussian station and hence the strain rate is known at this stage of computation, then the rate-dependent yield stress  $\sigma_{yk}$  of this  $k$ th sublayer at station  $j$  is

$$\sigma_{yk} = \sigma_{ok} \left( 1 + \left| \frac{\Delta \tilde{\epsilon}_j / \Delta t}{D} \right|^{\frac{1}{p}} \right) \quad (\text{A.29})$$

where  $D$  and  $p$  are empirically-determined constants\* for the material and may, in general, be different for each sublayer,  $\sigma_{ok}$  is the static uniaxial yield stress of the  $k$ th sublayer at any  $j$ th Gaussian station and is defined by

$$\sigma_{ok} = E \epsilon_k$$

\* See the footnote on page 39.

Finally, by employing the standard finite-element assembling procedure, the resulting equations of motion for the "complete discretized structure" are

$$[M^*]\{\ddot{q}^*\} + ([K^*] + [K_s^*])\{q^*\} = \{F^*\} + \{F_q^{*NL}\} + \{F_p^{*L}\} + \{F_p^{*NL}\} \quad (A.30)$$

where the nomenclature of each term is explained in Subsection 2.3.

#### A.2 Solution Procedure for JET 5A

The Houbolt operator is a 4-point backward difference implicit operator and is chosen to solve the equations of motion expressed in the conventional form, Eq. 2.2. In this solution scheme, the  $\{\ddot{q}^*\}$  at any instant of time  $t_{m+1}$  are approximated by a 4-point backward-difference expression:

$$\{\ddot{q}^*\}_{m+1} = \frac{2\{q^*\}_{m+1} - 5\{q^*\}_m + 4\{q^*\}_{m-1} - \{q^*\}_{m-2}}{(\Delta t)^2} + O(\Delta t)^2 \quad (A.31)$$

Employing Eq. A.31, the conventional form of the dynamic equations of equilibrium, Eq. A.30, becomes

$$\begin{aligned} \left\langle 2[M^*] + (\Delta t)^2([K^*] + [K_s^*]) \right\rangle \{q^*\}_{m+1} = (\Delta t)^2 \left\langle \{F^*\}_{m+1} + \{F_q^{*NL}\}_{m+1} + \{F_p^{*L}\}_{m+1} + \{F_p^{*NL}\}_{m+1} \right\rangle \\ + [M^*] \left( 5\{q^*\}_m - 4\{q^*\}_{m-1} + \{q^*\}_{m-2} \right) \end{aligned} \quad (A.32)$$

It should be noted that the generalized nodal load vectors  $\{F_q^{*NL}\}_{m+1}$ ,  $\{F_p^{*L}\}_{m+1}$  and  $\{F_p^{*NL}\}_{m+1}$  (which may be due to large-deflections and elastic-plastic effects) depend on the displacements (or stresses, strains) at the time instant  $t_{m+1}$ , but these remain to be determined; thus, linear extrapolation by using the generalized nodal load vectors at two previous time steps is employed to estimate these forces values:

$$\begin{aligned} \{ \ddot{F}_q^{*NL} \}_{m+1} + \{ \ddot{F}_p^{*L} \}_{m+1} + \{ \ddot{F}_p^{*NL} \}_{m+1} &= 2 \left( \{ \ddot{F}_q^{*NL} \}_m + \{ \ddot{F}_p^{*L} \}_m + \{ \ddot{F}_p^{*NL} \}_m \right) \\ &- \left( \{ \ddot{F}_q^{*NL} \}_{m-1} + \{ \ddot{F}_p^{*L} \}_{m-1} + \{ \ddot{F}_p^{*NL} \}_{m-1} \right) \end{aligned} \quad (A.33)$$

This estimation should be reasonably good for very small  $\Delta t$  but will deteriorate with increasing  $\Delta t$ .

In order to apply the calculation method represented by Eqs. A.32 and A.33, one must take into account the prescribed initial conditions,  $\{q^*\}_0$ ,  $\{\dot{q}^*\}_0$ , and  $\{\ddot{q}^*\}_0$ . The following "starting procedure" for this method provides the generalized displacements  $\{q^*\}_1$  at  $t_1 = 1\Delta t$ , and  $\{q^*\}_{-1}$  at a negative (fictitious) time instant  $t_{-1} = -1\Delta t$ .

By employing the following approximations:

$$\{\dot{q}^*\}_0 = \frac{2\{q^*\}_1 + 3\{q^*\}_0 - 6\{q^*\}_{-1} + \{q^*\}_{-2}}{6(\Delta t)} \quad (A.34)$$

and

$$\{\ddot{q}^*\}_0 = \frac{\{q^*\}_1 - 2\{q^*\}_0 + \{q^*\}_{-1}}{(\Delta t)^2} + O(\Delta t)^2 \quad (A.35)$$

one has

$$\{q^*\}_{-1} = (\Delta t)^2 \{\ddot{q}^*\}_0 + 2\{q^*\}_0 - \{q^*\}_1 \quad (A.36)$$

$$\{q^*\}_{-2} = 6(\Delta t)^2 \{\ddot{q}^*\}_0 + 6(\Delta t) \{\dot{q}^*\}_0 + 9\{q^*\}_0 - 8\{q^*\}_1 \quad (A.37)$$

Substituting Eqs. A.36 and A.37 into Eq. A.32 for  $m = 0$  and approximating the generalized nodal load vectors due to large-deflections and elastic-plastic effects at time step  $t_1$  by their values at time zero, one obtains

$$\begin{aligned} \left( 6[M^*] + (\Delta t)^2 ([K^*] + [K_s^*]) \right) \{q^*\}_1 &= (\Delta t)^2 \left( \{F^*\}_1 + \{ \ddot{F}_q^{*NL} \}_0 + \{ \ddot{F}_p^{*L} \}_0 + \{ \ddot{F}_p^{*NL} \}_0 \right) \\ &+ [M^*] \left( 2(\Delta t)^2 \{\ddot{q}^*\}_0 + 6(\Delta t) \{\dot{q}^*\}_0 + 6\{q^*\}_0 \right) \end{aligned} \quad (A.38)$$

where  $\{\ddot{q}^*\}_0$  can be calculated from

$$[M^*]\{\ddot{q}^*\}_0 = \{F^*\}_0 - ([K^*] + [K_s^*])\{q^*\}_0 + \left( \{\ddot{F}_f^*{}^{NL}\}_0 + \{\ddot{F}_p^*{}^L\}_0 + \{\ddot{F}_p^*{}^{NL}\}_0 \right) \quad (A.39)$$

Since the right-hand side of Eq. A.38 is known, one can solve for  $\{q^*\}_1$ . After the  $\{q^*\}_1$  have been determined,  $\{q^*\}_{-1}$  can be computed from Eq. A.36. One can then proceed to calculate  $\{q^*\}_2$  from Eqs. A.32 and A.33, then  $\{q^*\}_3$ ,  $\{q^*\}_4$ , etc.

## APPENDIX B

### GOVERNING EQUATIONS ON WHICH CIVM-JET 5B IS BASED

The governing equations for CIVM-JET 5B are similar to those discussed for JET 5A in Appendix A, except that (1) prescribed initial velocities and/or prescribed externally-applied forces acting on the containment/deflector ring structure are not accommodated, (2) a diagonal lumped rather than a consistent mass matrix is used, and (3) ring/fragment impact and interaction must now be taken into account. The new matters pertinent to CIVM-JET 5B are discussed in the following subsections, whose headings identify the principal subject matter.

At this point it is useful to recall the general flow of information and computations in CIVM-JET 5B as depicted in Fig. 9. The key aspects of that process are discussed in the following subsections.

#### B.1 Equations of Motion of the C/D Ring Structure

The equations of motion for the finite-element representation of the containment/deflector (C/D) ring structure are represented by Eq. A.30 except that now  $\{F^*\} = 0$  and a diagonal lumped mass matrix is to be used; all other formulation and discussion in Appendix A prior to Eq. A.30 also apply to CIVM-JET 5B.

The rationale for employing a diagonal lumped-mass representation for the C/D ring structure which is to be subjected to fragment-impact attack has been discussed in Subsection 2.3, page 11. For the present multilayer, multi-material curved-ring element, a diagonal lumped-mass matrix is constructed from the consistent mass matrix ( $m^c$ , Eq. A.18b) according to the following rules (chosen for their convenience):

$$(m_{11})_L = m_{11}^c + m_{15}^c$$

$$(m_{22})_L = m_{22}^c + m_{26}^c$$

$$(m_{33})_L = m_{33}^c \quad ; \quad (m_{44})_L = m_{44}^c$$

(B.1)

$$(m_{55})_L = m_{55}^c + m_{51}^c$$

$$(m_{66})_L = m_{66}^c + m_{61}^c$$

$$(m_{77})_L = m_{77}^c ; (m_{88})_L = m_{88}^c$$

This insures that  $(m_{11})_L + (m_{55})_L = (m_{22})_L + (m_{66})_L =$  the total mass of the element; these quantities pertain to the "translational degrees of freedom  $v_i, w_i, v_{i+1},$  and  $w_{i+1}$ ". The remaining terms refer to the degrees of freedom  $\psi_i, \chi_i, \psi_{i+1},$  and  $\chi_{i+1}$ . Exploratory calculations indicate that the predicted structural response of an impulsively-loaded structure (a simple beam, for example) is rather insensitive to the type of mass lumping applied\* to these degrees of freedom and compares well with that obtained by using the consistent mass matrix. It turns out also that the Eq. B.1 mass lumping produces a (perhaps advantageous) smaller  $\omega_{\max}$  than does the consistent mass or the footnote-cited (\*) diagonal mass lumping.

## B.2 Collision-Interaction Analysis, Including Friction

In the present collision-interaction analysis, the curved variable-thickness multilayer containment/deflection ring is represented by straight-line segments (Fig. B.1): (a) to identify in a simple and approximate way the space occupancy of the beam segment under imminent impact attack and (b) to derive the impact equations. The inertia effects of the impacted beam segments are taken into account by means of lumped-mass collision model; that is, the ring is treated as having only point masses lumped at each nodal station as indicated in Fig. B.2. Other simplifying assumptions which are invoked in the present analysis are described in Subsection 2.2.

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\* That is the lumping given by Eq. B.1 wherein  $(m_{33})_L, (m_{44})_L, (m_{77})_L,$  and  $(m_{88})_L$  are computed in a fashion analogous to that indicated in Eq. B.1 for  $(m_{11})_L, (m_{22})_L, (m_{55})_L,$  and  $(m_{66})_L$ .



For the lumped-mass collision model, the impact-affected beam segments are represented, as depicted in the exploded-line schematic of Fig. B.2, by concentrated masses  $m_1, m_2, \dots, m_{j+1}, \dots, m_k$  (or  $i+k-1$ ), respectively, where the ring-fragment collision point is encompassed by the  $j$ th segment which is bounded by nodal station  $j$  and  $j+1$  ---- a clockwise numbering sequence is used. In the collision analysis, it is convenient to resolve and discuss impulses, velocities, etc., for both of the fragment and the ring impact-affected nodes in directions normal (N) and tangential (T) to the straight line segment  $j$ ; the positive normal direction is always taken from the inside toward the outside of the ring, while the positive-tangential direction is along the straight line from node  $j$  toward node  $j+1$  (see Fig. B.2a). Consequently, the lumped-mass velocities for each of the impact-affected nodes and the idealized-fragment velocities are expressed with respect to this local N,T inertial coordinate system as  $(v_{IN}, v_{IT}), (v_{2M}, v_{2T})$  ----  $(v_{kN}, v_{kT})$ , and  $(v_{fN}, v_{fT})$  in the exploded schematic shown in Fig. B.2a.

It is assumed that the instantaneous collision process results in a normal-direction impulse  $\tilde{p}_N$  and a tangentially directed impulse  $\tilde{p}_T$  applied to the ring, and in equal but anti-parallel impulses to the fragment. The impulses applied to the ring are assumed to be distributed over the impact-affected nodes (see Fig. B.2b) as

$$\left. \begin{aligned} p_{iN} &= C \left( 1 - \frac{|s_i|}{L_{eff}} \right) \tilde{p}_N \equiv C \alpha'_i \tilde{p}_N \\ p_{iT} &= C \left( 1 - \frac{|s_i|}{L_{eff}} \right) \tilde{p}_T \equiv C \alpha'_i \tilde{p}_T \end{aligned} \right\} i=1,2,\dots,k \quad (B.2)$$

where (see Fig. B.2b) the effective length\*,  $L_{eff}$ , bounds the impact-affected zone of the ring, which is the fraction of the ring that responds with momentum changes due to the collision of a fragment,  $s_i$  is the distance measured from the impacted point to the  $i$ th impact-affected node, and the constant,  $C$ , is determined by assuming that the sum of the impulse applied to each impact-affected node equals the total impulse imparted; thus,

\*

One estimate for  $L_{eff}$  (called EFLN in the program) is  $L_{eff} \doteq \Delta t (E/\rho)^{1/2}$  where  $\Delta t$  is the finite-difference-calculation time increment and  $(E/\rho)^{1/2}$  is the largest longitudinal rod wave speed of the layers in the layered structure;  $E$  is the elastic modulus and  $\rho$  is the mass per unit volume. Another estimate from through-the-thickness stress wave propagation considerations is  $L_{eff} \doteq nh$  where  $h$  is the total thickness of the layered structure and  $n$  is some number, typically like  $2 \leq n \leq 4$ .

$$\sum_{i=1}^k p_{iN} = \tilde{p}_N \quad (\text{or } \sum_{i=1}^k p_{iT} = \tilde{p}_T) \quad (\text{B.2a})$$

Therefore, one has

$$C = 1 / \sum_{i=1}^k \left( 1 - \frac{|s_i|}{L_{\text{eff}}} \right) \equiv 1 / \sum_{i=1}^k \alpha'_i \quad (\text{B.2b})$$

The impact-affected nodes are those nodes located within the impact affected zone; that is  $|s_i| < L_{\text{eff}}$ . However, it is assumed that the two-mass nodes  $j$  and  $j+1$  of the segment  $j$  which encompasses the impact point always respond to impact with momentum changes, even if the distance from the impact point to one or both of the two nodes ( $j$  and  $j+1$ ) is greater than  $L_{\text{eff}}$ . Let  $\beta$  and  $\gamma$  be the distances measured from the "point of fragment impact" to masses  $m_j$  and  $m_{j+1}$ , respectively, as indicated in Fig. B.2. The distribution of the impulses is estimated in the following manner:

- (1) If  $\beta \geq L_{\text{eff}}$  and  $\gamma < L_{\text{eff}}$ , then (Fig. B.2c):

$$p_{iN} = p_{jN} = C \alpha'_i \tilde{p}_N \quad (\text{B.3})$$

$$p_{iT} = p_{jT} = C \alpha'_i \tilde{p}_T$$

where

$$\alpha'_1 = \frac{\gamma}{\beta} \alpha'_2 \quad \text{and} \quad C = 1 / \sum_{i=1}^k \alpha'_i \quad (\text{B.3a})$$

- (2) If  $\beta < L_{\text{eff}}$  and  $\gamma \geq L_{\text{eff}}$ , then (Fig. B.2d):

$$p_{kN} = p_{(j+1)N} = C \alpha'_k \tilde{p}_N \quad (\text{B.4})$$

$$p_{kT} = p_{(j+1)T} = C \alpha'_k \tilde{p}_T$$

where

$$\alpha'_k = \frac{\beta}{\gamma} \alpha'_{k-1} \quad \text{and} \quad C = 1 / \sum_{i=1}^k \alpha'_i \quad (\text{B.4a})$$

- (3) If  $\beta \geq L_{\text{eff}}$  and  $\gamma \geq L_{\text{eff}}$ , then (Fig. B.2e)

$$p_{1N} = p_{jN} = C \gamma \tilde{p}_N \equiv C \alpha'_1 \tilde{p}_N \quad (\text{B.5a})$$

$$p_{2N} = p_{(j+1)N} = C \beta \tilde{p}_N \equiv C \alpha'_2 \tilde{p}_N$$

$$p_{iT} = p_{jT} = C \gamma \tilde{p}_T \equiv C \alpha'_i \tilde{p}_T \quad (\text{B.5b})$$

$$p_{2T} = p_{(j+1)T} = C \beta \tilde{p}_T \equiv C \alpha'_2 \tilde{p}_T$$

where

$$C = 1 / (\beta + \gamma) \quad (\text{B.5c})$$

It should be emphasized here that the determination of which mass nodes fall within the impact-affected region is a discrete process in the sense that only mass node locations are considered instead of considering the true volume of mass included in the impact-affected region of the structure. Such an approximation is made necessary by the use of a lumped-mass model in the collision-interaction analysis. In essence, the use of a lumped-mass model implies that the nodal mass represents the mass distribution in a region of the structure surrounding the node, and, thus, by including a mass node in the impact-affected region, one is automatically including, in the impact-affected region, that portion of mass in the region of the node. It is clear that, in general, this approximate technique will result in having more or less structural mass included in the impact-affected region compared with the true structural mass within  $L_{eff}$ . However, in an average sense, this discrepancy is within the overall approximate nature of the impact-interaction analysis. In addition, the calculation of  $L_{eff}$ , which defines the distance the collision-imparted impulse "signal" travels in the structure during a finite time interval, is based on the global increment in time,  $\Delta t$ . This implies that the collision occurs at the beginning of a time step, and that the "signal" travels for a length of time equal to  $\Delta t$ . In actuality the time of impact may occur at any moment within a  $\Delta t$ . However, as detailed in Subsection B.5, the impact interaction solution assumes that all impacts occur at the beginning of a time step. This approximation of  $L_{eff}$  counterbalances the discrete process of determining which mass nodes fall within the impact-affected region. It is believed that these calculations, although approximate, will yield reasonable results for the fragment-impact-induced structural response.

Denoting by primes the "after-impact" translational and/or rotational velocities, the impulse-momentum law may be written to characterize the "instantaneous impact behavior" of the system, as follows:

Normal-Direction Translation Impulse-Momentum Law

$$m_f [V'_{fN} - V_{fN}] = - \tilde{p}_N \quad \text{(fragment)} \quad (B.6)$$

$$\left. \begin{aligned} m_1 [V'_{1N} - V_{1N}] &= \alpha_1 \tilde{p}_N \\ m_2 [V'_{2N} - V_{2N}] &= \alpha_2 \tilde{p}_N \\ &\vdots \\ m_k [V'_{kN} - V_{kN}] &= \alpha_k \tilde{p}_N \end{aligned} \right\} \quad \begin{array}{l} \text{(ring impact-affected} \\ \text{nodes)} \end{array} \quad (B.7)$$

Tangential-Direction Translational Impulse-Momentum Law

$$m_f [V'_{fT} - V_{fT}] = - \tilde{p}_T \quad \text{(fragment)} \quad (B.8)$$

$$\left. \begin{aligned} m_1 [V'_{1T} - V_{1T}] &= \alpha_1 \tilde{p}_T \\ m_2 [V'_{2T} - V_{2T}] &= \alpha_2 \tilde{p}_T \\ &\vdots \\ m_k [V'_{kT} - V_{kT}] &= \alpha_k \tilde{p}_T \end{aligned} \right\} \quad \begin{array}{l} \text{(ring impact-affected} \\ \text{nodes)} \end{array} \quad (B.9)$$

Rotational Impulse-Momentum Law

$$I_f [\omega'_f - \omega_f] = r_f \tilde{p}_T \quad \text{(fragment)} \quad (B.10)$$

where

$m_f$  = mass of the fragment

$I_f$  = mass moment of inertia of the fragment  
about its CG

$r_f$  = the radius of the circular disk model  
of the fragment

$\tilde{p}_N$  = normal-direction impulse

$\tilde{p}_T$  = tangential-direction impulse

$\alpha_i$  = proportional constant which is equal to  $(C\alpha'_i)$  as defined  
by Eqs. B.2 through B.5c.

The relative velocity of sliding  $S'$  and the relative velocity of approach  $A'$  at the immediate "contact points" between the fragment (at  $C_f$ ) and the ring

segment j (at  $C_r$ ) are defined by

$$S' = [V'_{fT} - \omega'_f r_f] - [\alpha_1 V'_{1T} + \alpha_2 V'_{2T} + \dots + \alpha_k V'_{kT}] \quad (B.11)$$

$$A' = V'_{fN} - [\alpha_1 V'_{1N} + \alpha_2 V'_{2N} + \dots + \alpha_k V'_{kN}] \quad (B.12)$$

Substituting Eqs. B.6 through B.10 into Eqs. B.11 and B.12, one obtains

$$S' = S_o - B_1 \tilde{p}_T \quad (B.13)$$

$$A' = A_o - B_2 \tilde{p}_N \quad (B.14)$$

where the initial (pre-impact) relative velocity of sliding  $S_o$ , the initial relative velocity of approach  $A_o$ , and the geometrical constants  $B_1$  and  $B_2$  are given by

$$S_o = [V_{fT} - \omega_f r_f] - [\alpha_1 V_{1T} + \alpha_2 V_{2T} + \dots + \alpha_k V_{kT}] \quad (B.15)$$

$$A_o = V_{fN} - [\alpha_1 V_{1N} + \alpha_2 V_{2N} + \dots + \alpha_k V_{kN}] \quad (B.16)$$

$$B_1 = \frac{1}{m_f} + \frac{r_f^2}{I_f} + \frac{\alpha_1^2}{m_1} + \frac{\alpha_2^2}{m_2} + \dots + \frac{\alpha_k^2}{m_k} \quad (B.17)$$

$$B_2 = \frac{1}{m_f} + \frac{\alpha_1^2}{m_1} + \frac{\alpha_2^2}{m_2} + \dots + \frac{\alpha_k^2}{m_k} \quad (B.18)$$

where in Eqs. B.15 and B.16 by definition  $A_o \geq 0$ ; otherwise, the two bodies will not collide with each other. Also, if  $S_o \geq 0$ , the fragment slides initially along the ring segment. It perhaps should be noted that sliding of the bodies on each other is assumed to occur at the value of "limiting friction" which requires that  $p_T = |\mu p_N|$ , and when  $p_T < |\mu p_N|$ , only rolling (i.e., no sliding) exists. For a given value of  $e$  and a given value of  $\mu$  which, respectively, describes the degree of "plasticity" of the collision process, and accounts for the frictional properties (roughness) of the contact surfaces<sup>+</sup>,  $2(k+1)+3$  equations (Eqs. B.6 - B.10 and Eqs. B.13 - B.14) can be solved to obtain the post-impact quantities  $(V'_{1N}, V'_{1T})$ ,  $(V'_{2N}, V'_{2T})$ ,  $\dots$ ,  $(V'_{kN}, V'_{kT})$ ,  $(V'_{fN}, V'_{fT})$  and  $\omega'_f$  as well as  $\tilde{p}_N$  and  $\tilde{p}_T$ ; these are the  $2(k+1)+3$  "unknowns".

<sup>+</sup>For  $\mu$  and  $e$  effects, see pages 335 and 336.

The graphic technique which provides a convenient way to obtain the values of  $\tilde{p}_N$  and  $\tilde{p}_T$  at the instant of the termination of impact as described in Ref. 5 is employed in the present collision-interaction analysis. In this technique, the trajectory of an "image" point  $\bar{P}$  in the plane formed by the impulse coordinates  $\tilde{p}_N$  and  $\tilde{p}_T$  (Fig. B.3) represents the state of the colliding bodies at each instant of the contact interval. The image point  $\bar{P}$  which is initially located at the origin and is denoted by  $\tilde{p}_0$  ( $\tilde{p}_N = 0$ ,  $\tilde{p}_T = 0$ ) will always proceed in the upper half-plane with increasing  $\tilde{p}_N$ . The locations of the line of no sliding  $S' = 0$  and the line of maximum approach  $A' = 0$  are determined by the system constants  $B_1$  and  $B_2$ . From Eqs. B.13 through B.18, it is noted that  $B_1$  and  $B_2$  are positive always; also the lines  $S' = 0$  and  $A' = 0$  are parallel to the  $\tilde{p}_N$  axis and the  $\tilde{p}_T$  axis, respectively, and intersect with each other at point  $P_3$  in the first quadrant of the  $\tilde{p}_N, \tilde{p}_T$  plane as shown in Fig. B.3. Depending on the values of the coefficient of sliding friction  $\mu$ , the coefficient of restitution  $e$ , the system constants  $B_1$  and  $B_2$ , and the initial conditions  $S_0$  and  $A_0$ , several variations of the impact process may occur and will be discussed in the following.

First, the cases in which the coefficient of sliding friction  $\mu$  ranges from  $0 < \mu < \infty$  will be considered; the two special cases with  $\mu = 0$  (perfectly-smooth contact surfaces) and  $\mu = \infty$  (completely rough surfaces) will be discussed shortly thereafter.

Case I: If  $0 < \mu < \infty$ , the friction angle  $\nu$  and the angle  $\Lambda$  formed with the  $\tilde{p}_N$  axis by the line connecting  $P_0$  and  $P_3$  are defined by

$$\text{and } \nu = \tan^{-1} \mu \quad (B.19)$$

$$\Lambda = \tan^{-1} \left( \frac{B_2 S_0}{B_1 A_0} \right) \quad (B.20)$$

Initially, the image point  $\bar{P}$  travels from point  $P_0$  along the path  $P_0 L$  which subtends an angle  $\nu$  with the  $\tilde{p}_N$  axis because the limiting friction impulse  $p_T = \mu p_N$  is developed during the initial stage of impact. Subsequently:

- (a) if  $\mu = \tan \nu < \tan \Lambda$  (Fig. B.3a), line  $P_0 L$  will intersect the line of maximum approach  $A' = 0$  at point  $P_1$ , before reaching the line of no sliding  $S' = 0$ . The intersection

point  $P_1$  represents the state at the instant of the termination of the approach period. This is followed by the restitution period; the impact process ceases at point  $P'$  (path  $P_0 - P_1 - P'$ ). The coordinates of  $P'$  are<sup>+</sup>

$$\tilde{p}_N = (1+e) p_{N1} \quad (B.21)$$

$$\tilde{p}_T = \mu \tilde{p}_N = \mu(1+e) p_{N1} \quad (B.22)$$

where  $p_{N1}$ , the ordinate of point  $P_1$  is determined from the simultaneous solution of equations  $p_T = \mu p_N$  and  $A' = 0$ , and is given by

$$p_{N1} = \frac{A_0}{B_2} \quad (B.23)$$

- (b) However, if  $\mu = \tan \bar{v} \geq \tan \Lambda$  (Fig. B.3b), line  $P_0L$  will intersect the line of no sliding  $S' = 0$  first at the intersection point  $P_2$  which marks the end of the initial sliding phase. The image point  $\bar{P}$  then will continue to proceed along the line of no sliding  $S' = 0$  through the intersection point  $P_3$  with line  $A' = 0$  to the end of impact at point  $P'$  (path  $P_0 - P_2 - P_3 - P'$ ). The final values of  $\tilde{p}_N$  and  $\tilde{p}_T$  are:

$$\tilde{p}_N = (1+e) p_{N3} \quad (B.24)$$

$$\tilde{p}_T = \frac{S_0}{B_1} \quad (B.25)$$

where  $p_{N3}$  is the ordinate of point  $P_3$  which represents the end of the approach period and is given by

$$p_{N3} = \frac{A_0}{B_2} \quad (B.26)$$

The above solution process can be specialized to represent the cases with  $\mu = 0$  and  $\mu = \infty$ .

Case II: If  $\mu = 0$  (perfectly smooth contact surfaces), line  $P_0L$  coalesces with the  $p_N$  axis. The image point  $\bar{P}$  will move along the  $p_N$  axis to the end of

<sup>+</sup> Coefficient of restitution  $e$ : perfectly elastic  $e = 1$ ; perfectly plastic  $e = 0$ ; and intermediate  $0 < e < 1$ .

impact. Thus

$$\tilde{p}_N = (1+e) \frac{A_o}{B_2} \quad (B.27)$$

$$\tilde{p}_T = 0 \quad (B.28)$$

Case III: If  $\mu = \infty$  (completely rough contact surface), point  $\bar{P}$  moves initially along the  $P_T$  axis to the intersection with  $S' = 0$ , then will follow the line  $S' = 0$  to the end of impact. The post impact value of  $\tilde{p}_N$  and  $\tilde{p}_T$  are

$$\tilde{p}_N = (1+e) \frac{A_o}{B_2} \quad (B.29)$$

$$\tilde{p}_T = \frac{S_o}{B_1} \quad (B.30)$$

Knowing the values of  $\tilde{p}_N$  and  $\tilde{p}_T$  at the end of impact for the above discussed various impact processes, the corresponding post-impact velocities then can be determined from Eqs. B.6 through B.10 as follows:

$$\left. \begin{aligned} V'_{IN} &= V_{IN} + \frac{\alpha_1 \tilde{p}_N}{m_1} \\ V'_{IT} &= V_{IT} + \frac{\alpha_1 \tilde{p}_T}{m_1} \end{aligned} \right\} \quad \text{Node 1} \quad (B.31)$$

$$\left. \begin{aligned} V'_{2N} &= V_{2N} + \frac{\alpha_2 \tilde{p}_N}{m_2} \\ V'_{2T} &= V_{2T} + \frac{\alpha_2 \tilde{p}_T}{m_2} \end{aligned} \right\} \quad \text{Node 2} \quad (B.32)$$

$$\left. \begin{aligned} V'_{kN} &= V_{kN} + \frac{\alpha_k \tilde{p}_N}{m_k} \\ V'_{kT} &= V_{kT} + \frac{\alpha_k \tilde{p}_T}{m_k} \end{aligned} \right\} \quad \text{Node k} \quad (B.33)$$



$$\left. \begin{aligned} V'_{fN} &= V_{fN} - \frac{\tilde{p}_N}{m_f} \\ V'_{fT} &= V_{fT} - \frac{\tilde{p}_T}{m_f} \\ \omega'_f &= \omega_f + \frac{r_f \tilde{p}_T}{I_f} \end{aligned} \right\} \text{Fragment} \quad (\text{B.34})$$

Thus, this approximate analysis provides the post-impact velocity information for the impact-affected nodes of the ring and for the fragment so that the time-wise step-by-step solution of this ring/fragment response problem may proceed. Note that these post-impact velocity components are given in directions N and T at each node of the idealized impact-affected ring segments; as explained later, these velocity components are then transformed to (different) directions appropriate for the curved-ring dynamic response analysis.

### B.3 Prediction of Containment/Deflector Ring Motion and Position

The timewise solution of the resulting equations of motion for the "complete assembled discretized structure", Eq. A.30<sup>+</sup>, may be accomplished by employing an appropriate timewise finite-difference scheme. The Houbolt operator which is a 4-point backward difference implicit operator is chosen for use in the present analysis. In this solution scheme, the  $\{\ddot{q}^*\}$  at any instant of time  $t_m$  are approximated by a 4-point backward-difference expression:

$$\{\ddot{q}^*\}_m = \frac{2\{q^*\}_m - 5\{q^*\}_{m-1} + 4\{q^*\}_{m-2} - \{q^*\}_{m-3}}{(\Delta t)^2} \quad (\text{B.35})$$

Employing Eq. B.35, Eq. A.30<sup>+</sup> becomes

$$\begin{aligned} \langle 2[M^*] + (\Delta t)^2([K] + [K_s]) \rangle \{q^*\}_m &= (\Delta t)^2 \left( \{F_q^{*NL}\}_m + \{F_p^{*L}\}_m + \{F_p^{*NL}\}_m \right) \\ &+ [M^*] \left( 5\{q^*\}_{m-1} - 4\{q^*\}_{m-2} + \{q^*\}_{m-3} \right) \end{aligned} \quad (\text{B.36})$$

It should be noted that the generalized nodal load vectors  $\{F_q^{*NL}\}_m$ ,  $\{F_p^{*L}\}_m$ , and  $\{F_p^{*NL}\}_m$  which may be due to large-deflections and elastic-plastic effects) depend on the displacements (or stresses, strains) at that time instant  $t_m$ , but these

<sup>+</sup> Now with  $\{F\} \equiv 0$ .

remain to be determined; thus, linear extrapolation<sup>+</sup> by using the generalized nodal load vectors at two previous time steps is employed to estimate these force values. Thus, one has

$$\begin{aligned} \langle 2[M^*] + (\Delta t)^2([K] + [K_s]) \rangle \{ \ddot{q}^* \}_m &= (\Delta t)^2 \left( \{ \ddot{F}_f^{*NL} \} + \{ \ddot{F}_p^{*L} \} + \{ \ddot{F}_p^{*NL} \} \right)_{m-1} \\ &+ (\Delta t)^2 \left( \{ \ddot{F}_f^{*NL} \} + \{ \ddot{F}_p^{*L} \} + \{ \ddot{F}_p^{*NL} \} \right)_{m-2} + [M^*] \left( 5 \{ \ddot{q}^* \}_{m-1} - 4 \{ \ddot{q}^* \}_{m-2} + \{ \ddot{q}^* \}_{m-3} \right) \end{aligned} \quad (B.37)$$

It follows that one can solve for  $\{q^*\}_m$ , since all of the quantities on the right-hand side are known. However, a fragment-ring collision may occur between time instants  $t_{m-1}$  and  $t_m$ ; this would require a "correction" to the  $\{q^*\}_m$  found from Eq. B.37. Thus, one first uses Eq. B.36 to form a trial value (overscript T):

$$\{ \Delta \ddot{q}^* \}_m = \{ \ddot{q}^* \}_m - \{ \ddot{q}^* \}_{m-1} \quad (B.38)$$

Next, the collision inspection and correction procedures, which will be described in Subsection B.6, are performed to determine the actual displacement increments  $\{\Delta q^*\}_m$ . Then, the actual displacement at the  $t_m$  is given by

$$\{ q^* \}_m = \{ q^* \}_{m-1} + \{ \Delta q^* \}_m \quad (B.39)$$

No such trial-and-correction procedure is needed if only prescribed external forces were applied to the containment/deflection ring.

In order to apply the calculation method represented by Eqs. B.37, one must taken into account the prescribed initial conditions,  $\{q\}_0$ ,  $\{\dot{q}\}_0$ , and, if present,  $\{F^*\}_0$ . The following "starting procedure" for this method provides the generalized displacements  $\{q^*\}$  at  $t_1 = 1\Delta t$ , and  $\{q^*\}_{-1}$  at a negative (fictitious) time instant  $t_{-1} = -1\Delta t$ .

By employing the following approximations:

$$\{ \dot{q}^* \}_0 = \frac{2 \{ q^* \}_1 + 3 \{ q^* \}_0 - 6 \{ q^* \}_{-1} + \{ q^* \}_{-2}}{6(\Delta t)} \quad (B.40)$$

and

$$\{ \ddot{q}^* \}_0 = \frac{\{ q^* \}_1 - 2 \{ q^* \}_0 + \{ q^* \}_{-1}}{(\Delta t)^2} \quad (B.41)$$

<sup>+</sup>Because of this extrapolation (aside from impact considerations themselves) the maximum time step which will lead to results of suitable engineering accuracy remain unknown but clearly is limited although the Houbolt operator itself exhibits unconditional stability.

one has

$$\{\dot{q}^*\}_{-1} = (\Delta t)^2 \{\ddot{q}^*\}_0 + 2\{\dot{q}^*\}_0 - \{\dot{q}^*\}_1 \quad (\text{B.42})$$

$$\{\dot{q}^*\}_{-2} = 6(\Delta t)^2 \{\ddot{q}^*\}_0 + 6(\Delta t)\{\dot{q}^*\}_0 + 9\{\dot{q}^*\}_1 - 8\{\dot{q}^*\}_2 \quad (\text{B.43})$$

Substituting Eqs. B.42 and B.43 into Eq. B.37 for  $m = 1$  and approximating the generalized nodal load vectors due to large-deflections and elastic-plastic effects at time step  $t_1$  by their values at time zero, one obtains

$$\begin{aligned} \langle 6[M^*] + (\Delta t)^2([K^*] + [K_s^*]) \rangle \{\dot{q}^*\}_1 = (\Delta t)^2 \left( \{\ddot{F}_q^*{}^{NL}\}_0 + \{\ddot{F}_p^*{}^L\}_0 + \{\ddot{F}_p^*{}^{NL}\}_0 \right) \\ + [M^*] \langle 2(\Delta t)^2 \{\ddot{q}^*\}_0 + 6(\Delta t)\{\dot{q}^*\}_0 + 6\{\dot{q}^*\}_1 \rangle \end{aligned} \quad (\text{B.44})$$

where  $\{\ddot{q}\}_0$  can be calculated from

$$[M^*]\{\ddot{q}^*\}_0 = \{\ddot{F}^*\}_0 - ([K^*] + [K_s^*])\{\dot{q}^*\}_0 \quad (\text{B.45})$$

#### B.4 Prediction of Fragment Motion and Position

In the present analysis, the fragment is assumed (see Refs. 3,4) to be undeformable and, for analysis convenience to be circular; hence, its equations of motion for the case of no externally-applied forces are:

$$m_f \ddot{Y}_f = 0 \quad (\text{B.46})$$

$$m_f \ddot{Z}_f = 0 \quad (\text{B.47})$$

$$I_f \ddot{\theta} = 0 \quad (\text{B.48})$$

where  $(Y_f, Z_f)$  and  $(\ddot{Y}_f, \ddot{Z}_f)$  denote, respectively, the global coordinates and acceleration components of the center of gravity of the fragment (see Fig. B.2).

$\theta$  represents the angular displacement of the fragment in the  $\omega_f$  direction (Fig. B.2).

In timewise finite-difference form Eqs. B.46 through B.48 become

$$(\Delta \overset{T}{Y}_f)_m = (\Delta Y_f)_{m-1} \quad (B.49)$$

$$(\Delta \overset{T}{Z}_f)_m = (\Delta Z_f)_{m-1} \quad (B.50)$$

$$(\Delta \overset{T}{\theta})_m = (\Delta \theta)_{m-1} \quad (B.51)$$

where overscript "T" signifies a trial value which requires modification, as explained later, if ring-fragment collision occurs between  $t_{m-1}$  and  $t_m$ .

By an inspection procedure to be described shortly, the instant of ring-fragment collision is determined, and the resulting collision-induced velocities which are imparted to the fragment and to the affected ring segments are determined in accordance with the analysis of Subsection B.2.

## B.5 Collision Inspection and Solution Procedure

### B.5.1 One-Fragment Attack

The collision inspection and solution procedure will be described first for the case in which only one idealized fragment is present. With minor modifications, this procedure can also be applied for an n-fragment attack as discussed in Subsection B.5.2.

Equation B.37 can be rewritten as follows

$$\begin{aligned} & \left\langle 2[M^*] + (\Delta t)^2 ([K^*] + [K_s]) \right\rangle \{\ddot{q}^*\}_{m+1} \\ &= (\Delta t)^2 \left\langle \{\ddot{F}_q^{NL}\}_{m+1} + \{\ddot{F}_p^L\}_{m+1} + \{\ddot{F}_p^{NL}\}_{m+1} \right\rangle + 2[M^*] (\{\ddot{q}^*\}_m + \{\ddot{q}^*\}_m \Delta t) \end{aligned} \quad (B.52)$$

in order to solve for a trial value of displacements at time step  $m+1$ , knowing the quantities at time step  $m$ .

The following procedure, indicated in the flow diagram of Fig. 9, may be employed to predict the motions of the ring and rigid fragment, their possible collision, the resulting collision-imparted velocities experienced by each, and the subsequent motion of each body:

Step 1:

Let it be assumed at time  $t_m$  that the displacements  $\{q^*\}_m$ ,  $(Y_f)_m$ , and  $(Z_f)_m$  and displacement increments  $\{\Delta q^*\}_m$ ,  $(\Delta Y_f)_m$ , and  $(\Delta Z_f)_m$  are known. One can then calculate the strain increments  $(\Delta \epsilon)_m$  at all Gaussian stations along and through the thickness of the ring.

Step 2:

Using a suitable constitutive relation for the ring material, the stress increments  $(\Delta \sigma)_m$  and the plastic strain increments  $(\Delta \epsilon_m^p)$  at corresponding Gaussian stations within each finite element can be determined from the known strain increments  $(\Delta \epsilon)_m$ . This information permits determining all quantities on the right-hand side of Eq. 52.

Step 3:

Solve Eq. B.52 for the trial ring displacements  $\{q^*\}_{m+1}^T$ , then solve for the trial displacement increments,  $\{\Delta q^*\}_{m+1}^T$ , by using Eq. B.38, and use Eqs. B.49 through B.51 for the trial fragment displacement increments  $(\Delta Y_f)_{m+1}^T$ ,  $(\Delta Z_f)_{m+1}^T$ , and  $(\Delta \theta)_{m+1}^T$ .

The ring node velocities  $\{\dot{q}^*\}_m$  at time  $t_m$  are calculated by the following Houbolt expression:

$$\begin{aligned} \{\dot{q}^*\}_m &= \frac{3\{q^*\}_m - 4\{q^*\}_{m-1} + \{q^*\}_{m-2}}{2 \Delta t} \\ &= \frac{3\{\Delta q^*\}_m - \{\Delta q^*\}_{m-1}}{2 \Delta t} \end{aligned} \quad (B.53)$$

if an impact has not occurred in the previous time step (post-impact corrections will be described below).

It is assumed that the fragment velocities,  $(\dot{Y}_f)_m$ ,  $(\dot{Z}_f)_m$ , and  $(\dot{\theta}_f)_m$  at time  $t_m$  are known.

Since one or more ring-fragment collisions may have occurred between  $t_m$  and  $t_{m+1}$ , the following sequence of steps may be employed to determine whether or not a collision occurred and, if so, to effect a correction of the displacement increments of the impact-affected ring segments and of the fragment.

Step 4:

In the present scheme, several collisions may occur during a given global time step  $\Delta t = (t_{m+1} - t_m)$ . This can be accommodated by repeating these checks until no further impacts can be found and corrected. Because the impact inspection is most conveniently carried out in the global Y,Z coordinate system, one first transforms the nodal displacement vector at time  $t_{m+1}$ ,  $\{q^*\}_{m+1}$ , into the global Y,Z coordinate system; note that  $\{q^*\}_{m+1}$  is the trial value obtained from Eq. B.52. The fragment information is already in the global Y,Z system and the values at time  $t_{m+1}$  are found from the following equations:

$$\begin{aligned} (Y_f)_{m+1} &= (Y_f)_m + (\dot{Y}_f)_m \Delta t \\ (Z_f)_{m+1} &= (Z_f)_m + (\dot{Z}_f)_m \Delta t \\ (\theta_f)_{m+1} &= (\theta_f)_m + (\dot{\theta}_f)_m \Delta t \end{aligned} \tag{B.54}$$

Having completed these initializations, the following sequence of substeps may be employed to determine whether or not a collision occurs within the  $\Delta t$ .

Step 4a:

To check for the possibility of a collision between the fragment and ring element  $j$  (approximated as a straight beam) as depicted in Fig. B.5, compute the trial projection  $(\bar{p}_j^T)_{m+1}$  of the line from ring node  $j$  to point  $C_f$  at the center of the fragment, upon the straight line connecting ring nodes  $j$  and  $j+1$ , as follows, at time instant  $t_{m+1}$ :

$$\begin{aligned} (\bar{p}_j^T)_{m+1} &= (\bar{Y}_j^T - \bar{Y}_f^T) \cos(\delta_j^T)_{m+1} \\ &\quad + (\bar{Z}_j^T - \bar{Z}_f^T) \sin(\delta_j^T)_{m+1} \end{aligned} \tag{B.55}$$

where  $(\delta_j^T)_{m+1}$  is the angle measured counterclockwise from the global Y axis to the vector from node  $j$  to node  $j+1$  and where the Y,Z are inertial Cartesian coordinates obtained from

$\{\bar{q}^*\}_{m+1}$ ,  $(\bar{Y})_{m+1}$  etc. Now, examine  $(\bar{p}_j)^T_{m+1}$ ; three cases are illustrated in Fig. B.5a.

Step 4b:

If  $(\bar{p}_j)^T_{m+1} < 0$  or if  $(\bar{p}_j)^T_{m+1} > \ell_j$  where  $\ell_j > 0$ , a collision between the fragment and ring element  $j$  is impossible. Proceed to check ring element  $j+1$ , etc., for the possibility of a collision of the fragment with other ring elements. Note that  $\ell_j$  is the length of the  $j$ th element at time  $t_{m+1}$ .

Step 4c:

If  $0 \leq (\bar{p}_j)^T_{m+1} \leq \ell_j$ , a collision with ring element  $j$  is possible, and further checking is pursued. Next, calculate the fictitious "penetration distance"  $(\bar{a}_j)^T_{m+1}$  of the fragment into ring element  $j$  at point  $C_r$  by (see Fig. B.5b):

$$(\bar{a}_j)^T_{m+1} = \left[ \frac{1}{4} (h_{1j} + h_{2j}) + r_f \right]_{m+1} - \left[ \bar{d}_j \right]_{m+1} \quad (\text{B.56})$$

where

$\left[ \frac{1}{4} (h_{1j} + h_{2j}) \right]$  = average distance from the reference surface to the inner surface of the ring element which is approximated as a straight beam in this "collision calculation".

$r_f$  = radius of the fragment

$$\begin{aligned} \left[ \bar{d}_j \right]_{m+1} = & - \left[ \bar{Y}_j - \bar{Y}_f \right]_{m+1} \sin \left( \bar{\delta}_j \right)_{m+1} \\ & + \left[ \bar{Z}_j - \bar{Z}_f \right]_{m+1} \cos \left( \bar{\delta}_j \right)_{m+1} \end{aligned} \quad (\text{B.57})$$

= the projection of the line connecting node  $j$  with the center of the fragment upon a line perpendicular to the line joining nodes  $j$  and  $j+1$ .

Next, examine  $(\bar{a}_j)^T_{m+1}$  which is indicated schematically in Fig. 5b and is given by Eq. B.56.

Step 5:

The impact with the largest penetration is corrected first. The fragment and nodal position are returned to their location at the beginning of the time step, i.e., time  $t_m$ . Then, the impact is always assumed to occur at the beginning of a time step regardless of when the "actual" time of contact occurred.

Based on the collision-interaction analysis developed in Subsection B.2, the post-impact velocities of the impact-affected ring nodes and the fragment are now calculated. That is, the pre-impact nodal velocities ( $\{\dot{q}^*\}$  at time  $t = t_m$ ) and fragment velocities ( $\dot{Y}_f, \dot{Z}_f, \dot{\theta}_f$  at time  $t + t_m$ ) are updated to their post-impact values using Eqs. B.31 through B.34.

(Note that Eqs. B.31-B34 are written in terms of an N,T coordinate system, as defined in Subsection B.2. Thus, the nodal and fragment velocities, assumed to be in the global Y,Z coordinate system prior to the collision-interaction analysis, must be transformed into the N,T system at the start of the collision-interaction analysis, and the resulting post-impact velocities, calculated in the N,T system via Eqs. B.31-B.34, must then be transformed back to the global Y,Z system after completion of the collision-interaction analysis.)

For convenience, the post-impact velocity information, in the global Y,Z coordinate system, is assumed to "replace" the pre-impact velocity information. Thus, the quantities  $\{\dot{q}^*\}_m$ ,  $(\dot{Y}_f)_m$ ,  $(\dot{Z}_f)_m$ , and  $(\dot{\theta}_f)_m$  now refer to the post-impact velocity of the ring-nodes and fragment at the time of "assumed contact",  $t_m$ .

Step 6:

A new trial displacement  $\{q^*\}_{m+1}$  is now calculated using Eq. B.52 and the new post-impact-corrected nodal velocities  $\{\dot{q}^*\}_m$ .



Step 7:

A decision must now be made concerning whether or not to continue on to another collision inspection. The collision inspection/correction process is repeated if the number of collision inspection/corrections within the current  $\Delta t$  has not exceeded a specified maximum<sup>+</sup> (equal to 5 per fragment in the present analysis). If this condition is violated, the program will immediately proceed to Step 8. Otherwise, the program proceeds to Step 4.

Step 8:

The delta quantities are now calculated for both the nodal and fragment displacements (i.e.,  $\{\Delta q^*\}_{m+1} = \{q_{m+1}\} - \{q_m\}$ ; this calculation occurs regardless of whether or not an impact occurred during the time step). The program now returns to the MAIN subprogram.

Step 9:

The nodal velocities at time  $t_{m+1}$  are now calculated. If no impact occurred during the previous time step, then Eq. B.53 is used to calculate  $\{\dot{q}^*\}_{m+1}$ . However, if impact occurred in the previous cycle, then Eq. B.53 is modified for all of the translational velocities<sup>++</sup> only. To find  $\{q^*\}_{m+1}$  from Eq. B.53, it is necessary to know  $\{q^*\}_{m-1}$ . This quantity, as previously stored by the program, has no meaningful value because impact has occurred since  $t_{m-1}$ . To approximate  $\{q^*\}_{m-1}$  a definition is given for the post-impact velocity  $\{\dot{q}^*\}_m$  as follows:

$$\{\dot{q}^*\}_m = \frac{\{q^*\}_{m+1} - \{q^*\}_{m-1}}{2 \Delta t} \quad (\text{B.58})$$

Solving Eq. B.58 for  $\{q^*\}_{m-1}$  and substituting this value into Eq. B.53, the following expression for the updated translational

<sup>+</sup>The specified maximum has been included to prevent the program endlessly looping at this point due to the use of a large  $\Delta t$  by the user and the fact that internal forces ( $\{F_q^{*NL}\}$ ,  $\{F_p^*L\}$ , and  $\{F_p^{*NL}\}$ ) in Eq. B.52 are extrapolated quantities, not updated within a  $\Delta t$ .

<sup>++</sup>Velocities associated with D.O.F.'s  $\psi$  and  $\chi$  are still calculated using Eq. B.53 only.

velocities is found:

$$\{\dot{q}^*\}_{m+1} = \frac{2}{\Delta t} \left( \{q^*\}_{m+1} - \{q^*\}_m \right) - \{\dot{q}^*\}_m \quad (\text{B.59})$$

At this point, a new set of strains is calculated and used to find the internal forces. With this quantity and the velocity at  $t_{m+1}$ , a trial value of  $\{q^*\}_{m+2}$  can be obtained from Eq. B.52 and the program returns to Step 4.

This solution procedure may be carried out for as many time steps as desired or may be terminated by invoking the use of a termination criterion such as, for example, the reaching of a critical value of the strain at the inner surface or the outer surface of the ring. Appropriate modifications of this approximate analysis could be made, if desired, to follow the behavior of the ring and the fragment after the initiation and/or completion of local fracturing of the ring has occurred; however, this has not been done in the present program.

Finally, note that it is possible for the fragment to come in contact with two ring elements simultaneously. In this situation, a correction would be made for the lower-numbered element first as noted in Step 5. A "flag" is set to indicate a simultaneous impact and these corrections are made before Step 6 is executed. A similar situation occurs when multiple fragments impact the ring simultaneously, as will be discussed in the next subsection.

#### B.5.2 N-Fragment Attack

In the case of "attack" by  $n$  idealized fragments, each with its individual  $m_f$ ,  $I_f$ ,  $r_f$ ,  $\omega_f$ ,  $V_{fN}$ , and  $V_{fT}$ , a similar procedure is used. During each  $\Delta t$ , the collision-inspection procedure is carried out for every fragment; none, some, or all of these  $n$  fragments may have collided with one or more of the ring segments. If any positive penetration distances are computed, the calculation of ring-fragment contact time will follow for each element and each of the  $n$  fragments in turn. This calculation sequence will identify the first ring-fragment contact within  $\Delta t$ , and the fragment number and element number involved in the collision. The appropriate corrections, as a result of this collision,

will be made, and the process will be repeated. The same fragment or a different fragment may collide with the ring structure; the appropriate corrections will then be made for this collision. This process is repeated until (1) more than 5 ring-fragment collisions occur for a given fragment, or (2) no more ring-fragment collisions are found within the global time step,  $\Delta t$ . After all of the corrections have been carried out for the present  $\Delta t$  time intervals, the calculation process of Fig. 9 proceeds similarly for the next  $\Delta t$ .

Note that it is possible for two or more fragments to impact the ring structure simultaneously. This plausible situation is accommodated in the present scheme. Because of the "flagging" scheme discussed in the previous subsection, the collision involving the lower fragment number will be corrected for first. Corrections will be made for all fragments involved in the simultaneous impact, before Step 6 is executed. In essence, the ring structure and fragment positions remain unaltered while a series of corrections is made, corresponding to all of the fragments which impact simultaneously.

Finally, it should be noted that no provisions have been made for collisions (or interactions) between the fragments themselves. Thus, all collisions (and subsequent interactions) are assumed to be between a fragment and the ring structure.

#### B.6 Ring-Fragment Collision on or Near a Constrained Node

The impact-interaction analysis presented in Subsection B.2 is based on the assumption that all nodes within the impact-affected region are free to respond with velocity changes as a result of ring-fragment collision. If any of the nodes within the impact-affected region are constrained, then the analysis of Subsection B.2 must be modified slightly. These modifications, and their subsequent application to the present analysis, are described in the present subsection.

For the present analysis, assume that one of the nodes within the impact-affected region is constrained such that no normal or tangential motion is permitted. Denote this node number by the subscript "c". At node c, the constraint will contribute a reaction force (or reaction impulse) so that the translational impulse-momentum relations (Eqs. B.7 and B.9) at node c must now be written as

$$m_c [V'_{CN} - V_{CN}] = \alpha_c \tilde{p}_N - p_N^R \quad (B.60a)$$

$$m_c [V'_{CT} - V_{CT}] = \alpha_c \tilde{p}_T - p_T^R \quad (B.60b)$$

where the additional terms  $p_N^R$  and  $p_T^R$  are the reaction impulses at node c in the normal and tangential directions, respectively. The pre-impact velocities,  $V_{CN}$  and  $V_{CT}$ , must be zero and because of the constraint, the post-impact velocities must also be zero, thus Eqs. B.60 state that the restraint "absorbs" all of the impulse associated with the constrained node.

The analysis developed in Subsection B.2 can be followed exactly if the value of  $\alpha$  for the constrained node is set equal to zero, i.e.

$$\alpha_c = 0 \quad (B.61)$$

This is equivalent to introducing equations of the form of Eq. B.60 and immediately solving for the reaction impulse, which yields a total value of zero on the right-hand side of Eq. B.60. In practice, the use of Eq. B.61 allows one to treat the special case of impact on or near a constrained node within the framework and equations developed in Subsection B.2.

It should be noted that the quantity  $\alpha'$  for the constrained node is not set equal to zero. This quantity defines the relative portion of the total imparted impulse which is associated with a given node which lies within the impact-affected region, and is calculated by using Eq. A.31 whether or not the node is constrained. In general, the constrained node may fall anywhere within the impact-affected region. Because of the character of the present impact interaction analysis in which only translational (not rotational) motion of the ring is considered (both translational and rotational motion are included in the global timewise solution), it is difficult to include the effects of impulse propagated past the constrained node. For the case where the node is ideally clamped, no information can propagate through the constraint. But if the node is pinned-fixed, rotational information could propagate past the constraint; to accommodate this situation, rotational

effects would have to be included in the analysis of Subsection B.2. An alternate, interim measure is taken in the present analysis, and is described next.

Assume that the point of contact and the effective length,  $L_{eff}$ , are such that the constrained node and nodes beyond the constrained node fall within the impact-affected region. Because the analysis of Subsection B.2 cannot predict the propagation of impact information past the constrained node, the effective length,  $L_{eff}$ , is, in the present scheme, artificially reduced (for the current  $\Delta t$  only) in such a way that the constrained node falls within the impact-affected region but no nodes past the constrained node fall in the impact-affected region. Having redefined  $L_{eff}$  in this fashion, the equations of Subsection B.2 are then followed exactly with Eq. B.61 being employed at the constrained node. This approach has the effect of concentrating the impact-induced impulse at those ring nodes on the impacted side of the constraint, with a portion of the impact-induced impulse being absorbed by the constraint, and no impulse being felt at nodes beyond the constrained node. However, it should be recognized that, although no impulse information is passed through the constrained node by the impact interaction analysis, the impact information will propagate through the constrained node, if physically possible, in the global timewise structural response solution.

For the case where impact occurs directly on a constrained node, only that constrained node is assumed to lie within the impact-affected region. Following the equations in Subsection B.2 and employing Eq. B.61, the fragment will simply rebound (as if impacting a rigid wall) and the ring structure will experience no momentum changes for this impact.

Finally, it should be noted that the present approach is an interim measure, and further effort is required to develop a more comprehensive approach for treating impact near a constrained node. However, the present method is believed to be sufficiently general, within the current overall assumptions of the analysis, to yield reasonable results for current engineering applications.

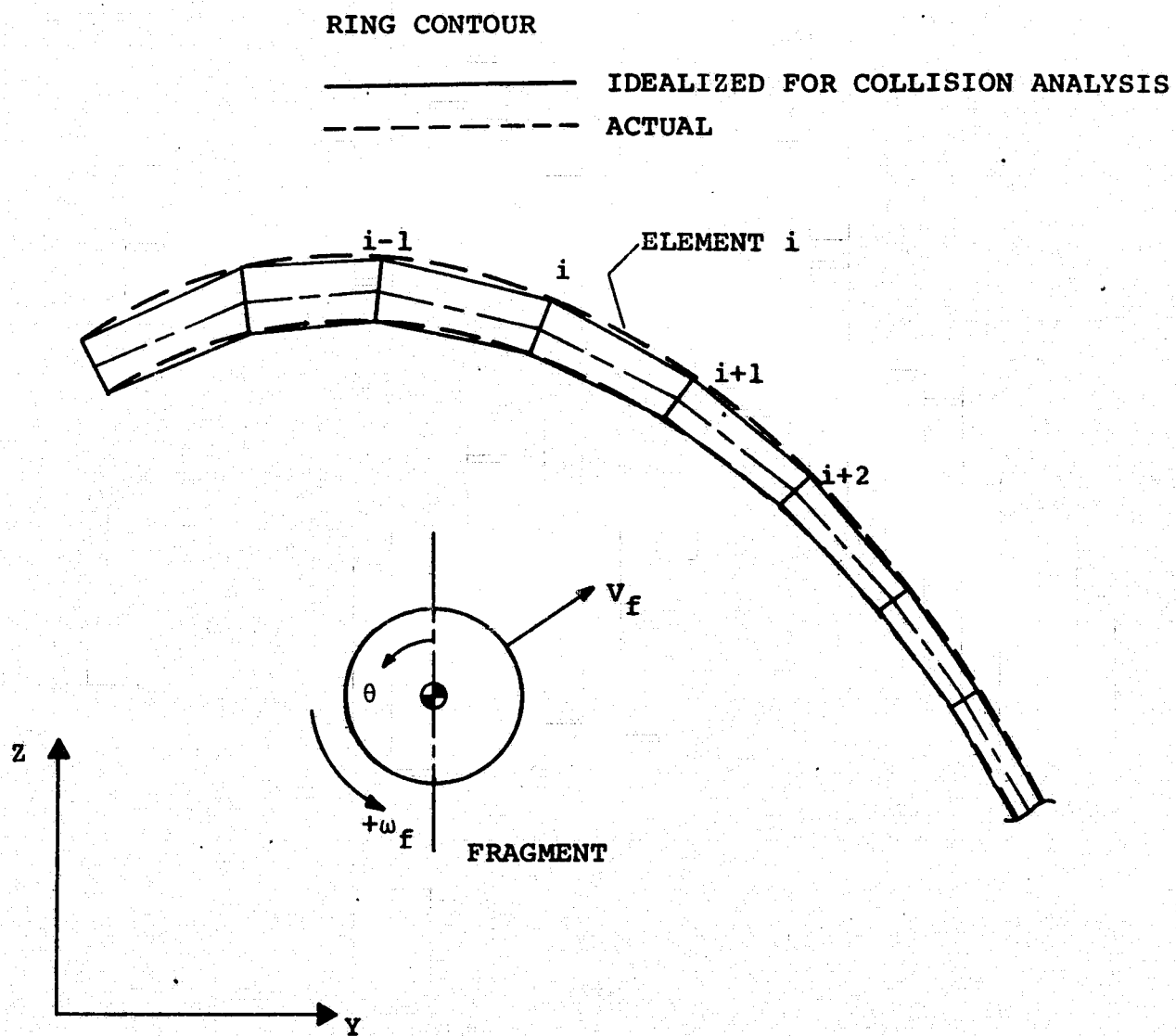
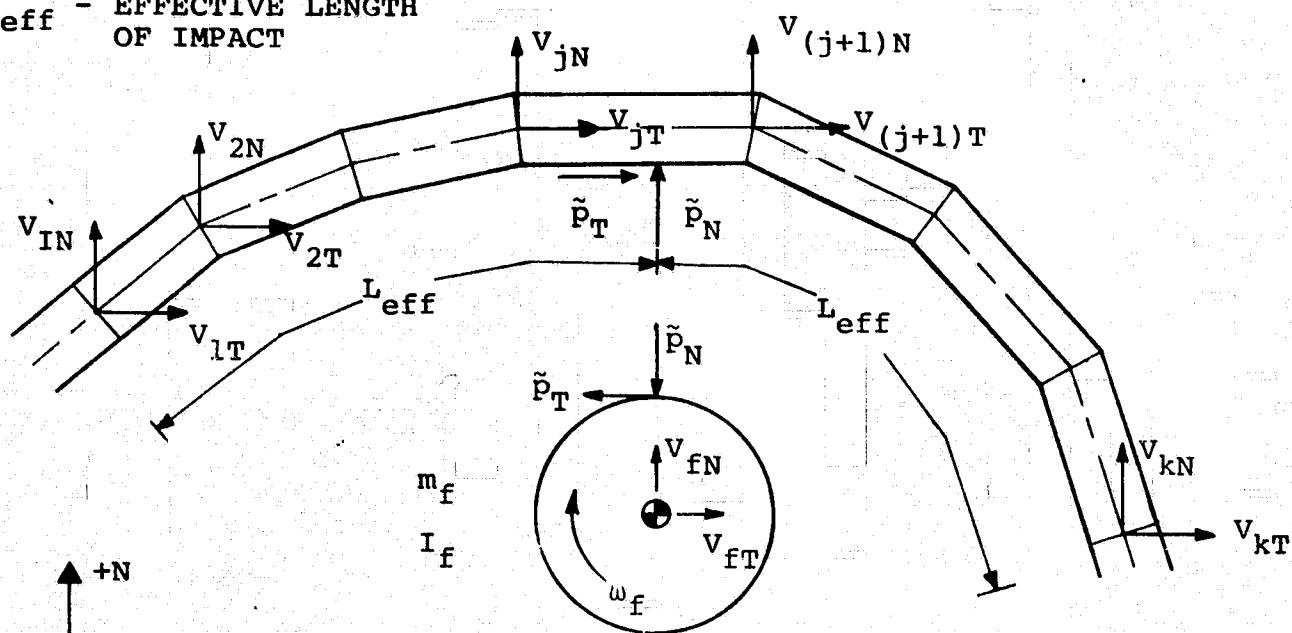
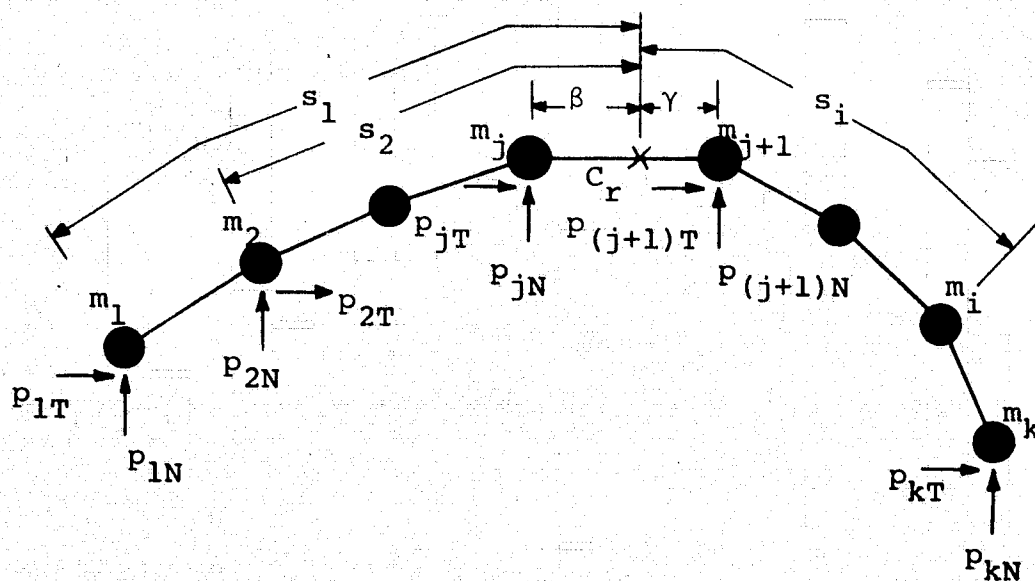


FIG. B.1 IDEALIZATION OF RING CONTOUR FOR COLLISION ANALYSIS

$L_{eff}$  - EFFECTIVE LENGTH  
OF IMPACT



(a) Impact-Affected Segments of the Ring



(b)  $\beta < L_{eff}$  and  $\gamma < L_{eff}$

FIG. B.2 EXPLODED SCHEMATICS OF THE LUMPED-MASS COLLISION MODELS

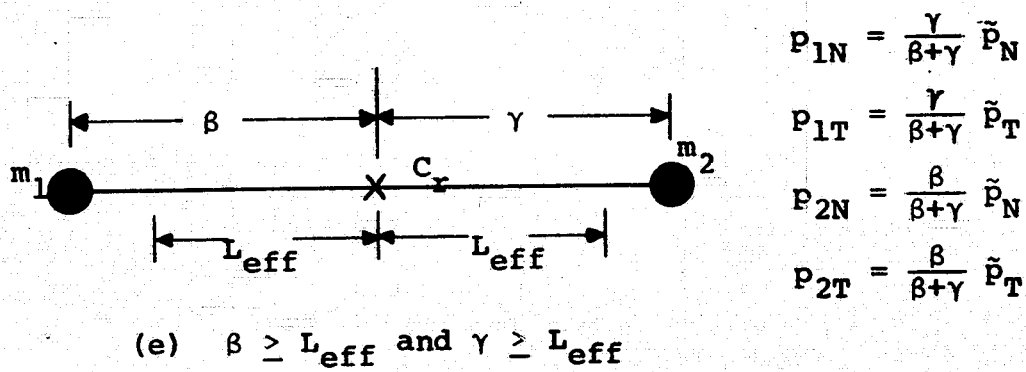
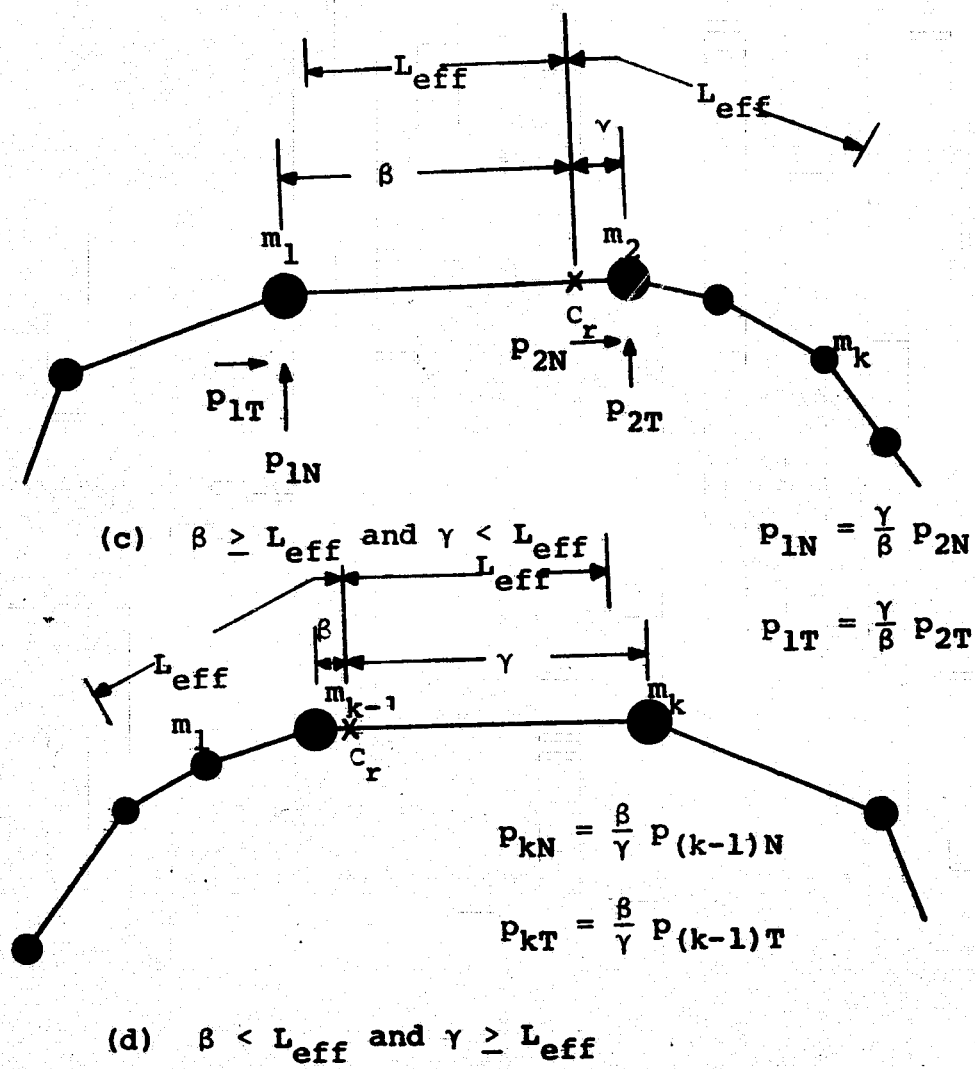
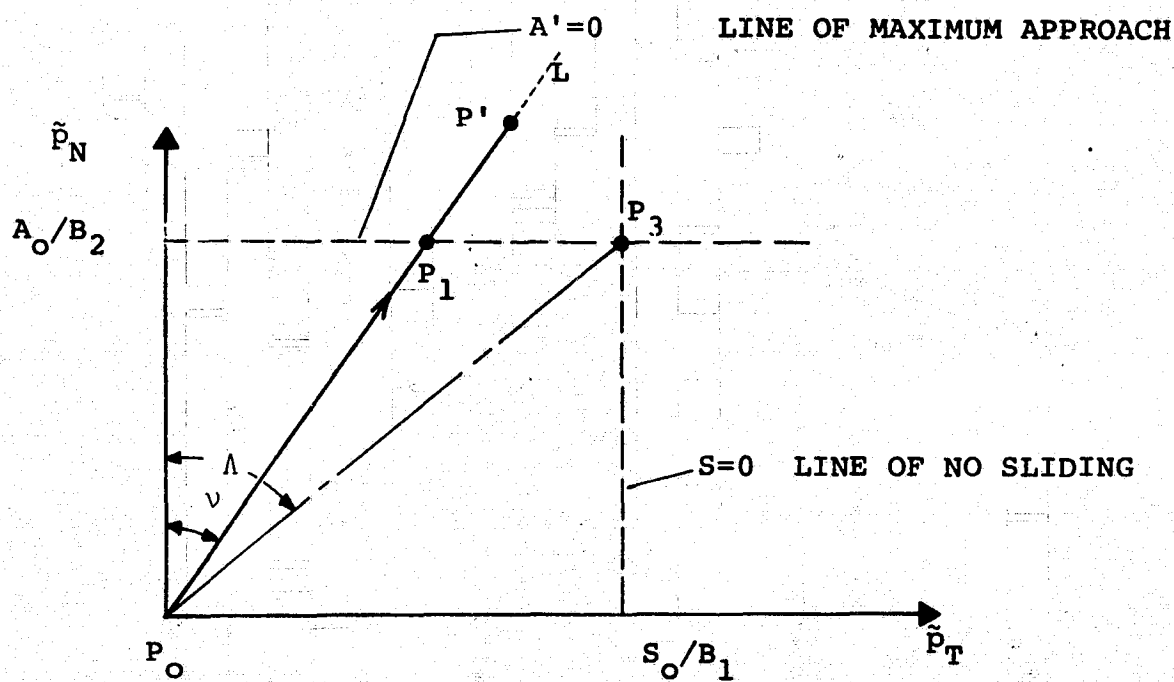
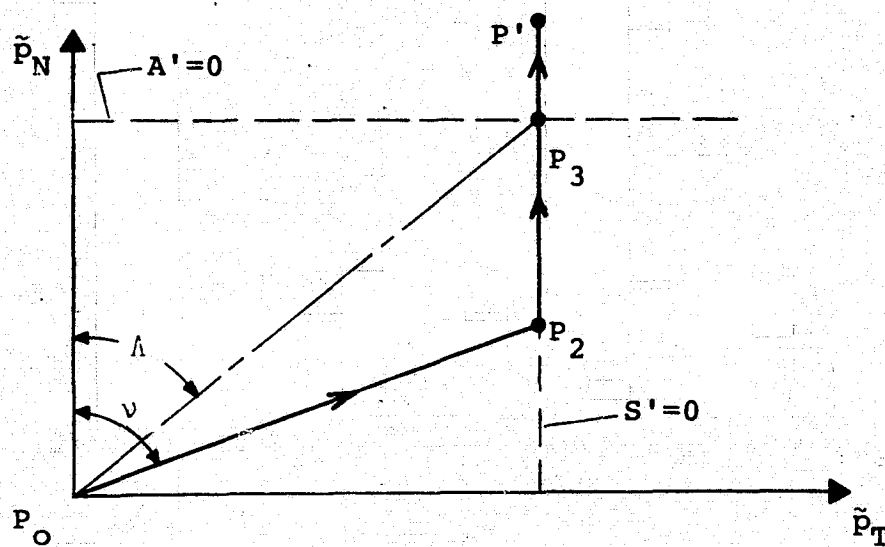


FIG. B.2 CONCLUDED





(a)  $v < \lambda$



(b)  $v \geq \lambda$

FIG. B.3 THE TRAJECTORY OF THE IMAGE POINT  $\bar{P}$  IN THE  $\tilde{p}_N, \tilde{p}_T$  PLANE TO DESCRIBE THE STATE AT EACH CONTACT INSTANT

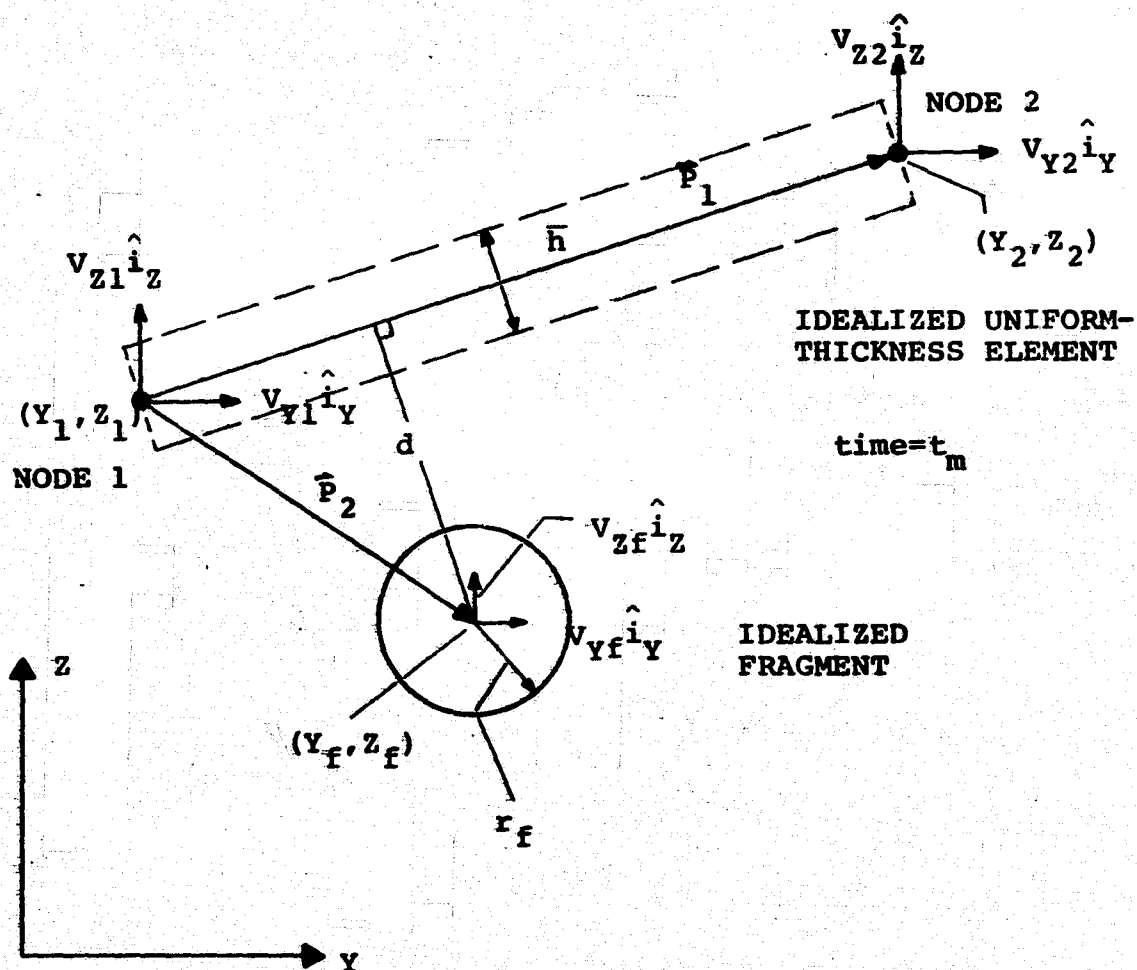


FIG. B.4 IDEALIZATIONS AND DEFINITIONS FOR CALCULATION OF TIME OF RING-FRAGMENT CONTACT

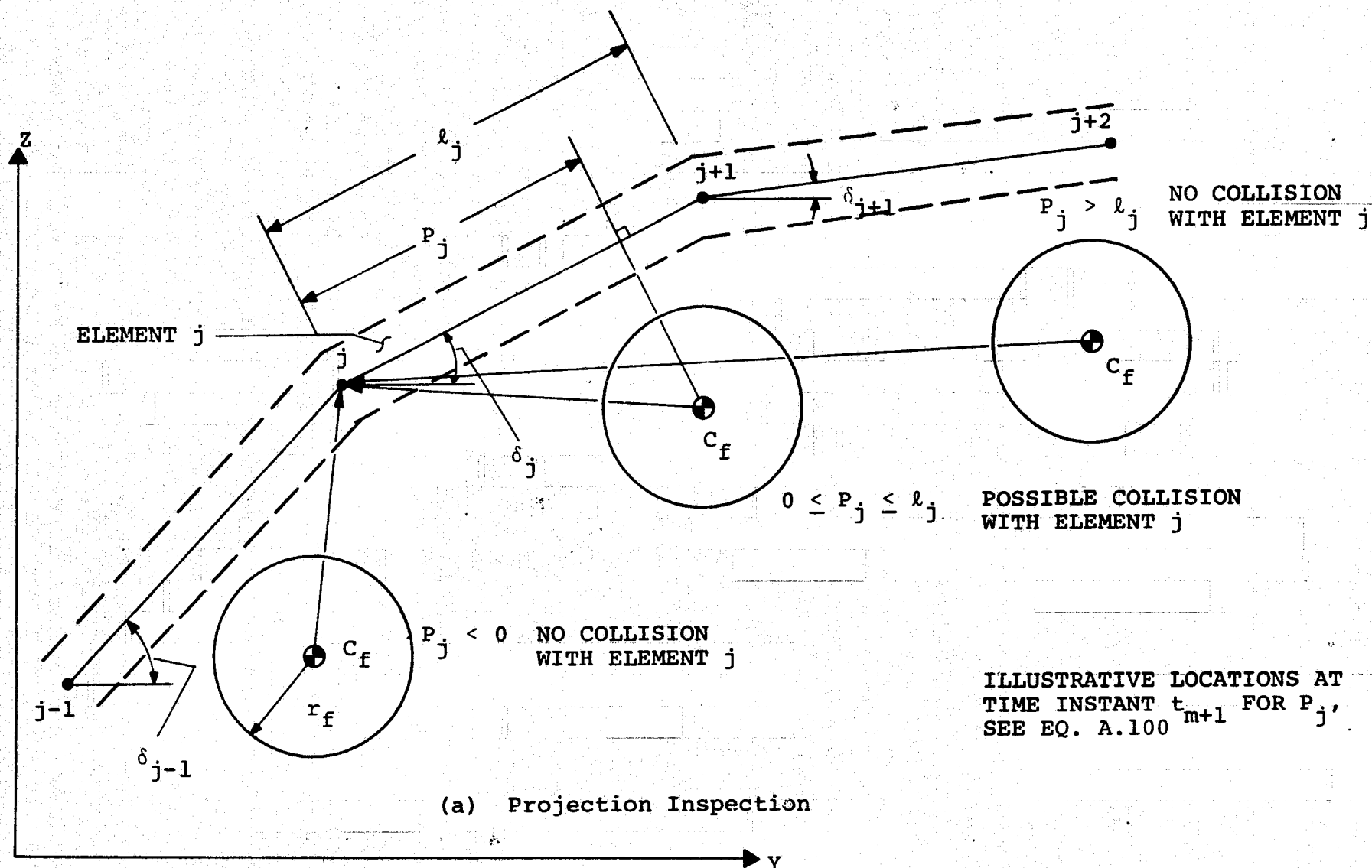
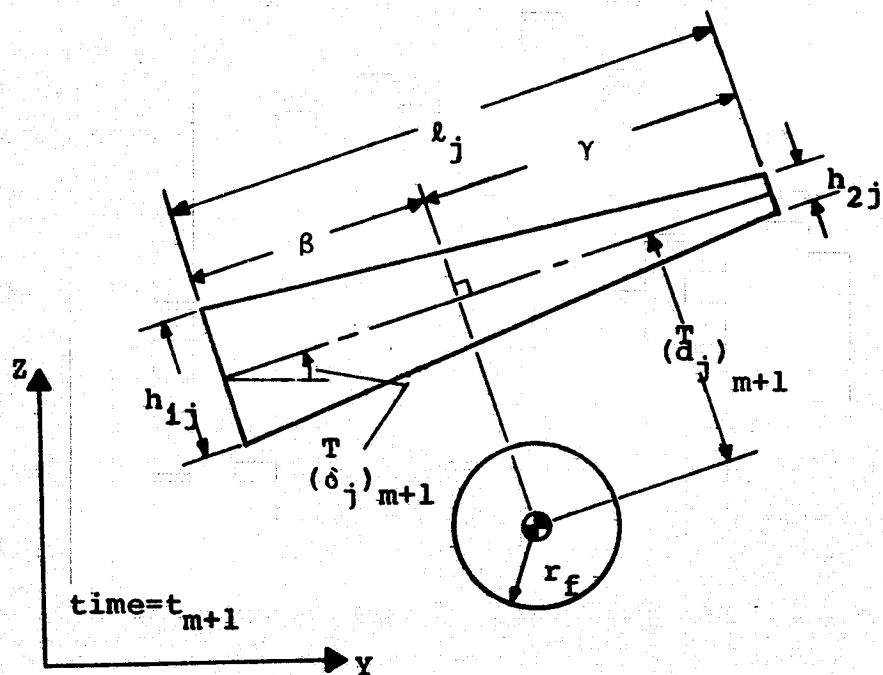
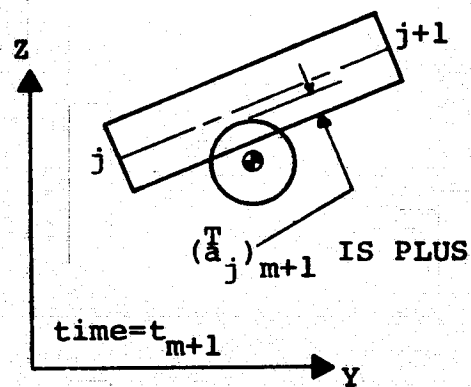
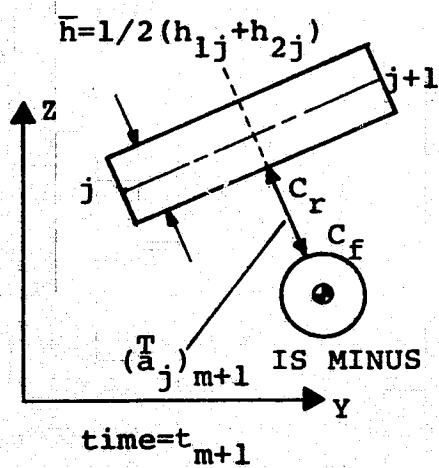


FIG. B.5 INSPECTION FOR DETERMINING A COLLISION OF THE FRAGMENT WITH THE RING



#### IDEALIZED UNIFORM-THICKNESS ELEMENT



(b) Penetration Inspection

FIG. B.5 CONCLUDED

## APPENDIX C

### SUMMARY OF THE CAPABILITIES OF MIT-ASRL COMPUTER CODES FOR PREDICTING TWO-DIMENSIONAL LARGE-DEFLECTION ELASTIC-PLASTIC TRANSIENT RESPONSES OF RING STRUCTURES

This description is intended to provide for the reader a convenient tabular summary of the principal features and capabilities of the two-dimensional transient large-deflection elastic-plastic structural response ring codes JET 1 (Ref. 1\*), JET 2 (Ref. 2), JET 3A-3D (Ref. 3), CIVM-JET 4B (Ref. 4), and JET 5A and CIVM-JET 5B (Ref. 5) developed under NASA NGR 22-009-339; the status of code availability is also indicated.

The JET 1 code of Ref. 1 pertains to single-layer complete, uniform-thickness, initially-circular rings of either temperature-independent or temperature dependent material properties. These rings may be subjected to prescribed: (a) initial velocities, (b) transient mechanical loading, and/or (c) steady nonuniform temperatures. The finite-difference method employed in this code had been shown previously (Ref. 6) to provide reliable predictions for the case of temperature-independent material properties.

The JET 2 code was written in order to extend this finite-difference analysis capability to treat multilayer rings -- cases anticipated to be of future concern. In the interests of efficiency and the minimization of computer storage requirements, temperature-dependent material properties and thermal loading features were omitted from JET 2; if these omitted features should turn out to be needed, they could be added later.

Since the JET 1 and JET 2 codes pertained to initially-circular, complete rings of uniform thickness whereas there was interest also in variable-thickness, arbitrarily curved, partial as well as complete rings, the JET 3 series of codes was developed. To accommodate these latter features as well as a variety of types of (1) boundary conditions, (2) elastic-foundation supports, and (3) point elastic supports, the more versatile finite-element analysis procedure was developed and employed.

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\* These references are identified in the reference list at the end of Appendix C.

For efficiency and user convenience, four versions of the JET 3 program were developed; each version accommodates both complete rings and partial rings. JET 3A and JET 3B pertain to uniform-thickness, initially-circular rings, and employ, respectively, the central-difference and the Houbolt finite-difference time operator; for certain cases, the latter finite-difference time operator may permit more economic converged transient response predictions than the former. The codes JET 3C and JET 3D are corresponding codes which accommodate variable-thickness, arbitrarily-curved rings.

In most of these codes (JET 1 through JET 3D, and JET 5A), the stimuli: (1) initial velocity or impulse conditions and/or (2) transient mechanical loading must be prescribed by the user or analyst. The externally-applied forces experienced by a complete or a partial ring from fragment impact are not provided within these codes. The user must supply his own estimate of the distribution and time histories of these forces. However, in the CIVM-JET 4B and CIVM-JET 5B codes, fragment/ring interaction and response effects are handled internally automatically for the idealized single-fragment and n-fragment cases provided and discussed in the Appendices of Refs. 4, 5, and 7.

The CIVM-JET 4B code (Ref. 4) was developed from a modified version of the JET 3C code, using the central difference timewise operator. The CIVM (collision imparted velocity method) handles a fragment-structure impact as a series of quasi-static momentum transfers between the attacking fragment and the local-impact-affected portion of the impacted structure. The solution proceeds as though a series of impulses has been applied to the impacted region of the structure. This code provides strain output at each Gaussian station, nodal location, and designated "additional points" for user convenience, and calculates the reaction forces at each constrained degree of freedom. Another feature of this code is the ability to accommodate branches which are used as additional structural supports. These branches can have material properties either the same or different from those present in the main structure.

The JET 5A and CIVM-JET 5B codes (Ref. 5) were written in order to extend the capabilities of the JET 3D and CIVM-JET 4B codes to multilayer

structures which are assumed to be hard-bonded and to deform in the Bernoulli-Euler fashion. Both codes (JET 5A and CIVM-JET 5B) contain the Houbolt timewise operator as well as the additional strain and reaction force output and structural support capabilities utilized in the CIVM-JET 4B code.

In convenient tabular form, the principal features and capabilities of the codes JET 1, JET 2, JET 3A-D, CIVM-JET 4B, JET 5A, and CIVM-JET 5B are given in the tabular summary on the following pages.

With respect to predicting ring structural response to fragment impact, note that codes CIVM-JET 4B and CIVM-JET 5B apply. The former pertains only to single-layer rings and employs the central-difference time operator, while CIVM-JET 5B applies to hard-bonded multilayer Bernoulli-Euler rings (including single layer rings) and utilizes the Houbolt finite-difference time operator. Thus, for single layer rings one could use either CIVM-JET 4B or CIVM-JET 5B, whereas only CIVM-JET 5B applies to multilayer rings.

With respect to deciding which of these two codes should be chosen to analyze fragment-induced structural response of single-layer rings, the following can be taken into consideration. CIVM-JET 4B utilizes the very compact and efficient unconventional formulation of the ring's equations of motion and hence involves minimum computations and storage per time step of calculation; on the other hand, this code utilizes the central difference time operator whose maximum time step size is limited to about  $\Delta t_{\max} \leq 1.6/\omega_{\max}$  where  $\omega_{\max}$  is the highest frequency of the linear elastic behavior of the structural model employed, unless impact-interaction convergence dictates a smaller value -- a condition not encountered thus far in calculation examples explored. Since CIVM-JET 5B uses the conventional form of the ring's equations of motion, more computations and storage per time step of calculation are needed than in CIVM-JET 4B; however, CIVM-JET 5B employs the Houbolt finite-difference time operator which permits one to use a time step size  $\Delta t$  larger by a factor of perhaps 3 to 10 or more than permitted by CIVM-JET 4B's central-difference operator unless the impact-interactions and convergence impose a more stringent limit. Because of these tradeoffs, it is not clear which of these two codes will be the more

efficient one for obtaining reliable converged predictions of impact-induced structural response of single-layer rings; it appears that further computational experience on various example problems will be needed before a clear choice can be made. However, on an equal-cost basis, experience to date indicates that one must use for CIVM-JET 5B a  $\Delta t$  at least 5 times as large as the maximum time step size permitted in CIVM-JET 4B to be competitive. In one example a 10-times larger  $\Delta t$  resulted in a CIVM-JET 5B prediction that failed to converge. Thus, until further computational experience has accumulated sufficiently, it would be advisable to begin with CIVM-JET 4B for analyzing "new problems" unless an intolerably small  $\Delta t$  is encountered, since this code exhibits usually a dramatic warning (computational blow up) when the chosen  $\Delta t$  is too large, whereas CIVM-JET 5B does not usually afford clear telltale signs of ill-behaved computations. With this CIVM-JET 4B starting point as guidance, one could explore the utility of employing CIVM-JET 5B with a time step size of perhaps 5 to 10 times larger.

For the analysis of ring response to prescribed external transient loads or to prescribed distributions of initial velocity (rather than fragment impact-induced response), similar considerations to those just discussed apply concerning the analysis of single-layer rings by JET 3C (which uses the central difference time operator) versus JET 5A (which employs the Houbolt operator); for these kinds of problems, experience to date indicates that response predictions of a given accuracy can be obtained more efficiently by using JET 5A's larger allowable  $\Delta t$  (i.e. by a factor of perhaps 6 to 10 or more than permitted by JET 3C). Finally, even for the analysis of single-layer rings for this class of (non-impact) problems, the use of the more recent and versatile JET 5A computer program is recommended over the use of JET 3D even though both of these codes employ the Houbolt operator.



[illegible]

Feature	JET 1	JET 2	JET 3A	JET 3B	JET 3C	JET 3D	CIVM-JET 4B	JET 5A	CIVM-JET 5B
<u>Material</u>									
Single Material	x	-	x	x	x	x	x	x	x
Different for Each Layer	-	x	-	-	-	-	-	x	x
Homogeneous	x	x	x	x	x	x	x	x	x
Initially Isotropic	x	x	x	x	x	x	x	x	x
Temperature Independent	x	x	x	x	x	x	x	x	x
Temperature Dependent	x	-	-	-	-	-	-	-	-
EL	x	x	x	x	x	x	x	x	x
EL-PP	x	x	x	x	x	x	x	x	x
EL-LSH	x	x	x	x	x	x	x	x	x
EL-SH	x	x	x	x	x	x	x	x	x
EL-SH-SR	x	x	x	x	x	x	x	x	x
<u>Stimuli</u>									
Initial Velocity									
Arbitrary	x	x	x	x	x	x	-	x	-
Half-Sine over each of Selected Regions	x	x	x	x	x	x	-	x	-
Mechanical Loading									
Arbitrary Spatial Distribution with Arb. Time History	-	x	x	x	x	x	-	x	-
Half-Sine over each of Selected Regions	x	x	x	x	x	x	-	x	-
Triangular Time History	x	x	x	x	x	x	-	x	-
Arbitrary Time History	-	x	x	x	x	x	-	x	-
Thermal Loads (Temp. Distribution)									
Distribution Thru Thickness	x	-	-	-	-	-	-	-	-
Time-Independent Prescribed Circumferential Distribution	x	-	-	-	-	-	-	-	-
Impacting Fragments									
Single	-	-	-	-	-	-	x	-	x
Multiple	-	-	-	-	-	-	x	-	x
Friction	-	-	-	-	-	-	x	-	x

Feature	JET 1	JET 2	JET 3A	JET 3B	JET 3C	JET 3D	CIVM-JET 4B	JET 5A	CIVM-JET 5B
<u>Deflections: Bernoulli-Euler</u>									
<u>Type Only</u>									
Small	x	x	x	x	x	x	x	x	x
Arbitrarily Large	x	x	x	x	x	x	x	x	x
<u>OUTPUT INFORMATION</u>									
<u>At Selected Times</u>									
Energy/Work Type and Amount	x	x	x	x	x	x	x	x	x
Nodal Station Data									
Locations Y,Z	x	x	x	x	x	x	x	x	x
Displacements	-	-	x	x	x	x	x	x	x
Moment Resultant	x	x	x	x	x	x	x	x	x
Circum. Force Resultant	x	x	x	x	x	x	x	x	x
Circumferential Strains									
Inner Surface	x	x	x	x	x	x	x	x	x
Outer Surface	x	x	x	x	x	x	x	x	x
Location where Prescribed Value is Exceeded	-	x	x	x	x	x	-	-	-
Strain at Gaussian Stations	-	-	-	-	-	-	x	x	x
Strain at Additional Location	-	-	-	-	-	-	x	x	x
Support Reaction Forces	-	-	-	-	-	-	x	x	x
<u>At Certain Other Times</u>									
Time of First Yielding	x	x	-	-	-	-	-	-	-
Time when Strain First Exceeds a Prescribed Value	-	x	x	x	x	x	-	-	-
Time, Location, and Value of Largest Strain Reached During Run	-	-	x	x	x	x	(For Each Substructure)		
							x	x	x
<u>CAPACITY INFORMATION</u>									
Maximum No. of Finite-Difference Stations*	100	100	-	-	-	-	-	-	-
Maximum No. of Finite Elements*	-	-	50	50	50	50	50	50	50
* These limits can be circumvented by altering the dimensions of appropriate program variables (see each source reference).									

# STRUCTURAL RESPONSE COMPUTER CODE STATUS<sup>c</sup>

<u>Code</u>	<u>Capability</u>	<u>Status</u>	<u>Availability</u>
JET 3	2-D Single-Layer Beams and Rings Subjected to Prescribed Transient Loads or Initial Velocity Distributions (No Fragment Impact)	Complete (Ref. 3)	a
CIVM-JET 4B	2-D Single-Layer Beams and Rings Subjected Only to Fragment Impact	Complete (Ref. 4)	"b
JET 5A	2-D Multilayer Bernoulli-Euler Beams and Rings Subjected to Prescribed Transient Loads or Initial Velocity Distributions	Complete (Ref. 5)	b
CIVM-JET 5B	2-D Multilayer B-E Beams and Rings Subjected Only to Fragment Impact	Complete (Ref. 5)	b
PLATE and CIVM-PLATE	3-D Single-Layer Initially-Flat Panels Subjected, Respectively, to (1) Prescribed Transient Loads and/or Initial Velocity Distributions or (2) Fragment Impact Only	In Progress	--

a: Available from COSMIC, Barrow Hall, University of Georgia, Athens, GA. 30601; contact MIT for errata.

b: Available under a copyright licensing agreement from MIT. Contact Prof. E.A. Witmer, Room 41-213, MIT, Cambridge, MA. 02139.

c: JET1(Ref. 1) and JET 2 (Ref. 2) have not been maintained and are available only from the listings in the cited references; in turn, these references are available only from the National Technical Information Service (NTIS), Springfield, VA. 22161.

#### REFERENCES FOR APPENDIX C

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4. Stagliano, T.R., Spilker, R.L. and Witmer, E.A., "User's Guide to Computer Program CIVM-JET 4B to Calculate the Transient Structural Responses of Partial and/or Complete Structural Rings to Engine Rotor Fragment Impact", MIT ASRL TR 154-9, March 1976. (Available as NASA CR-134907.)
5. Wu, R.W.-H., Stagliano, T.R., Witmer, E.A. and Spilker, R.L., "User's Guide to Computer Programs JET 5A and CIVM-JET 5B to Calculate the Large Elastic-Plastic Dynamically-Induced Deformations of Multilayer Partial and/or Complete Structural Rings", MIT ASRL TR 154-10, November 1978.
6. Balmer, H.A. and Witmer, E.A., "Theoretical-Experimental Correlation of Large Dynamic and Permanent Deformations of Impulsively-Loaded Simple Structures", Massachusetts Institute of Technology, AFFDL-TDR-64-108, July 1964.
7. Collins, T.P. and Witmer, E.A., "Application of the Collision-Imparted Velocity Method for Analyzing the Responses of Containment and Deflector Structures to Engine Rotor Fragment Impact", ASRL TR 154-8, MIT, August 1973. (Available as NASA CR-134494.)

## APPENDIX D

### SUMMARY OF GAUSSIAN NUMERICAL INTEGRATION OR QUADRATURE

Gaussian numerical integration (or quadrature) is a convenient and efficient method for the numerical evaluation of line, surface, and/or volume integrals. For one-dimensional (or line) integration, Gaussian numerical n-station integration is of the form [14, Ch. 8]:

$$\int_{-1}^{+1} F(x) dx \doteq \sum_{j=1}^n H_j F(x_j) \quad (D.1)$$

where

$H_1, H_2, \dots, H_n$  are tabulated weighting factors associated with sampling locations  $x_j, j=1, 2, \dots, n$ .

$F(x_j)$  represents the value of  $F(x)$  at prescribed unequally-spaced "sampling stations"  $x_j$  (or  $a_j \equiv x_j$ ) for  $j=1, 2, \dots, n$

For n-station Gaussian quadrature, polynomials of degree  $2n-1$  and smaller are integrated exactly [14]. Sampling locations  $a_j$  and weights  $H_j$  follow for the Gaussian numerical integration evaluation [14-17] represented by Eq. D.1 for  $n=2, 3, 4, 5, 6, 7, 8, 9$ , and 10 (values for  $n$  up to 96 may be found in Ref. 16):

<u>Station</u>	<u>Weight</u>
<u>+a</u>	<u>H</u>
$n = 2$	
0.57735 02691 89626	1.00000 00000 00000
$n = 3$	
0.77459 66692 41483	0.55555 55555 55556
0.00000 00000 00000	0.88888 88888 88889
$n = 4$	
0.86113 63115 94053	0.34785 48451 37454
0.33998 10435 84856	0.65214 51548 62546

<u>Station</u>	<u>Weight</u>
<u>+a</u>	<u>H</u>
n = 5	
0.90617 98459 38664	0.23692 68850 56189
0.53846 93101 05683	0.47862 86704 99366
0.00000 00000 00000	0.56888 88888 88889
n = 6	
0.93246 95142 03152	0.17132 44923 79170
0.66120 93864 66265	0.36076 15730 48139
0.23861 91860 83197	0.46791 39345 72691
n = 7	
0.94910 79123 42759	0.12948 49661 68870
0.74153 11855 99394	0.27970 53914 89277
0.40584 51513 77397	0.38183 00505 05119
0.00000 00000 00000	0.41795 91836 73469
n = 8	
0.96028 98564 97536	0.10122 85362 90376
0.79666 64774 13627	0.22238 10344 53374
0.52553 24099 16329	0.31370 66458 77887
0.18343 46424 95650	0.36268 37833 78362
n = 9	
0.96816 02395 07626	0.08127 43883 61574
0.83603 11073 26636	0.18064 81606 94857
0.61337 14327 00590	0.26061 06964 02935
0.32425 34234 03809	0.31234 70770 40003
0.00000 00000 00000	0.33023 93550 01260
n = 10	
0.97390 65285 17172	0.06667 13443 08688
0.86506 33666 88985	0.14945 13491 50581
0.67940 95682 99024	0.21908 63625 15982
0.43339 53941 29247	0.26926 67193 09996
0.14887 43389 81631	0.29552 42247 14753

The above tabulation applies to  $\int_{-1}^{+1} F(x) dx \doteq \sum_{j=1}^n H_j F(a_j)$  where  $-1 < a_j < 1$ .  
However, these entries can be modified to apply to any interval  $[a,b]$  as follows to evaluate:

$$\int_a^b F(x) dx \doteq \sum_{j=1}^n W_j F(x_j) \quad (D.2)$$

For Eq. D.2, the "new"  $W_j$  and  $x_j$  for given  $H_j$  and  $a_j$  become:

$$\begin{aligned} W_j &= \frac{a+b}{2} H_j \\ x_j &= \left( \frac{|a|+|b|}{2} \right) (1 + a_j) \end{aligned} \quad (D.2a)$$

For example, consider

$$\int_0^1 F(x) dx \doteq \sum_{j=1}^n W_j F(x_j) \quad (D.3)$$

Hence,

$$\begin{aligned} W_j &= \left( \frac{0+1}{2} \right) H_j \\ x_j &= \left( \frac{0+1}{2} \right) (1 + a_j) \end{aligned} \quad (D.4)$$

For the 3-station case ( $n=3$ ), for example, one obtains:

j	$a_j$	$H_j$	$x_j$	$W_j$
1	-.77459...	0.55555...	0.11270166...	0.277777...
2	0	0.88888...	0.50	0.44444...
3	+.77459	0.55555...	0.8872983...	0.277777...

Similarly, one may perform Gaussian quadrature in two and three dimensions by, respectively,

$$\int_{-1}^{+1} \int_{-1}^{+1} F(\xi, \eta) d\xi d\eta \doteq \sum_{i=1}^n \sum_{j=1}^m H_i H_j F(\xi_i, \eta_j) \quad (D.5)$$

$$\int_{-1}^{+1} \int_{-1}^{+1} \int_{-1}^{+1} F(\xi, \eta, \zeta) d\xi d\eta d\zeta \doteq \sum_{i=1}^p \sum_{j=1}^q \sum_{k=1}^r H_i H_j H_k F(\xi_i, \eta_j, \zeta_k) \quad (D.6)$$

Conversions similar to those given by Eq. D.2a may be employed for other limits of integration.

For quadrature over triangles, cones, tetrahedra, etc., see Refs. 14, 15, and 17.